# Calculus II

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**Theorem 1.** A is closed  $\iff$  every accumulation point for A is in A

Proof. "  $\Longrightarrow$  " Let  $A \subseteq \mathbb{R}^n$ ,  $A = A \cup \partial A$ . Then  $\forall p \in \bar{\mathcal{D}}(A)$ ,  $C_r(p)_{\setminus p} \cap A \neq \emptyset \ \forall C \in \mathcal{C}_p$ . if  $p \notin A$  then  $C_r(p)$  has elements that dont belong to  $A \Rightarrow p \in \partial A$ . "  $\Longleftarrow$  " Let  $p \in \partial A \Rightarrow \forall C \in \mathcal{C}_p$  of center r with  $r \in \mathbb{R}$  by definition we can find some  $x \in C_{\setminus p} \cap A$ , so that means  $p \in \bar{\mathcal{D}}(A) \Rightarrow p \in A$ .

## 1 Limits

**Definition 1.** Let  $A \subseteq \mathbb{R}^2$  and  $(x_0, y_0)$  an accumulation point for A. we define  $A^*$  as follows:

$$A^* = \{ (\rho, \theta) \in [0, +\infty] \times [0, 2\pi] : (x_0 + \rho \cos(\theta), y_0 + \rho \sin(\theta)) \in A \}.$$

**Proposition 1.** Lets suppose that exist a circle C of center  $(x_0, y_0)$  such that  $C_{\{(x_0, y_0)\}} \subseteq A$  let r be the radius of the circle and as a consequence  $(0, r] \times [0, 2\pi] \subseteq A^*$ 

$$\begin{array}{l} \textit{Proof. Let $C_{\diagdown\{(x_0,y_0)\}}$ and } \begin{cases} 0<\rho\leqslant r\\ 0\leqslant\theta\leqslant 2\pi \end{cases} \text{ if } (\rho,\theta)\in(0,r]\times[0,2\pi]\\ \text{then } (x_0+\rho\cos(\theta),y_0+\rho\sin(\theta))\in C_{\diagdown\{(x_0,y_0)\}}\subseteq A\Rightarrow(\rho,\theta)\in A^*. \end{array}$$

**Definition 2.** Let  $\theta \in [0, 2\pi]$  and  $\forall \rho \in (0, r]$  we define  $\varphi_{\theta}(\rho) = F(\rho, \theta)$  if  $\rho \in (0, r], (\rho, 0) \in A^*$  so the  $\lim_{\rho \to 0} \varphi(\rho) = l \in \mathbb{R}$ . If that limit exists that means  $\forall \theta \in [0, 2\pi]$  and  $\forall \varepsilon > 0$ ,  $\exists \delta > 0 \ \forall \rho \in (0, r]$  with

If that limit exists that means  $\forall \theta \in [0, 2\pi]$  and  $\forall \varepsilon > 0$ ,  $\exists \delta > 0 \ \forall \rho \in (0, r]$  with  $\rho < \delta \ |\varphi_{\theta} - l| < \varepsilon$ .

We say that  $\lim_{\rho\to 0} \varphi(\rho) = l \in \mathbb{R}$  Uniformly With Respect To (U.W.R.T)  $\theta$ .

**Theorem 2.** Let  $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$  with  $(x_0, y_0)$  accumulation point for A. Follows the equivalence:

$$\lim_{(x,y)\to(x_0,y_0)} f(x,y) = l \in \bar{\mathbb{R}} \iff \lim_{\rho\to 0} F(\rho,\theta) = l \ U.W.R.T \ \theta.$$

Proof. Let  $l \in \bar{\mathbb{R}}$ .

" 
$$\Longrightarrow$$
 "  $\lim_{(x,y)\to(x_0,y_0)} f(x,y) = l$  so  $\forall \varepsilon > 0, \exists \delta > 0 : \forall (x,y) \in A$  with  $\|(x,y)-(x_0,y_0)\| < \delta, |f(x,y)-l| < \varepsilon.$ 

We have to prove that  $\forall \varepsilon > 0$ ,  $\exists \delta > 0 : \forall \theta \in [0, 2\pi]$ ,  $\forall \rho(0, r]$  with  $\rho < \delta |F(\rho, \theta) - l| < \varepsilon$ .

Let  $\varepsilon > 0$ ,  $\theta \in [0, 2\pi]$ ,  $\rho \in (0, r]$  with  $\rho < \delta$ , we create the system that changes the coordinates from cartesians to polars:

$$\begin{cases} x = x_0 + \rho \cos(\theta) \\ y = y_0 + \rho \sin(\theta) \end{cases} \quad \rho = \sqrt{(x - x_0)^2 + (y - y_0)^2}$$

 $\rho \in (0,r], \ \theta \in [0,2\pi] \in (0,r] \times [0,2\pi] \subseteq A^*, \ (\rho,\theta) \in A^* \Rightarrow (x,y) \in A.$ 

Now 
$$0 < \sqrt{(x-x_0)^2 + (y-y_0)^2} = \rho < \delta \Rightarrow |f(x,y) - l| < \varepsilon.$$
  
  $\Rightarrow |f(x_0 + \rho\cos(\theta), y_0 + \rho\sin(\theta)) - l| < \varepsilon \Rightarrow |F(\rho, \theta) - l| < \varepsilon.$ 

"  $\Leftarrow=$ "  $\forall \varepsilon > 0, \exists \delta \leq r : \forall \theta \in [0, 2\pi] \text{ and } \forall \rho \text{ with } 0 < \rho < \delta \Rightarrow |F(\rho, \theta) - l| < \varepsilon.$ 

We have to prove that  $\forall \varepsilon > 0, \exists \delta > 0, \forall (x,y) \in A \text{ with } \sqrt{(x-x_0)^2 + (y-y_0)^2} = \|(x,y) - (x_0,y_0)\| < \delta \Rightarrow |f(x,y) - l| < \varepsilon.$ 

Let  $\varepsilon > 0$ ,  $\delta \le r$ ,  $(x,y) \in A$ ,  $\sqrt{(x-x_0)^2 + (y-y_0)^2} < \delta$ , we switch coordinates with  $\rho$  and  $\theta$  as follows:

$$\begin{cases} x = x_0 + \rho \cos(\theta) \\ y = y_0 + \rho \sin(\theta) \end{cases} \quad \rho = \sqrt{(x - x_0)^2 + (y - y_0)^2}$$

 $0 < \rho < \delta \le r \Rightarrow \rho \in (0, r], \ \theta \in [0, 2\pi].$ 

We notice that  $|F(\rho,\theta)-l|<\varepsilon$ , so  $|f(x_0+\rho\cos(\theta),y_0+\rho\sin(\theta))-l|<\varepsilon$  $\Rightarrow |f(x,y)-l|<\varepsilon$ .

**Definition 3.** We say that  $\theta \in [0, 2\pi]$  is admissible if  $0 \in \bar{\mathcal{D}}(A_{\theta})$ .

**Theorem 3.**  $\lim_{\rho \to 0} F(\rho, \theta) = l \in \mathbb{R}$  U.W.R.T  $\theta \iff \lim_{\rho \to 0} \varphi(\rho) = 0$ .

Corollary 1.  $\lim_{\rho \to 0} F(\rho, \theta) = l \in \mathbb{R}$  U.W.R.T  $\theta \iff \exists$  a function  $\psi(\rho)$  such that  $\lim_{\rho \to 0} \psi(\rho) = 0$  and  $\forall \theta \mid F(\rho, \theta) - l \mid \leqslant \psi(\rho)$ .

**Definition 4.** Let  $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$  with A open.

let  $(x_0, y_0) \in A$ ,  $\varphi(x) = f(x, y_0)$  and  $\psi = f(x_0, y)$ . A is open that means that those two functions are well defined.

#### Differentiability

**Definition 5.** Let be  $f: A \subseteq \mathbb{R}^n \to \mathbb{R}$  with A Open. Let  $\bar{x} \in A$  and let  $i \leq n$ , we denote as  $\varphi_i(x_i) = f(\bar{x}_1, \bar{x}_2, ..., \bar{x}_{i-1}, \bar{x}_i, \bar{x}_{i+1}, ..., \bar{x}_n)$ . Notice that  $\bar{x}$  is an internal point so then it exist an interval where  $\varphi_i$  is well defined.

**Definition 6.** We say that f is partially derivable with respect to the variable  $x_i$  in the point  $\bar{x}$  if  $\varphi_i$  is derivable in that point. We denote as  $\frac{\partial f}{\partial x_i}$  the partial derivative with respect to  $x_i$  in the point  $\bar{x}$ .

**Definition 7.** The gradient of a function in n variables is defined as follows:

$$\nabla f : \bar{x} \in A \mapsto \left(\frac{\partial f}{\partial x_1}, ..., \frac{\partial f}{\partial x_n}\right) \in \mathbb{R}^n$$

#### The case of two variables

Let  $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$  with A open, and let  $(x_0, y_0) \in A$ .  $(x_0, y_0, f(x_0, y_0)) \in \mathcal{G}(f)$ . The equation of the plane that passes for  $(x_0, y_0, f(x_0, y_0))$  is  $Z = f(x_0, y_0) + a(X - x_0) + b(Y - y_0)$  where  $a, b \in \mathbb{R}$ .

**Definition 8.** We say that f is partially derivable with respect to x in  $(x_0, y_0)$  if  $\varphi$  is differentiable in  $x_0$ . in that case we  $\varphi$  is the partial derivative of f in the variable x and its written  $\frac{\partial f}{\partial x}$ 

**Definition 9.** We define the gradient as  $\nabla f: (x,y) \in A \mapsto \left(\frac{\partial f}{\partial x}, \frac{\partial f}{\partial y}\right) \in \mathbb{R}^2$ 

**Definition 10.** We say that f is differentiable in the point  $(x_0, y_0)$  if exists  $a, b \in \mathbb{R}$  such that:

$$\lim_{(x,y)\to(x_0,y_0)} \frac{f(x,y) - f(x_0,y_0) - a(X-x_0) - b(Y-y_0)}{\|(x,y) - (x_0,y_0)\|} = 0 \ (\triangle)$$

f is differentiable in the point  $(x_0, y_0)$  if exists a plane that passes in the point  $(x_0, y_0, f(x_0, y_0))$  that approximates the graph of the function f.

**Proposition 2.** If f is differentiable in the point  $(x_0, y_0)$ , f is partially derivable with respect to x and y such that  $a = \frac{\partial f(x_0, y_0)}{\partial x}$  and  $b = \frac{\partial f(x_0, y_0)}{\partial y}$ 

**Definition 11.** if f is differentiable in a point  $(x,y) \in A$ , the differential in the point is defined as follows:

$$d_{(x,y)}f:(h,k)\in\mathbb{R}^2\longmapsto \frac{\partial f(x,y)}{\partial x}h+\frac{\partial f(x,y)}{\partial y}k\in\mathbb{R}$$

**Corollary 2.** f is differentiable in the point  $(x_0, y_0) \iff f$  is partially derivable in the point  $(x_0, y_0)$  and the  $(\Delta)$  is true.

**Theorem 4.** Let  $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$  with A. If  $\exists \frac{\partial f}{\partial x}$  and  $\frac{\partial f}{\partial y}$  in A and are continuos in a point  $(x_0, y_0)$ , then the function is differentiable in  $(x_0, y_0)$ .

**Theorem 5.** Let  $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$  with A open. If the function is differentiable in a point  $(x_0, y_0) \in A$  then is continuos in that point.

#### **Directional Derivatives**

If we take  $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$  and it's partial derivatives, we can take for example  $\frac{\partial f}{\partial x}$  as the direction of the function calculated on the line  $y = y_0$ . So let a

function be defined like the one before and let  $(\lambda, \mu) \in \mathbb{R}^2$  with  $\sqrt{\lambda^2 + \mu^2} = 1$ . Let r the line with the following equations:

$$\begin{cases} x = x_0 + \lambda t \\ y = y_0 + \mu t \end{cases}$$

 $(x_0, y_0)$  is internal to A so there exists a rectangle  $R_0$  of center  $(x_0, y_0)$ , so every line that passes in this point encounters a segment of the rectangle.

### Study of the maxima and minima

**Definition 12.** If a partial derivative  $\frac{\partial f}{\partial x}$  of a function  $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$  is partially derivable with respect to x in a point  $(x_0, y_0) \in A$  we say that f is partially derivable two times with respect to x in the point  $(x_0, y_0)$  ad it will be denoted as  $\frac{\partial f}{\partial x} f_x(x_0, y_0) = \frac{\partial^2 f(x_0, y_0)}{\partial x^2} = \frac{\partial^2 f}{\partial x^2}(x_0, y_0)$ .

The same goes for the other partial derivatives:  $\frac{\partial}{\partial y}f_x = \frac{\partial^2 f}{\partial x \partial y}$ ,  $\frac{\partial}{\partial x}f_y = \frac{\partial^2 f}{\partial y \partial x}$ ,...

**Definition 13.** We define the hessian matrix as follows:

$$\mathcal{D}^2 f = \begin{pmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{pmatrix}$$

**Definition 14.** The determinant of  $\mathcal{D}^2 f$  is:

$$\mathcal{H}(x,y) = \begin{vmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{vmatrix}$$

and is called the Hessian determinant.

**Theorem 6.** Let  $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$  with A open. Let's suppose that  $\exists$  the partial derivatives  $\frac{\partial^2 f}{\partial x \partial y}$  and  $\frac{\partial^2 f}{\partial y \partial x}$  continous in a point  $(x_0, y_0) \in A$ . So then  $\frac{\partial^2 f(x_0, y_0)}{\partial x \partial y} = \frac{\partial^2 f(x_0, y_0)}{\partial y \partial x}$ .

**Definition 15.** Let  $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$ , we say that  $(x_0, y_0) \in A$  is maxima (minima) for f if  $\forall (x, y) \in A$ ,  $f(x, y) \leqslant f(x_0, y_0)$  ( $f(x, y) \geqslant f(x_0, y_0)$ ).

**Theorem 7.** If f is continous and A is compact, f admits minima and maxima.

**Theorem 8.** Let  $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$  and let  $(x_0, y_0)$  an extreme relative in A