

```
Data:
Input
    — i flow id
   -L_{min}
    -L_{max}
    -h_{final}
    — P_i le path jusqu'à h_{final}
    --lp_i
    -- first_i
    — ensemble des C_k^l avec k \in lp_i et l \in P_i
    -\delta_i^{h_{final}}
x = 0;
for j \in lp_i do
   if first_i = first_{j,i} then
      tabPart1[x] = C_j^{first_i};
     x++;
   \mathbf{end}
end
if max(tabPart1) - 1 < 0) then
result = 0;
\mathbf{end}
else
   result = max(tabPart1) - 1;
end
for h \in P_i do
   resultPart2 = 0;
    tabPart2 = 0;
    if h \neq first_i then
       if h = first_{j,i} then
           m=0;
           for j \in lp_i do
             tabPart2[m] = C_i^h;
           end
           resultPart2+ = max(tabPart2) - 1;
        else if h \in (first_{j,i}; last_{j,i}] and first_{j,i} \neq first_{i,j} then
           m=0;
           for j \in lp_i do
              tabPart2[m] = C_i^h;
           resultPart2+ = max(tabPart2) - 1;
        else if lp_i \neq \emptyset then
           m=0;
           for j \in lp_i do
              tabPart2[m] = C_j^h;
           resultPart2+ = max(tabPart2) - C_i^{pre_i(h)} + L_{max} - L_{min};
        else
         | resultPart2 = 0;
        \mathbf{end}
       if tabPart2 \geq 0 then
           result+ = resultPart2;
           resultPart2 = 0;
       \mathbf{end}
    end
\mathbf{end}
```