

Bretagne-Pays de la Loire École Mines-Télécom

Machine Learning Approaches: Decision Trees

2. Decision Trees Induction Algorithms

2.a. ID3 Algorithm

2.b. Classification And Regression Tree, CART, Algorithm

- 3. Overfitting problem
- 4. Regression trees for prediction

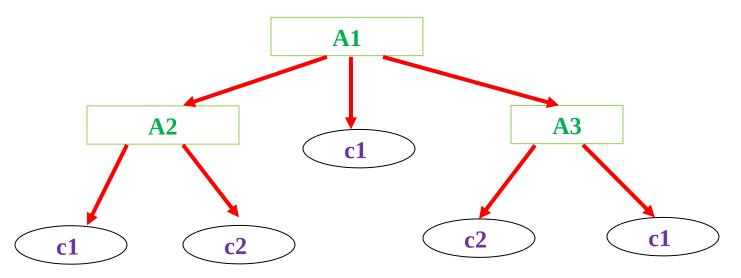






DECISION TREE: Piecewise constant tree-like algorithm obtained with recursive partitioning of the input data space (i.e., \Re^K) into axis-parallel regions, labeled with class value, where:

Each *interior node* tests an attribute Each *branch* corresponds to an attribute value Each *leaf node* is labelled with a class



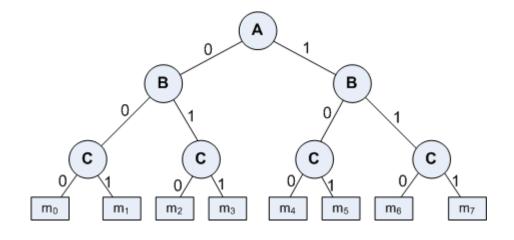




A Decision Tree is an important data structure known to solve many computational problems

Example: Binary Decision Tree

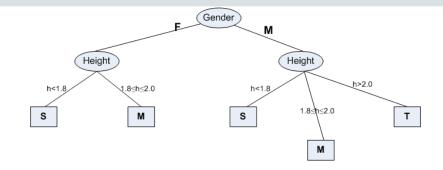
Α	В	С	f
0	0	0	m_0
0	0	1	m_1
0	1	0	m_2
0	1	1	m_3
1	0	0	m_4
1	0	1	m_5
1	1	0	m ₆
1	1	1	m_7







Some Characteristics



- Decision tree may be n-ary, $n \ge 2$
- Decision tree is not unique, as different ordering of internal nodes can give different decision tree
- Decision tree helps us to classify data

Internal nodes are some attribute

Edges are the values of attributes

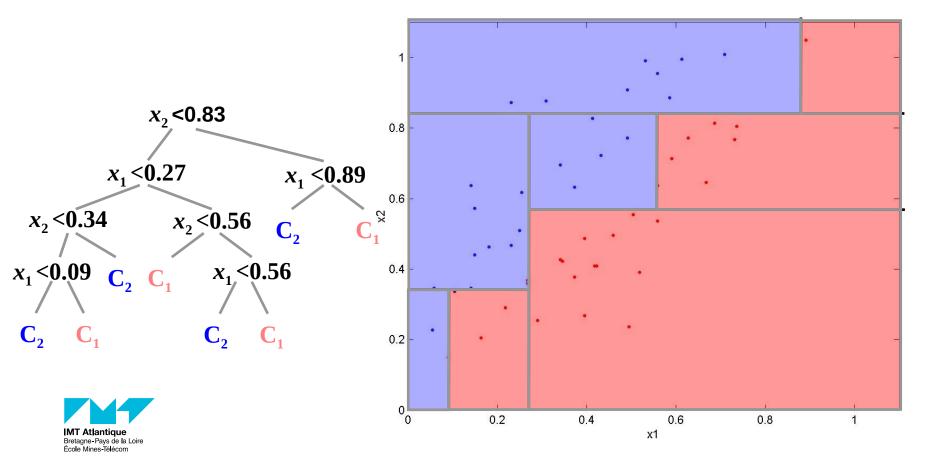
External nodes are the outcome of classification







- Splits are parallel to the axes
- At every step of the "binary" partitioning, data in the current node is split "at best" (i.e., to have the greatest decrease, in term of heterogeneity in the two child nodes



- 2.a. ID3 Algorithm
- 2.b. Classification And Regression Tree,

CART, Algorithm





Decision tree induction (i.e., construction):

- A top-down, recursive and divide-and-conquer approach
- The procedure is to choose an attribute and split it into from a larger training set into smaller training sets.
- Different algorithms have been proposed to take a good control over
 - . Choosing the best attribute to be splitted, and
 - **Splitting criteria**





Learning decision trees from training data

Goal: Build a decision tree to classify examples of a concept using supervised learning from a training set

$$B = \{(X_n, Y_n) \mid n = 1,...,N\}$$

Properties we want the decision tree to have?

- 1. It should be consistent with the learning training set
 - Trivial algorithm: construct a decision tree that has one path to a leaf for each example
 - Problem: it does not capture useful information from the database
- 2. It should be as simple as possible

Generate all trees and pick the simplest one that is consistent with the learning sample.

Problem: intractable, there are too many trees



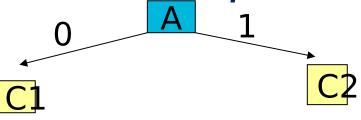


Learning decision trees from training data

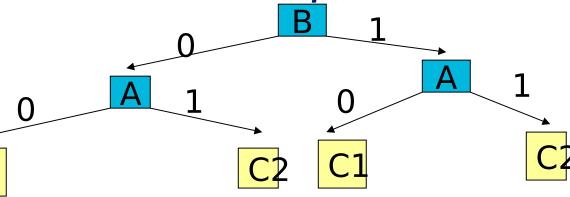
Example

Α	В	Class
0	1	C1
0	0	C1
1	1	C2
1	0	C2

Attribute A is chosen first:



Attribute B is chosen first:







A Tree learning algorithm allows to choose the tree structure and to determine the predictions at leaf nodes

Predictions: to minimize the misclassification error, associate the majority class among the learning sample cases reaching this node



Top-Down induction learning of decision trees

$$B = \{(X_n, Y_n) \mid n = 1,...,N\}$$

Choose « best » attribute
Split the learning sample

Split the learning sample

IF: all sample data from the training set have the same class Create a leaf with that class

ELSE:

Proceed recursively until each sample data is correctly classified







Which attribute is best?

We should maximize the class separation at each step, i.e., make successors as pure as possible



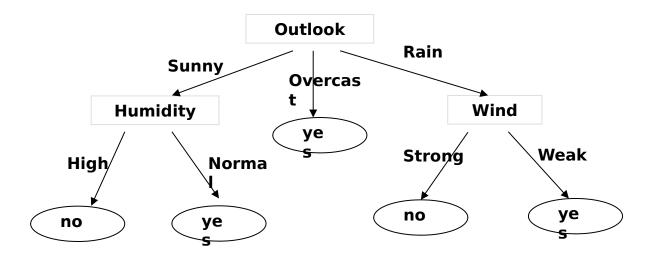
This will favour short paths in the trees







Tree decision model: Use of decision rules



A rule set is finally derived from a decision tree where a rule is generated for each path in the decision tree from the root to a leaf. The left-hand side of a rule is easily built from the label of the nodes and the labels of the arcs



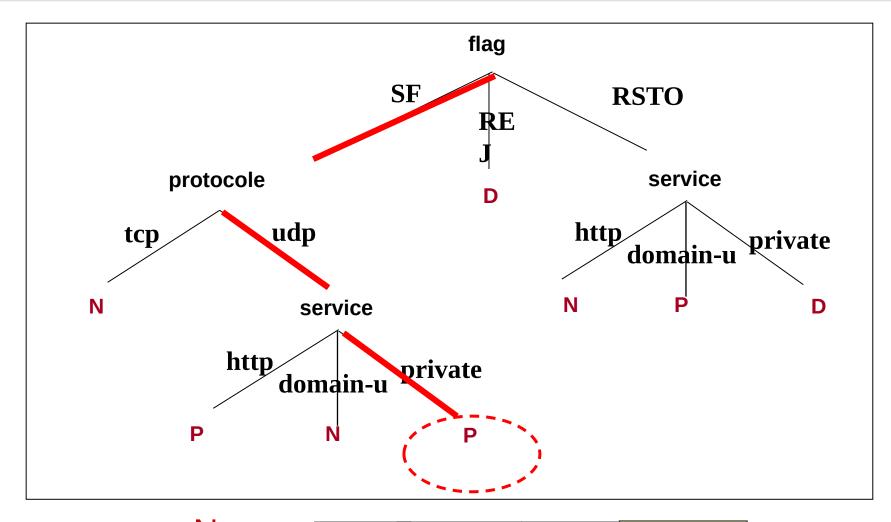


Protocole	Service	Flag	Classe
tcp	http	http SF	
tcp	http	RSTO	Normal
tcp	http	REJ	Probing
tcp	time	SF	Probing
tcp	time	SO	DOS
tcp	auth	SF	Normal
tcp	auth	SO	DOS
tcp	private	SF	Normal
tcp	private	SF	Normal
tcp	private	REJ	Probing
tcp	private	RSTO	DOS
tcp	private	SO	DOS
udp	domain_u	SF	Normal
udp	private	SF	DOS
tcp	http	RSTO	Normal
tcp	private	RSTO	DOS
tcp	http	SF	Normal













udp Private

SF

C=?

2.a. ID3 Algorithm

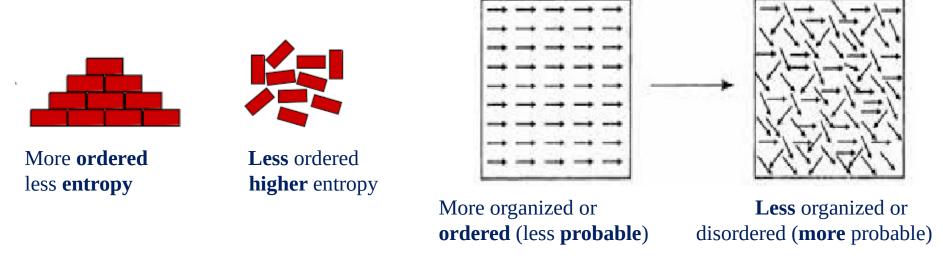
2.b. Classification And Regression Tree,

CART, Algorithm





ID3 algorithm is based on the use of entropy in order to measure how informative a node is



In a classification job, entropy is an important concept, which is considered as an information-theoretic measure of the "uncertainty" contained in a training data (due to the presence of more than one classes)





ID3 algorithm is based on the use of Shannon's entropy in order to measure how informative a node is



Splitting (on any attribute) has the property that average entropy of the resulting training subsets is less than or equal to that of the previous training set



ID3 algorithm defines a measurement of a splitting called <u>Information Gain</u> to determine the goodness of a split:

The attribute with the largest value of information gain is chosen as the splitting attribute and

it partitions into a number of smaller training sets based on the distinct values of attribute under split.

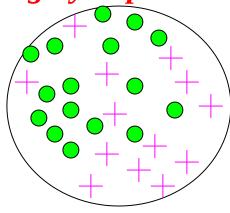




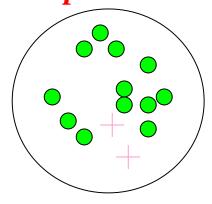


Measure of impurity!

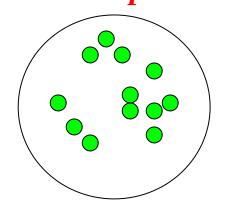
Highly impure set



Impure set



Minimal impure set

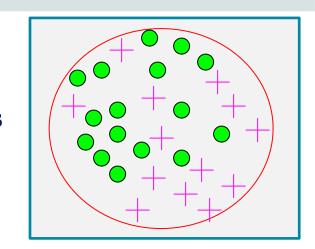






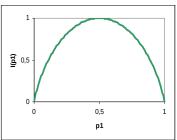
$$Entropy = \sum_{i} - p_{i} \log_{2} p_{i}$$

p_i (Class « i » probability) : Proportion of samples labeled from class « i » in the considered set

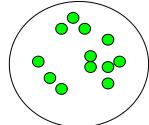




Two classes:

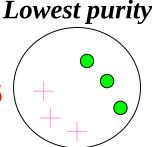


Highest purity



Entropy =
$$-1 \log_2 1 = 0$$

Entropy = -0.5log₂0.5-0.5log₂0.5







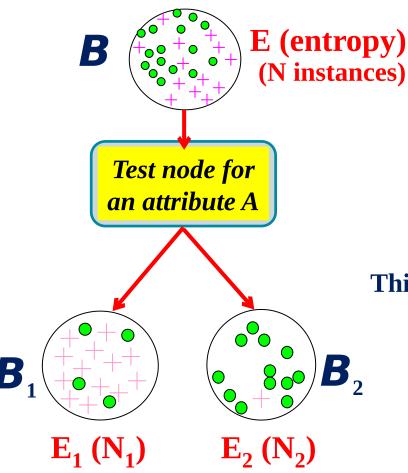
- Entropy takes it's minimum value (zero) if and only if all the instances have the same class (i.e., the training set with only one non-empty class, for which the probability 1)
- Entropy takes its maximum value when the instances are equally distributed among K possible classes. In this case, the maximum value of the entropy is







Information Gain splitting criterion



Information Gain
(due to attribute A)
=

$$E - \{(N_1/N) E_1 + (N_2/N) E_2\}$$

This represents the difference between:

Information needed to identify an element of **B** and

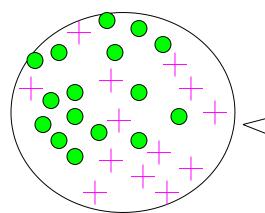
Information needed to identify an element of **B** after the value of attribute A has been obtained





Example

N= 30 instances)

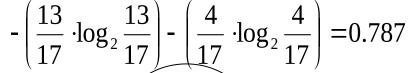


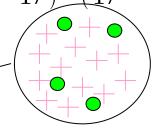
$$\mathbf{E} = -\left(\frac{14}{30} \cdot \log_2 \frac{14}{30}\right) - \left(\frac{16}{30} \cdot \log_2 \frac{16}{30}\right) = 0.996$$

Mean weighted entropy =
$$\left(\frac{17}{30} \cdot 0.787\right) + \left(\frac{13}{30} \cdot 0.391\right) = 0.615$$

Information Gain = 0.996 - 0.615 = 0.38

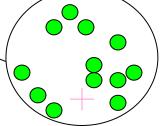






$$N_1 = 17$$

$$-\left(\frac{1}{13} \cdot \log_2 \frac{1}{13}\right) - \left(\frac{12}{13} \cdot \log_2 \frac{12}{13}\right) = 0.391$$

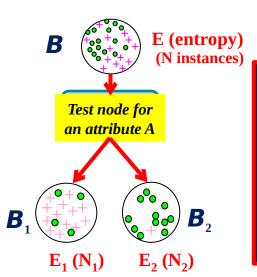


$$N_3 = 13$$





Information Gain splitting criterion



Information Gain is used to rank attributes and to build decision trees where at each node is located the attribute with the greatest information gain among the attributes not yet considered in the path from the root





Example

Attributs	Pif	Temp	Humid	Vent
Valeurs possibles	soleil,couvert,pluie	chaud,bon,frais	normale,haute	vrai,faux

N°	Pif	Temp	Humid	Vent	Golf
1	soleil	chaud	haute	faux	NePasJouer
2	soleil	chaud	haute	vrai	NePasJouer
3	couvert	chaud	haute	faux	Jouer
4	pluie	bon	haute	faux	Jouer
5	pluie	frais	normale	faux	Jouer
6	pluie	frais	normale	vrai	NePasJouer
7	couvert	frais	normale	vrai	Jouer
8	soleil	bon	haute	faux	NePasJouer
9	soleil	frais	normale	faux	Jouer
10	pluie	bon	normale	faux	Jouer
11	soleil	bon	normale	vrai	Jouer
12	couvert	bon	haute	vrai	Jouer
13	couvert	chaud	normale	faux	Jouer
14	pluie	bon	haute	vrai	NePasJouer

Entropie de l'ensemble initial d'exemples

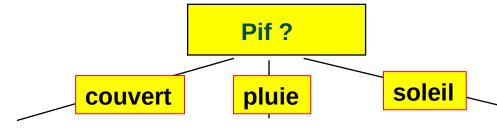
 $E = -9/14 \log_2(9/14) - 5/14 \log_2(5/14)$





Entropie des sous-arbres associés au test sur Pif?

+ J3,J4,J5,J7,J9,J10,J11,J12,J13 - J1,J2, J6,J8,J14



+ J3,J13,J7,J12

+ J4,J5,J10

+ J9,J11

_ J6,J14

J1,J8,J2

$$\mathbf{E_1} = \mathbf{0}$$

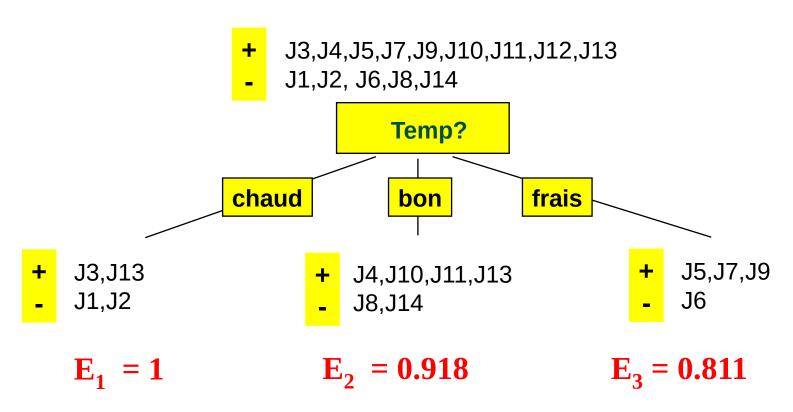
$$E_2 = 0.971$$

$$E_3 = 0.971$$





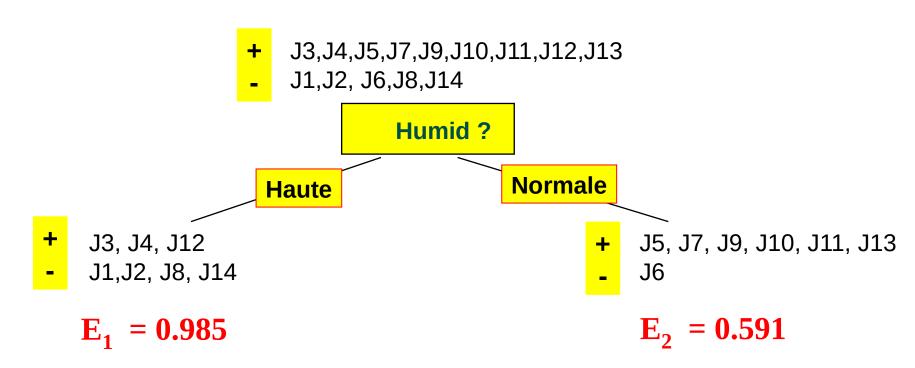
Entropie des sous-arbres associés au test sur TEMPS?







Entropie des sous-arbres associés au test sur Humid?







Entropie des sous-arbres associés au test sur Vent?

- J3,J4,J5,J7,J9,J10,J11,J12,J13
- J1,J2, J6,J8,J14

Vent? faux vrai J7,J11,J12 J2,J6,J14

> $\mathbf{E_1} = \mathbf{1}$ Gain(Temp) = 0.029 bits Gain(Pif) = **0.246** bits Gain(Humid) = 0.151 bitsGain(Vent) = 0.048 bits

J3,J4,J5,J9,10,J13

J1,J8

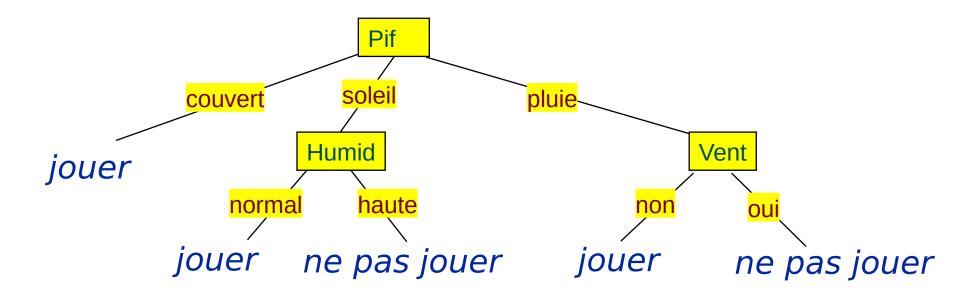
 $E_2 = 0.811$

Choix de l'attribut Pif pour le premier test





Application récursive ID3: Arbre final obtenu :





2.a. ID3 Algorithm

2.b. Classification And Regression Tree,

CART, Algorithm





2.b. Classification And Regression Trees, CART 33

CART is a technique that generates a binary decision tree

ID3 uses Information gain as a measure to select the best attribute to be splitted, whereas <u>CART does the same but</u> <u>using another measurement called Gini index</u>



GINI INDEX If a data set T contains examples from n classes, gini index, aini(T) is defined as:

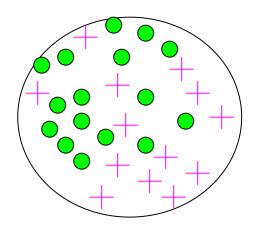
$$gini(T) = 1 - \sum_{j=1}^{n} p_j^2$$

where p_i is the relative frequency of class j in T





2.b. Classification And Regression Trees, CART



n = 2, $p_1 = 14/30$, $p_1 = 16/30$

Note: gini(T) measures the "impurity" of data set T.

The smallest value of gini(T) is zero which it takes when all the classifications are same (if the classes in T are skewed)

It takes its largest value , when the classes are evenly distributed between the tuples, that is the frequency of each class is

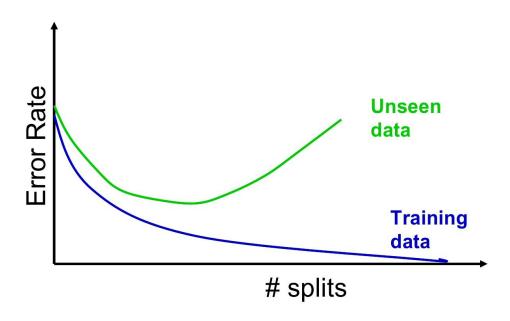






STOPPING TREE GROWTH

Natural end of process is 100% purity in each leaf
Overfitting leads to low predictive accuracy of new data
Past a certain point, the error rate for the validation data starts
to increase

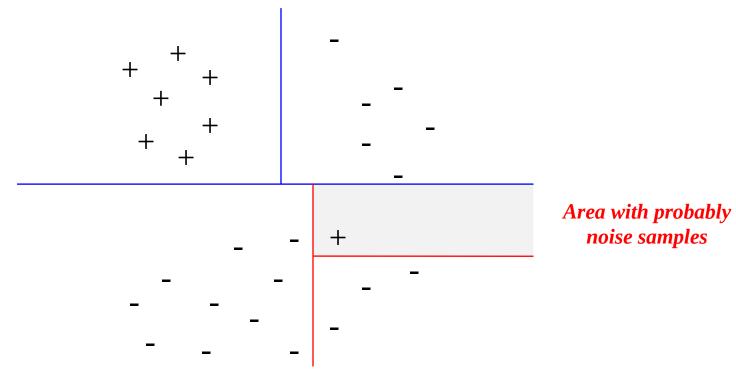






REASONS OF OVERFITTING

Overfits the data will end up fitting noise in the data



We may not have enough data in some part of the learning sample to make a good decision





HOW CAN WE AVOID OVERFITTING?



Pre-pruning: stop growing the tree earlier, before it reaches the point where it perfectly classifies the learning sample.

Stop splitting a node if:

The number of objects is too small

The impurity is low enough

The best test is not statistically significant (according to some statistical test)



Post-pruning: allow the tree to overfit and then post-prune the tree

Compute a sequence of trees $\{T_1, T_2, ...\}$ where

 T_1 is the complete tree

 T_i is obtained by removing some test nodes from T_{i-1}

Select the tree T_i^* from the sequence that minimizes the error on a validation sample set

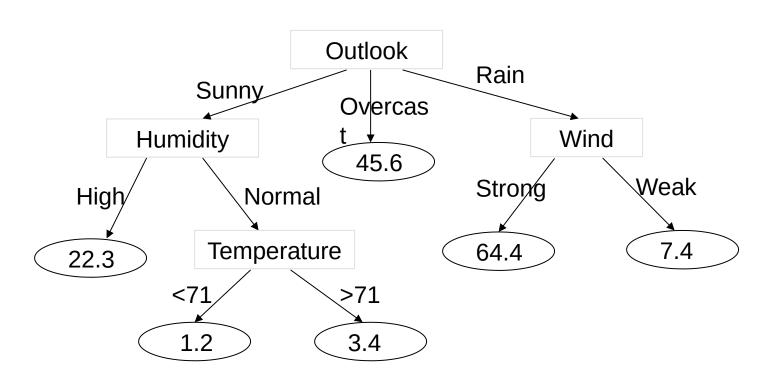








A regression Tree: Has exactly the same model as a decision tree, but with a number (called the prediction value) in each leaf instead of a class









The regression tree targets to segment the "predictor space" into sub-regions and to learn from the training set the value to predict



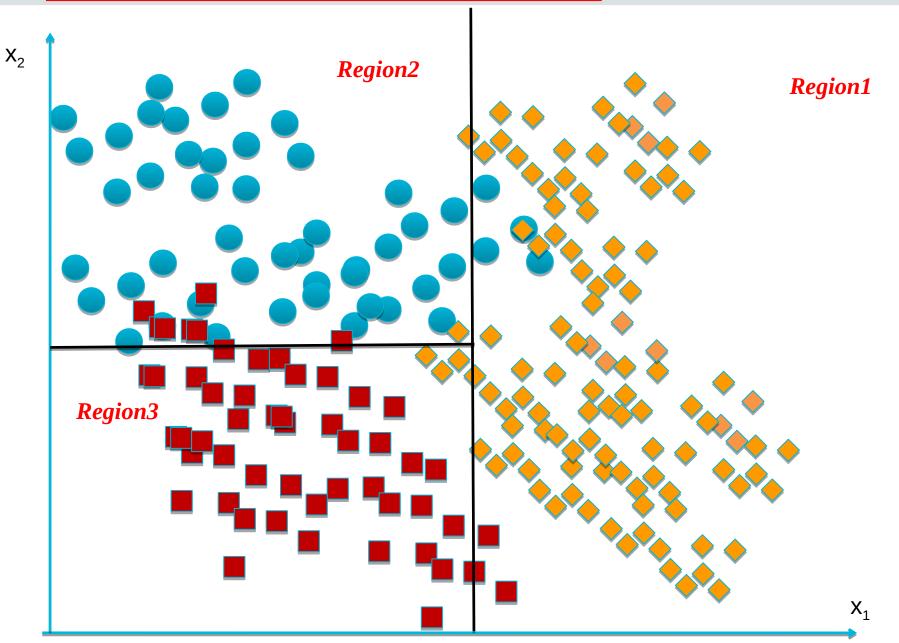
Building a regression tree

1. Building a decision tree (using a label information, categorical attribute) followed by

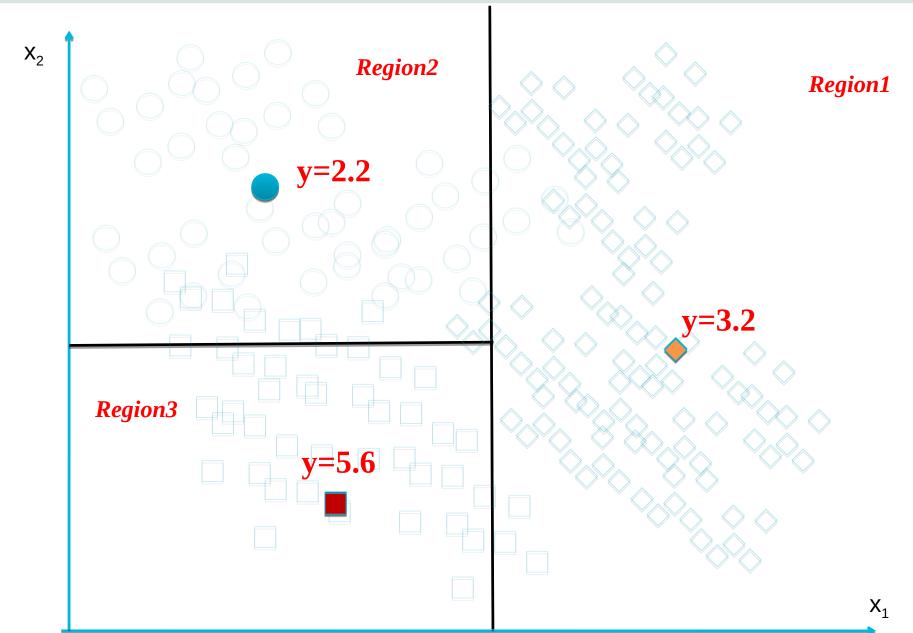
The use, as prediction values) of the mean or mode or median of the variable (to predicted) of the training examples in sub-regions













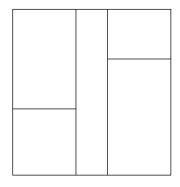


Building a regression tree

2. Direct building the regression tree (without the step of constructing a decision tree)

Find boxes R_1, \ldots, R_M that minimize:

$$\sum_{\mathbf{m}=1,...,\mathbf{M}} \sum_{\mathbf{Sample(i)} \in R_{\mathbf{m}}} \left[\left[x_{\mathbf{i}} - x_{\mathbf{i}} (R_{\mathbf{M}}) \right]^{2} \right]$$



 $x_{\rm i}(R_{\rm m})$: mean response value of all training observations in the $R_{\rm m}$ region

