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Objective

Develop a parallel **branch-and-bound** algorithm to compute the **chromatic number** of graphs using the Vega supercomputer.

Vega architecture

CPU CLUSTER : 960 nodes, each with 2 AMD Rome 7H12 CPUs with 64 cores, for a total of 1,920 and 122,880 cores.

GPU CLUSTER : 60 nodes, each 4 Nvidia A100 GPUs and 2 AMD Rome 7h12 Cpus240 NVIDIA, for a total of 240 A100 GPUs

This project aims to leverage HPC capabilities to solve complex combinatorial optimization problems in graph theory.

Zykov algorithm

Given two non-adjacent vertices $x, y \in V$ two new graphs can be defined:

- G'_{xy} where x and y are contracted or merged into one single vertex xy .
- G''_{xy} where the edge $\{x, y\}$ has been added

A recursive algorithm, called Zykov's tree (Figure 1), can be built upon the following theorem:

Theorem 1 The chromatic number of G is given by the recurrence

$$\chi(G) = \min\{\chi(G'_{xy}), \chi(G''_{xy})\}$$

such that $x, y \in V(G)$ and $\{x, y\} \notin E(G)$

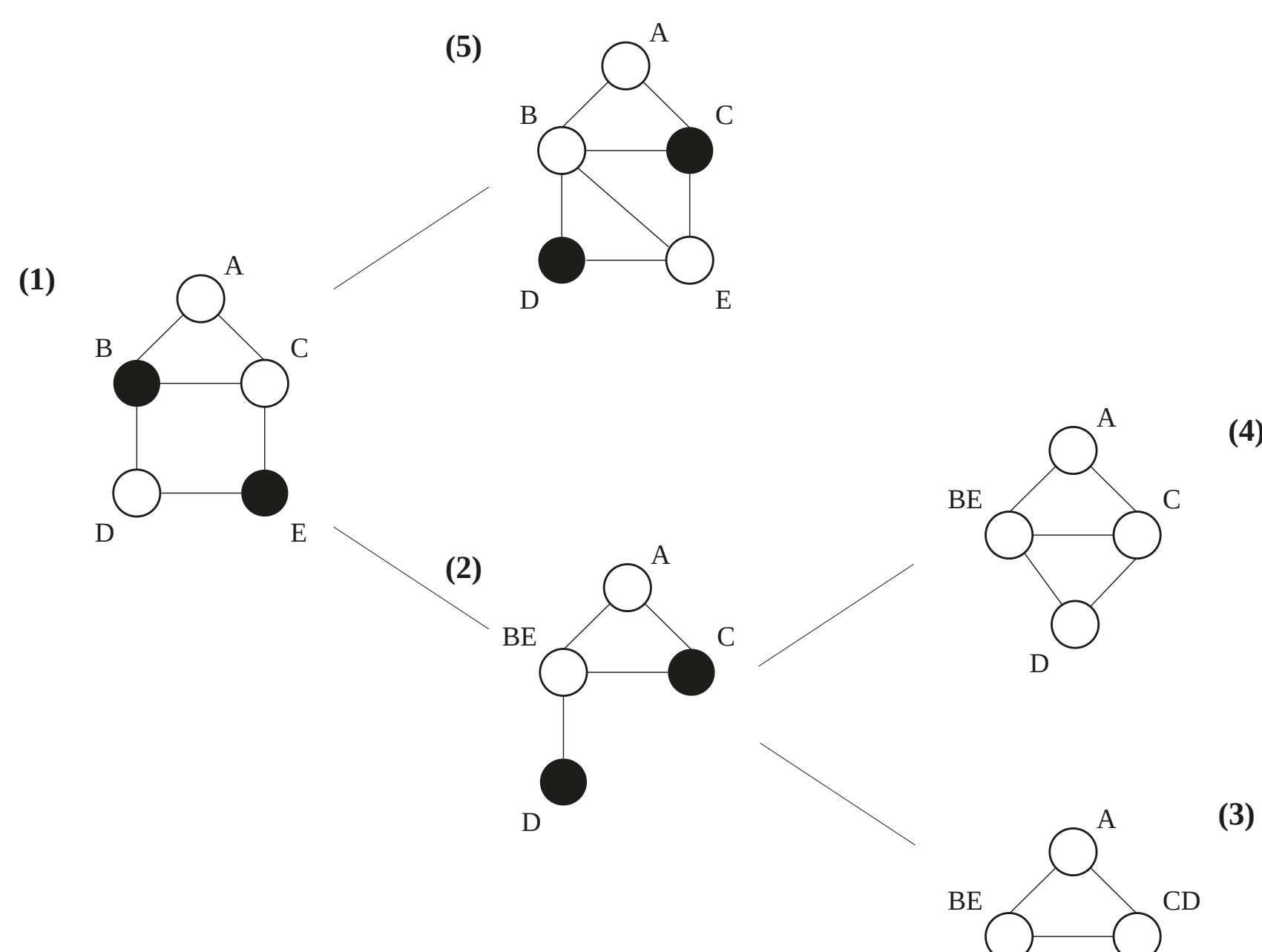


Figure 1: Zykov's tree

Leaf of the graph = complete graph - Size of **smallest leaf** = *chromatic number*.

At each node **lower bound** and **upper bound** computed:

$$lb(\chi) \leq \chi(G) \leq ub(\chi)$$

Prune the graph when: $best_ub(\chi) \leq current_lb(\chi)$

Coloring and clique heuristics

Color heuristics are used for calculating the upper bound. The most remarkable example is **DSatur**, as well as *Greedy* and *Recolor*.

Algorithm 1 DSatur coloring

```

1: procedure DSATURCOLOR( $G$ )
2:   Initialize  $max\_color \leftarrow 0$ 
3:   while  $G$  not empty do
4:      $v \leftarrow GETMAXSATDEGREE(G)$ 
5:     for  $i = 1 \rightarrow max\_color$  do
6:       if can be assigned color  $i$  then
7:          $color[v] \leftarrow i$  break
8:       end if
9:     end for
10:    if not assigned then
11:       $max\_color \leftarrow max\_color + 1$ 
12:       $color[v] \leftarrow max\_color$ 
13:    end if
14:  end while
15: end procedure

```

Clique heuristics are used for calculating upper bound; we adopted **FastWClq** algorithm.

Branching strategy

At each step vertices (u, v) are chosen such that **merging minimizes the graph**:

$$(u, v) = \arg \min_{(u, v) \in V} |N(u) \cap N(v)|$$

where $N(u)$ is the set of neighbors of u

Graph Representation

Operation	Adjacency Matrix	Edge List	CSR	Adjacency List
Add Edge	$O(1)$	$O(1)$	$O(E)$	$O(1)$
Remove Edge	$O(1)$	$O(E)$	$O(E)$	$O(k)$
Add Vertex	$O(E)$	$O(1)$	$O(1)$	$O(1)$
Remove Vertex	$O(E)$	$O(E)$	$O(E)$	$O(E)^1$
Merge Vertices	$O(E)$	$O(E)$	$O(E)$	$O(E)^1$
Get Neighbors	$O(V)$	$O(E)$	$O(1)$	$O(1)$

¹More precisely $O((avg_neighbors)^2)$, which typically it is much less

We used **Adjacency list** representation since it is the most flexible

MPI & OpenMPI

Parallelize execution using **MPI** and **OpenMP**.

Work Distribution Models

- Simple Approach: Master orchestrates tasks.
- Scalable Approach 1 and 2: Each process explores its own search space, sharing solutions from time to time.

Multi-Threaded Processing

- Terminator: Monitors execution time and stops processes if needed.
- Gatherer: Collects solutions and updates global best results.
- Employer: Manages work-stealing (Idle workers take over unfinished tasks to balance the load)

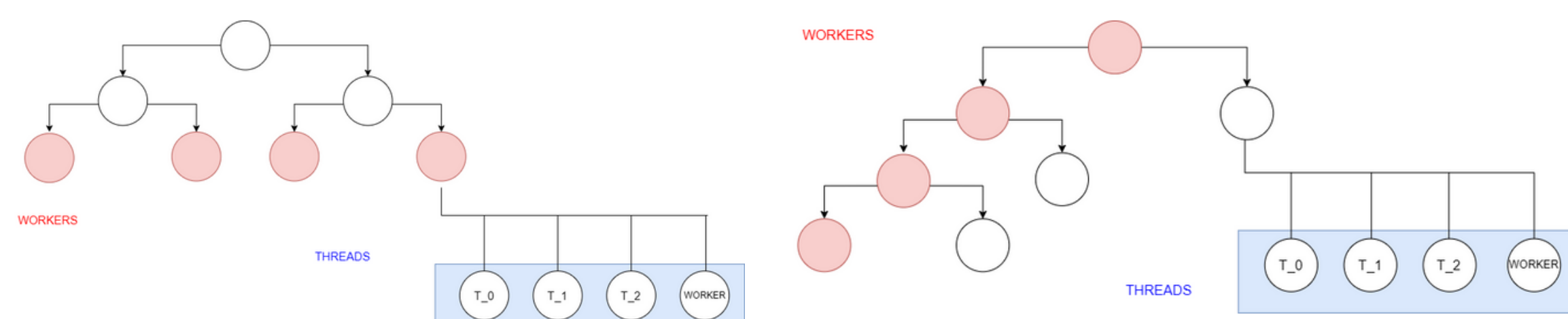


Figure 2: balanced algorithm

Figure 3: unbalanced algorithm

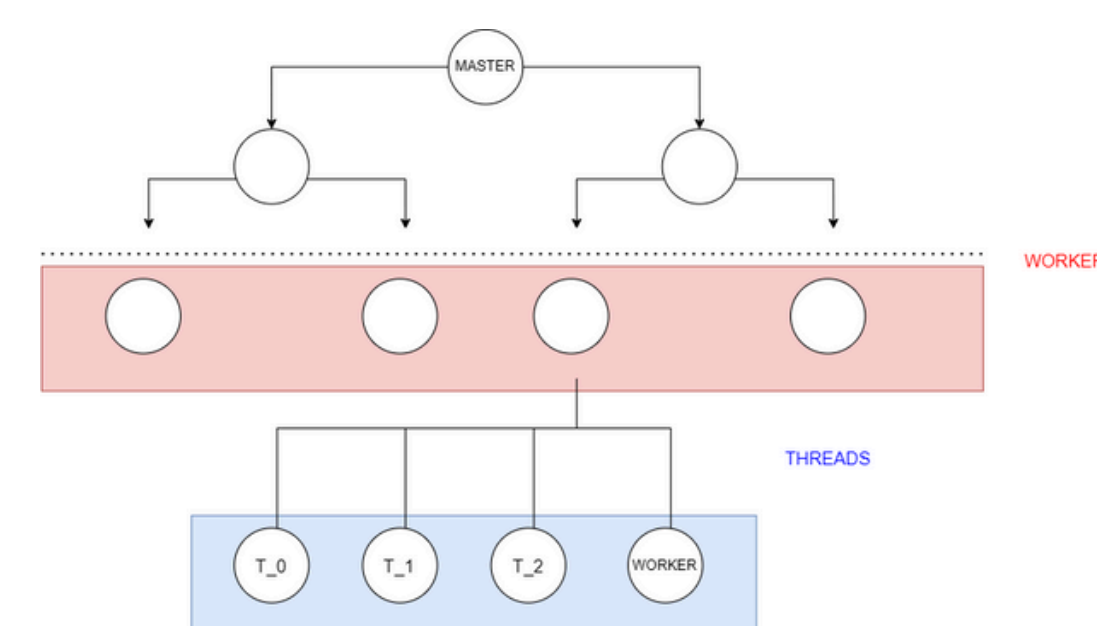
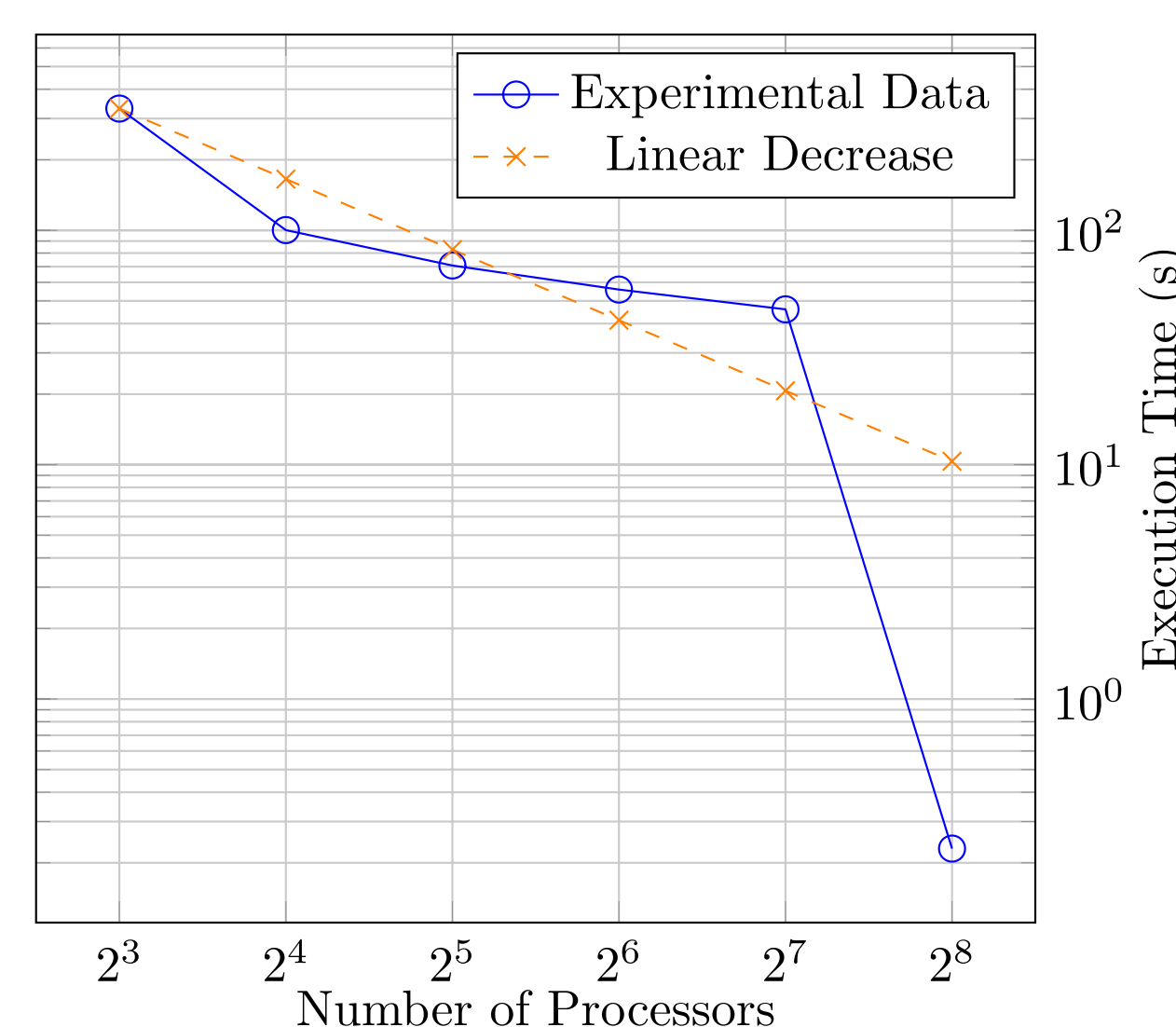


Figure 4: simple algorithm

Results

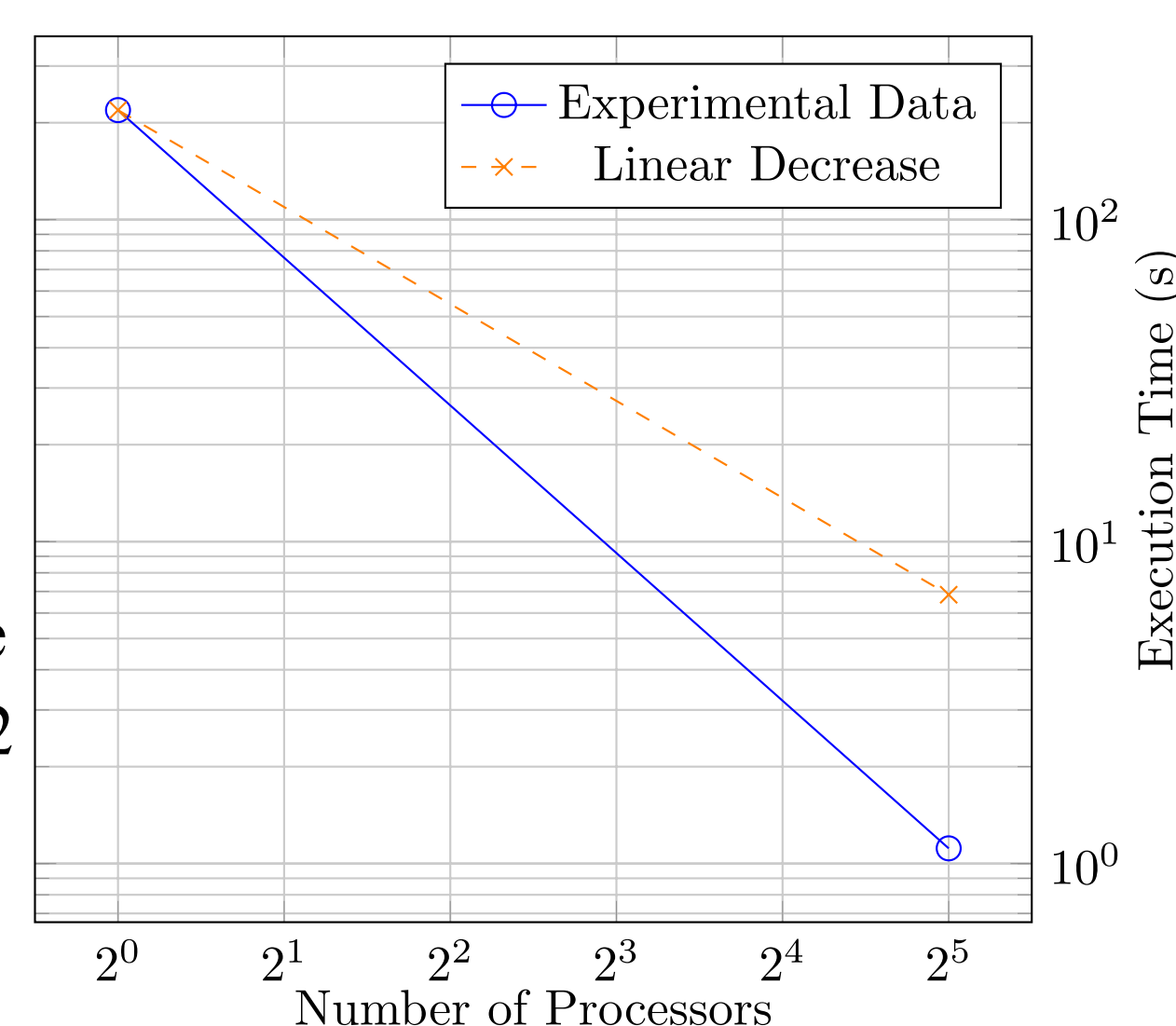
MPI proc	Cores	Time (s)
1	1	> 10000
8	32	330.91
16	64	100.22
32	128	70.78
64	256	55.89
128	512	46.01
256	1024	0.23

Strong scaling (queen7_7.col):
superlinear speedup due to more pruning



MPI proc	Cores	Time (s)
1	1	218.86
32	128	1.12

Strong scaling (queen9_9.col).
superlinear speedup due to more pruning. Plateau reached with 32 cores.



Conclusions

The proposed parallel branch-and-bound algorithm demonstrates **strong scalability**. Further optimizations for sparse graphs remain an open direction

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