Laboratory 1: Introduction in MAPLE

Computation in Maple

```
Maple can make simple computations using the operators:
```

```
- addition
        - difference
        - multiplication
        - division
Λ
        - power
        - factorial
!
sqrt() - square root
exp() - the exponential function
       - the logarithm function
sin(), cos(), tan(), cot() - trigonometric functions sinus, cosine, tangent, cotangent
> 1+2-3;
                                                  0
> 2*3/7+3^2;
> sqrt(100);
                                                 10
> 3^2;
                                                  9
> sqrt(5);
                                                \sqrt{5}
> sqrt(5.0);
                                            2.236067977
```

When an integer is entered in the square root expression, MAPLE performs a *symbolic calculation*, if a decimal number is entered, MAPLE executes a numerical calculation with a precision of 10 digits. The **evalf** function returns the numeric value of the specified expression.

Variables

1.250000000

When we need the numerical evaluation of the previous expression we can use the command evalf(%)

We can use the Greek letters

```
> alpha, beta, gamma, Alpha, Beta, Gamma; \alpha,\,\beta,\,\gamma,\,A,\,B,\,\Gamma
```

Remark: The expression **Pi** has the numerical value of this number, while the expression **pi** returns the respective greek letter

Functions and graphical representation

> restart;

The **restart** command clears the memory from the used values.

A single variable function can be defined as follows:

 $> f:=x->\sin(x)/x;$

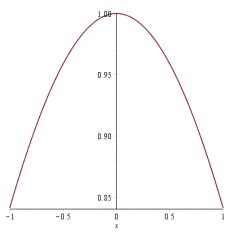
- $f := x \rightarrow \frac{\sin(x)}{x}$
- > f(3*Pi/2), f(1.5);
- $-\frac{2}{3\pi}$, 0.6649966577

> f(a+b);

 $\frac{\sin(a+b)}{a+b}$

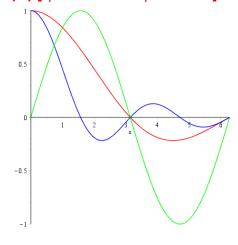
For graphical representation we need to load plots package using with command

- > with(plots):
- > plot(f(x),x=-1..1);



We can plot more than one function in the same window specifying the functions list $[f_1(x), f_2(x), f_3(x)]$ and the corresponding color list $[c_1, c_2, c_3]$:

> plot([f(x),f(2*x),sin(x)],x=0..2*Pi,color=[red,blue,green]);



If the functions list is larger, the operator \$ in the form (expr\$i=m..n) can be used to generate it. It returns the list obtained by replacing i between m and n in the expression expr. For example, for the function $f_n(x) = \frac{x}{\left(1 + x^2\right)^n}$ if we want to generate the graphical representations of the functions

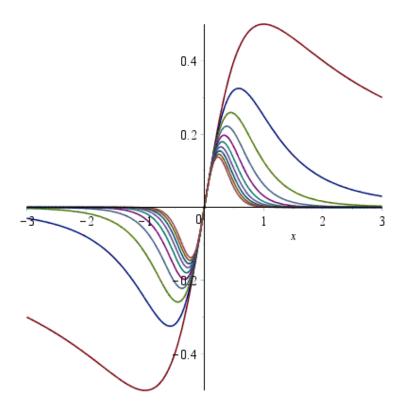
 $f_1(x)$, ..., $f_{10}(x)$ first we construct the list and then the graphs using **plot** command:

$$> f := (x,n) - x/(1+x^2)^n;$$

$$f := (x, n) \rightarrow \frac{x}{\left(1 + x^2\right)^n}$$

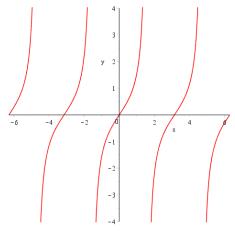
$$list_f := \frac{x}{x^2 + 1}, \frac{x}{(x^2 + 1)^2}, \frac{x}{(x^2 + 1)^3}, \frac{x}{(x^2 + 1)^4}, \frac{x}{(x^2 + 1)^5}, \frac{x}{(x^2 + 1)^6}, \frac{x}{(x^2 + 1)^7}, \frac{x}{(x^2 + 1)^8}, \frac{x}{(x^2 + 1)^9}, \frac{x}{(x^2 + 1)^{10}}$$

> plot([list_f],x=-3..3);



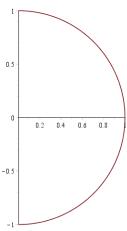
In the case of discontinuous points we need to use the option **discont = true**:

$$>$$
 plot(tan(x), x = -2*Pi..2*Pi, y = -4..4, discont = true);



If a curve is given in a parametric form (for example: $x(t) = \sin(t)$, $y(t) = \cos(t)$, $t = 0 ... \pi$;) we use the instruction:

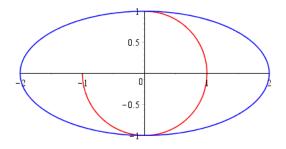
> plot([sin(t),cos(t),t=0..Pi]);



In this case, the **plot** function argument is a list of 3 components: [x(t), y(t), t=a..b] the first variable represents the x coordinate, the second y coordinate, the third variable the parameter range. In order to represent in the same graph several curves given in parametric form the **plot** function argument will be a list of curves list, for example for curves:

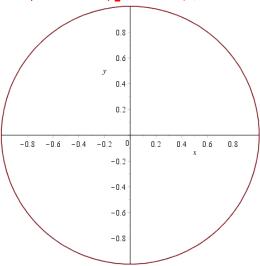
(C1):
$$x(t) = \sin(t)$$
 (C2): $x(t) = 2\sin(t)$, $t = 0..2 \pi$
 $y(t) = \cos(t)$, $t = 0..2 \pi$

> plot([[sin(t),cos(t),t=0..3/2*Pi], [2*sin(t),cos(t),t=0..2*Pi]],
color=[red,blue], scaling=constrained);



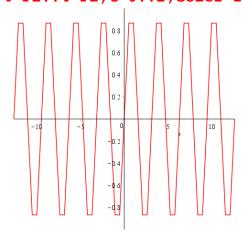
In the case of a curve given by the implicit equation we use the instruction **implicitplot**:

> implicitplot(x^2+y^2=1,x=-1..1,y=-1..1);



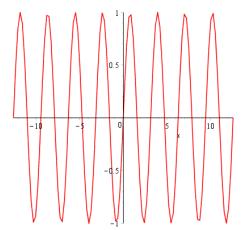
If we need to visualize the parameter dependence of a function we can use the command **animate** (right click on the image, select *Animation* and *Play*)

> animate(sin(x*t),x=-4*Pi..4*Pi,t=0..2,color=red);



If we nedd a higher precision we specify the number of points and the number of frames:

> animate(sin(x*t), x=-4*Pi..4*Pi, t=0..2, color=red, numpoints=100,
frames=100);



Limits, Derivates, Integrals

> restart:

The sequences limits and functions limits can be obtained using the limit command:

```
> limit(1/n,n=infinity);
0
> limit(sin(x)/x,x=0);
1
> limit(exp(x), x=infinity);
```

undefined

The derivation of the functions can be made in two ways: using **diff** command or using the derivation operator **D**:

 $> f:=x->exp(x^2)+3;$

> limit(1/x, x=0, real);

$$f := x \rightarrow e^{x^2} + 3$$

The **diff** command executes the derivation of the given expression with respect to the specified variable. The derivation operator **D** returns the derivate as a function.

> diff(f(x),x);

$$2 x e^{x^2}$$

the second order derivate is given by

> diff(f(x),x,x);

$$2e^{x^2} + 4x^2e^{x^2}$$

also we can use the option **x\$n** to get n-order derivative

> diff(f(x),x\$2);

$$2 e^{x^2} + 4 x^2 e^{x^2}$$

> diff(f(x), x\$3);

$$12 x e^{x^2} + 8 x^3 e^{x^2}$$

Using the derivation operator:

```
> D(f)(x);

2 x e^{x^2}

> D(f)(1);

2 e

> (D@D)(f)(x);

2 e^{x^2} + 4x^2 e^{x^2}

> (D@Q2)(f)(x);

6 e

> (D@Q2)(f)(x);

2 e^{x^2} + 4x^2 e^{x^2}

> (D@QD)(f)(x);

12 x e^{x^2} + 8x^3 e^{x^2}

12 x e^{x^2} + 8x^3 e^{x^2}
```

The computation of the indefinite integral or antiderivative can be made using the **int** command:

```
> int(cos(x),x);
```

sin(x)

if the integration limits are specified x=a..b then the definite integral value is obtained:

```
> int(cos(x),x=0..Pi);
> int(1/x,x=1..infinity);
```

Not always MAPLE can compute the definite integral value:

```
> int( sin( sqrt(1 - x^3) ), x = 0..1 );
\int_0^1 \sin(\sqrt{-x^3 + 1}) dx
```

but it can obtain an approximate value using numerical approximation methods:

```
> evalf( int( sin( sqrt(1 - x^3) ), x = 0..1 ) );
0.7315380065
```

Algebraic equations and systems of algebraic equations. Linear algebra

Algebraic equations and systems of algebraic equations can be solved using the **solve** command:

```
> restart:

> solve( x^2 + 3*x + 2=0 );

-1, -2

> solve( x^2 + x + 1=0 );

-\frac{1}{2} + \frac{1}{2}I\sqrt{3}, -\frac{1}{2} - \frac{1}{2}I\sqrt{3}
```

The **fsolve** command solves the equations using numerical methods to obtain approximating solutions:

```
> solve( x^3 + x = 27 );

\frac{1}{6} (2916 + 12\sqrt{59061})^{1/3} - \frac{2}{(2916 + 12\sqrt{59061})^{1/3}},

-\frac{1}{12} (2916 + 12\sqrt{59061})^{1/3} + \frac{1}{(2916 + 12\sqrt{59061})^{1/3}}

+\frac{1}{2} I\sqrt{3} \left( \frac{1}{6} (2916 + 12\sqrt{59061})^{1/3} + \frac{2}{(2916 + 12\sqrt{59061})^{1/3}} \right), -\frac{1}{12} (2916 + 12\sqrt{59061})^{1/3}

+\frac{1}{(2916 + 12\sqrt{59061})^{1/3}} - \frac{1}{2} I\sqrt{3} \left( \frac{1}{6} (2916 + 12\sqrt{59061})^{1/3} + \frac{2}{(2916 + 12\sqrt{59061})^{1/3}} \right)

> fsolve( x^3 + x = 27 );

2.888941572

> solve( \tan(x) - x = 2 );

RootOf(-\tan(Z) + Z + 2)

> fsolve( \tan(x) - x = 2 );

1.274392662
```

In the case of the equation systems the same command is used, the equations are placed between the braces

> solve({x+2*y=1,x-y=3},{x,y});
$$\left\{ x = \frac{7}{3}, y = -\frac{2}{3} \right\}$$

Linear Algebra

In the case of operations with vectors and matrices the linear algebra package linalg must be loaded:

```
> with(linalg):
```

Vectors can be defined as follows:

```
> A := matrix([[1,0],[3,2]]);
```

```
A := \left[ \begin{array}{c} 1 & 0 \\ 3 & 2 \end{array} \right]
> B := matrix([ [1, 0], [2, 1] ]);
                                                B := \left[ \begin{array}{c} 1 & 0 \\ 2 & 1 \end{array} \right]
 We have the following operations for matrices:
> evalm(A + B); # matrices summation
> evalm(2*A); # multiplying a matrix by a scalar
> evalm(A &* B); # matrices multiplication
> evalm(A &* (v+w)); # multiplying a matrix by a vector
                                                   [26]
> det(A); # determinant of A
> evalm(A^(-1)); # calculate the inverse matrix of A
> eigenvals (A); # calculate the eigenvalues of A
> eigenvects (A); # calculate the eigenvectors of A
                                    [2, 1, {[ 0 1 ]}], [1, 1, {[ 1 -3 ]}]
```