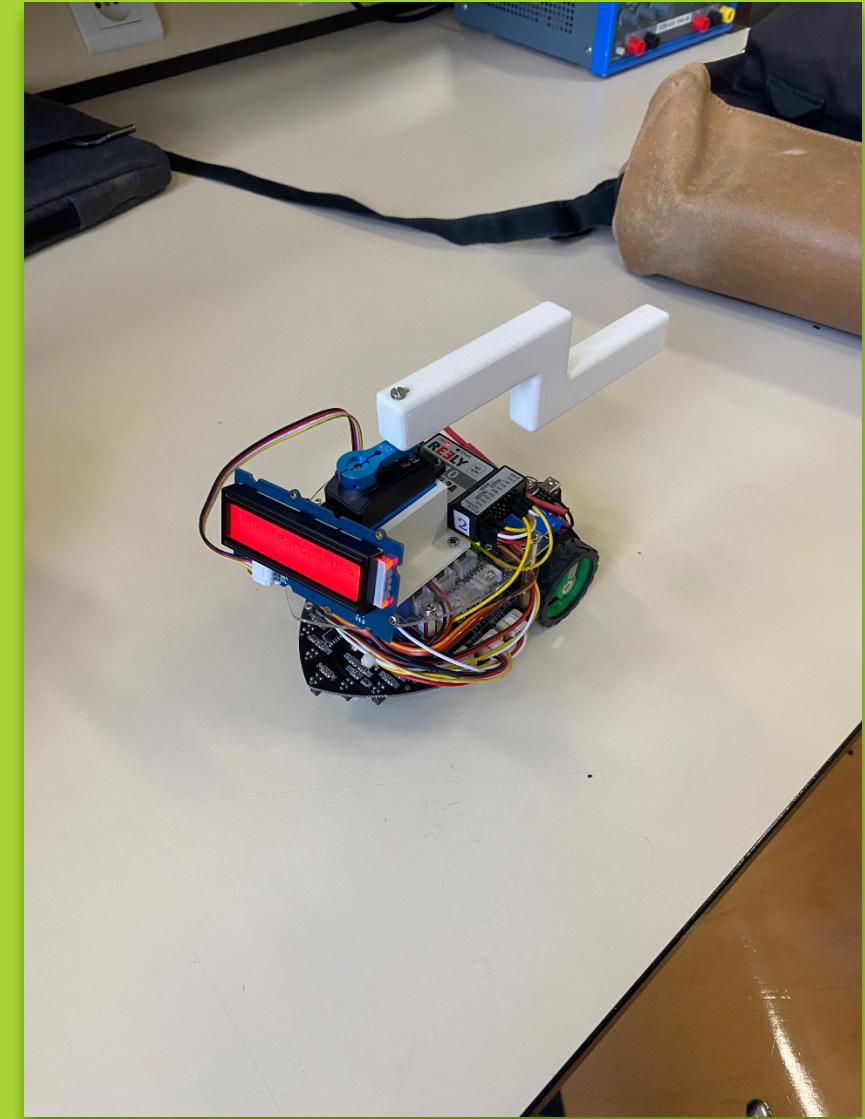


Projet Robotik

1STI2D

Corrieras Lucas



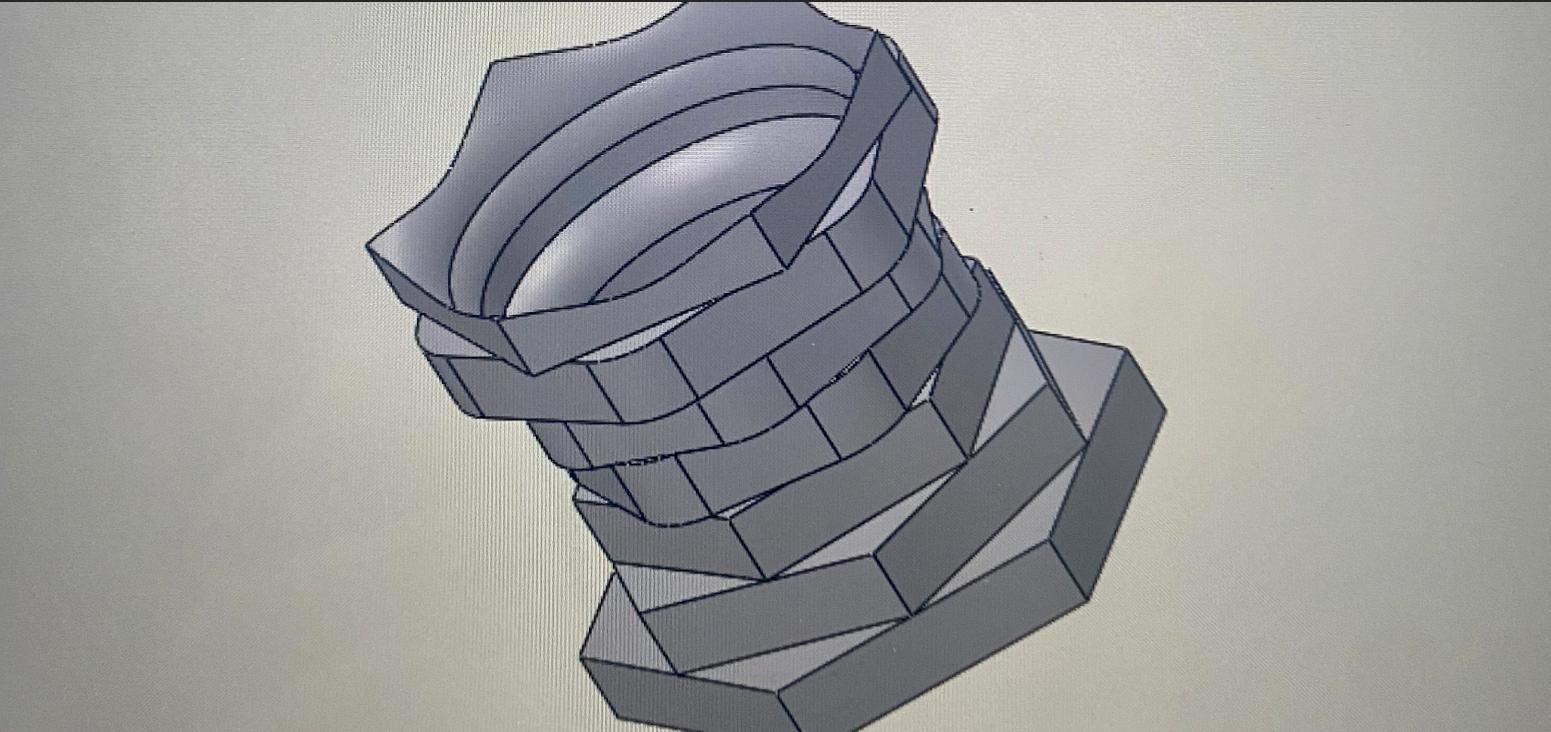
Qu'elles sont les objectifs de ce projet

TEAM WORK



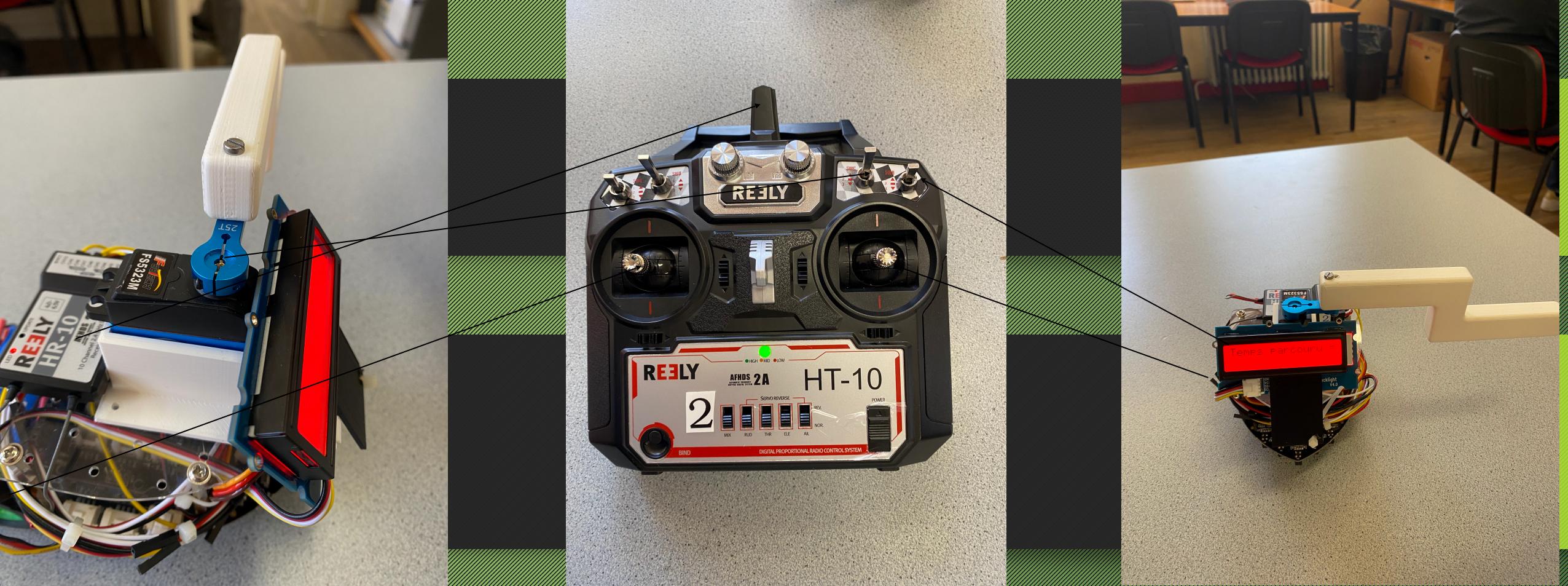
Visual Paradigm
Online





Cahier des charges

Première tâche



Cahier des charges

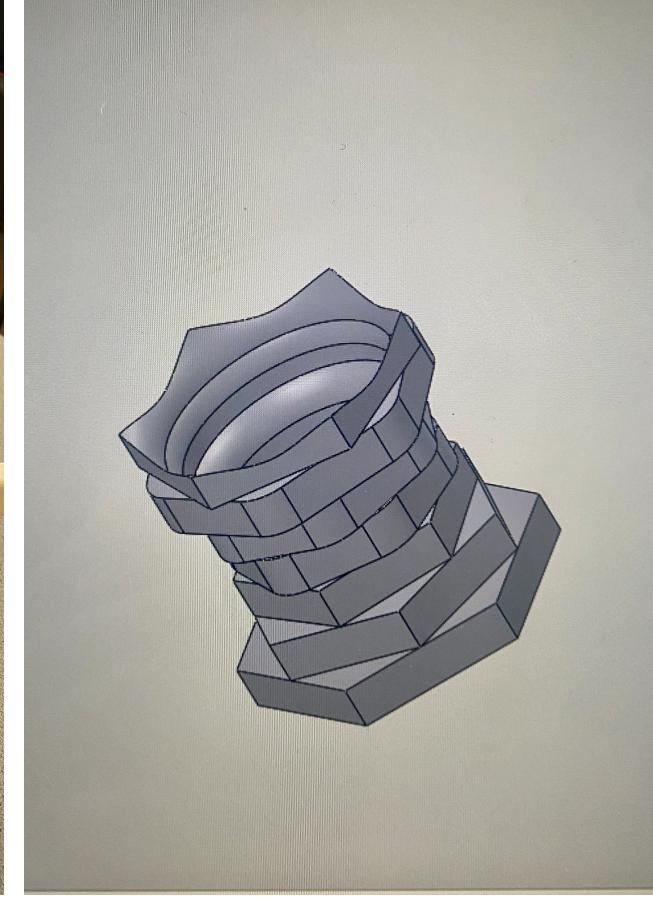
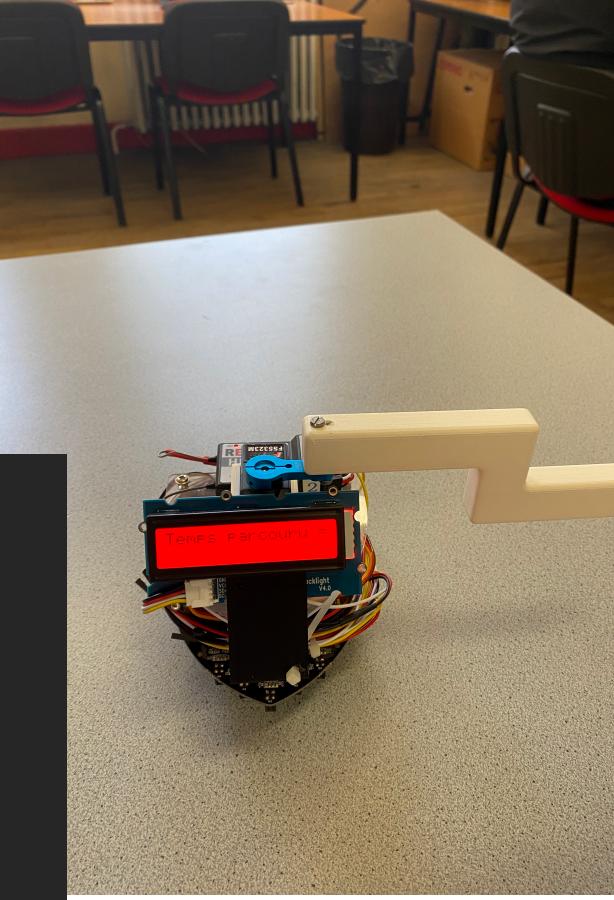
Deuxièmes
tâche

Cahier des charges

Résultat obtenu et
résultat attendue

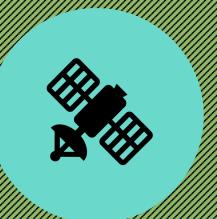


Modification possible à l'avenir



```
void loop() {  
 60  
 61    int sensor1 = digitalRead(pinSensor1);  
 62    int sensor2 = digitalRead(pinSensor2);  
 63    int sensor3 = digitalRead(pinSensor3);  
 64    int sensor4 = digitalRead(pinSensor4);  
 65    int sensor5 = digitalRead(pinSensor5);  
 66}
```

Conclusion



ROBOTIK