

First-arrival traveltimes tomography based on the adjoint-state method

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Outline

Introduction

Motivation

Theory

Implementation

Fast-sweeping method

Exemples

Gradient calculation

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Motivation

Gradient of the misfit function

- ▶ Misfit function for a single-shot

$$J(c) = \frac{1}{2} \int_{\partial\Omega} d\mathbf{r} |T(c, \mathbf{r}) - T_{obs}(\mathbf{r})|^2 \quad (1)$$

- ▶ Gradient method

$$c_{n+1} = c_n - \alpha_n \nabla J(c_n), \quad (2)$$

where α is a positive scalar.

Gradient of the misfit function

- Extended misfit function

$$\begin{aligned} L(c, t, \lambda) = & \frac{1}{2} \int_{\partial\Omega} d\mathbf{r} |t(\mathbf{r}) - T_{obs}(\mathbf{r})|^2 \\ & - \frac{1}{2} \int_{\Omega} d\mathbf{x} \lambda(\mathbf{x}) \left(|\nabla t(\mathbf{x})|^2 - \frac{1}{c(\mathbf{x})^2} \right) \end{aligned} \quad (3)$$

- for $t(\mathbf{x}) = T(\mathbf{x})$

$$L(c, T, \lambda) = J(c) \quad (4)$$

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Examples

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- ▶ Eikonal equation

$$|\nabla T(\mathbf{x})|^2 = \frac{1}{c^2(\mathbf{x})} \quad (5)$$

$$T(\mathbf{x}_s) = 0 \quad (6)$$

- ▶ Adjoint-state system

$$\Lambda(\mathbf{r})\mathbf{n}(\mathbf{r}) \cdot \nabla T(\mathbf{r}) = T(\mathbf{r}) - T_{obs}(\mathbf{r}) \quad (7)$$

$$\nabla \cdot \Lambda(\mathbf{x})\nabla T(\mathbf{x}) = 0 \quad (8)$$

Fast-sweeping method

- ▶ Godunov upwind FD scheme

$$\left[\frac{(T(\mathbf{x}) - T(\mathbf{x})^{xmin})^+}{\Delta x} \right]^2 + \left[\frac{(T(\mathbf{x}) - T(\mathbf{x})^{zmin})^+}{\Delta z} \right]^2 = \frac{1}{c^2(\mathbf{x})}$$

Fast-sweeping method

- ▶ Initialize $T(\mathbf{x}_s) = 0$ and assign very large positive values to the rest of the grid points.
- ▶ Update grid points with Gauss-Seidel and keep the smallest value between the old and the calculated. $\min(T_{old}, T^*)$
- ▶ Check the convergence $\|T^{n+1} - T^n\|_{L1} \leq \varepsilon$ for $\varepsilon > 0$

Fast-sweeping method

- ▶ Adjoint-state

$$\frac{\partial}{\partial x}(a\lambda) + \frac{\partial}{\partial z}(b\lambda) = 0 \quad (9)$$

where $a = \partial t(x, z)/\partial x$ and $b = \partial t(x, z)/\partial z$

- ▶ a and b values

$$a_{i+\frac{1}{2},j} = \frac{t_{i+1,j} - t_{i,j}}{\Delta x}, \quad a_{i-\frac{1}{2},j} = \frac{t_{i,j} - t_{i-1,j}}{\Delta x} \quad (10)$$

$$b_{i,j+\frac{1}{2}} = \frac{t_{i,j+1} - t_{i,j}}{\Delta z}, \quad b_{i,j-\frac{1}{2}} = \frac{t_{i,j} - t_{i,j-1}}{\Delta z} \quad (11)$$

► Introducing the notations:

$$a_{i+\frac{1}{2},j}^{\pm} = \frac{a_{i+\frac{1}{2},j} \pm |a_{i+\frac{1}{2},j}|}{2} \quad (12)$$

$$a_{i-\frac{1}{2},j}^{\pm} = \frac{a_{i-\frac{1}{2},j} \pm |a_{i-\frac{1}{2},j}|}{2} \quad (13)$$

$$b_{i,j+\frac{1}{2}}^{\pm} = \frac{b_{i,j+\frac{1}{2}} \pm |b_{i,j+\frac{1}{2}}|}{2} \quad (14)$$

$$b_{i,j-\frac{1}{2}}^{\pm} = \frac{b_{i,j-\frac{1}{2}} \pm |b_{i,j-\frac{1}{2}}|}{2} \quad (15)$$

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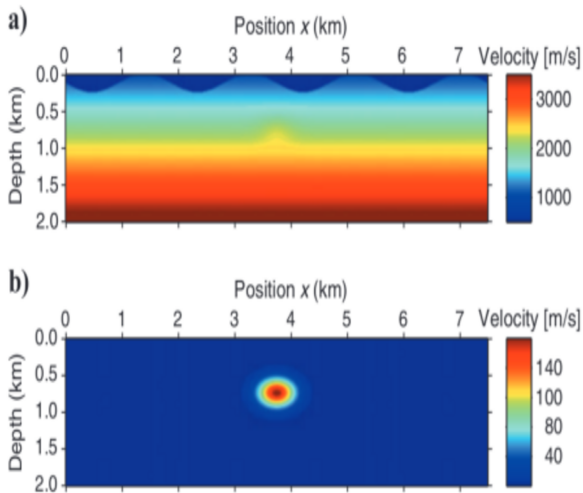
Exemples

Gradient calculation

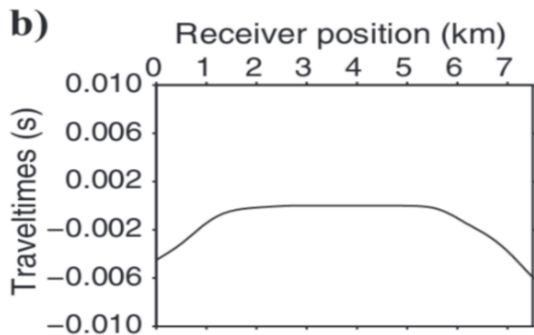
Gradient calculation

- ▶ Constant vertical-gradient velocity model with a velocity anomaly.
- ▶ 2km in depth and 7.5km laterally. 12.5m by 12.5 grid size.
- ▶ 600 sources and 600 receivers for each source.

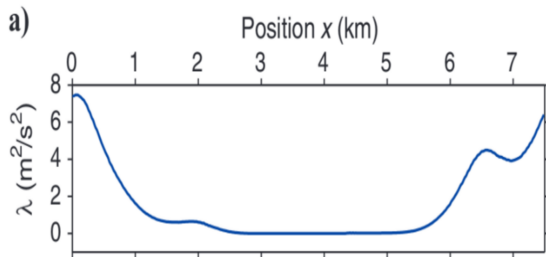
Fast Sweeping Method



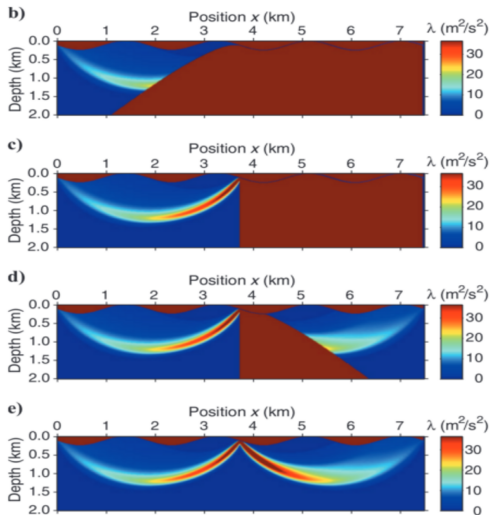
Fast Sweeping Method



Fast Sweeping Method



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