

src/robot_status.cpp

```
graph TD; A[src/robot_status.cpp] --> B[ros/ros.h]; A --> C[assignment_rt1_2/RobotStatus.h];
```

A diagram illustrating the dependencies of the file `src/robot_status.cpp`. The file is shown in a grey box at the top. Two blue arrows point from it to two white boxes below: `ros/ros.h` on the left and `assignment_rt1_2/RobotStatus.h` on the right.

ros/ros.h

assignment_rt1_2/RobotStatus.h