

# Learning and Reasoning in Logic Tensor Networks

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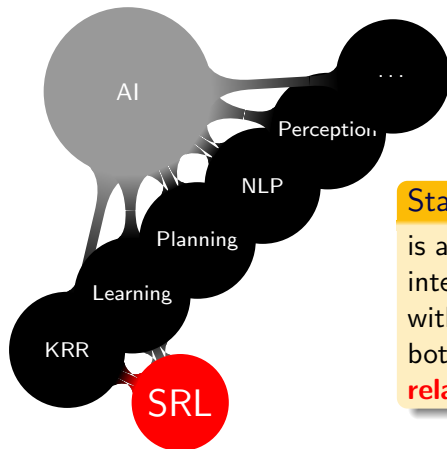
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May 7, 2017

# The SRL Mindmap



## Statistical Relational Learning

is a subdiscipline of artificial intelligence that is concerned with domain models that exhibit both **uncertainty** and **complex relational structure**.

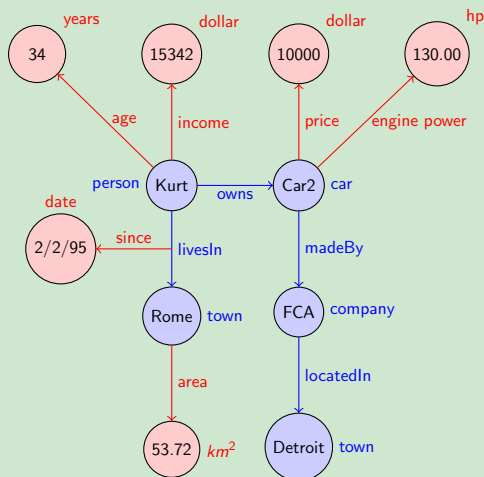
# Hybrid domains

We are interested in Statistical Relational Learning over hybrid domains, i.e., domains that are characterized by the presence of

- structured data (categorical/semantic);
- continuous data (continuous features);

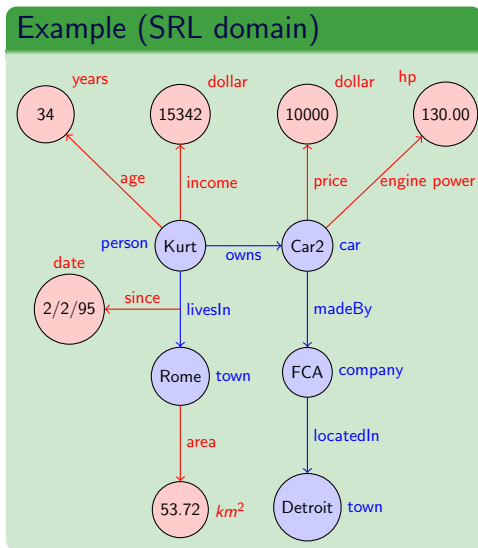
# Hybrid domains

## Example (SRL domain)



# Tasks in Statistical Relational Learning

- **Object Classification:**  
Predicting the type of an object based on its relations and attributes;
- **Relation detection:**  
Predicting if two objects are connected by a relation, based on types and attributes of the participating objects;
- **Regression:** predicting the (distribution of) values of the attributes of an object, (a pair of related objects) based on the types and relations of the object(s) involved.

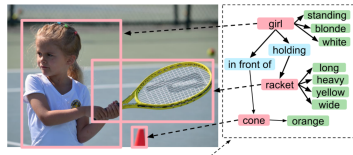


# Real-world uncertain, structured and hybrid domains

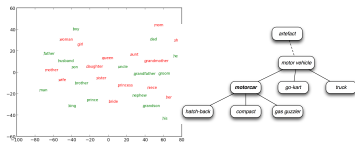
**Robotics:** a **robot's location** is a continuous values while the **the types of the objects it encounters** can be described by discrete set of classes



**Semantic Image Interpretation:** The **visual features** of a bounding box of a picture are continuous values, while the **types of objects** contained in a bounding box and the **relations between them** are taken from a discrete set



**Natural Language Processing:** The **distributional semantics** provide a vectorial (numerical) representation of the meaning of words, while WordNet associates to each word a set of **synsets** and a set of **relations with other words** which are finite and discrete



# Semantic Image interpretation

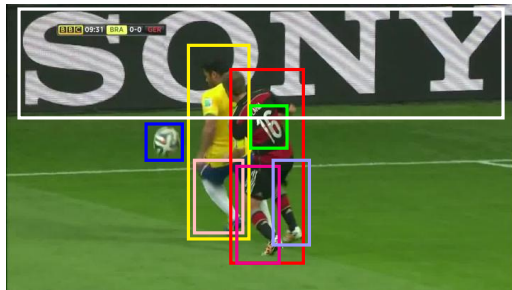
## semantic Image Interpretation (SII)



# Semantic Image interpretation

## semantic Image Interpretation (SII)

- detect the **main objects** shown in the picture;

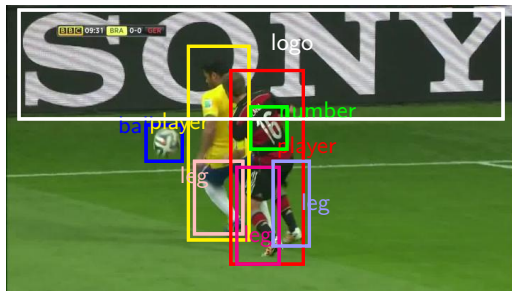




# Semantic Image interpretation

## semantic Image Interpretation (SII)

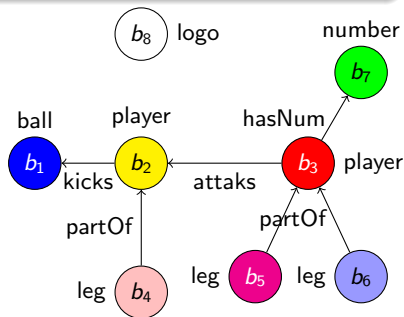
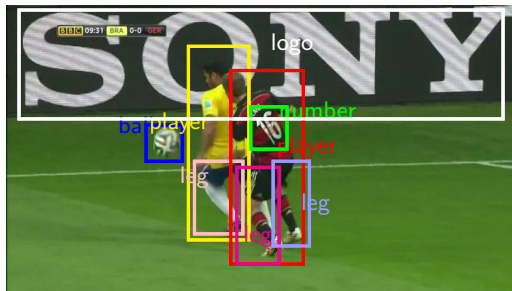
- detect the **main objects** shown in the picture;
- assign to each object an **object type**;



# Semantic Image interpretation

## semantic Image Interpretation (SII)

- detect the **main objects** shown in the picture;
- assign to each object an **object type**;
- determine the **relations** between the objects as shown in the picture
- represent the outcome of the detection in a **semantic structure**.





# Language - to specify knowledge about models

Two sorted first order language: (abstract sort and numeric sort)

- Abstract constant symbols ( $b_1, b_2, \dots, b_8$ );
- Abstract relation symbols ( $\text{player}(x)$ ,  $\text{ball}(x)$ ,  $\text{partOf}(x,y)$ ,  $\text{hasNum}(x,y)$ );
- Numeric function symbols ( $\text{xBL}(x)$ ,  $\text{yBL}(x)$ ,  $\text{width}(x)$ ,  $\text{height}(h)$ ,  $\text{area}(x)$ ,  $\text{color}(x)$ ,  $\text{contRatio}(x,y)$ );

COLOR CODE:

-  denotes objects and relations of the domain structure;
-  denotes attributes and relations between attributes of the numeric part of the domain.

# Domain description and queries

## Example (Domain description:)

knowledge about object detection:

$xBL(b_1) = 23$ ,  $yBL(b_1) = 73$ ,

$width(b_1) = 20$ ,  $height(b_1) = 21$

$xBL(b_2) = 45$ ,  $yBL(b_1) = 70$ ,

$width(b_1) = 40$ ,  $height(b_1) = 104 \dots$

$contRatio(b_2, b_4) = 1.0$ ,

$contRatio(b_2, b_5) = 0.4$ ,  $\dots$

# Domain description and queries

## Example (Domain description:)

knowledge about object detection:

$xBL(b_1) = 23$ ,  $yBL(b_1) = 73$ ,

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$contRatio(b_2, b_5) = 0.4, \dots$

---

partial knowledge about object types and relations

$ball(b_1)$ ,  $player(b_2)$ ,  $player(b_3)$ ,

$leg(b_4)$ ,  $leg(b_5)$ ,  $partOf(b_3, b_2)$ ,

$kicks(b_2, b_1)$ ,  $hasNum(b_3, b_7), \dots$

# Domain description and queries

## Example (Domain description:)

knowledge about object detection:

$$xBL(b_1) = 23, yBL(b_1) = 73,$$

$$width(b_1) = 20, height(b_1) = 21$$

$$xBL(b_2) = 45, yBL(b_1) = 70,$$

$$width(b_1) = 40, height(b_1) = 104 \dots$$

$$contRatio(b_2, b_4) = 1.0,$$

$$contRatio(b_2, b_5) = 0.4, \dots$$

---

partial knowledge about object types and relations

$$ball(b_1), player(b_2), player(b_3),$$

$$leg(b_4), leg(b_5), partOf(b_3, b_2),$$

$$kicks(b_2, b_1), hasNum(b_3, b_7), \dots$$

---

ontological axioms

$$\forall xy. partOf(x, y) \wedge leg(x) \rightarrow player(y),$$

$$\forall xy. kick(x, y) \rightarrow player(x) \wedge ball(y),$$

$$\forall xy. partOf(x, y) \rightarrow contRatio(x, y) > .9$$

$$\forall x. player(x) \rightarrow \neg ball(x),$$

# Domain description and queries

## Example (Domain description:)

knowledge about object detection:

$xBL(b_1) = 23$ ,  $yBL(b_1) = 73$ ,  
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 $contRatio(b_2, b_4) = 1.0$ ,  
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$ball(b_1)$ ,  $player(b_2)$ ,  $player(b_3)$ ,  
 $leg(b_4)$ ,  $leg(b_5)$ ,  $partOf(b_3, b_2)$ ,  
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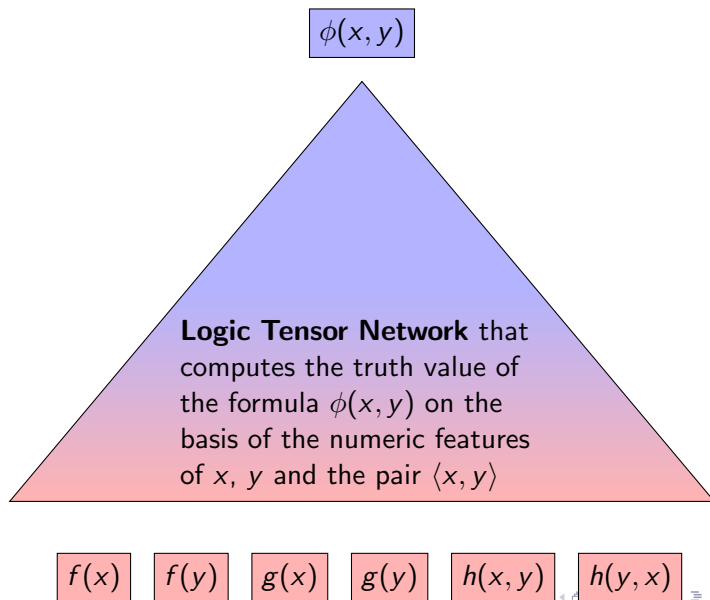
## Example (Queries)

Query about missing knowledge about object types and relations

$player(b_{10})$  |  $xBL(b_{10}) = 83$ ,  
 $yBL(b_{10}) = 42$ ,  
 $width(b_{10}) = 30$   
 $\dots$

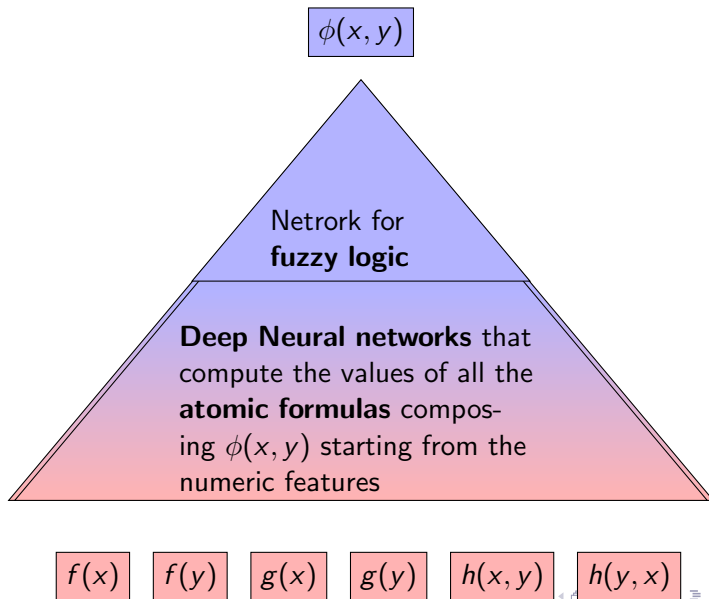
$partOf(b_{10}, b_{11})$  |  $xBL(b_{10}) = 83$ ,  
 $yBL(b_{10}) = 42$ ,  
 $width(b_{10}) = 30$   
 $\dots$   
 $xBL(b_{11}) = 83$ ,  
 $yBL(b_{11}) = 42$ ,  
 $width(b_{11}) = 30$   
 $\dots$   
 $contRatio(b_{10}, b_{11}) = 0.6$   
 $contRatio(b_{11}, b_{10}) = 0.9$   
 $\dots$

# Logic Tensor Network basic idea





# Logic Tensor Network basic idea



# LTN for predicates

$n$  unary numeric function  $f_1(x), \dots, f_n(x)$  and  $m$  binary numeric function  $g_1(x, y), \dots, g_m(x, y)$

LTN for unary predicate/type  $P(x)$

$$LTN_P(\mathbf{v}) = \sigma \left( u_P^T \tanh \left( \mathbf{v}^T W_P^{[1:k]} \mathbf{v} + V_P \mathbf{v} + b_P \right) \right)$$

$w_P \in \mathbb{R}^{k \times n \times n}$ ,  $V_P \in \mathbb{R}^{k \times n}$ ,  $b_P \in \mathbb{R}^k$ , and  $u_P \in \mathbb{R}^k$  are parameters.

LTN for binary relation  $R(x, y)$

$$LTN_P(\mathbf{v}) = \sigma \left( u_P^T \tanh \left( \mathbf{v}^T W_P^{[1:k]} \mathbf{v} + V_P \mathbf{v} + b_P \right) \right)$$

$w_P \in \mathbb{R}^{k \times h \times h}$ ,  $V_P \in \mathbb{R}^{k \times h}$ ,  $b_P \in \mathbb{R}^k$ , and  $u_P \in \mathbb{R}^k$  are parameters, and  $h = 2(n + m)$  = the total number of numeric features that can be obtained applying  $f_i$  and  $g_i$  to  $x$  and  $y$ .

# Fuzzy semantics for propositional connectives

- In fuzzy semantics **atoms** are assigned with some **truth value in real interval  $[0,1]$**
- connectives have functional semantics. e.g., a binary connective  $\circ$  must be interpreted in a function  $f_{\circ} : [0,1]^2 \rightarrow [0,1]$ .
- Truth values are **ordered**, i.e., if  $x > y$ , then  $x$  is a stronger truth than  $y$
- Generalization of classical propositional logic:
  - 0 corresponds to **FALSE** and
  - 1 corresponds to **TRUE**

# Fuzzy semantics for connectives and quantifiers

## Lukasiewicz T-norm, T-conorm, residual, and precomplement

T-norm	$a \wedge b$	$=$	$\max(0, a + b - 1)$
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T-conorm	$a \vee b$	$=$	$\min(1, a + b)$
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residual	$a \rightarrow$	$=$	$\begin{cases} \text{if } a > b & 1 - a + b \\ \text{if } a \leq b & 1 \end{cases}$
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precomplement	$\neg a$	$=$	$1 - a$
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aggregation	$\forall x. a(x)$	$=$	$\lim_{n \rightarrow \infty} \left( \frac{1}{n} \sum_{i=1}^n (a(i)^{-1})^{-1} \right)$
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Alternatively, use Gödel or Product T-norm, and geometric or arithmetic mean as aggregator.

# Constructive semantics for Existential quantifier

- LTN interprets existential quantifiers constructively via Skolemization.
- Every formula  $\forall x_1, \dots, x_n \exists y \phi(x_1, \dots, x_n, y)$  is rewritten as  $\forall x_1, \dots, x_m \phi(x_1, \dots, x_n, f(x_1, \dots, x_m))$ ,
- by introducing a new  $m$ -ary function symbol  $f$ ,

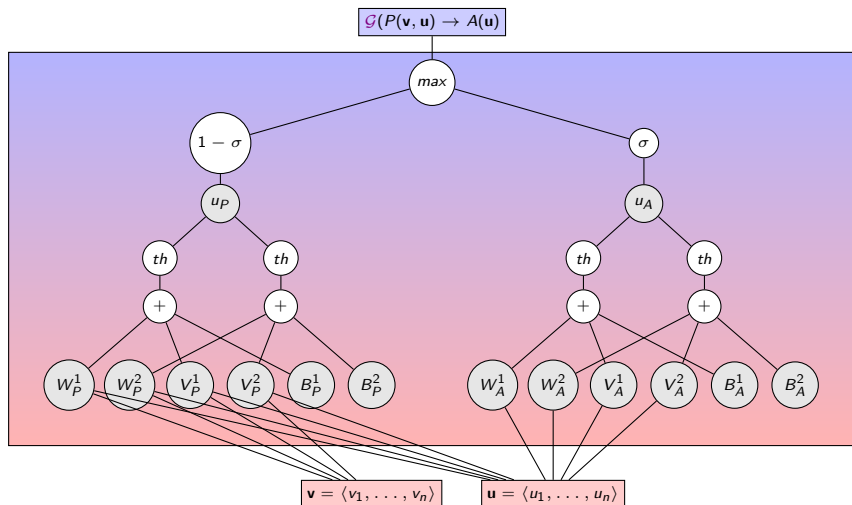
## Example

$$\forall x. (cat(x) \rightarrow \exists y. partof(y, x) \wedge tail(y))$$

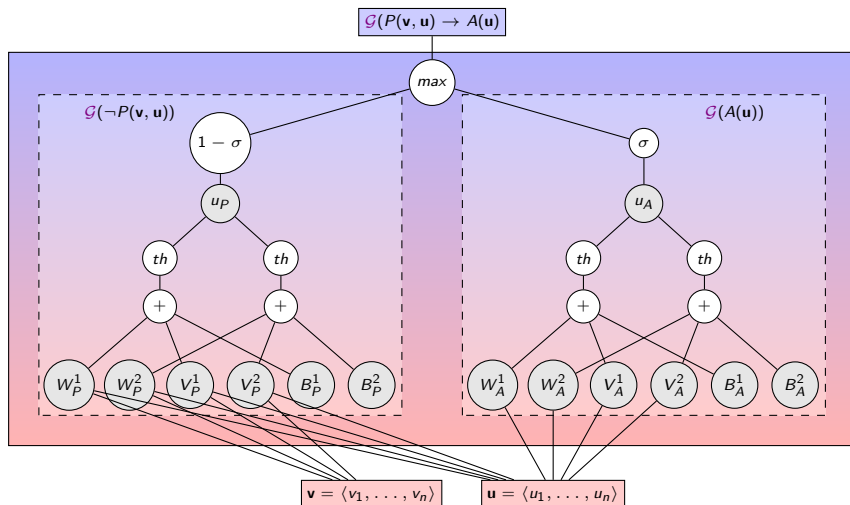
is transformed in

$$\forall x (cat(x) \rightarrow partOf(tailOf(x), x) \wedge tail(tailOf(x)))$$

# Grounding = relation between logical symbols and data



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# Parameter learning = best satisfiability

Given a FOL theory  $K$  the **best satisfiability problem** as the problem of finding the set of parameters  $\Theta$  of the LTN, then the problems become

$$\mathcal{G}^* = LTN(K, \Theta^*)$$

$$\Theta^* = \operatorname{argmax}_{\Theta} \left( \min_{K \models \phi} LTN(K, \Theta)(\phi) \right)$$



# Learning from model description and answering queries

K

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 $ball(b_1), player(b_2), player(b_3),$   
 $leg(b_4), leg(b_5), partOf(b_3, b_2),$   
 $kicks(b_2, b_1), hasNum(b_3, b_7), \dots$   
 $\forall xy. partOf(x, y) \wedge leg(x) \rightarrow player(y),$   
 $\forall xy, kick(x, y) \rightarrow player(x) \wedge ball(y),$   
 $\forall xy partOf(x, y) \rightarrow contRatio(x, y) > .9$   
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# Learning from model description and answering queries

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K



Q

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$LTN_{K, \Theta^*} \left( \begin{array}{c|c} player(b_{10}) & \begin{array}{l} xBL(b_{10}) = 83, \\ yBL(b_{10}) = 42, \\ width(b_{10}) = 30 \\ \dots \end{array} \end{array} \right)$

# Semantic Image interpretation

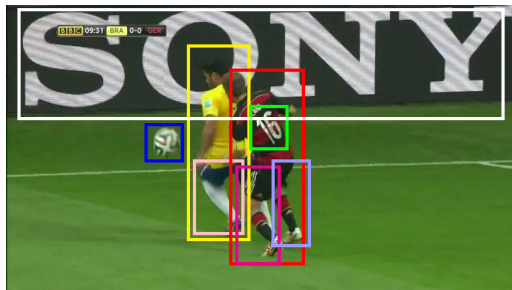
## semantic Image Interpretation (SII)



# Semantic Image interpretation

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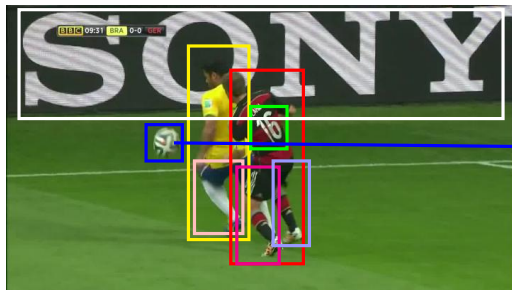
- object detection: Fast RCNN (state of the art object detector)



# Semantic Image interpretation

## semantic Image Interpretation (SII)

- object detection: Fast RCNN (state of the art object detector)
- Fast-RCNN returns candidate bounding boxes, associated with weights for each object class;

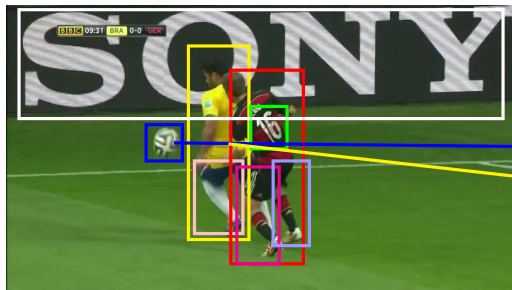


$xBL(b_1) = 12$   
 $yBL(b_1) = 27$   
 $width(b_1) = 30$   
 $height(b_1) = 30$   
 $rcnn_{ball}(b_1) = .8$   
 $rcnn_{player}(b_1) = .3$   
 $rcnn_{logo}(b_1) = .02$   
...

# Semantic Image interpretation

## semantic Image Interpretation (SII)

- object detection: Fast RCNN (state of the art object detector)
- Fast-RCNN returns candidate bounding boxes, associated with weights for each object class;

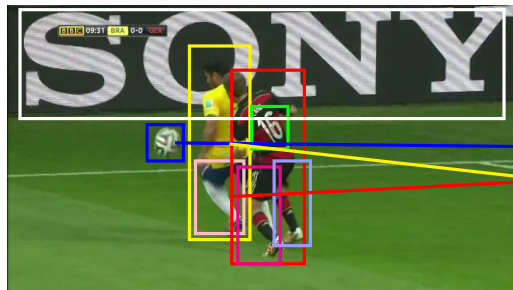


$xBL(b_1) = 12$   
 $yBL(b_1) = 27$   
 $xBL(b_1) = 14$   
 $yBL(b_1) = 17$   
 $width(b_1) = 40$   
 $height(b_1) = 100$   
 $rcnn_{ball}(b_1) = .1$   
 $rcnn_{player}(b_1) = .7$   
 $rcnn_{logo}(b_1) = .02$   
...

# Semantic Image interpretation

## semantic Image Interpretation (SII)

- object detection: Fast RCNN (state of the art object detector)
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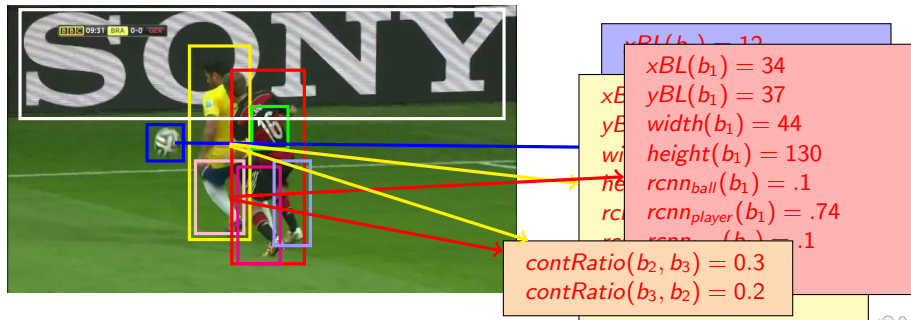
$xBL(b_1) = 34$   
 $yBL(b_1) = 37$   
 $width(b_1) = 44$   
 $height(b_1) = 130$   
 $rcnn_{ball}(b_1) = .1$   
 $rcnn_{player}(b_1) = .74$   
 $rcnn_{logo}(b_1) = .1$   
...



# Semantic Image interpretation

## semantic Image Interpretation (SII)

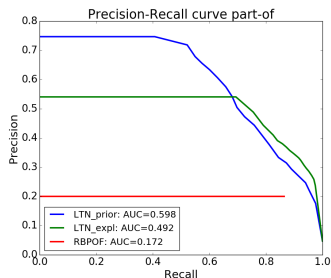
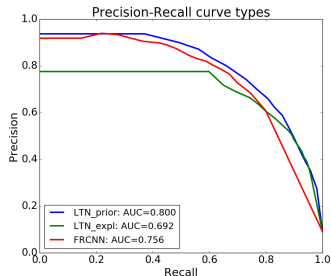
- object detection: Fast RCNN (state of the art object detector)
- Fast-RCNN returns candidate bounding boxes, associated with weights for each object class;
- For each pair of bounding boxe we compute additional binary feature that measure the mutual overlap between the two bounding boxes.



# LTN evaluation on PascalPart dataset

- PascalPart contains **10103 pictures** annotated with a set of bounding boxes labelled with object types (60 classes among animals, vehicles, and indoor objects)
- We train an LTN with the approx 2/3 pictures and test on 1/3. by including the following **background knowledge**
  - ▶ positive/negative examples for object classes (from training set)  
 $wheel(bb1), car(bb2), \neg horse(bb2), \neg person(bb4)$
  - ▶ positive/negative examples for relations (we focus on parthood relation).  $partOf(bb1, bb2), \neg partOf(bb2, bb3), \dots$ ,
  - ▶ general axioms about parthood relation:  
 $\forall x. car(x) \wedge partof(y, x) \rightarrow wheel(y) \vee mirror(y) \vee door(y) \vee \dots$

# LTN for SII results

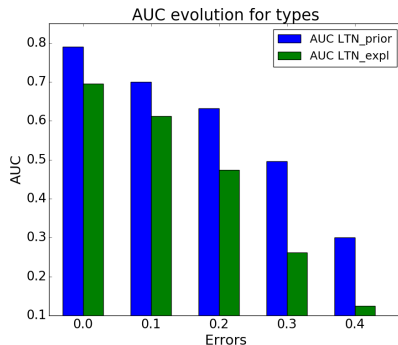
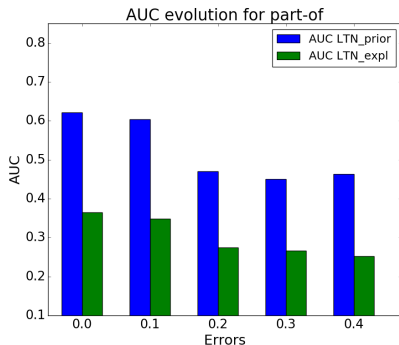


- $LTN_{prior}$  is an LTN trained with positive and negative examples + general axioms about partOf relation
- $LTN_{expl}$  is an LTN trained only with positive and negative examples of types and partOf
- $FRCNN$  is the baseline proposal classification for types given by Fast-RCNN
- $RBPOF$  is the baseline for partOf based on the naive criteria

*area containment  $\geq$  threshold*

# Robustness w.r.t. noisy data

- logical axioms improve the robustness of the system in presence of noise in the labels of training data.
- e artificially add an increasing amount of noise to the PascalPart-dataset training data, and we measure the degradation of the performance,



# Conclusions

- we introduce **Logic Tensor Networks**, a general framework for SRL that integrates fuzzy logical reasoning and machine learning based on neural networks;
- We apply LTN to the challenging problem of **semantic image interpretation**;
- We experimentally show that the **usage of logic based background knowledge improves the performance** of automatic classification based only on numeric features.

Thanks for your attention