

IGERT Data Science : Graph Algorithms

Nirman Kumar

University of California, Santa-Barbara

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Why study Graphs and Graph algorithms

Graphs are useful in modeling complex systems with interacting components

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Graphs are useful in modeling complex systems with interacting components

**We look at, understand, and interact with graphs locally:
Graph algorithms compute more global properties**

Graphs - Mathematics and Computer Science

Graphs have a deep Mathematical theory

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**“Intrinsic” to computer science - represent hard problems,
program states and execution, search structures, etc.**

Network Science

Network Science :: Graphs

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Network Science :: Graphs

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Statistical Mechanics :: Mechanics

Examples of “real networks”

- ▶ **The internet**
- ▶ **The WWW**
- ▶ **The Power Grid**
- ▶ **Collaboration network**
- ▶ **Citations**

An indispensable tool : Visualization



Courtesy : The OPTE project

Goals of Network Science

Understand and infer “macro” properties of networks

- ▶ **Network vulnerability**
- ▶ **How things spread : information, epidemics etc.**
- ▶ **Identifying “important” nodes in networks**
- ▶ ...

Graph theory and Algorithms

Page rank : Google's secret formula

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**Depends on computing over the WWW network -
EFFICIENTLY**

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**Graph algorithms : indispensable to compute statistics on
large networks**

Fundamental graph problems

- ▶ **Traversals**
- ▶ **Connectivity**
- ▶ **Shortest paths**
- ▶ **Identifying subgraphs with specific structure**
- ▶ **Characterizing graphs**
- ▶ **Optimization problems**
- ▶ ...

The Shortest Path problem

Given graph and a vertex s find shortest paths from s to all other vertices.

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- ▶ Map routing, robot navigation, urban traffic planning
- ▶ Network routing protocols (OSPF, BGP, RIP)
- ▶ ...

Traversals : Depth First Search (DFS)

Visit all vertices of the graph

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Visit all vertices of the graph

Procedure DFS(G, v)

begin

 label v as discovered

forall the edges from v to w in $G.adjacentEdges(v)$ **do**

if w is not labeled as discovered **then**

 recursively call DFS(G, w)

end

end

end

Non recursive DFS

Procedure DFS-iterative(G, s)

begin

$S \leftarrow$ empty stack

$S.\text{push}(s)$

while S is not empty **do**

$v \leftarrow S.\text{pop}()$

if v is not labeled as discovered **then**

 label v as discovered

forall the edges from v to w in $G.\text{adjacentEdges}(v)$ **do**

$S.\text{push}(w)$

end

end

end

end

Breadth First Search

Can compute shortest paths in unweighted graphs!

Breadth First Search

Procedure BFS(G, s)

begin

$s.\text{dist} \leftarrow 0$

for $\text{currDist} \leftarrow 0$ **to** $|V|$ **do**

for *all vertices* v **do**

if v *not labeled as discovered* and $v.\text{dist} == \text{currDist}$ **then**

 Label v as discovered

forall the *edges from* v *to* w *in* $G.\text{adjacentEdges}(v)$ **do**

 Handle w

end

end

end

end

end

Breadth First Search

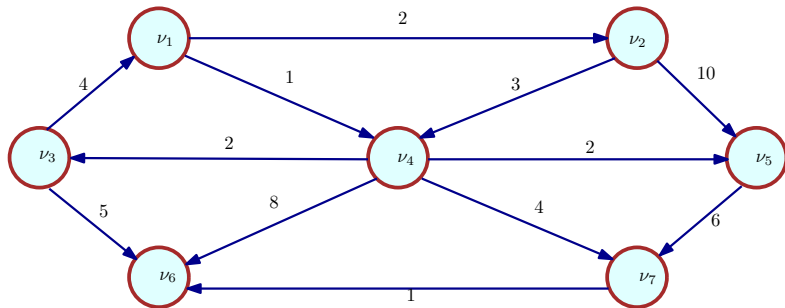
Runtime : $O(|V|^2)$

Breadth First Search

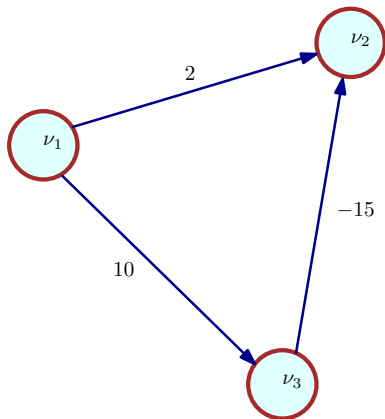
Runtime : $O(|V|^2)$

Can achieve $O(|V| + |E|)$ using a smarter implementation

Edge weighted graphs



Negative edge weights



Main structural properties of Shortest Paths

- ▶ **Prefixes of shortest paths are shortest paths**
- ▶ **Shortest paths from s - make up a tree**

Advancing the frontier

- ▶ **At any time we know the distance of some vertices**

Advancing the frontier

- ▶ At any time we know the distance of some vertices
- ▶ How do we discover further?

Advancing the frontier

- ▶ At any time we know the distance of some vertices
- ▶ How do we discover further?
- ▶ Relaxation of an edge $(v, w) : d(w) = \min(d(w), d(v) + c_{vw})$

Dijkstra algorithm : Generalize BFS

- **Store d_v , $v.\text{isKnown}$, $v.\text{path}$**

Dijkstra algorithm : Generalize BFS

- ▶ **Store d_v , $v.\text{isKnown}$, $v.\text{path}$**
- ▶ **Pick vertex with minimum d_v (that is not known)**

Dijkstra algorithm : Generalize BFS

- ▶ **Store d_v , $v.\text{isKnown}$, $v.\text{path}$**
- ▶ **Pick vertex with minimum d_v (that is not known)**
- ▶ **Mark it known**

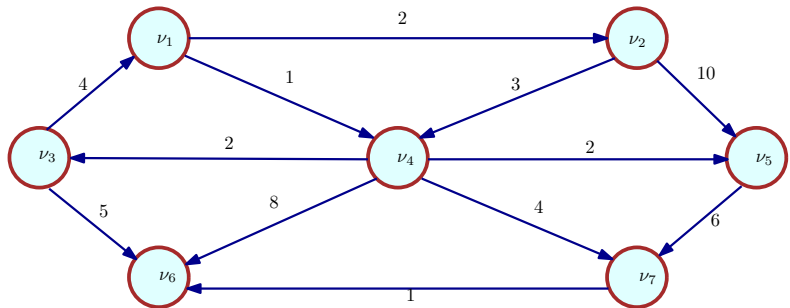
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- ▶ Store d_v , $v.\text{isKnown}$, $v.\text{path}$
- ▶ Pick vertex with minimum d_v (that is not known)
- ▶ Mark it known
- ▶ Relax all edges outgoing from it

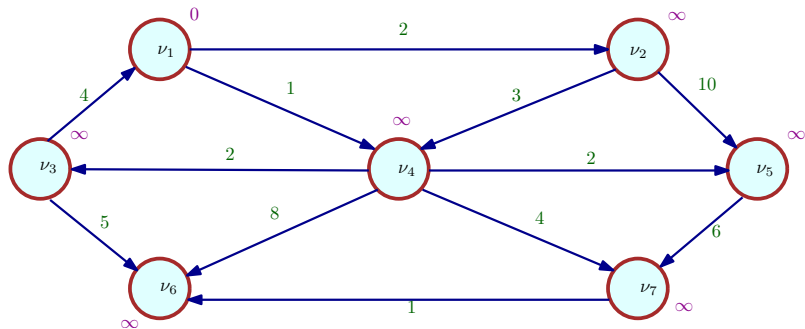
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- ▶ Relax all edges outgoing from it
- ▶ Repeat until all vertices are known

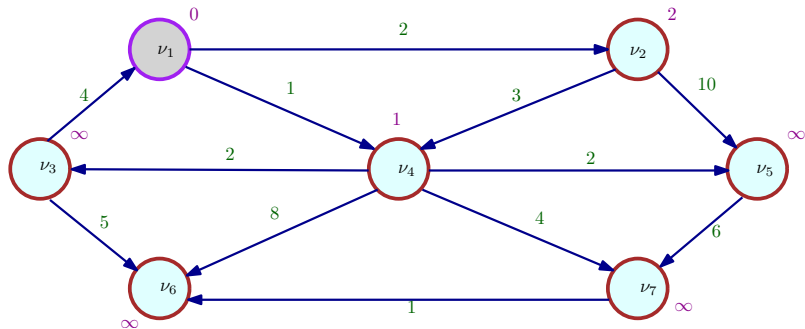
Example of Dijkstra in action



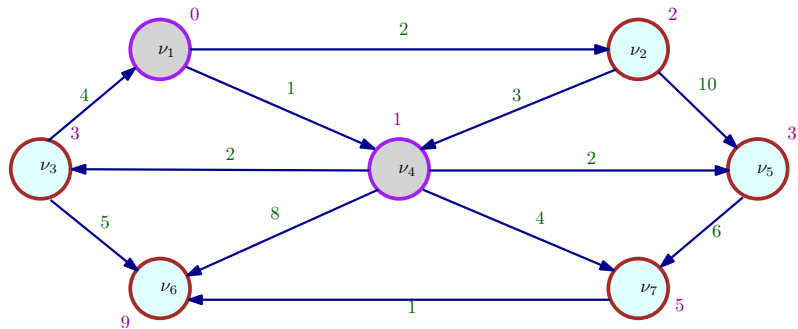
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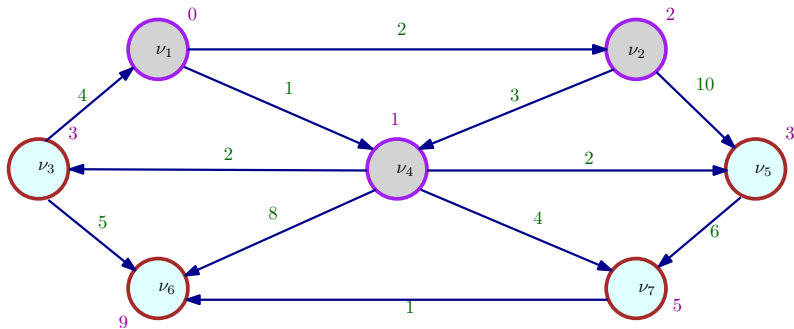
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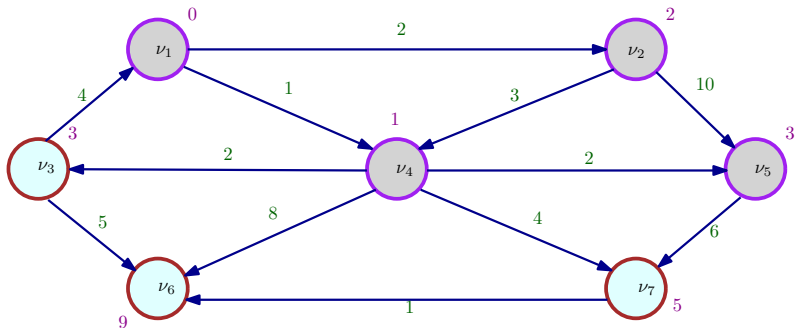
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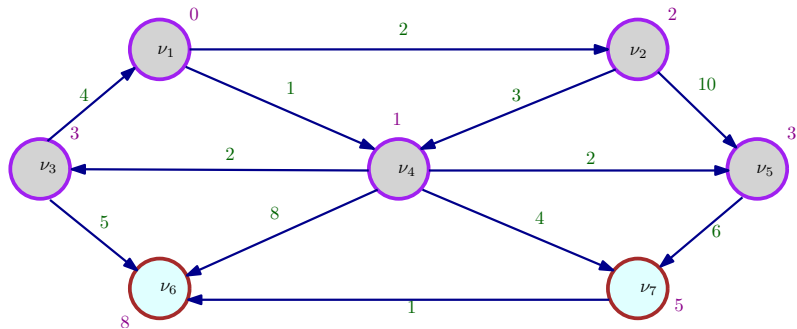
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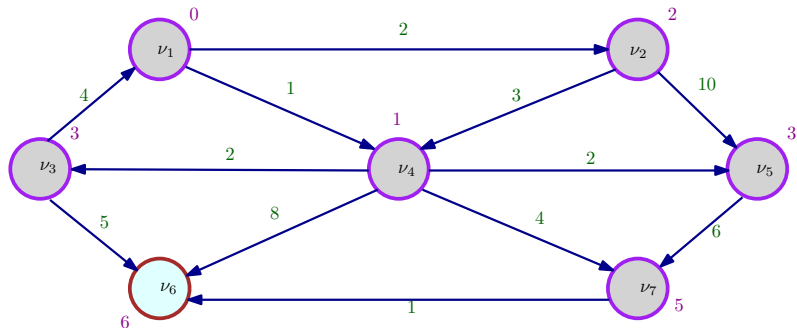
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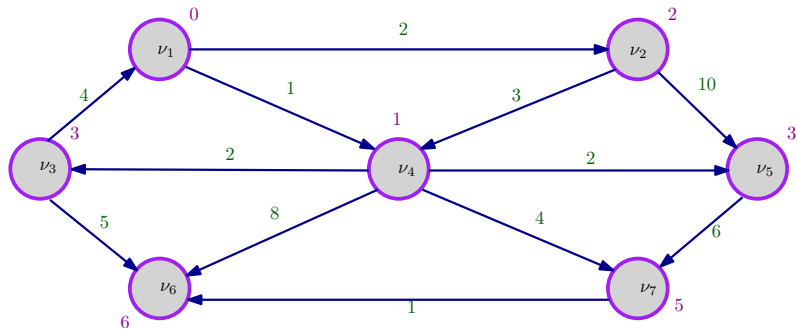
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How efficient is Dijkstra

Naive implementation : $O(|E| + |V|^2) = O(|V|^2)$

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Using a heap : $O(|E| \log |V|)$

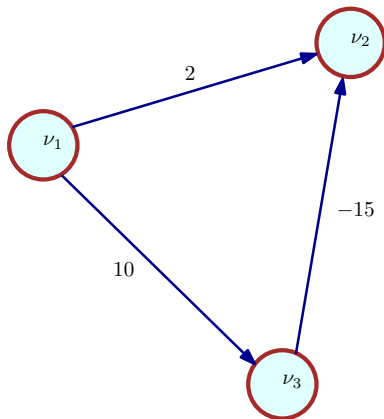
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Naive implementation : $O(|E| + |V|^2) = O(|V|^2)$

Using a heap : $O(|E| \log |V|)$

Using Fibonacci heap : $O(|E| + |V| \log |V|)$

Negative edge weights!



The Bellman Ford algorithm

```
Procedure Bellman-Ford( $G, s$ ) begin  
  |  $s.\text{dist} \leftarrow 0$  ;  
  | for  $i \leftarrow 1$  to  $|V|$  do  
  |   | Relax each edge  
  | end  
end
```

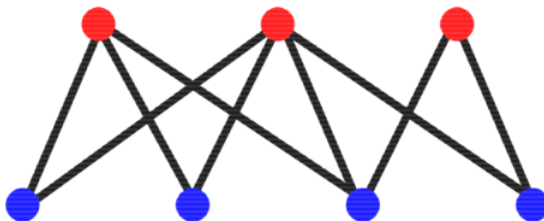
Runtime : $O(|E||V|)$

All-Pairs Shortest Path

- ▶ **Can run $|V|$ Dijkstra's** - $O(|E||V| \log |V|)$
- ▶ **Floyd Warshall** - $O(|V|^3)$

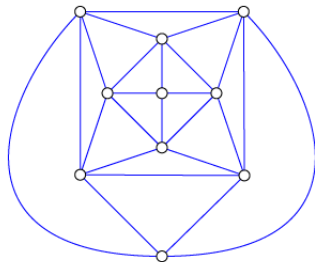
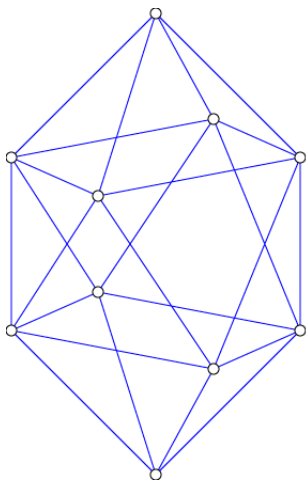
Graphs with special structure

Bipartite : $V = V_1 \cup V_2$, edges only between V_1, V_2



Graphs with special structure

Planar: Can be drawn in the plane without crossings - sparse



Back to networks

How can we model real networks?

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**Doing mathematical analysis on the abstracted models helps
us understand networks**

Models should fit

Models should be guided by observed properties

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Test their computed properties against observed ones

Some common network models

- ▶ **Random graph models - why?**
- ▶ **Random (n, m) graphs**
- ▶ **Erdős-Rényi model**
- ▶ **Albert-Barbási model - preferential attachment**
- ▶ **Watts Strogatz model - small world phenomena**

Summary statistics and Performance metrics

- ▶ Diameter and mean path length
- ▶ Clustering, average clustering, global clustering
- ▶ Degree distribution
- ▶ Centrality and its distribution

The definitions

Clustering coefficient: $C_i = 2L_i/k_i(k_i - 1)$

Global clustering coefficient : $\frac{3 \times \text{Number of triangles}}{\text{Number of connected triples}}$

Betweenness Centrality

$$g(v) = \text{Normalizing factor} \times \sum_{s \neq v \neq t} \frac{\sigma_{st}(v)}{\sigma_{st}}$$

Why so many network models are needed?

- ▶ Erdős-Rényi model does not capture global clustering
- ▶ Watts-Strogatz model captures small world properties
- ▶ Networks *grow* - how can we accommodate that?

Graphs algorithms - the message

Network Science is important

Graphs algorithms - the message

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Understanding graphs and computing with them is the key to understanding networks better

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Network Science is important

Understanding graphs and computing with them is the key to understanding networks better

Need approximate but very fast algorithms for basic tasks