

# Lucas Plant

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## Education

### Georgia Institute of Technology | Atlanta, GA

BS Electrical Engineering | Minor in Computing Intelligence (AI/ML)

*Specialization in Robotics, Control Systems, and Signal Processing*

**Awards:** Eagle Scout, Faculty Honors/Deans list

**Professional Organizations:** Electrify GT, SHPE, Brazilian Student Association, GT Grand Challenges

**Relevant Coursework:** Control System Design, Machine Learning, Digital Signal Processing, Random Signals, Robotics and Perception, Numerical Methods of Optimization, Automation and Robotics, Data Structures and Algorithms

*Expected Graduation: May 2026*

**GPA 4.00**

## Experience

### Dynamics and Control Systems Laboratory

Atlanta Georgia

#### Undergraduate Research Assistant

August 2024 – Present

*DCSL is a lab at Georgia Tech Researching visual SLAM, motion planning, and control systems for aerospace robotics*

- Developing a **distributed multi-agent visual SLAM** pipeline for **satellites** in orbit
- Designed and implemented an **Extended Kalman Filter** to fuse **IMU** and **VICON** measurements for state estimation
- Applied rotational dynamics, **signal processing**, and regression techniques experimentally determine IMU alignment
- Developed embedded C/MATLAB drivers for digital IMUs, increasing sampling rate by 5x
- Wrote firmware to control thrusters with **PWM** signals and telemeter pressure data to the main computer
- Integrated a **trajectory generator** into an open-source Blender-based **satellite simulator** for testing SLAM algorithms

### SpaceX

Hawthorne, CA

#### Falcon Avionics Testing – Engineering Intern

May – August 2024 and 2025

- Redesigned hardware and software for **power management** and **serial communication** in **Redundant IMU** test systems
- Refactored automated thermal test infrastructure, **saving 350 hours** of lead/chamber time per year
- Identified and implemented **improvements for programming firmware**, reducing engineering debug time in production
- Developed a low cost **ethernet** test system to measure latency with **nanosecond** accuracy
- Created a portable testing system for **root cause analysis**, hardware development, and radiation testing
- Diagnosed and fixed critical production blocking problems under tight operational timelines

### Tesla

Palo Alto, CA

#### Vehicle Software – Firmware Integration Intern – Steering Team

August 2023 – December 2023

- Developed analysis tools to evaluate **closed loop tracking performance** of steering controllers under autopilot control
- Created new **calibration** routines for steering force **sensors** increasing the reliability of vehicles
- Conducted **systems-level** testing to evaluate vehicle software and identify **root causes** in development firmware
- Collaborated to bring up a new **HIL** (Hardware In the Loop) table to test steering software integration and testing
- Worked with suppliers to roll out big fixes and firmware improvements in a timely manner.

## Projects and Involvement

### Laboratory for Intelligent Decision and Autonomous Robots (LIDAR)

January 2026 – Present

- Training a **learned world model** for task-level planning and control on a Unitree G1 humanoid **robot**

### Senior Capstone Design

January 2026 – Present

- Designing trajectory generation and **control algorithms** for autonomous **quadrotor landing** on a moving platform
- Using ARUCO tags for visual **state estimation** relative to the moving platform

### Personal Projects

- Developed Web based **simulator** for visualizing and testing **dynamical systems** and **control systems**
- Created a GUI for visualizing **digital signal** processing concepts such as windowing and sampling
- Programmed the SO101 robot arm to track an ARUCO tag using the **manipulator Jacobian** and **PID** based visual servoing

### Engineering Clubs (HyTech Racing and Yellow Jacket Space Program)

August 2022 – January 2024

- Designed, manufactured, and debugged **PCBs** with several tools for rockets and racecars.

## Skills and Awards

- **Programming:** Python, C/C++, MATLAB, Java, Fortran, SQL, Arduino
- **Software:** ROS2, MuJoCo, IsaacSim, OpenCV, Pytorch, Altium, Wireshark, Vector CAN tools, Simulink
- **Hardware:** PCB Design, Soldering, Breadboarding, Harnessing, Oscilloscopes, NI tools
- **Languages:** English (native), Portuguese (conversational), Spanish (beginning conversational), French (beginning)