

Penalized tensor B-spline neural network regression

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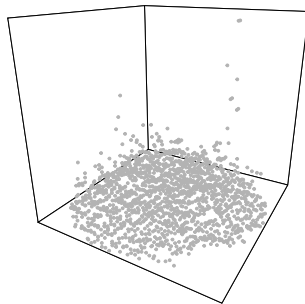
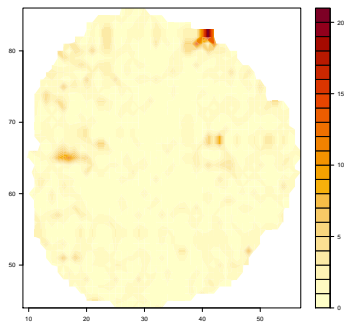
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Introduction

FMRI

- Brain activity captured by local changes in oxygenation pattern
- Spatial smoothing prior to statistical analysis



Motivation

- Traditional non-adaptive regression estimators often fail to capture local trend such as sudden peak.
- We propose an adaptive regression estimator based on neural network with activation function having compact support.
- Application in neurophysiology, quality control, etc.

Model and estimator

Model

■ Data : $\{(y_i, x_{1i}, x_{2i})\}_{i=1}^N$

■ Model :

$$y_i = f(x_{1i}, x_{2i}) + \varepsilon_i$$

y_i : response

(x_{1i}, x_{2i}) : input

ε_i : random error with mean 0

Tensor B-spline neural network

- Tensor B-spline neural network (TBNN) function :

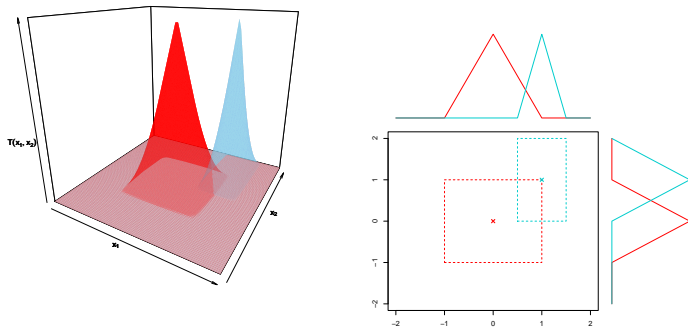
$$f_{\theta}(x_1, x_2) = \beta_0 + \sum_{m=1}^M \beta_m \sigma(\alpha_{0m}^1 + \alpha_{1m}^1 x_1) \sigma(\alpha_{0m}^2 + \alpha_{1m}^2 x_2)$$

$\sigma(\cdot)$: B-spline activation function

$$\theta = (\beta_0, \beta_1, \alpha_{01}^1, \alpha_{11}^1, \alpha_{01}^2, \alpha_{11}^2 \dots, \alpha_{1M}^2) \in \mathbb{R}^{5M+1}$$

- β : weight of tensor B-spline activated node
- $(\alpha_0^1, \alpha_1^1, \alpha_0^2, \alpha_1^2)$: parameter determining the center and support of tensor B-spline activation function

Tensor B-spline activation function



$$\blacktriangle : (\alpha_0^1, \alpha_1^1, \alpha_0^2, \alpha_1^2) = (0, 1, 0, 1)$$

$$\blacktriangle : (\alpha_0^1, \alpha_1^1, \alpha_0^2, \alpha_1^2) = (-2, 2, -1, 1)$$

Penalized tensor B-spline neural network estimator

- Penalized empirical risk with λ :

$$R^\lambda(\theta) = \frac{1}{2N} \sum_{i=1}^N (y_i - \mathbf{f}_\theta(x_{1i}, x_{2i}))^2 + \lambda \text{pen}(\theta)$$

$\lambda \geq 0$: complexity parameter

- Penalty function :

$$\text{pen}(\theta) = \sum_{m=1}^M |\beta_m|$$

- Penalized TBNN estimator :

$$\hat{f} = \mathbf{f}_{\hat{\theta}^\lambda}$$

where $\hat{\theta}^\lambda = \operatorname{argmin}_{\theta \in \mathbb{R}^{5M+1}} R^\lambda(\theta)$

Implementation

Coordinate descent algorithm

- Objective function : penalized empirical risk
- Coordinate descent algorithm :

$$\tilde{\theta}_j \leftarrow \operatorname{argmin}_{\theta_j \in \mathbb{R}} R^\lambda(\tilde{\theta}_1, \dots, \tilde{\theta}_{j-1}, \theta_j, \tilde{\theta}_{j+1}, \dots, \tilde{\theta}_J)$$

where \sim indicates the vector of current values and $J = 5M + 1$

- 1 Update $\tilde{\beta}$ with ℓ_1 -penalty
 - 2 Update $\tilde{\alpha}_0^1, \tilde{\alpha}_1^1, \tilde{\alpha}_0^2, \tilde{\alpha}_1^2$
- Initialization scheme specialized in TBNN

Complexity parameter selection

- Complexity parameter λ controls the number of nodes.
- Optimal complexity parameter is selected by

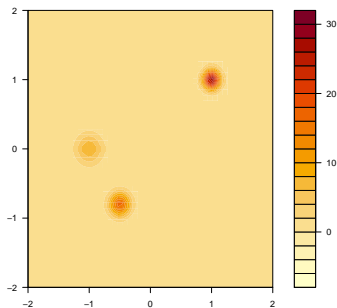
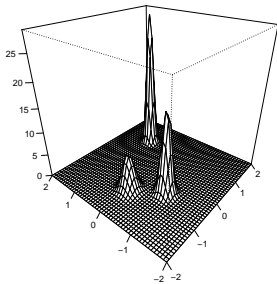
$$\text{BIC} = N \log R(\hat{\theta}^\lambda) + \text{dim} \log N$$

where dim = the number of nodes

Numerical studies

Simulation set-up

- True regression function with local peak

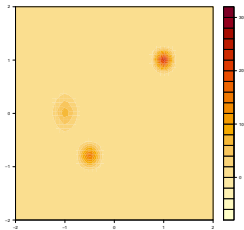


- Error : $\mathcal{N}(0, 2^2)$

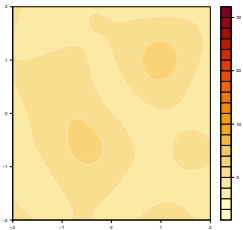
- Competitor :

- 1 Smoothing spline
- 2 Adaptive P-spline

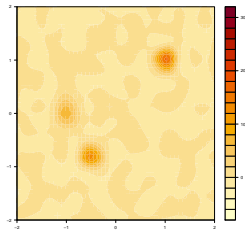
Simulation result



(a) TBNN



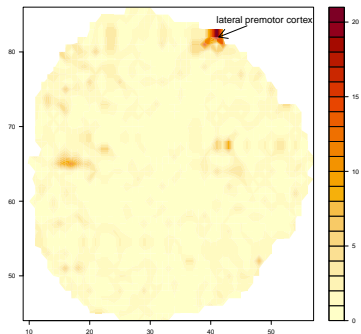
(b) Smoothing spline



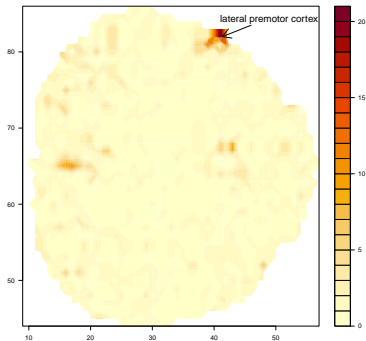
(c) Adaptive P-spline

FMRI data

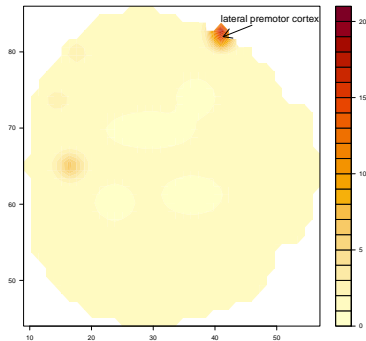
- Input : coordinate of cutting-plane of brain
- Response : FPQ
- 1567 points
- Subject conduct verbal fluency task
- Local peak on lateral premotor cortex



Penalized tensor B-spline neural network fit

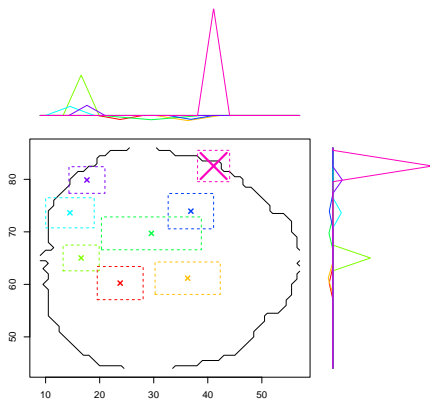


(a) FMRI data



(b) TBNN

Penalized tensor B-spline neural network nodes



(a) total 8 nodes

big marked node : capture the peak

Conclusion

Conclusion

- We develop an adaptive regression estimator based on TBNN.
- The proposed estimator effectively captures local peak with global pattern compared to the existing method.
- The node pruning process is done in the data-adaptive way by ℓ_1 -penalization.
- Application to FMRI data exhibits a desired performance.

Appendix

Tensor B-spline activation function

- Tensor B-spline activation function :

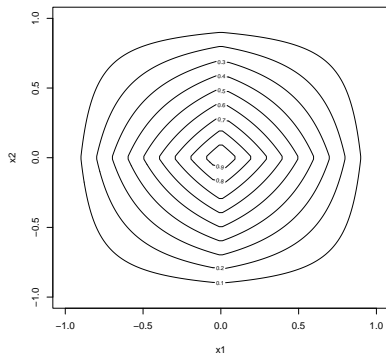
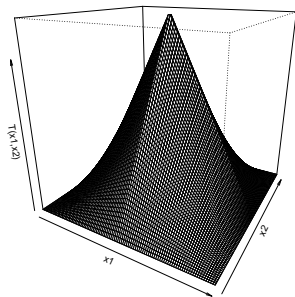
$$\mathsf{T}(x_1, x_2) = \sigma(a^1 + b^1 x_1) \sigma(a^2 + b^2 x_2)$$

where

$$\sigma(z) = \begin{cases} 1 + z & \text{if } z \in [-1, 0) \\ 1 - z & \text{if } z \in [0, 1) \\ 0 & \text{if otherwise} \end{cases}$$

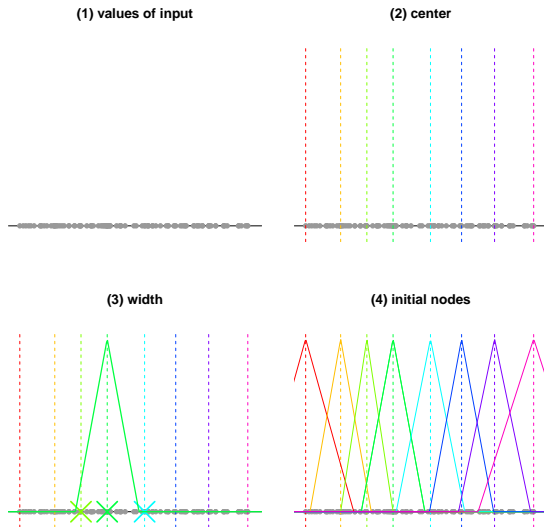
- Center : $\left(-\frac{a^1}{b^1}, -\frac{a^2}{b^2}\right)$
- Support : $\left[\frac{-(1+a^1)}{b^1}, \frac{1-a^1}{b^1}\right] \times \left[\frac{-(1+a^2)}{b^2}, \frac{1-a^2}{b^2}\right]$

Tensor B-spline activation function plot



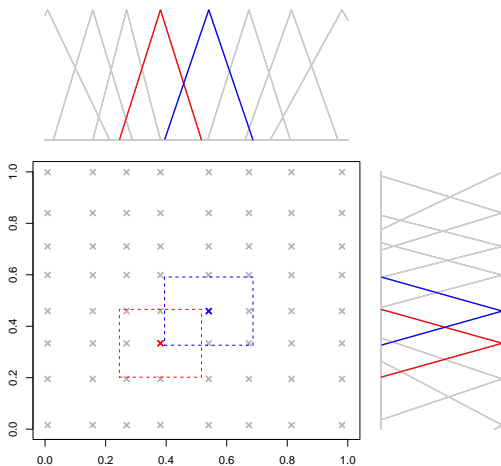
Initialization scheme on marginal line

■ Initialization on x_1 axis



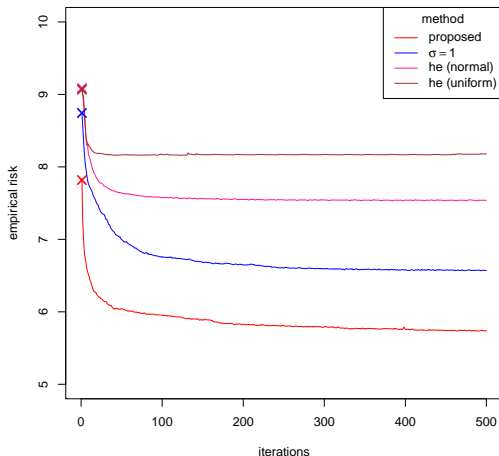
Initialization scheme on plane

- Tensor product of B-spline activation functions on x_1 and x_2 axis



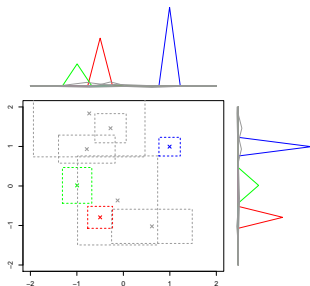
Initialization scheme comparison

- Comparison between the proposed scheme and others

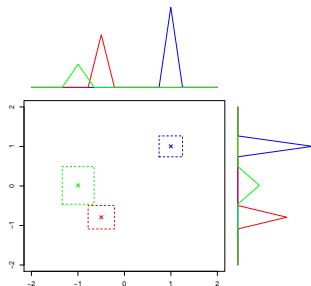


Role of complexity parameter

- Example for $\lambda_1 < \lambda_2$



(a) λ_1 : 8 nodes



(b) λ_2 : 3 nodes

Simulation result table

Error	N	TBNN	Smoothing spline	Adaptive P-spline
$\mathcal{N}(0, 2^2)$	1000	0.3646 (0.0694)	2.3400 (0.0109)	1.1021 (0.0207)
	2000	0.1648 (0.0280)	2.3180 (0.0050)	0.7627 (0.0117)
$\mathcal{N}(0, 4^2)$	1000	0.9442 (0.1167)	2.5940 (0.0347)	2.2457 (0.0705)
	2000	0.4210 (0.0604)	2.4545 (0.0173)	1.5790 (0.0346)

Averaged MSE (standard error) over 100 repetitions