

```
Data:
Input
-i flow id
-L_{min}
-L_{max}
-h_{final}
-P_i le path jusqu'à h_{final}
Local
-lp_i
- first_i
– ensemble des C_k^l avec k \in lp_i et l \in P_i
-\delta_i^{h_{final}}
x = 0;
for j \in lp_i do
   if first_i = first_{j,i} then
       tabPart1[x] = C_j^{first_i};
    \mathbf{end}
end
if max(tabPart1) - 1 < 0) then
    result = 0;
end
else
    result = max(tabPart1) - 1;
end
for h \in P_i do
   resultPart2 = 0;
    tabPart2 = 0;
    if h \neq first_i then
       if h = first_{j,i} then
           m = 0;
           for j \in lp_i do
               tabPart2[m] = C_i^h;
           \quad \text{end} \quad
           resultPart2+ = max(tabPart2) - 1;
       else if h \in (first_{j,i}; last_{j,i}] and first_{j,i} \neq first_{i,j} then
           m=0;
           for j \in lp_i do
               tabPart2[m] = C_i^h;
           resultPart2+ = max(tabPart2) - 1;
       else if lp_i \neq \emptyset then
           m=0;
           for j \in lp_i do
               tabPart2[m] = C_j^h;
           resultPart2+ = max(tabPart2) - C_i^{pre_i(h)} + L_{max} - L_{min};
       else
           resultPart2 = 0;
       end
       if tabPart2 \ge 0 then
           result+ = resultPart2;
           resultPart2 = 0;
       end
    end
end
```