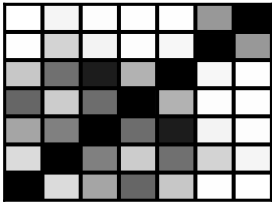
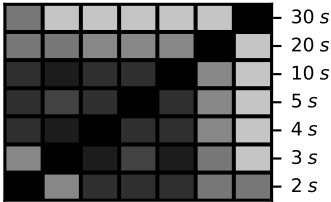


# LSTM Reference

$R^2$  (%)



x and y offset



Speed, heading, and time