

Automata: Short Course

COMP SCI 2SD3

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Alphabet: an *arbitrary* (usually finite) set of elements, often denoted by the symbol Σ .

Sequence:

- an element $x = (a_1, a_2, \dots, a_k) \in \Sigma^k$, where Σ^k is a Cartesian product of Σ 's.

For convenience we write $x = a_1 a_2 \dots a_k$.

- a function $\phi : \{1, \dots, k\} \rightarrow \Sigma$, such that $\phi(1) = a_1, \dots, \phi(k) = a_k$.

♣ The two above definitions are in a sense identical since:

$$\underbrace{\Sigma \times \dots \times \Sigma}_n \equiv \{f \mid f : \{1, \dots, k\} \rightarrow \Sigma\}.$$

- Frequently a *sequence* is considered as a primitive undefined concept that is understood and does not need any explanation.

Sequences and strings

- If the elements of Σ are *symbols*, then a *finite* sequence of symbols is often called a *string* or a *word*.
- ♣ In concurrency theory *sequences* are often called **traces** (for example in the textbook for this course).
- The *length* of a sequence x , denoted $|x|$, is the number of elements composing the sequence. For example $|aba| = 3$, $|aabbcc| = 5$.
- The *empty sequence*, ε , is the sequence consisting of zero symbols, i.e. $|\varepsilon| = 0$.
- A *prefix* of a sequence is any number of leading symbols of that sequence, and a *suffix* is any number of trailing symbols (any number means 'zero included'). For example a sequence (word, trace) *abca* has the following prefixes: ε , *a*, *ab*, *abc*, *abca*, and the following suffixes: *abca*, *bca*, *ca*, *a*, ε .

Concatenation

- *Concatenation* (operation)

Let $x = a_1 \dots a_k$, $y = b_1 \dots b_l$. Then

$$x \circ y = a_1 \dots a_k b_1 \dots b_l.$$

We usually write xy instead of $x \circ y$.

- Properties of concatenation:

① $x(yz) = (xy)z$

② $\varepsilon x = x\varepsilon = x$

Fact. A triple $(\Sigma, \circ, \varepsilon)$ is a *monoid* (recall 2LC3).

- Power operator: $x^0 = \varepsilon$, $x^1 = x$ and $x^k = \underbrace{x \dots x}_k$.

- Recursive definition of power:

$$x^0 = \varepsilon$$

$$x^{k+1} = x^k x.$$

Σ^* and Formal Language

- Let Σ be a finite alphabet. Then we define Σ^* as:

$$\Sigma^* = \{a_1 \dots a_k \mid a_i \in \Sigma \wedge k \geq 0\},$$

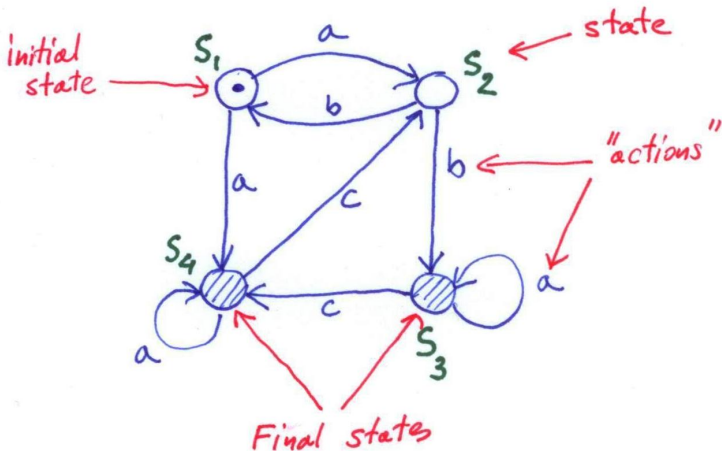
i.e. the set of all sequences, including ε , built from the elements of Σ .

- For example
 $\{a, b\}^* = \{\varepsilon, a, b, aa, ab, ba, bb, aaa, aba, aab, \dots\}$, all sequences built from a and b .
- $\emptyset^* = \{\varepsilon\}$
- If $\Sigma \neq \emptyset$ then $|\Sigma^*| = \infty$.
- A (*formal*) *language* over Σ is any subset of Σ^* , including the empty set \emptyset and Σ^* .
- For example $\{ab, cba, ba, bbbb\} \subseteq \{a, b, c\}^*$ is a finite language, while
 $\{abc, ba, ab, abb, abbb, \dots, ab^k, \dots\} \subseteq \{a, b\}^*$ is an infinite language.

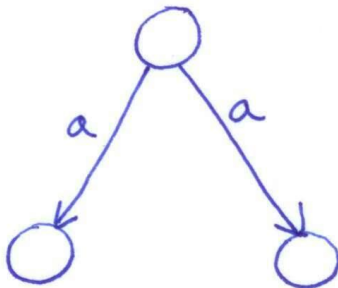
Automata or State Machines

- There is a set of **states** Q .
 Q may be finite, then we have finite state machines.
- There is a set of **actions/operations** that allow to move from one state to another state.
- There is a **transition function/relation** that allow movement from one state to another state using actions/operations.
- There is an **initial state**.
- There *might be* **final states**.
- The concept of a **current state** may easily be introduced.
- The set of actions/operations is finite.
- There is a concept of **nondeterministic choice**.

(Finite) Automata or (Finite) State Machines: an example



Automata: Non-determinism



Deterministic Automata

Definition

A **deterministic (finite) automaton** (**state machine**) is a 5-tuple:

$$M = (\Sigma, Q, \delta, s_0, F),$$

where: Σ is the **alphabet** (finite) (**input alphabet**),

Q is the **set of states** (finite),

$\delta : Q \times \Sigma \rightarrow Q$ is the **transition function**,

$s_0 \in Q$ is the **initial state**,

$F \subseteq Q$ is the set of **final states**.

Definition ($\hat{\delta}$ function, also often denoted as δ^*)

We extend the function δ to $\hat{\delta} : Q \times \Sigma^* \rightarrow Q$ as follows:

- $\forall q \in Q. \hat{\delta}(q, \varepsilon) = q$
- $\forall q \in Q. \forall x \in \Sigma^*. \forall a \in \Sigma. \hat{\delta}(q, xa) = \delta(\hat{\delta}(q, x), a).$

$\hat{\delta}$ function, also often denoted as δ^*

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 - $\forall q \in Q. \forall x \in \Sigma^*. \forall a \in \Sigma. \hat{\delta}(q, xa) = \delta(\hat{\delta}(q, x), a).$
-
- The above definition of $\hat{\delta}$ is *recursive* and the recursion is *on the length of x* .
 - Intuitively $\delta(q, a)$ is the state that can be reached from q in **one** step, while $\hat{\delta}(q, x)$ is the state that can be reached from q in **$|x|$** steps by using δ in each step.
 - For example $\hat{\delta}(q, abcd) = \delta(\delta(\delta(\delta(q, a), b), c), d).$
 - **We usually write δ instead of $\hat{\delta}$ when it does not lead to any misunderstanding.**
 - For example $\delta(q, abcd) = \delta(\delta(\delta(\delta(q, a), b), c), d).$

Definition (Language)

For every automaton M , the set

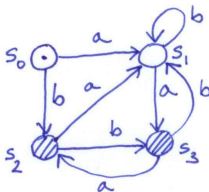
$$L(M) = \{x \mid \hat{\delta}(s_0, x) \in F\}$$

is called the language accepted/generated by M .

- The language is just a set of all sequences (words, traces) that can be derived by starting from the initial state travelling through automaton (using δ as *next state* function) and ending in some *final state*.
- It is possible to leave a final state!
- In concurrency we often do not have final states! In such a case we assume that each state is a final state, i.e. $F = Q$!

Deterministic Automaton: an Example

- Consider the following deterministic automaton M



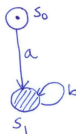
- We have: $\Sigma = \{a, b\}$, $Q = \{s_0, s_1, s_2, s_3\}$, $F = \{s_2, s_3\}$ and the below table shows the transition function δ .

| δ | a | b |
|----------|-------|-------|
| s_0 | s_1 | s_2 |
| s_1 | s_3 | s_1 |
| s_2 | s_1 | s_3 |
| s_3 | s_2 | s_1 |

- For example $ab, bbaa \notin L(M)$, while $aaa, abbbaab \in L(M)$.

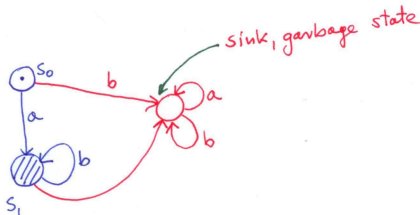
Problems!

(1) We **cannot** specify:

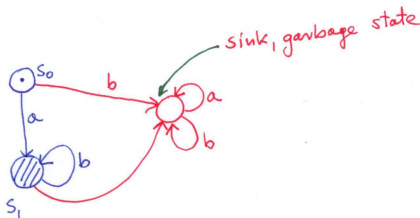


The meaning is pretty simple: “*first execute a and next execute any number of b , including none.*” However, for the first definition we have $\delta(s_0, a) = s_1$ and $\delta(s_1, b) = s_1$, but what about $\delta(s_0, b) = ?$ and $\delta(s_1, a) = ?$. For the second definition we have $a(s_0) = s_1$ and $b(s_1) = s_1$ but still $b(s_0) = ?$ and $a(s_1) = ?$.

UGLY SOLUTION



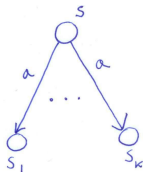
UGLY SOLUTION



- This solution is good for illustration, problematic for real systems as we have to introduce entities that may not exist in the real system!
- The standard solution involves the concept of **non-determinism**.

Non-determinism: Problem #1

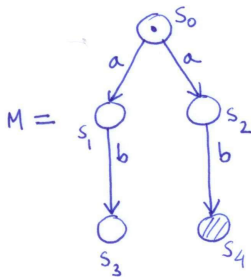
- Notation for 'power set': $2^Q = \mathcal{P}(Q) = \{X \mid X \subseteq Q\}$, and clearly $\emptyset \in 2^Q$.
- Problem #1: How to model the below situation?



- The standard solution
 $\delta(s, a) = \{s_1, \dots, s_k\}$, which implies $\delta : Q \times \Sigma \rightarrow 2^Q$,

Non-determinism: Problem #2

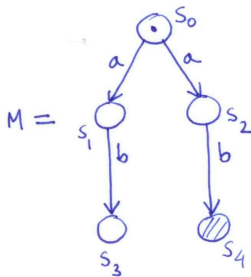
- Consider the following automaton:



- Which is true? $ab \in L(M)$ or $ab \notin L(M)$?

Non-determinism: Problem #2

- Consider the following automaton:

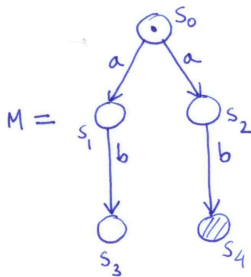


- Which is true? $ab \in L(M)$ or $ab \notin L(M)$?

Usually it is assumed that $ab \in L(M)$. It is called **angelic semantics**.

Non-determinism: Problem #2

- Consider the following automaton:



- Which is true? $ab \in L(M)$ or $ab \notin L(M)$?

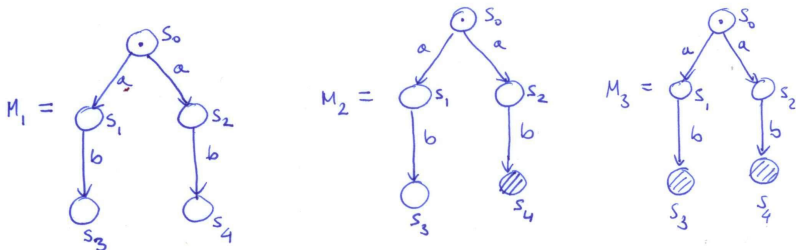
Usually it is assumed that $ab \in L(M)$. It is called **angelic semantics**.

Angelic vs Demonic Semantics

- **Angelic:** At each state an *angel* will tell you where to go, so if there is a good choice you will make it. The only bad case is when all choices are bad.
- **Demonic:** At each state a *demon* will tell you where to go, so if there is a bad choice you will make it. The only good case is when all choices are good.
- *Demonic semantics* is much less popular. It is relatively new and was motivated by *fault tolerant systems*. In this class we will use only *angelic* semantics. I have mentioned demonic, to show that non-determinism is more complex than the one presented in most textbooks.

Angelic vs Demonic Semantics - An Example

- Consider the three automata below:



- Let $L_A(M_i)$, $i = 1, 2, 3$ denote a language defined by M_i under *angelic* semantics, and let $L_D(M_i)$, $i = 1, 2, 3$ denote a language defined by M_i under *demonic* semantics. Note that $L_A(M_1) = L_D(M_1) = \emptyset$, $L_A(M_2) = \{ab\}$, $L_D(M_2) = \emptyset$ and $L_A(M_3) = L_D(M_3) = \{ab\}$.

Definition (Non-deterministic Automaton)

A **non-deterministic (finite) automaton** (**state machine**) is a 5-tuple:

$$M = (\Sigma, Q, \delta, s_0, F),$$

where: Σ is the **alphabet** (finite) (**input alphabet**),

Q is the **set of states** (finite),

$\delta : Q \times \Sigma \rightarrow 2^Q$ is the **transition function**,

$s_0 \in Q$ is the **initial state**,

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Definition (non-deterministic $\hat{\delta}$ function)

We extend the function δ to $\hat{\delta} : Q \times \Sigma^* \rightarrow 2^Q$ as follows:

- $\forall q \in Q. \hat{\delta}(q, \varepsilon) = \{q\}$
- $\forall q \in Q. \forall x \in \Sigma^*. \forall a \in \Sigma. \hat{\delta}(q, xa) = \bigcup_{s \in \hat{\delta}(q, x)} \delta(s, a).$

Sometimes, by a small abuse of notation, we write
 $\hat{\delta}(q, xa) = \delta(\hat{\delta}(q, x), a).$

Language Defined by a Non-deterministic Automaton

Definition (Angelic semantics)

For every automaton M , the set

$$L(M) = \{x \mid \hat{\delta}(s_0, x) \cap F \neq \emptyset\}$$

is called the language accepted/generated by M .

Definition (Demonic semantics)

For every automaton M , the set

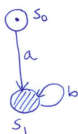
$$L(M) = \{x \mid \hat{\delta}(s_0, x) \subseteq F\}$$

is called the language accepted/generated by M .

We will not consider demonic semantics in this course.

Non-determinism: Example 1

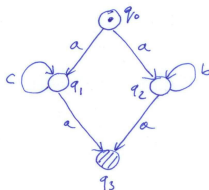
- Consider the following example:



- Standard model: $\Sigma = \{a, b\}$, $Q = \{s_0, s_1\}$, $F = \{s_1\}$.
 $\delta(s_0, a) = \{s_1\}$, $\delta(s_0, b) = \emptyset$,
 $\delta(s_1, a) = \emptyset$, $\delta(s_1, b) = \{s_1\}$.
- In this case we do not have 'splits' like the one from page 15, all outcomes of the function δ are either singletons or empty set, so intuitively this is rather a deterministic system.
- However formally the automaton is non-deterministic.

Non-determinism: Example 2

- Consider the following example:



- Classical model: $\Sigma = \{a, b, c\}$, $Q = \{q_0, q_1, q_2, q_3\}$, $F = \{q_3\}$.
 $\delta(q_0, a) = \{q_1, q_2\}$, $\delta(q_0, b) = \delta(q_0, c) = \emptyset$,
 $\delta(q_1, a) = \{q_3\}$, $\delta(q_1, b) = \emptyset$, $\delta(q_1, c) = \{q_1\}$,
 $\delta(q_2, a) = \{q_3\}$, $\delta(q_2, b) = \{q_2\}$, $\delta(q_2, c) = \emptyset$,
 $\delta(q_3, a) = \delta(q_3, b) = \delta(q_3, c) = \emptyset$
- 'Local' model: $\Sigma = \{a, b, c\}$, $Q = \{q_0, q_1, q_2, q_3\}$, $F = \{q_3\}$.
 $a = \{(q_0, q_1), (q_0, q_2), (q_1, q_3), (q_2, q_3)\}$, $b = \{(q_2, q_2)\}$,
 $c = \{(q_1, q_1)\}$.

Another Approach to Non-determinism

Definition

An **automaton** (**state machine**) is a 5-tuple:

$$M = (\Sigma, Q, \delta, s_0, F),$$

where: Σ is the **alphabet** (finite),

Q is the **set of states** (finite),

$\delta : Q \times \Sigma \rightarrow 2^Q$ is the **transition function**,

$s_0 \in Q$ is the **initial state**,

$F \subseteq Q$ is the set of **final states**.

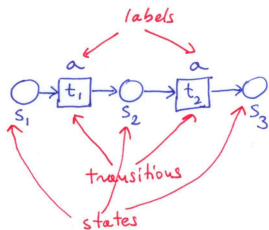
Definition

- M is **deterministic** iff $\forall q \in Q. \forall a \in \Sigma. |\delta(q, a)| \leq 1$
- M is **strictly deterministic** iff $\forall q \in Q. \forall a \in \Sigma. |\delta(q, a)| = 1$

These definitions are often used in the papers that deal with applications rather than theory.

Labelled Transition Systems

- **Transition** (from Collins Dictionary):
“*a passing or change from one place, state, condition, etc., to another.*”
- Consider the case: $s_1 \xrightarrow{a} s_2 \xrightarrow{a} s_3$
Can “*a*” be called a transition?
- Transitions, state and labels:



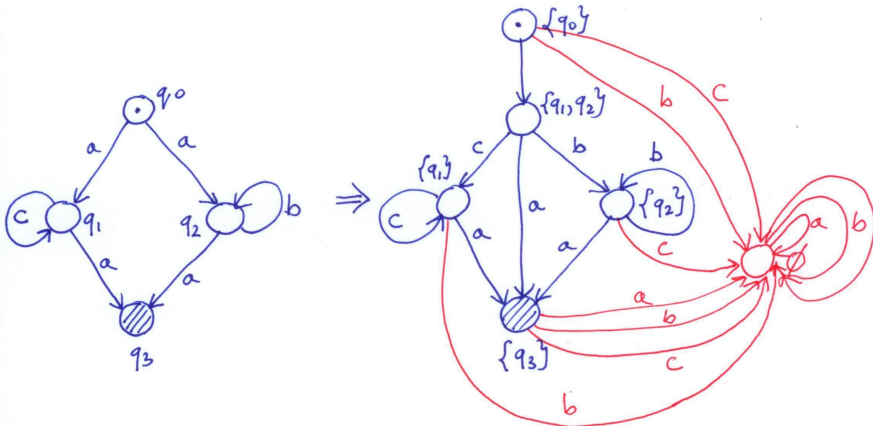
- Transitions are **unique**: $t_1 \iff s_1 \xrightarrow{a} s_2$
- Transitions (labelled) are usually needed and used for modelling concurrency.

Non-determinism vs Determinism: Example

- Does non-determinism increases the descriptive power?

Non-determinism vs Determinism: Example

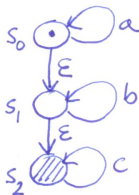
- Does non-determinism increase the descriptive power?
NO. See an example below and Theorem on next page.



Theorem

*Let L be a language accepted by a **non-deterministic finite automaton** M , i.e. $L = L(M)$. There exists a **deterministic finite automaton** M' such that $L(M') = L$.*

Invisible (silent) Actions or ε -moves



- In many cases we need to model **invisible actions**!

Definition

A **non-deterministic automaton with ε -moves** is:

$$M = (Q, \Sigma, \delta, q_0, F),$$

where: Q, Σ, q_0, F are as usual, and:

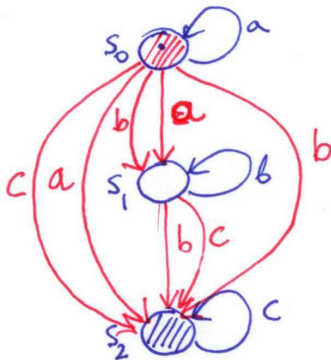
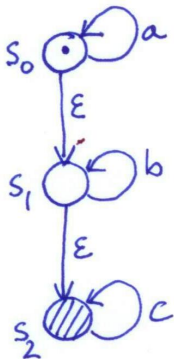
$$\delta : Q \times (\Sigma \cup \{\varepsilon\}) \rightarrow 2^Q.$$

- **Problem:** ε has **two** interpretations:
 - 1 Do nothing,
 - 2 Go to another state by executing invisible (silent) action.

Theorem

*If L is accepted by a nondeterministic automaton **with** ε -moves, then L is also accepted by a nondeterministic automaton **without** ε -moves.*

Removal of ϵ -moves: An example



- We may then transform the non-deterministic automaton from the right hand side into appropriate deterministic one.

Equivalence of Finite Automata

Definition

Two automata M_1 and M_2 are **equivalent** if and only if $L(M_1) = L(M_2)$.

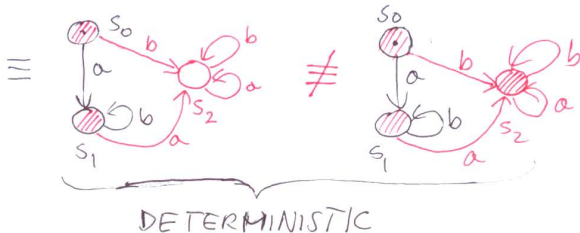
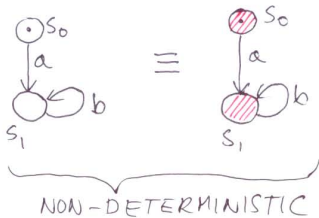
Conclusion

Non-deterministic automata, nondeterministic automata with ϵ -moves, and deterministic automata are all equivalent.

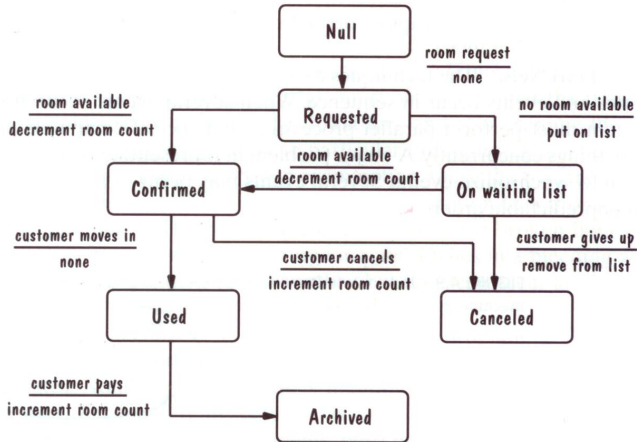
- *Equivalence* means only the same language, other properties may differ.
- For example the concept of 'demonic semantics' does not make much sense for deterministic automata as we do not have non-deterministic choices.
- For any deterministic automaton M , if all states are finite then then $L(M) = \Sigma^*$, so this concept also has very little sense.

No Final States

- No final states is equivalent to all states are final, i.e.
 $F = \emptyset \equiv F = Q$.
- But this makes sense only for nondeterministic automata.

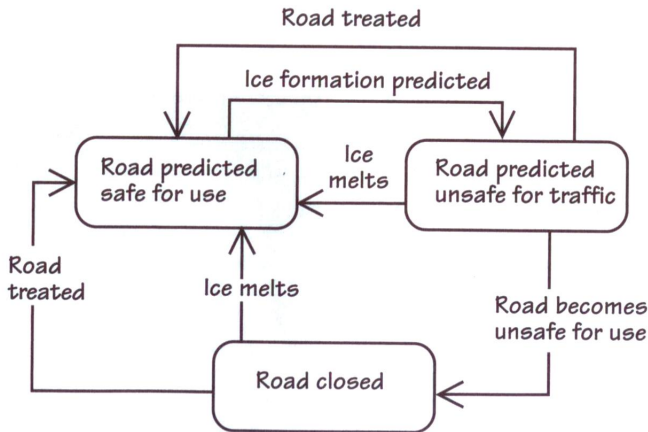


Modelling Dynamic Systems With Automata: Hotel Reservation



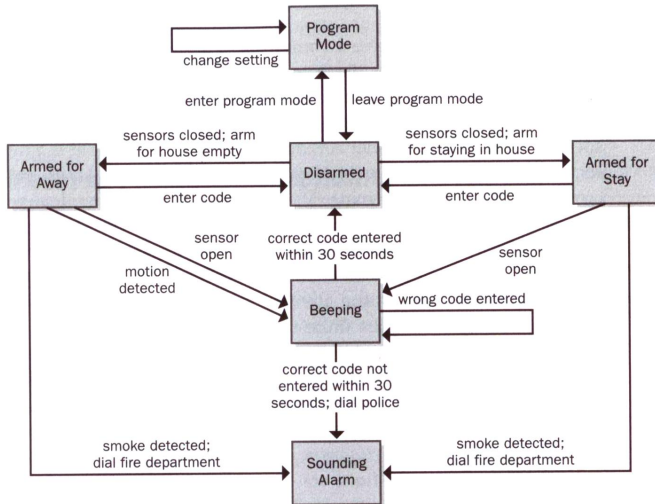
- No arrow to initial state and no arrow from final state.

Road Deicing



- Neither initial nor final state specified.

Simplified Home Security



- Neither initial nor final state specified.

- **FOR THIS KIND OF APPLICATIONS AUTOMATA ARE USUALLY NONDETERMINISTIC**, or **deterministic in the sense of the definition from page 23**.

Regular Expressions: Intuition

$(0 \cup 1)0^*$ $\rightarrow \{0, 00, 000, \dots, 1, 10, 100, 1000, \dots\}$
'zero or one followed by any number of zeros including none'

ab^* $\rightarrow \{a, ab, abb, abbb, \dots\}$

$(a \cup b)^*$ $\rightarrow \{a, b\}^*$
'all strings (including ε) that can be built from a and b '

$(a \cup \varepsilon)(b \cup \varepsilon) =$
 $ab \cup \varepsilon b \cup a\varepsilon \cup \varepsilon\varepsilon =$
 $ab \cup b \cup a \cup \varepsilon$ $\rightarrow \{\varepsilon, a, b, ab\}$

Definition (Formal Definition of Regular Expressions)

Let Σ be an alphabet. A string R built from the elements of $\Sigma \cup \{\varepsilon, \emptyset, (,), \cup, *\}$ is a **regular expression**, if it is defined by the following rules:

- 1 \emptyset, ε and each $a \in \Sigma$ are *regular expressions*.
- 2 $(R_1 \cup R_2)$ is a *regular expression* if R_1 and R_2 are regular expressions.
- 3 $(R_1 R_2)$ is a *regular expression* if R_1 and R_2 are regular expressions.
- 4 $(R)^*$ is a *regular expression* if R is a regular expression.
- 5 There are no other regular expressions.

The set of all regular expressions over the alphabet Σ will be denoted by $\text{Rex}(\Sigma)$.

- We usually skip some parenthesis.
- Rules: ** first, followed by concatenation, and finally \cup* , unless parentheses say differently.

Languages Defined by Regular Expressions

Definition (Interpretation)

Let $L : \text{Rex}(\Sigma) \rightarrow 2^{\Sigma^*}$ be the following function called **interpretation**:

- 1 $L(\emptyset) = \emptyset, L(\varepsilon) = \varepsilon, L(a) = \{a\}$
- 2 $L((R_1 \cup R_2)) = L(R_1) \cup L(R_2)$
- 3 $L((R_1 R_2)) = L(R_1)L(R_2)$
- 4 $L((R)^*) = L(R)^*$

Definition (Language)

For every regular expression R , $L(R)$ is a **language defined by R** .

A class of all languages defined by regular expressions will be denoted by \mathcal{L}_{REX} .

Languages Defined by Regular Expressions: Examples

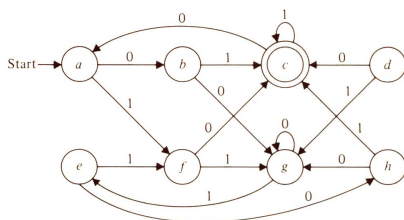
- $L((0 \cup 1)0^*) = \{0, 00, 000, \dots, 1, 10, 100, 1000, \dots\}$
 - $L(ab^*) = \{a, ab, abb, abbb, abbbb, \dots\}$
 - $L((a \cup \varepsilon)(b \cup \varepsilon)) = \{\varepsilon, a, b, ab\}$
 - We customarily often identify a regular expression R with $L(R)$ but technically R is **not** $L(R)$.
- ♣ **A question:** What is the relationship between \mathcal{L}_R and \mathcal{L}_{REX} ?

Theorem

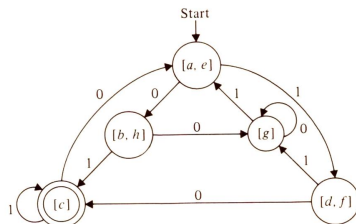
$$\mathcal{L}_R = \mathcal{L}_{\text{REX}}$$

Minimization of Deterministic Finite Automata

- Consider the following two deterministic automata:



M_1

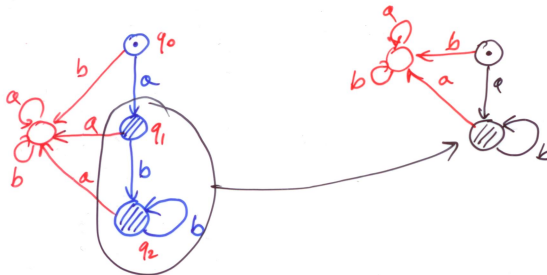


M_2

- It can be proved that $L(M_1) = L(M_2)$, and clearly M_2 has less states.
- It can be proved that M_2 is the minimum state automaton that is equivalent to M_1 , i.e. $L(M_1) = L(M_2)$.

Intuitions for Minimization

Consider the following two automata, both generating the language ab^* :



The states q_1 and q_2 of the left automaton are *equivalent*, so they, and appropriate arrows, can be glued together.

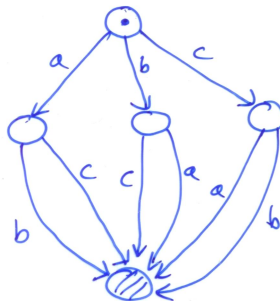
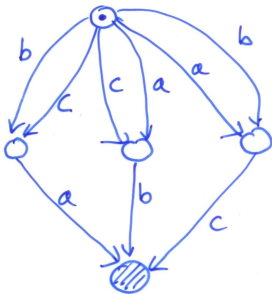
Theorem

*For every deterministic automaton M_1 there is the minimum state deterministic automaton M_2 such that $L(M_1) = L(M_2)$.
The automaton M_2 is unique up to the names of states.*

Non-deterministic Automata and Minimization Problem

- The word 'deterministic' is important and cannot be omitted!
- Consider the following two non-deterministic automata, both generating the language

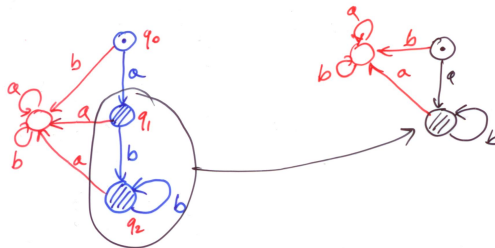
$$L = \{ab, ac, bc, ba, ca, cb\}$$



- Both automata above are minimum state and there is no way to make them identical!

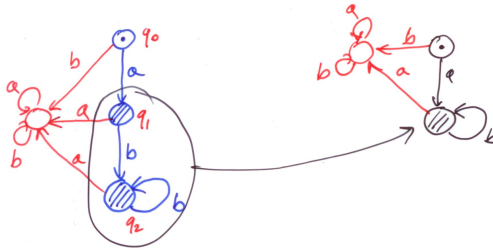
Non-deterministic Automata and Minimization Problem

- When talking about Minimum State Non-deterministic automaton (usually when we discuss some application), we usually mean the case as below (no non-deterministic splits):



- If we forgot about red part, both automata are non-deterministic and the black automaton on the right can be interpreted as the minimum state automaton equivalent to the blue automaton on the left.
- However, to derive formally the back automaton on the right from the blue on left we need to add the red parts.

Non-deterministic Automata and Minimization Problem



- Labelled Transition Systems are almost always non-deterministic and the statements 'minimal', 'minimization', etc., in the textbook, refer to the meaning from the previous slide.