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**MÉCANIQUE DU SOLIDE DÉFORMABLE**

**TRAVAUX DIRIGÉS**

**Luca Di Stasio**



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## **List of Acronyms**

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## *List of Acronyms*

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## List of Symbols



## **Abstract**





# 1. Systèmes de coordonnées curvilignes

## 1.1. Énoncé

### 1.1.1. Problème A

### 1.1.2. Problème B

## 1.2. Corrigé

### 1.2.1. Problème A

$$\begin{cases} x = x(\xi, \eta, \zeta) \\ y = y(\xi, \eta, \zeta) \\ z = z(\xi, \eta, \zeta) \end{cases} \longleftrightarrow \begin{cases} \xi = \xi(x, y, z) \\ \eta = \eta(x, y, z) \\ \zeta = \zeta(x, y, z) \end{cases} \quad (1)$$

$$f(x, y, z) = f(x(\xi, \eta, \zeta), y(\xi, \eta, \zeta), z(\xi, \eta, \zeta)) \quad (2)$$

$$f(\xi, \eta, \zeta) = f(\xi(x, y, z), \eta(x, y, z), \zeta(x, y, z)) \quad (3)$$

$$\nabla_{xyz}^2 f(x, y, z) = \frac{\partial^2 f}{\partial x^2} + \frac{\partial^2 f}{\partial y^2} + \frac{\partial^2 f}{\partial z^2} \quad (4)$$

$$\begin{cases} \frac{\partial f}{\partial x} = \frac{\partial f}{\partial \xi} \frac{\partial \xi}{\partial x} + \frac{\partial f}{\partial \eta} \frac{\partial \eta}{\partial x} + \frac{\partial f}{\partial \zeta} \frac{\partial \zeta}{\partial x} \\ \frac{\partial f}{\partial y} = \frac{\partial f}{\partial \xi} \frac{\partial \xi}{\partial y} + \frac{\partial f}{\partial \eta} \frac{\partial \eta}{\partial y} + \frac{\partial f}{\partial \zeta} \frac{\partial \zeta}{\partial y} \\ \frac{\partial f}{\partial z} = \frac{\partial f}{\partial \xi} \frac{\partial \xi}{\partial z} + \frac{\partial f}{\partial \eta} \frac{\partial \eta}{\partial z} + \frac{\partial f}{\partial \zeta} \frac{\partial \zeta}{\partial z} \end{cases} \quad (5)$$





$$\frac{\partial^2 f}{\partial \eta \partial \xi} = \frac{\partial^2 f}{\partial \xi \partial \eta} \quad \frac{\partial^2 f}{\partial \eta \partial \zeta} = \frac{\partial^2 f}{\partial \zeta \partial \eta} \quad \frac{\partial^2 f}{\partial \xi \partial \zeta} = \frac{\partial^2 f}{\partial \zeta \partial \xi} \quad (13)$$

$$\begin{aligned} \nabla_{\xi\eta\zeta}^2 f(\xi, \eta, \zeta) = & \left[ \left( \frac{\partial \xi}{\partial x} \right)^2 + \left( \frac{\partial \xi}{\partial y} \right)^2 + \left( \frac{\partial \xi}{\partial z} \right)^2 \right] \frac{\partial^2 f}{\partial \xi^2} + \\ & + \left[ \left( \frac{\partial \eta}{\partial x} \right)^2 + \left( \frac{\partial \eta}{\partial y} \right)^2 + \left( \frac{\partial \eta}{\partial z} \right)^2 \right] \frac{\partial^2 f}{\partial \eta^2} + \\ & + \left[ \left( \frac{\partial \zeta}{\partial x} \right)^2 + \left( \frac{\partial \zeta}{\partial y} \right)^2 + \left( \frac{\partial \zeta}{\partial z} \right)^2 \right] \frac{\partial^2 f}{\partial \zeta^2} + \\ & + 2 \left[ \left( \frac{\partial \xi}{\partial x} \right) \left( \frac{\partial \eta}{\partial x} \right) + \left( \frac{\partial \xi}{\partial y} \right) \left( \frac{\partial \eta}{\partial y} \right) + \left( \frac{\partial \xi}{\partial z} \right) \left( \frac{\partial \eta}{\partial z} \right) \right] \frac{\partial^2 f}{\partial \xi \partial \eta} + \\ & + 2 \left[ \left( \frac{\partial \eta}{\partial x} \right) \left( \frac{\partial \zeta}{\partial x} \right) + \left( \frac{\partial \eta}{\partial y} \right) \left( \frac{\partial \zeta}{\partial y} \right) + \left( \frac{\partial \eta}{\partial z} \right) \left( \frac{\partial \zeta}{\partial z} \right) \right] \frac{\partial^2 f}{\partial \eta \partial \zeta} + \\ & + 2 \left[ \left( \frac{\partial \xi}{\partial x} \right) \left( \frac{\partial \zeta}{\partial x} \right) + \left( \frac{\partial \xi}{\partial y} \right) \left( \frac{\partial \zeta}{\partial y} \right) + \left( \frac{\partial \xi}{\partial z} \right) \left( \frac{\partial \zeta}{\partial z} \right) \right] \frac{\partial^2 f}{\partial \xi \partial \zeta} \end{aligned} \quad (14)$$

### Coordonnées cylindriques

$$\begin{cases} x = r \cos \theta \\ y = r \sin \theta \\ z = z \end{cases} \longleftrightarrow \begin{cases} r = \sqrt{x^2 + y^2} \\ \theta = \tan^{-1} \left( \frac{y}{x} \right) \\ z = z \end{cases} \quad (15)$$

$$\begin{cases} \frac{\partial r}{\partial x} = \frac{1}{2} \frac{2x}{\sqrt{x^2 + y^2}} = \frac{r' \cos \theta}{r'} \\ \frac{\partial r}{\partial y} = \frac{1}{2} \frac{2y}{\sqrt{x^2 + y^2}} = \frac{r' \sin \theta}{r'} \\ \frac{\partial r}{\partial z} = 0 \end{cases} \quad (16)$$

### Coordonnées sphériques

#### 1.2.2. Problème B

$$\begin{cases} x = x(\xi, \eta, \zeta) \\ y = x(\xi, \eta, \zeta) \\ z = x(\xi, \eta, \zeta) \end{cases} \longleftrightarrow \begin{cases} \xi = \xi(x, y, z) \\ \eta = \eta(x, y, z) \\ \zeta = \zeta(x, y, z) \end{cases} \quad (17)$$

$$f(x, y, z) = f(\xi(\eta, \zeta), y(\xi, \eta, \zeta), z(\xi, \eta, \zeta)) \quad (18)$$

$$f(\xi, \eta, \zeta) = f(\xi(x, y, z), \eta(x, y, z), \zeta(x, y, z)) \quad (19)$$

$$\nabla f_{xyz} = \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \\ \frac{\partial f}{\partial z} \end{bmatrix} = \frac{\partial f}{\partial x} \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} + \frac{\partial f}{\partial y} \begin{bmatrix} 0 \\ 1 \\ 0 \end{bmatrix} + \frac{\partial f}{\partial z} \begin{bmatrix} 0 \\ 0 \\ 1 \end{bmatrix} = \frac{\partial f}{\partial x} \mathbf{i}_x + \frac{\partial f}{\partial y} \mathbf{j}_y + \frac{\partial f}{\partial z} \mathbf{k}_z \quad (20)$$

$$\nabla f = \begin{bmatrix} \frac{\partial f}{\partial x} \\ \frac{\partial f}{\partial y} \\ \frac{\partial f}{\partial z} \end{bmatrix} = \begin{bmatrix} \frac{\partial f}{\partial \xi} \frac{\partial \xi}{\partial x} + \frac{\partial f}{\partial \eta} \frac{\partial \eta}{\partial x} + \frac{\partial f}{\partial \zeta} \frac{\partial \zeta}{\partial x} \\ \frac{\partial f}{\partial \xi} \frac{\partial \xi}{\partial y} + \frac{\partial f}{\partial \eta} \frac{\partial \eta}{\partial y} + \frac{\partial f}{\partial \zeta} \frac{\partial \zeta}{\partial y} \\ \frac{\partial f}{\partial \xi} \frac{\partial \xi}{\partial z} + \frac{\partial f}{\partial \eta} \frac{\partial \eta}{\partial z} + \frac{\partial f}{\partial \zeta} \frac{\partial \zeta}{\partial z} \end{bmatrix} = \frac{\partial f}{\partial \xi} \begin{bmatrix} \frac{\partial \xi}{\partial x} \\ \frac{\partial \xi}{\partial y} \\ \frac{\partial \xi}{\partial z} \end{bmatrix} + \frac{\partial f}{\partial \eta} \begin{bmatrix} \frac{\partial \eta}{\partial x} \\ \frac{\partial \eta}{\partial y} \\ \frac{\partial \eta}{\partial z} \end{bmatrix} + \frac{\partial f}{\partial \zeta} \begin{bmatrix} \frac{\partial \zeta}{\partial x} \\ \frac{\partial \zeta}{\partial y} \\ \frac{\partial \zeta}{\partial z} \end{bmatrix} \quad (21)$$

$$\begin{aligned} \mathbf{i}_\xi &= \frac{1}{\sqrt{\left(\frac{\partial \xi}{\partial x}\right)^2 + \left(\frac{\partial \xi}{\partial y}\right)^2 + \left(\frac{\partial \xi}{\partial z}\right)^2}} \begin{bmatrix} \frac{\partial \xi}{\partial x} \\ \frac{\partial \xi}{\partial y} \\ \frac{\partial \xi}{\partial z} \end{bmatrix} \\ \mathbf{j}_\eta &= \frac{1}{\sqrt{\left(\frac{\partial \eta}{\partial x}\right)^2 + \left(\frac{\partial \eta}{\partial y}\right)^2 + \left(\frac{\partial \eta}{\partial z}\right)^2}} \begin{bmatrix} \frac{\partial \eta}{\partial x} \\ \frac{\partial \eta}{\partial y} \\ \frac{\partial \eta}{\partial z} \end{bmatrix} \\ \mathbf{k}_\zeta &= \frac{1}{\sqrt{\left(\frac{\partial \zeta}{\partial x}\right)^2 + \left(\frac{\partial \zeta}{\partial y}\right)^2 + \left(\frac{\partial \zeta}{\partial z}\right)^2}} \begin{bmatrix} \frac{\partial \zeta}{\partial x} \\ \frac{\partial \zeta}{\partial y} \\ \frac{\partial \zeta}{\partial z} \end{bmatrix} \end{aligned} \quad (22)$$

$$\begin{aligned}\nabla_{\xi\eta\zeta}f &= \frac{\partial f}{\partial \xi} \sqrt{\left(\frac{\partial \xi}{\partial x}\right)^2 + \left(\frac{\partial \xi}{\partial y}\right)^2 + \left(\frac{\partial \xi}{\partial z}\right)^2} \cdot \mathbf{i}_\xi + \\ &\quad + \frac{\partial f}{\partial \eta} \sqrt{\left(\frac{\partial \eta}{\partial x}\right)^2 + \left(\frac{\partial \eta}{\partial y}\right)^2 + \left(\frac{\partial \eta}{\partial z}\right)^2} \cdot \mathbf{j}_\eta + \\ &\quad + \frac{\partial f}{\partial \zeta} \sqrt{\left(\frac{\partial \zeta}{\partial x}\right)^2 + \left(\frac{\partial \zeta}{\partial y}\right)^2 + \left(\frac{\partial \zeta}{\partial z}\right)^2} \cdot \mathbf{k}_\zeta = \\ &= \begin{bmatrix} \frac{\partial f}{\partial \xi} \sqrt{\left(\frac{\partial \xi}{\partial x}\right)^2 + \left(\frac{\partial \xi}{\partial y}\right)^2 + \left(\frac{\partial \xi}{\partial z}\right)^2} \\ \frac{\partial f}{\partial \eta} \sqrt{\left(\frac{\partial \eta}{\partial x}\right)^2 + \left(\frac{\partial \eta}{\partial y}\right)^2 + \left(\frac{\partial \eta}{\partial z}\right)^2} \\ \frac{\partial f}{\partial \zeta} \sqrt{\left(\frac{\partial \zeta}{\partial x}\right)^2 + \left(\frac{\partial \zeta}{\partial y}\right)^2 + \left(\frac{\partial \zeta}{\partial z}\right)^2} \end{bmatrix}\end{aligned}\tag{23}$$

**Coordonnées cylindriques**

**Coordonnées sphériques**

## **2. Second section**





## **A. First appendix**

