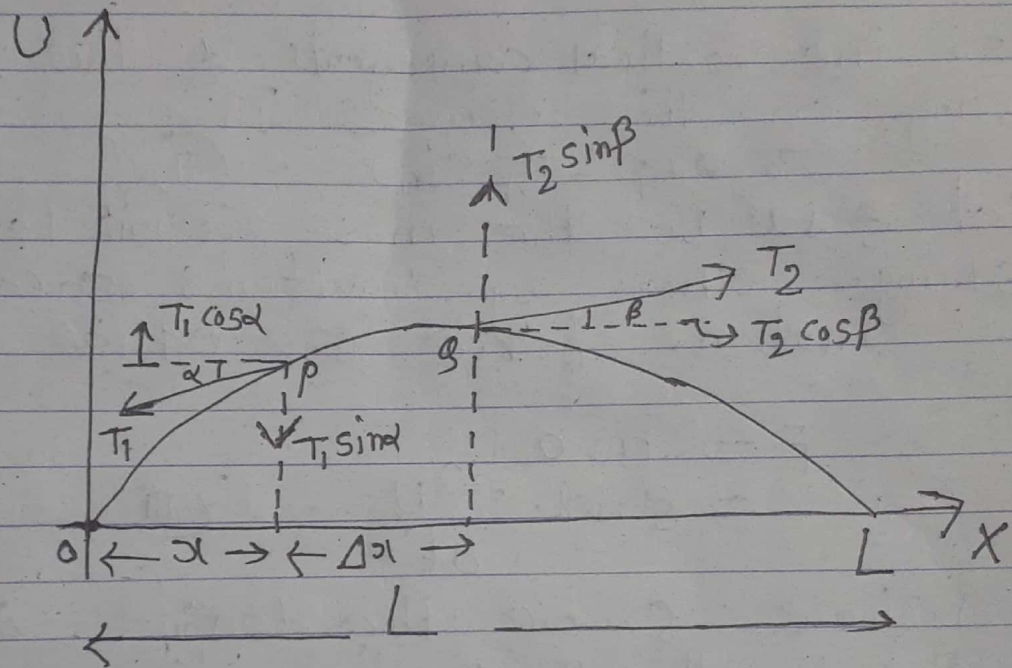


①

Wave equation (vibration of string)

Derivation of one dimensional wave equation



consider a tightly stretched elastic string of length $OL = L$ and fix it at the ends O and L . When the string vibrates, each point of the string makes small vibration on U -axis which is shown in figure.

Let $P(x, U)$ and $Q(x + \Delta x, U + \Delta U)$ be two neighbouring points on the string. Let T_1 and T_2 be the tension at the points P and Q where the tensions makes angles α and β with x -axis. Since the point of the string moves vertically, there is no motion in the horizontal direction. Thus

(2)

the horizontal components of the tension must be equal i.e. constant

$$\therefore T_1 \cos \alpha = T_2 \cos \beta = T \quad (\text{say}) \quad \dots (I)$$

Also the vertical components of the force acting on this element is

$$T_2 \sin \beta - T_1 \sin \alpha \quad \dots (II)$$

Let $\rho \Delta x$ be the mass per unit length of string. Then by Newton's second law of motion, force is equal to

$$F = m a \\ = \rho \Delta x \cdot \frac{\partial^2 U}{\partial t^2} \quad \dots (III)$$

Where ρ be the density, Δx is the length of portion string and $\frac{\partial^2 U}{\partial t^2}$ is acceleration

From eqn (II) and (III)

$$T_2 \sin \beta - T_1 \sin \alpha = \rho \Delta x \cdot \frac{\partial^2 U}{\partial t^2} \quad \dots (IV)$$

Now dividing eqn (IV) by (II), we get

$$\frac{T_2 \sin \beta}{T_2 \cos \beta} = \frac{T_1 \sin \alpha}{T_1 \cos \alpha} = \frac{\rho \Delta x \cdot \frac{\partial^2 U}{\partial t^2}}{T}$$

$$\tan \beta - \tan \alpha = \frac{\rho \Delta x}{T} \cdot \frac{\partial^2 U}{\partial t^2} \quad \dots (V)$$

(3)

We know that $\tan \alpha$ and $\tan \beta$ are the slopes of the string at x and $x + \Delta x$ respectively

Where $\tan \alpha = \left. \frac{\partial u}{\partial x} \right|_{\text{at } x}$

$$\tan \beta = \left. \frac{\partial u}{\partial x} \right|_{\text{at } x + \Delta x}$$

Eqn (v) becomes, we get

$$\left[\left. \frac{\partial u}{\partial x} \right|_{\text{at } x + \Delta x} - \left. \frac{\partial u}{\partial x} \right|_{\text{at } x} \right] = \frac{\rho \Delta x}{T} \cdot \frac{\partial^2 u}{\partial t^2}$$

$$\therefore \frac{1}{\Delta x} \left[\left. \frac{\partial u}{\partial x} \right|_{\text{at } x + \Delta x} - \left. \frac{\partial u}{\partial x} \right|_{\text{at } x} \right] = \frac{\rho}{T} \cdot \frac{\partial^2 u}{\partial t^2}$$

Taking limit $\Delta x \rightarrow 0$ on both sides, we get

$$\therefore \lim_{\Delta x \rightarrow 0} \frac{1}{\Delta x} \left[\left. \frac{\partial u}{\partial x} \right|_{x + \Delta x} - \left. \frac{\partial u}{\partial x} \right|_x \right] = \lim_{\Delta x \rightarrow 0} \frac{\rho}{T} \frac{\partial^2 u}{\partial t^2}$$

$$\therefore \lim_{\Delta x \rightarrow 0} \left[\frac{\left. \frac{\partial u}{\partial x} \right|_{x + \Delta x} - \left. \frac{\partial u}{\partial x} \right|_x}{\Delta x} \right] = \frac{\rho}{T} \cdot \frac{\partial^2 u}{\partial t^2}$$

(4)

$$\text{or } \frac{\partial^2 U}{\partial x^2} = \frac{\rho}{T} \cdot \frac{\partial^2 U}{\partial t^2}$$

$$\text{or } \frac{\rho}{T} \cdot \frac{\partial^2 U}{\partial t^2} = \frac{\partial^2 U}{\partial x^2}$$

$$\text{or } \frac{\partial^2 U}{\partial t^2} = \frac{T}{\rho} \frac{\partial^2 U}{\partial x^2}$$

$$\text{or } \boxed{\frac{\partial^2 U}{\partial t^2} = c^2 \frac{\partial^2 U}{\partial x^2}}$$

$$\text{Where } c^2 = \frac{T}{\rho}$$

This is the required one dimensional wave equation.

(5)

Solution of one dimensional wave equation under certain initial and Boundary conditions

Solution:- We have one dimensional wave eqn is

$$\frac{\partial^2 U}{\partial t^2} = c^2 \frac{\partial^2 U}{\partial x^2} \dots (1)$$

Where $U(x, t)$ is the deflection of the string with boundary condition
 $U(0, t) = 0$ and $U(L, t) = 0$ for all t (2)

then its initial condition is
 $U(x, 0) = f(x) \dots (3)$ initial deflection

$\frac{\partial U}{\partial t} \bigg|_{t=0} = g(x) \dots (4)$ initial velocity

Suppose $U(x, t) = F(x) \cdot G(t) \dots (5)$

be the Solution of eqn (1)
Differentiating eqn (5) w.r. to x and t

$$\frac{\partial^2 U}{\partial t^2} = F \cdot \ddot{G} \quad \text{and} \quad \frac{\partial^2 U}{\partial x^2} = F'' G$$

Where

dots denotes derivative w.r. to t
prime denotes derivative w.r. to x
putting these values in eqn (1)
we get

(6)

$$F \ddot{G} = c^2 F'' G$$

$$\Rightarrow \frac{F''}{F} = \frac{\ddot{G}}{G \cdot c^2}$$

$$\Rightarrow \frac{F''}{F} = \frac{\ddot{G}}{G \cdot c^2} = K \text{ (say)}$$

which gives

$$F'' - FK = 0 \quad \dots (6)$$

$$\ddot{G} - c^2 K G = 0 \quad \dots (7)$$

These are second order ordinary differential equation. We have to determine F and G from eqn (6) and (7) under boundary conditions.

Also, we have

$$U(x, t) = F(x) \cdot G(t)$$

$$\text{i.e. } U(0, t) = F(0) \cdot G(t) = 0$$

$$U(L, t) = F(L) \cdot G(t) = 0$$

for all t

For solving eqn (6) we have to generate boundary condition (b.c.)

if $G = 0$, then $U = 0$ which is no meaning or interest. So $G \neq 0$

Then we get

$$F(0) = 0 = F(L) \quad \dots (8)$$

(7)

Case (i) Let $K = 0$ then eqn (6) becomes

$$F'' = 0$$

integrating

$$F' = a$$

again integrating

$$F = ax + b \quad (9)$$

Where a and b are constants. We have to find a and b under boundary condition.

We have

$$F(0) = 0 \text{ and } F(L) = 0$$

$$\therefore F(x) = ax + b$$

$$\text{or } F(0) = a \cdot 0 + b$$

Again

$$F(L) = aL + b$$

$$0 = b$$

$$0 = aL + 0$$

$$\therefore b = 0$$

$$\therefore a = 0$$

We get $a = b = 0$

putting these values of a and b in eqn (9)

$$F = 0 \cdot x + 0 \Rightarrow F = 0$$

Which is no interest.

Case (ii) Suppose that $K > 0$
ie K is positive



(2)

$$\text{Let } K = \lambda^2$$

Then eqn (6) becomes

$$F'' - \lambda^2 F = 0$$

its auxiliary eqn is

$$m^2 - \lambda^2 = 0$$

$$m = \pm \lambda$$

its general solution is

$$F(x) = A \cdot e^{\lambda x} + B \cdot e^{-\lambda x} \quad \dots (10)$$

Where A and B are constants to be determine under boundary condition.

$$\text{i.e. } F(0) = A \cdot e^0 + B \cdot e^0$$

$$0 = A + B$$

$$A + B = 0 \quad \dots (i)$$

$$\text{Again } F(L) = A \cdot e^{\lambda L} + B \cdot e^{-\lambda L}$$

$$0 = A \cdot e^{\lambda L} + B \cdot e^{-\lambda L}$$

$$A \cdot e^{\lambda L} + B \cdot e^{-\lambda L} = 0 \quad \dots (ii)$$

Solving (i) and (ii) we get

$$A = B = 0$$

~~Eqn~~ Eqn (10) becomes

$$F = 0 \Rightarrow U = 0$$

This is also no interest.

(9)

case (iii) Let $K < 0$
i.e. K is negative
Suppose $K = -p^2$
Eqn (6) becomes

$$F'' + p^2 F = 0$$

A.E. is

$$m^2 + p^2 = 0$$

$$m = \pm pi$$

its general solution is

$$F(x) = e^{px} (A \cos qx + B \sin qx) \quad \text{Where}$$
$$F(x) = e^{0 \cdot x} (A \cos px + B \sin px) \quad \begin{matrix} p = \text{real part} \\ q = \text{imaginary part} \end{matrix}$$

$$F(x) = A \cos px + B \sin px \quad \dots (11)$$

using boundary condition

$$F(0) = A \cos 0 + B \sin 0$$

$$0 = A \cdot 1 + 0$$

$$\therefore A = 0$$

Also

$$F(L) = A \cos pL + B \sin pL$$

$$0 = 0 \cdot \cos pL + B \sin pL$$

$$\therefore B \sin pL = 0$$

(10)

Let $B \neq 0$. So

$$\begin{aligned}\sin pL &= 0 \\ \sin pL &= \sin n\pi\end{aligned}$$

$$pL = n\pi$$

$$p = \frac{n\pi}{L} \quad \text{where } n \text{ is an integer}$$

We have $B \neq 0$, setting $B = 1$

Eqn (11) becomes

$$f(x) = 0 \cdot \cos px + 1 \cdot \sin \frac{n\pi}{L} \cdot x$$

$$f(x) = \sin \frac{n\pi}{L} \cdot x$$

We obtain infinitely many solⁿ

$$f(x) = f_n(x)$$

$$\text{i.e. } f_n(x) = \sin \frac{n\pi}{L} \cdot x \quad \dots (12)$$

$$\text{for } n = 1, 2, 3, \dots$$

Similarly for solution of eqn (7) is

$$\ddot{G} - c^2 K G = 0$$

We have

$$K = -p^2 = -\left(\frac{n\pi}{L}\right)^2$$

Then Eqn (7) becomes

(11)

$$\ddot{G} + c^2 \left(\frac{n\pi}{L} \right)^2 G = 0$$

$$\text{or } \ddot{G} + \left(\frac{cn\pi}{L} \right)^2 G = 0$$

$$\ddot{G} + \lambda_n^2 G = 0 \quad \text{where } \lambda_n = \frac{cn\pi}{L}$$

its auxiliary eqn is

$$m^2 + \lambda_n^2 = 0$$

$$\therefore m = \pm \lambda_n i \quad \text{here } p=0, q=\lambda_n$$

its general solution

$$G(t) = e^{pt} (B_n \cos \lambda_n t + B_n^* \sin \lambda_n t)$$

$$G(t) = e^0 (B_n \cos \lambda_n t + B_n^* \sin \lambda_n t)$$

$$G(t) = B_n \cos \lambda_n t + B_n^* \sin \lambda_n t$$

$$\text{i.e. } G_n(t) = B_n \cos \lambda_n t + B_n^* \sin \lambda_n t$$

Therefore required solution of eqn (1) is

$$U_n(x, t) = F_n(x) \cdot G_n(t)$$

$$= \sin \frac{n\pi}{L} x (B_n \cos \lambda_n t + B_n^* \sin \lambda_n t)$$

By fundamental theorem the solution of given wave eqn is the infinitely

(12)

many U_n . Thus

$$U(x, t) = \sum_{n=1}^{\infty} U_n(x, t)$$

$$\Rightarrow U(x, t) = \sum_{n=1}^{\infty} (B_n \cos \lambda_n t + B_n^* \sin \lambda_n t) \sin \frac{n\pi}{L} x \quad (13)$$

From eqn (3) [initial condition]

$$U(x, 0) = b(x)$$

Then eqn (13) becomes

$$U(x, 0) = \sum_{n=1}^{\infty} (B_n \cos 0 + B_n^* \sin 0) \cdot \sin \frac{n\pi}{L} x$$

$$\text{i.e. } b(x) = \sum_{n=1}^{\infty} B_n \sin \frac{n\pi}{L} x$$

Which is Fourier sine series and its co-efficient B_n is given by

$$B_n = \frac{2}{L} \int_0^L b(x) \sin \frac{n\pi}{L} x \, dx$$

Also, we have

$$\left. \frac{\partial U}{\partial t} \right|_{t=0} = g(x)$$

eqn (13) becomes

(13)

$$\Rightarrow \left[\sum_{n=1}^{\infty} (-B_n \ln \sin \ln t + B_n^* \ln \cos \ln t) \sin \frac{n\pi x}{L} \right]_{t=0} = g(x)$$

$$\Rightarrow \sum_{n=1}^{\infty} B_n^* \ln \sin \frac{n\pi x}{L} = g(x) \quad \text{put } t=0$$

$$\therefore g(x) = \sum_{n=1}^{\infty} B_n^* \ln \sin \frac{n\pi x}{L}$$

Which is also Fourier sine series of $g(x)$. its coefficient is given by

$$B_n^* \ln = \frac{2}{L} \int_0^L g(x) \sin \frac{n\pi x}{L} dx$$

$$B_n^* = \frac{2}{\ln L} \int_0^L g(x) \sin \frac{n\pi x}{L} dx$$

$$= \frac{2}{\frac{\ln L}{L}} \int_0^L g(x) \sin \frac{n\pi x}{L} dx$$

$$\text{where } \ln = \frac{\ln L}{L}$$

$$= \frac{2}{\ln L} \int_0^L g(x) \sin \frac{n\pi x}{L} dx$$

(14)

Therefore we get required solution of one dimensional wave eqn is

$$U(x, t) = \sum_{n=1}^{\infty} (B_n \cos \lambda_n t + B_n^* \sin \lambda_n t) \sin \frac{n\pi}{L} x$$

Where

$$B_n = \frac{2}{L} \int_0^L b(x) \sin \frac{n\pi}{L} x dx$$

$$B_n^* = \frac{2}{cn\pi} \int_0^L g(x) \sin \frac{n\pi}{L} x dx$$

Where $b(x)$ and $g(x)$ are initial deflection and initial velocity of the string respectively.