

# Yanqi Liu

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| <b>EDUCATION</b>  | <b>UNIVERSITY OF MICHIGAN</b>  | <b>Ann Arbor, MI</b> |
|                   | <ul style="list-style-type: none"><li>• <b>College of Engineering</b>      <b>May, 2017</b>      <b>GPA: 3.92/4.00</b></li><li>• BSE in Computer Engineering, Minor in Business</li><li>• Honors: Engineering Dean's list, James B. Angell Scholar, University Honors</li></ul>  |                      |
| <b>COURSE</b>     | Computer Vision (A+), Embedded Control, Introduction to Computer Organization, Programming and Data Structure (A+), Data Structure and Algorithm, Signal Processing  |                      |
| <b>EXPERIENCE</b> | <b>APRIL Lab</b>   | <b>Ann Arbor, MI</b> |
| Jun 2015-Present  | <b>Undergraduate Researcher</b> <ul style="list-style-type: none"><li>• Utilized camera installed on robotic car to detect drivable area</li><li>• Devised HSI color detection algorithm with the implementation of illumination invariant to remove shadow interference achieving 90% accuracy</li><li>• Implemented Sobel edge detection method for indoor corridor area detection for up to 97% accuracy</li><li>• Enhanced research skills in data labeling, statistical analysis and paper writing</li></ul>                |                      |
| Fall 2015         | <b>EECS 442 Class Project</b><br><b>Hand Augmented Reality</b> <ul style="list-style-type: none"><li>• Implemented real-time program to utilize webcam to display 3D object in sync with pose of hand</li><li>• Utilized OpenCV implementations to achieve hand segmentation, contouring and camera pose estimation</li><li>• Developed cross-frame figure tip tracking method to stabilize object display</li></ul>   |                      |
| Summer 2014       | <b>INTERNSHIP- A2B BIKESHARE</b>   | <b>Ann Arbor, MI</b> |
|                   | <b>Electrical Engineer</b> <ul style="list-style-type: none"><li>• Enhanced low-level programming skills through programing for decoding GPS command and communicating with other device using I2C</li><li>• Designed and programmed GPS tracker using cellular module to retain GPS information</li><li>• Learned programming in Arduino, AVR C and circuit board design using EAGLE</li><li>• Exercised engineering skills as well as skills in marketing and selling</li></ul>  |                      |
| Fall&Winter 2013  | <b>Undergraduate Research Opportunity Program- APRIL Lab</b>   | <b>Ann Arbor, MI</b> |
|                   | <b>Research Assistant</b> <ul style="list-style-type: none"><li>• Developed calibration system with camera and laser pointer to increase calibration accuracy for low-cost robotic building</li><li>• Developed forward and inverse kinematics algorithm using VIS to control arm gesture to reach object in given position</li><li>• Implemented image processing method to detect brightest spot of video stream</li><li>• Exercised research skills and teamwork experiences through weekly programing tasks</li></ul>        |                      |
| 2012-2015         | <b>BLUELab-HAGLEY GAP</b>  | <b>Ann Arbor, MI</b> |
|                   | <b>Financial Chair</b> <ul style="list-style-type: none"><li>• Acquired financial experiences and skills of planning team budget, planning for travel for 6 people and applying for university funding for \$4000</li><li>• Traveled to Jamaica in May, 2013, built three Bio-sand filters, taught SODIS lessons in Minto school and tested the water quality in the area</li><li>• Enhanced collaborative ability by designing, testing and building with a group of engineers with different engineering backgrounds</li></ul> |                      |
| Jan. 2016-Present | <b>EECS 370 Instructional Aide</b>   | <b>Ann Arbor, MI</b> |
|                   | <ul style="list-style-type: none"><li>• Taught 1-hour discussion and 3-hour office hour every week</li><li>• Designed homework and exams and answered questions on Piazza</li></ul>  |                      |
| <b>ADDITIONAL</b> | Computer: C++, C, Java, Matlab<br>Professional Organizations: member of IEEE and HKN   |                      |