







# **Ensembling deep transformation models**

Advances in statistical modeling with neural networks

**Lucas Kook**, Andrea Goetschi, Philipp FM Baumann, Torsten Hothorn, Beate Sick

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Kook\_Lucas

C LucasKook



### Available data:

Tabular



Image



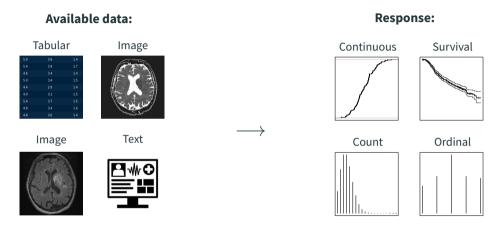
Image



Text



1



How do changes in the predictors propagate to the **distribution** of the response?

1

# Setup

### Available data:

Tabular







Image

Text





# Setup

### Available data:

Tabular



Image



Image



Text



## **Response:**

Continuous



Survival



Count



Ordinal



#### Available data:

Tabular



Image



Image



Text



How can we handle non-tabular data?

## **Response:**

Continuous



Survival



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How can we cover all response types?

$$F_{Y|X=x}(\cdot) := \mathbb{P}(Y \leq \cdot \mid X = x)$$

• Normal linear regression

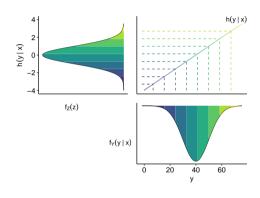
$$F_{Y|\mathbf{X}=\mathbf{x}}(y) = \Phi(\sigma^{-1}(y - \alpha + \mathbf{x}^{\top}\boldsymbol{\beta}))$$

• Proportional odds logistic regression

$$F_{Y|\mathbf{X}=\mathbf{x}}(y_k) = \operatorname{expit}(\vartheta_k + \mathbf{x}^{\top}\boldsymbol{\beta})$$

• Cox proportional hazards model

$$F_{Y|X=x}(y) = 1 - \exp(-\exp(\log \Lambda_0(y) + x^{\top}\beta))$$



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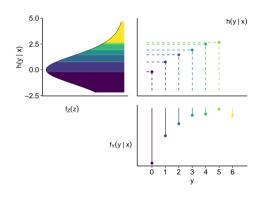
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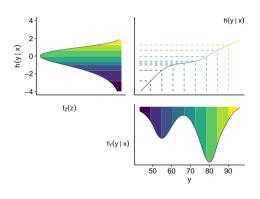
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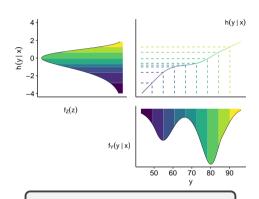
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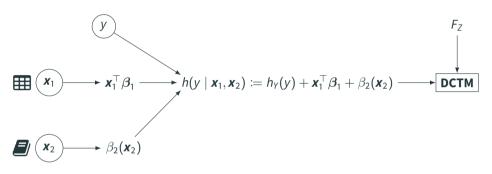
• And many more ...



### **Transformation models**

$$F_{Y|X=x}(y) = F_{Z}(h_{Y}(y) + x^{\top}\beta)$$

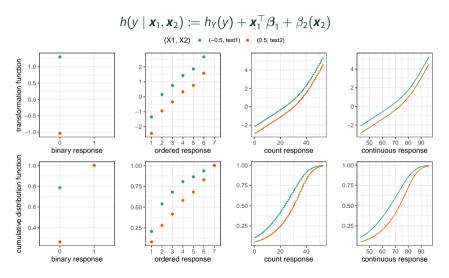
## **Example: Parametrization of an additive transformation function**



DCTM: Deep conditional transformation model III: Tabular data

10.48550/arXiv.2211.13665

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# DCTMs are not enough

Individual deep learning models may make unreliable predictions

#### **Common criticism:**

- No uncertainty quantification
- Small sample sizes
- Stochastic fitting procedure

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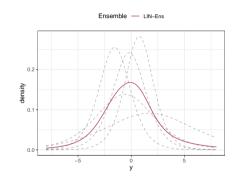
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### **Deep ensembles** improve prediction

- 1. Fit *M* instances of the same model
- 2. Average their *M* predictions



$$ar{F}_{Y|X=x}^{M}(\cdot) = \sum_{m=1}^{M} F_{Y|X=x}^{m}(\cdot)$$

6

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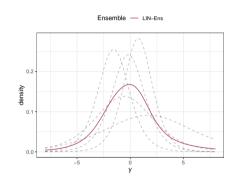
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Deep ensembles lose additivity and interpretability!



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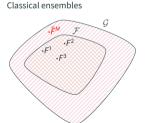
### **Transformation ensembles**

Transformation ensembles average the **transformation function** instead

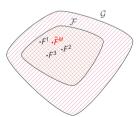
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10.48550/arXiv.2205.12729

• Remain partially interpretable



Transformation ensembles



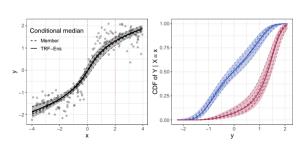
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10.48550/arXiv.2205.12729

- Remain partially interpretable
- Quantify algorithmic uncertainty
- Perform **on par** with deep ensembles

## Deep Interpretable Ensembles

Lucas Kook $^{1,2},$  Andrea Götschi $^1,$  Philipp F. M. Baumann $^3,$  Torsten Hothorn $^1,$  Beate Sick $^{1,2}$ 

#### 1. Model formula

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fm <- vote_count \sim 0 + s(budget, df = 6) + popularity + deep(texts)
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#### 2. Neural network

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embd_mod <- function(x) x |>
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  layer_lstm(units = 50, return_sequences = TRUE) |>
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  layer_dense(25) |> layer_dropout(rate = 0.2) |> layer_dense(5) |>
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m <- deeptrafo(fm, data = train, list_of_deep_models = list(deep = embd_mod))</pre>
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#### 4. Fit ensemble

```
ens <- ensemble(m, n_ensemble = 3, epochs = 50, batch_size = 64)</pre>
```

# **Example: Movie ratings**

Prediction for a single movie from the test data

• Budget:  $2.7 \times 10^8$  \$

• Popularity: 57.93

 Overview: "superman returns discover 5 absence allowed lex luthor walk free closest abandoned moved luthor plots ultimate revenge millions killed change planet forever ridding steel"

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#### **Test NLL:**

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unlist(logLik(ens_deep, newdata = test,
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## members1 members2 members3 mean ensemble
## 8.24 8.28 8.16 8.23 8.11
```

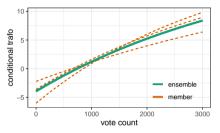
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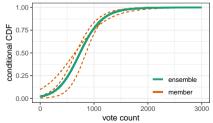
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#### Collaborators

David Rügamer

Oliver Dürr

Philipp FM Baumann

Andrea Götschi







