Calculus II

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Theorem 1. A is closed \iff every accumulation point for A is in A

Proof. " \Longrightarrow " Let $A \subseteq \mathbb{R}^n$, $A = A \cup \partial A$. Then $\forall p \in \bar{\mathcal{D}}(A)$, $C_r(p)_{\setminus p} \cap A \neq \emptyset \ \forall C \in \mathcal{C}_p$. if $p \notin A$ then $C_r(p)$ has elements that dont belong to $A \Rightarrow p \in \partial A$. " \Longleftarrow " Let $p \in \partial A \Rightarrow \forall C \in \mathcal{C}_p$ of center r with $r \in \mathbb{R}$ by definition we can find some $x \in C_{\setminus p} \cap A$, so that means $p \in \bar{\mathcal{D}}(A) \Rightarrow p \in A$.

1 Limits

Definition 1. Let $A \subseteq \mathbb{R}^2$ and (x_0, y_0) an accumulation point for A. we define A^* as follows:

$$A^* = \{ (\rho, \theta) \in [0, +\infty] \times [0, 2\pi] : (x_0 + \rho \cos(\theta), y_0 + \rho \sin(\theta)) \in A \}.$$

Proposition 1. Lets suppose that exist a circle C of center (x_0, y_0) such that $C_{\{(x_0, y_0)\}} \subseteq A$ let r be the radius of the circle and as a consequence $(0, r] \times [0, 2\pi] \subseteq A^*$

$$\begin{array}{l} \textit{Proof. Let $C_{\diagdown\{(x_0,y_0)\}}$ and } \begin{cases} 0<\rho\leqslant r\\ 0\leqslant\theta\leqslant 2\pi \end{cases} \text{ if } (\rho,\theta)\in(0,r]\times[0,2\pi]\\ \text{then } (x_0+\rho\cos(\theta),y_0+\rho\sin(\theta))\in C_{\diagdown\{(x_0,y_0)\}}\subseteq A\Rightarrow(\rho,\theta)\in A^*. \end{array}$$

Definition 2. Let $\theta \in [0, 2\pi]$ and $\forall \rho \in (0, r]$ we define $\varphi_{\theta}(\rho) = F(\rho, \theta)$ if $\rho \in (0, r], (\rho, \theta) \in A^*$ so the $\lim_{\rho \to 0} \varphi(\rho) = l \in \mathbb{R}$.

If that limit exists that means $\forall \theta \in [0, 2\pi]$ and $\forall \varepsilon > 0$, $\exists \delta > 0 \ \forall \rho \in (0, r]$ with $\rho < \delta \ |\varphi_{\theta} - l| < \varepsilon$.

We say that $\lim_{\rho\to 0} \varphi(\rho) = l \in \mathbb{R}$ Uniformly With Respect To (U.W.R.T.) θ .

Theorem 2. Let $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$ with (x_0, y_0) accumulation point for A. Follows the equivalence:

$$\lim_{(x,y)\to(x_0,y_0)} f(x,y) = l \in \bar{\mathbb{R}} \iff \lim_{\rho\to 0} F(\rho,\theta) = l \ U.W.R.T. \ \theta.$$

Proof. Let $l \in \bar{\mathbb{R}}$.

"
$$\Longrightarrow$$
 " $\lim_{(x,y)\to(x_0,y_0)} f(x,y) = l$ so $\forall \varepsilon > 0, \exists \delta > 0 : \forall (x,y) \in A$ with $\|(x,y)-(x_0,y_0)\| < \delta, |f(x,y)-l| < \varepsilon.$

We have to prove that $\forall \varepsilon > 0$, $\exists \delta > 0 : \forall \theta \in [0, 2\pi], \ \forall \rho(0, r]$ with $\rho < \delta \ |F(\rho, \theta) - l| < \varepsilon$.

Let $\varepsilon > 0$, $\theta \in [0, 2\pi]$, $\rho \in (0, r]$ with $\rho < \delta$, we create the system that changes the coordinates from cartesians to polars:

$$\begin{cases} x = x_0 + \rho \cos(\theta) \\ y = y_0 + \rho \sin(\theta) \end{cases} \quad \rho = \sqrt{(x - x_0)^2 + (y - y_0)^2}$$

 $\rho \in (0,r], \ \theta \in [0,2\pi] \in (0,r] \times [0,2\pi] \subseteq A^*, \ (\rho,\theta) \in A^* \Rightarrow (x,y) \in A.$

Now
$$0 < \sqrt{(x-x_0)^2 + (y-y_0)^2} = \rho < \delta \Rightarrow |f(x,y) - l| < \varepsilon.$$

 $\Rightarrow |f(x_0 + \rho\cos(\theta), y_0 + \rho\sin(\theta)) - l| < \varepsilon \Rightarrow |F(\rho, \theta) - l| < \varepsilon.$

" \Longleftarrow " $\forall \varepsilon > 0, \exists \delta \leq r : \forall \theta \in [0, 2\pi] \text{ and } \forall \rho \text{ with } 0 < \rho < \delta \Rightarrow |F(\rho, \theta) - l| < \varepsilon.$

We have to prove that $\forall \varepsilon > 0, \exists \delta > 0, \forall (x,y) \in A$ with $\sqrt{(x-x_0)^2 + (y-y_0)^2} = \|(x,y) - (x_0,y_0)\| < \delta \Rightarrow |f(x,y) - l| < \varepsilon.$

Let $\varepsilon > 0$, $\delta \le r$, $(x,y) \in A$, $\sqrt{(x-x_0)^2 + (y-y_0)^2} < \delta$, we switch coordinates with ρ and θ as follows:

$$\begin{cases} x = x_0 + \rho \cos(\theta) \\ y = y_0 + \rho \sin(\theta) \end{cases} \quad \rho = \sqrt{(x - x_0)^2 + (y - y_0)^2}$$

 $0 < \rho < \delta \le r \Rightarrow \rho \in (0, r], \ \theta \in [0, 2\pi].$

We notice that $|F(\rho, \theta) - l| < \varepsilon$, so $|f(x_0 + \rho \cos(\theta), y_0 + \rho \sin(\theta)) - l| < \varepsilon$ $\Rightarrow |f(x, y) - l| < \varepsilon$.

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Definition 3. We say that $\theta \in [0, 2\pi]$ is admissible if $0 \in \bar{\mathcal{D}}(A_{\theta})$.

Theorem 3. $\lim_{\rho \to 0} F(\rho, \theta) = l \in \mathbb{R}$ U.W.R.T. $\theta \iff \lim_{\rho \to 0} \varphi(\rho) = 0$.

Corollary 1. $\lim_{\rho \to 0} F(\rho, \theta) = l \in \mathbb{R}$ U.W.R.T. $\theta \iff \exists$ a function $\psi(\rho)$ such that $\lim_{\rho \to 0} \psi(\rho) = 0$ and $\forall \theta \mid F(\rho, \theta) - l \mid \leqslant \psi(\rho)$.

Corollary 2. Let's suppose that $\lim_{\rho\to 0} F(\rho,\theta) = +\infty$.

 $\forall \rho \in (0,r] \ let \ h(\rho) = \inf\{F(\rho,\theta) : \theta \in [0,2\pi]\} \ so \ then \ \lim_{\rho \to 0} F(\rho,\theta) = +\infty \ U.W.R.T. \ \theta \Longleftrightarrow \lim_{\rho \to 0} h(\rho) = +\infty$

Obs 1. $\lim_{\rho \to 0} F(\rho, \theta) = +\infty$ *U.W.R.T.* $\theta \iff \exists$ *a function* $K(\rho)$ *s.t.* $\lim_{\rho \to 0} K(\rho) = +\infty$ *and* $F(\rho, \theta) \ge K(\rho)$

Corollary 3. Let's suppose that $\lim_{\rho\to 0} F(\rho,\theta) = -\infty$.

 $\forall \rho \in (0,r] \ \text{let} \ g(\rho) = \sup\{F(\rho,\theta): \theta \in [0,2\pi]\} \ \text{so then } \lim_{\rho \to 0} F(\rho,\theta) = -\infty \ U.W.R.T. \ \theta \Longleftrightarrow \lim_{\rho \to 0} g(\rho) = -\infty$

Definition 4. Let $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$ with A open.

let $(x_0, y_0) \in A$, $\varphi(x) = f(x, y_0)$ and $\psi = f(x_0, y)$. A is open that means that those two functions are well defined.

Differentiability

Definition 5. Let be $f: A \subseteq \mathbb{R}^n \to \mathbb{R}$ with A Open. Let $\bar{x} \in A$ and let $i \leq n$, we denote as $\varphi_i(x_i) = f(\bar{x}_1, \bar{x}_2, ..., \bar{x}_{i-1}, \bar{x}_i, \bar{x}_{i+1}, ..., \bar{x}_n)$. Notice that \bar{x} is an internal point so then it exist an interval where φ_i is well defined.

Definition 6. We say that f is partially derivable with respect to the variable x_i in the point \bar{x} if φ_i is derivable in that point. We denote as $\frac{\partial f}{\partial x_i}$ the partial derivative with respect to x_i in the point \bar{x} .

Definition 7. The gradient of a function in n variables is defined as follows:

$$\nabla f: \bar{x} \in A \longmapsto \left(\frac{\partial f}{\partial x_1}, ..., \frac{\partial f}{\partial x_n}\right) \in \mathbb{R}^n$$

The case of two variables

Let $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$ with A open, and let $(x_0, y_0) \in A$. $(x_0, y_0, f(x_0, y_0)) \in \mathcal{G}(f)$. The equation of the plane that passes for $(x_0, y_0, f(x_0, y_0))$ is $Z = f(x_0, y_0) + a(X - x_0) + b(Y - y_0)$ where $a, b \in \mathbb{R}$.

Definition 8. We say that f is partially derivable with respect to x in (x_0, y_0) if φ is differentiable in x_0 . in that case we φ is the partial derivative of f in the variable x and its written $\frac{\partial f}{\partial x}$

Definition 9. We define the gradient as $\nabla f:(x,y)\in A\longmapsto \left(\frac{\partial f}{\partial x},\frac{\partial f}{\partial y}\right)\in\mathbb{R}^2$

Definition 10. We say that f is differentiable in the point (x_0, y_0) if exists $a, b \in \mathbb{R}$ such that:

$$\lim_{(x,y)\to(x_0,y_0)} \frac{f(x,y) - f(x_0,y_0) - a(X - x_0) - b(Y - y_0)}{\|(x,y) - (x_0,y_0)\|} = 0 \ (\triangle)$$

f is differentiable in the point (x_0, y_0) if exists a plane that passes in the point $(x_0, y_0, f(x_0, y_0))$ that approximates the graph of the function f.

Proposition 2. If f is differentiable in the point (x_0, y_0) , f is partially derivable with respect to x and y such that $a = \frac{\partial f(x_0, y_0)}{\partial x}$ and $b = \frac{\partial f(x_0, y_0)}{\partial y}$

Definition 11. if f is differentiable in a point $(x,y) \in A$, the differential in the point is defined as follows:

$$d_{(x,y)}f:(h,k)\in\mathbb{R}^2\longmapsto\frac{\partial f(x,y)}{\partial x}h+\frac{\partial f(x,y)}{\partial y}k\in\mathbb{R}$$

Corollary 4. f is differentiable in the point $(x_0, y_0) \iff f$ is partially derivable in the point (x_0, y_0) and the (Δ) is true.

Theorem 4. Let $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$ with A. If $\exists \frac{\partial f}{\partial x}$ and $\frac{\partial f}{\partial y}$ in A and are continuos in a point (x_0, y_0) , then the function is differentiable in (x_0, y_0) .

Theorem 5. Let $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$ with A open. If the function is differentiable in a point $(x_0, y_0) \in A$ then is continuous in that point.

Directional Derivatives

If we take $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$ and it's partial derivatives, we can take for example $\frac{\partial f}{\partial x}$ as the direction of the function calculated on the line $y = y_0$. So let a function be defined like the one before and let $(\lambda, \mu) \in \mathbb{R}^2$ with $\sqrt{\lambda^2 + \mu^2} = 1$. Let r the line with the following equations:

$$\begin{cases} x = x_0 + \lambda t \\ y = y_0 + \mu t \end{cases}$$

 (x_0, y_0) is internal to A so there exists a rectangle R_0 of center (x_0, y_0) , so every line that passes in this point encounters a segment of the rectangle.

Study of the maxima and minima

Definition 12. If a partial derivative $\frac{\partial f}{\partial x}$ of a function $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$ is partially derivable with respect to x in a point $(x_0, y_0) \in A$ we say that f is partially derivable two times with respect to x in the point (x_0, y_0) ad it will be denoted as $\frac{\partial f}{\partial x} f_x(x_0, y_0) = \frac{\partial^2 f(x_0, y_0)}{\partial x^2} = \frac{\partial^2 f}{\partial x^2}(x_0, y_0)$.

The same goes for the other partial derivatives: $\frac{\partial}{\partial y}f_x = \frac{\partial^2 f}{\partial x \partial y}$, $\frac{\partial}{\partial x}f_y = \frac{\partial^2 f}{\partial y \partial x}$,...

Definition 13. We define the hessian matrix as follows:

$$\mathcal{D}^2 f = \begin{pmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{pmatrix}$$

Definition 14. The determinant of $\mathcal{D}^2 f$ is:

$$\mathcal{H}(x,y) = \begin{vmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{vmatrix}$$

and is called the Hessian determinant.

Theorem 6. Let $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$ with A open. Let's suppose that \exists the partial derivatives $\frac{\partial^2 f}{\partial x \partial y}$ and $\frac{\partial^2 f}{\partial y \partial x}$ continous in a point $(x_0, y_0) \in A$. So then $\frac{\partial^2 f(x_0, y_0)}{\partial x \partial y} = \frac{\partial^2 f(x_0, y_0)}{\partial y \partial x}$.

Definition 15. Let $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$, we say that $(x_0, y_0) \in A$ is maxima (minima) for f if $\forall (x, y) \in A$, $f(x, y) \leqslant f(x_0, y_0)$ ($f(x, y) \geqslant f(x_0, y_0)$).

Theorem 7. If f is continous and A is compact, f admits minima and maxima.

Theorem 8. Let $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$ and let $(x_0, y_0) \in \dot{A}$ a relative extreme and let f be partially derivable in (x_0, y_0) , so then $\frac{\partial f(x_0, y_0)}{\partial x} = 0$ and $\frac{\partial f(x_0, y_0)}{\partial y} = 0$. The points where the partial derivatives are 0 are said "critical points" of f, $(x_0, y_0) \in \dot{A}$ is an extreme ralative $\Rightarrow (x_0, y_0)$ is a critical point for f (\notin).

Obs 2. Let $(x_0, y_0) \in A$ and let $g(x, y) = f(x, y) - f(x_0, y_0)$, (x_0, y_0) is a relative minimum (relative maximum) for $f \iff \exists \ a \ circle \ C$ of center (x_0, y_0) such that $g \ge 0$ $(g \le 0)$.

Theorem 9. Let $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$ and let $(x_0, y_0) \in \dot{A}$ a relative extreme $\Longrightarrow \mathcal{H}(x_0, y_0) \geqslant 0$.

Theorem 10. Let $f: A \subseteq \mathbb{R}^2 \to \mathbb{R}$, $f \in \mathbb{C}^2$. Let $(x_0, y_0) \in \dot{A}$ a critical point and lets suppose that $\mathcal{H}(x_0, y_0) > 0 \Longrightarrow (x_0, y_0)$ is a relative extreme and is maximum or minimum depending on $\frac{\partial^2 f(x_0, y_0)}{\partial x^2}$ be < 0 or > 0.