



E0003

Place student sticker here

**Note:**

- During the attendance check a sticker containing a unique code will be put on this exam.
- This code contains a unique number that associates this exam with your registration number.
- This number is printed both next to the code and to the signature field in the attendance check list.

## Maschinelles Lernen

**Exam:** IN2064 / Endterm

**Date:** Friday 24<sup>th</sup> February, 2023

**Examiner:** Prof. Günnemann

**Time:** 17:00 – 19:00

P 1

P 2

P 3

P 4

P 5

P 6

P 7

P 8

P 9

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### Working instructions

- This exam consists of **16 pages** with a total of **9 problems**.  
Please make sure now that you received a complete copy of the exam.
- The total amount of achievable credits in this exam is 36 credits.
- Detaching pages from the exam is prohibited.
- Allowed resources:
  - Two-sided DIN A4 sheet of handwritten notes (a print of digitally handwritten notes is allowed).
- **No other material (e.g. books, cell phones, calculators) is allowed!**
- Physically turn off all electronic devices, put them into your bag and close the bag.
- There is scratch paper at the end of the exam (after problem 9).
- Write your answers only in the provided solution boxes or the scratch paper.
- If you solve a task on the scratch paper, clearly reference it in the main solution box.
- All sheets (including scratch paper) have to be returned at the end.
- **Only use a black or a blue pen (no pencils, red or greens pens!)**
- **For problems that say “Justify your answer” you only get points if you provide a valid explanation.**
- **For problems that say “Derive” you only get points if you provide a valid mathematical derivation.**
- **For problems that say “Prove” you only get points if you provide a valid mathematical proof.**
- If a problem does not say “Justify your answer”, “Derive” or “Prove”, it is sufficient to only provide the correct answer.

Left room from \_\_\_\_\_ to \_\_\_\_\_ / Early submission at \_\_\_\_\_



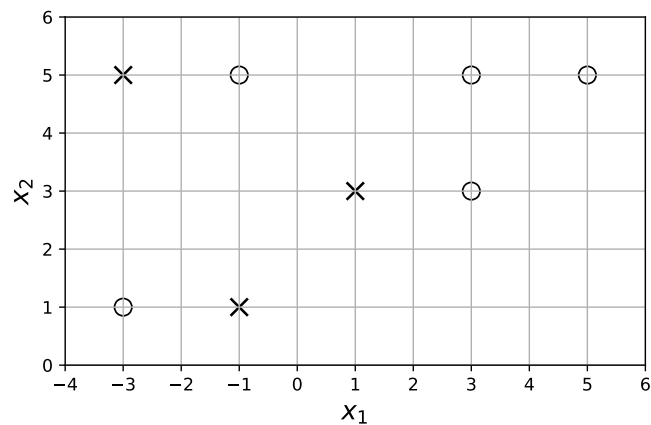
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## Problem 1 Decision trees (4 credits)

Consider the following two-dimensional classification dataset with the classes “0” (○ marker) and 1 (x marker).



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1	<input type="checkbox"/>
2	<input type="checkbox"/>

a) Draw a decision tree of maximum depth 3 that correctly classifies all datapoints. Each decision node must be of the form  $x_d \leq c$  with  $d \in \{1, 2\}$  and  $c \in \mathbb{R}$ . Also annotate each edge with “True” or “False” and each leaf node with “0” or “1”





0  
1  
2

b) We now consider a modified form of decision trees that **only** allows for decision nodes of the form  $a \cdot x_1 + b \leq x_2$  with  $a, b \in \mathbb{R}$ . In particular, nodes of the form  $x_1 \leq c$  are **not allowed**. Draw such a decision tree of maximum depth 2 that correctly classifies all datapoints. Also annotate each edge with “True” or “False” and each leaf node with “0” or “1”





## Problem 2 Probabilistic inference (3 credits)

Consider an infinite number of barns arranged on a regular grid  $\mathbb{Z}^2$ , with  $\mathbb{Z}$  being the set of all integers. An owl starts exploring the world at an unknown location  $\mathbf{x}^{(0)} \in \mathbb{Z}^2$ . Each day, it moves in one of four directions, according to the following distribution:

$$\begin{aligned} \Pr \left[ \mathbf{x}^{(t+1)} = \mathbf{x}^{(t)} + \begin{bmatrix} -1 \\ 0 \end{bmatrix} \mid \mathbf{x}^{(t)} \right] &= \frac{2}{8} & \Pr \left[ \mathbf{x}^{(t+1)} = \mathbf{x}^{(t)} + \begin{bmatrix} +1 \\ 0 \end{bmatrix} \mid \mathbf{x}^{(t)} \right] &= \frac{2}{8} \\ \Pr \left[ \mathbf{x}^{(t+1)} = \mathbf{x}^{(t)} + \begin{bmatrix} 0 \\ -1 \end{bmatrix} \mid \mathbf{x}^{(t)} \right] &= \frac{3}{8} & \Pr \left[ \mathbf{x}^{(t+1)} = \mathbf{x}^{(t)} + \begin{bmatrix} 0 \\ +1 \end{bmatrix} \mid \mathbf{x}^{(t)} \right] &= \frac{1}{8} \end{aligned}$$

0 ☐

1 ☐

a) After two days, you find the owl sleeping in  $\mathbf{x}^{(2)} = \begin{bmatrix} 6 & 8 \end{bmatrix}^\top$ . List all possible starting locations, i.e. all  $\mathbf{s} \in \mathbb{Z}^2$  such that  $\Pr \left[ \mathbf{x}^{(2)} = \begin{bmatrix} 6 & 8 \end{bmatrix}^\top \mid \mathbf{x}^{(0)} = \mathbf{s} \right] > 0$ .

0 ☐

1 ☐

2 ☐

b) **Derive** the maximum likelihood estimate for the starting location  $\mathbf{x}^{(0)}$ , i.e.  $\operatorname{argmax}_{\mathbf{s}} \Pr \left[ \mathbf{x}^{(2)} = \begin{bmatrix} 6 & 8 \end{bmatrix}^\top \mid \mathbf{x}^{(0)} = \mathbf{s} \right]$ .





### Problem 3 Linear regression (5 credits)

We want to perform regularized linear regression (without bias) on a dataset with  $N$  samples  $\mathbf{x}_i \in \mathbb{R}^d$  with corresponding targets  $y_i$  (represented compactly as  $\mathbf{X} \in \mathbb{R}^{N \times d}$  and  $\mathbf{y} \in \mathbb{R}^N$ ). You assume that your targets are normal distributed, i.e.,

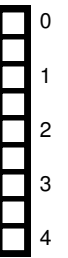
$$p(y_i | \mathbf{x}_i, \mathbf{w}) = \mathcal{N}(\mathbf{x}_i^\top \mathbf{w}, 1) = \frac{1}{\sqrt{2\pi}} \exp\left(-\frac{1}{2} (y_i - \mathbf{x}_i^\top \mathbf{w})^2\right). \quad (3.1)$$

To add regularization, you choose a Laplace prior on the parameters  $\mathbf{w} \in \mathbb{R}^d$ , i.e.,

$$p(\mathbf{w}) = \frac{1}{2\lambda} \prod_{i=1}^d \exp\left(-\frac{|w_i|}{\lambda}\right). \quad (3.2)$$

with hyperparameter  $\lambda > 0$ .

a) **Derive** the negative logarithm of the posterior distribution, i.e.,  $-\log p(\mathbf{w} | \mathbf{X}, \mathbf{y})$  (up to some normalization constant).



b) What is the advantage/difference of having such a Laplace prior over a Gaussian prior? **Justify your answer!**





## Problem 4 Optimization (6 credits)

Below, you are given two different functions and asked to **prove** convexity.

0

1

2

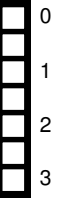
3

a) Prove that the subsequent function is convex in  $\mathbf{x} \in \mathbb{R}_{>0}^d$ , i.e., over the set of vectors solely consisting of positive entries  $x_i > 0$  for all  $i = 1, \dots, d$ :

$$f(\mathbf{x}) = \sum_{i=1}^d x_i \log x_i$$

**Hint:** Remember that a matrix  $\mathbf{A} \in \mathbb{R}^{d \times d}$  is positive semi-definite, if  $\forall \mathbf{z} \in \mathbb{R}^d : \mathbf{z}^\top \mathbf{A} \mathbf{z} \geq 0$





b) Let  $f_1 : \mathbb{R}^d \rightarrow \mathbb{R}$  and  $f_2 : \mathbb{R}^d \rightarrow \mathbb{R}$  be two convex functions. **Prove** that

$$h(\mathbf{x}) = \max\{f_1(\mathbf{x}), f_2(\mathbf{x})\}$$

is a convex function.

**Note:** For this, you are not allowed to use any convexity rules from the lecture without proving them.





## Problem 5 Deep Learning (5 credits)

The following code snippets all contain **exactly one error**. Your task is to spot the mistakes and explain how to fix it. **Justify your answer!**

We omitted variable initializations to avoid clutter. Assume that all variables were appropriately initialized.

0 ☐  
1 ☐  
2 ☐

a) Given an input  $\mathbf{x} \in \mathbb{R}^d$ , the subsequent class implements the ReLU layer  $f(x) = \max(0, x)$  and the corresponding backward pass.

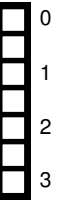
```
import numpy as np

class ReLU:
    def forward(self, inputs):
        self.cache = inputs
        out = np.maximum(inputs, 0)
        return out
    def backward(self, d_out):
        inputs = self.cache
        d_inputs = d_out * (inputs < 0)
        return d_inputs
```

```
relu = ReLU()
z = relu.forward(x)
d_x = relu.backward(1.0)
```







b) We have trained a model to perform multiclass classification over  $c$  classes on a dataset  $\mathbf{X} \in \mathbb{R}^{n \times d}$  and one-hot encoded targets  $\mathbf{y} \in \{0, 1\}^{n \times c}$  with  $\sum_{j=1}^c y_{i,j} = 1 \quad \forall i \in [1, \dots, n]$ . The model is defined as:  $\text{outputs} = \text{ReLU}(\mathbf{x} @ \mathbf{w}_1 + \mathbf{b}_1) @ \mathbf{w}_2 + \mathbf{b}_2$ . The model was trained to minimize the Cross Entropy between the one-hot encoded target and the prediction. Now, we want to obtain the normalized class probabilities as well as the predicted class.

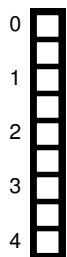
```
import torch
```

```
model.eval()
outputs = model.forward(x)
classprobs = torch.sigmoid(outputs)
y_hat = torch.argmax(classprobs, axis=1)
for i, (cp, yh) in enumerate(zip(classprobs, y_hat)):
    print(f"predicted class {yh} for sample {i} with probability {cp[yh]}")
```

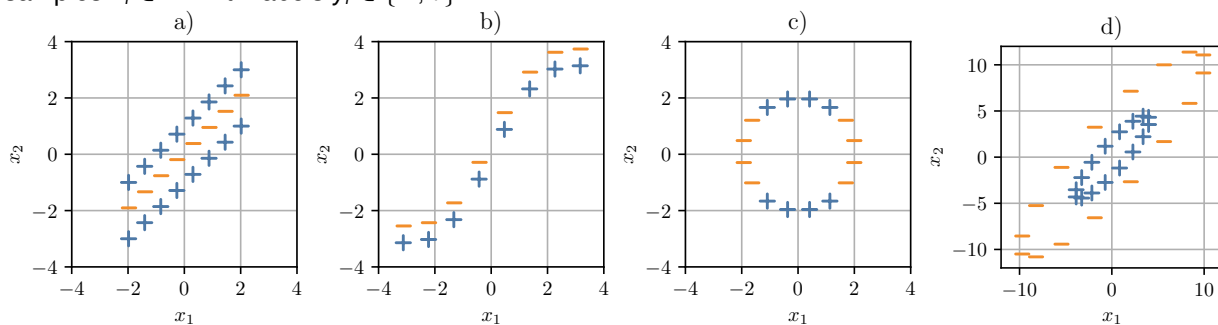




## Problem 6 Linear classification (4 credits)



We want to perform binary classification on four different datasets,  $t \in \{a, b, c, d\}$ , each consisting of  $N_t$  samples  $\mathbf{x}_i \in \mathbb{R}^2$  with labels  $y_i \in \{-, +\}$ :



You already came up with transformations  $\phi_1, \dots, \phi_4$  that transform the respective datasets such that they are linearly separable:

$$\phi_1(\mathbf{x}) = \hat{x}_1 \hat{x}_2 \quad (6.1)$$

$$\hat{\mathbf{x}} = \mathbf{x} \begin{bmatrix} \cos \frac{\pi}{4} & -\sin \frac{\pi}{4} \\ \sin \frac{\pi}{4} & \cos \frac{\pi}{4} \end{bmatrix}$$

$$\phi_2(\mathbf{x}) = x_2 - \sin(x_1) - x_1 \quad (6.2)$$

$$\phi_3(\mathbf{x}) = \left\| \begin{bmatrix} \frac{x_1}{2} \\ x_2 - x_1 \end{bmatrix} \right\|_2 \quad (6.3)$$

$$\phi_4(\mathbf{x}) = |x_1 - x_2| \quad (6.4)$$

Unfortunately, you forgot which transform belongs to which dataset. Assign the transformations  $\phi_1, \phi_2, \phi_3, \phi_4$  to the datasets  $a, b, c, d$  such that the transformed datasets are linearly separable. **Justify your answer!**





## Problem 7 Support Vector Machines and Kernels (4 credits)

You are given a dataset with  $N$  datapoints  $\{(\mathbf{x}_i, y_i)\}_{i=1}^N$  with  $\mathbf{x}_i \in \mathbb{R}^d$  and  $y_i \in \{-1, 1\}$  representing the class of datapoint  $i$ . We use the augmentation trick  $\mathbf{x} \mapsto \tilde{\mathbf{x}} = (\mathbf{x}, 1)$  to turn the affine decision function of an SVM classifier  $h(\mathbf{x}) = \mathbf{w}^\top \mathbf{x} + b$  (with explicit bias term) into a linear function  $\tilde{h}(\mathbf{x}) = \tilde{\mathbf{w}}^\top \tilde{\mathbf{x}}$  with  $\tilde{\mathbf{w}} = (\mathbf{w}, b) \in \mathbb{R}^{d+1}$ .

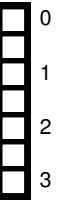
Now, we want to solve the adapted (maximum-margin) optimization problem

$$\begin{aligned} \min_{\tilde{\mathbf{w}}} \quad & \frac{1}{2} \tilde{\mathbf{w}}^\top \tilde{\mathbf{w}} \\ \text{subject to} \quad & y_i \tilde{\mathbf{w}}^\top \tilde{\mathbf{x}}_i - 1 \geq 0 \quad i = 1, \dots, N \end{aligned}$$

a) What is the Lagrangian function  $L(\tilde{\mathbf{w}}, \alpha)$  associated to the above problem, with  $\alpha_i \geq 0$  corresponding to the Lagrangian multipliers.



b) **Derive** the corresponding dual function  $g(\alpha)$ . It suffices to simplify  $g(\alpha)$  such that it does not contain any minimization or maximization term.



**Hint:** The Lagrangian function  $L(\tilde{\mathbf{w}}, \alpha)$  is convex in  $\tilde{\mathbf{w}}$ .





## Problem 8 PCA (3 credits)

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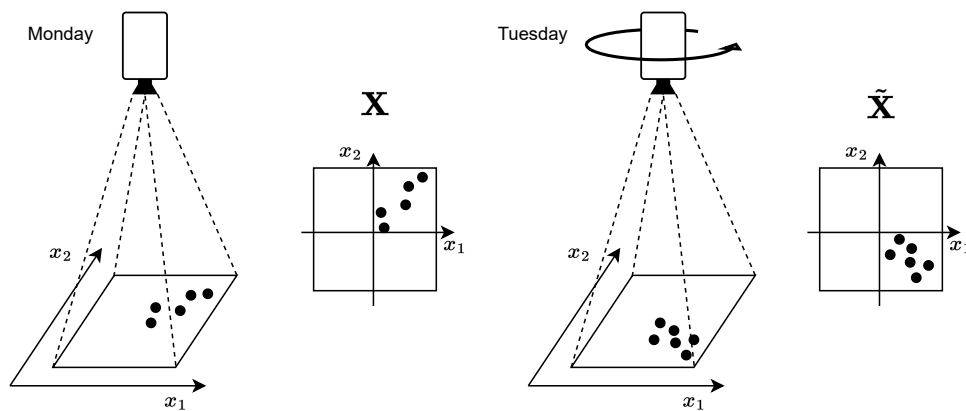
On Monday, you experimented with growing bacteria and took a photo of the result. You recorded the positions of bacteria as illustrated below. Each position is a two-dimensional coordinate, with the origin in the middle of the camera's frame. The positions are saved in a data matrix  $\mathbf{X} \in \mathbb{R}^{N \times 2}$ . On Tuesday, you repeated the experiment but did not set up the camera at the same angle. Tuesday's measurements are denoted with  $\tilde{\mathbf{X}} \in \mathbb{R}^{M \times 2}$ .

Since you assume the positions will follow the **same distribution** every day, you want to rotate the data recorded on Tuesday to **match the direction and shape** of the data from Monday. Unfortunately, the only data processing technique you know is PCA. Fortunately, this is enough to solve this problem. **Propose a solution and justify your answer.**

You have a function  $\text{PCA}(\mathbf{D})$  at your disposal, which takes data matrix  $\mathbf{D} \in \mathbb{R}^{a \times b}$  and returns  $\mathbf{\Gamma} \in \mathbb{R}^{b \times b}$  corresponding to the principal components, and  $\mathbf{\Lambda} \in \mathbb{R}^b$  corresponding to the eigenvalues. You also know the commands for basic matrix manipulation: addition, subtraction, multiplication and transpose.

Assume that PCA always gives you the desired eigenvectors, that is, ignore the potential sign flips in  $\mathbf{\Gamma}$ .

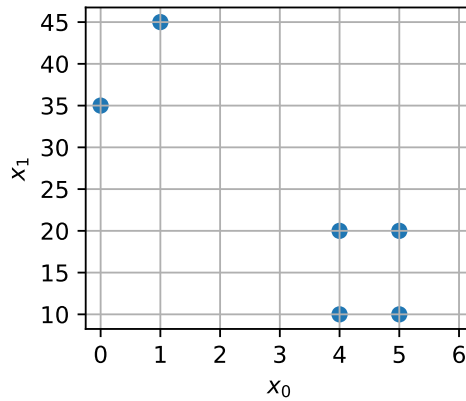
*Note: Figure below is just for illustration purposes. The angle and the values  $N$  and  $M$  are not given.*





## Problem 9 Clustering (2 credits)

You are given the following two-dimensional dataset  $\mathbf{X} \in \mathbb{R}^{n \times 6}$ :



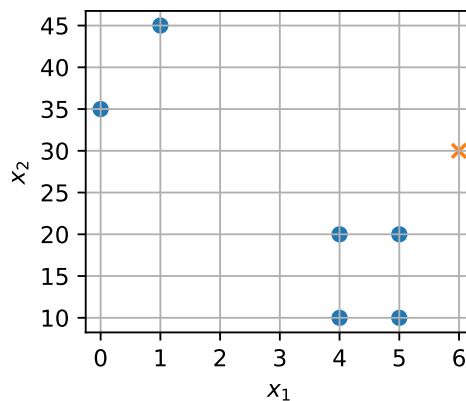
a) What are the globally optimal cluster centers  $\mu$  that minimize the k-means objective

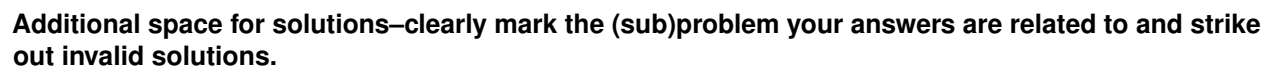
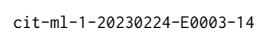
$$J(\mathbf{X}, \mathbf{Z}, \mu) = \sum_{i=1}^N \sum_{k=1}^K \mathbf{z}_{ik} \|\mathbf{x}_i - \mu_k\|_2^2 \quad (9.1)$$



with the assignment to the closest cluster centers  $\mathbf{Z}$ .

b) Now assume you want to infer the corresponding cluster for a new datapoint without updating the cluster centers  $\mu$ . To what cluster center in  $\mu$  does the new point (x) correspond to? **Justify your answer!**

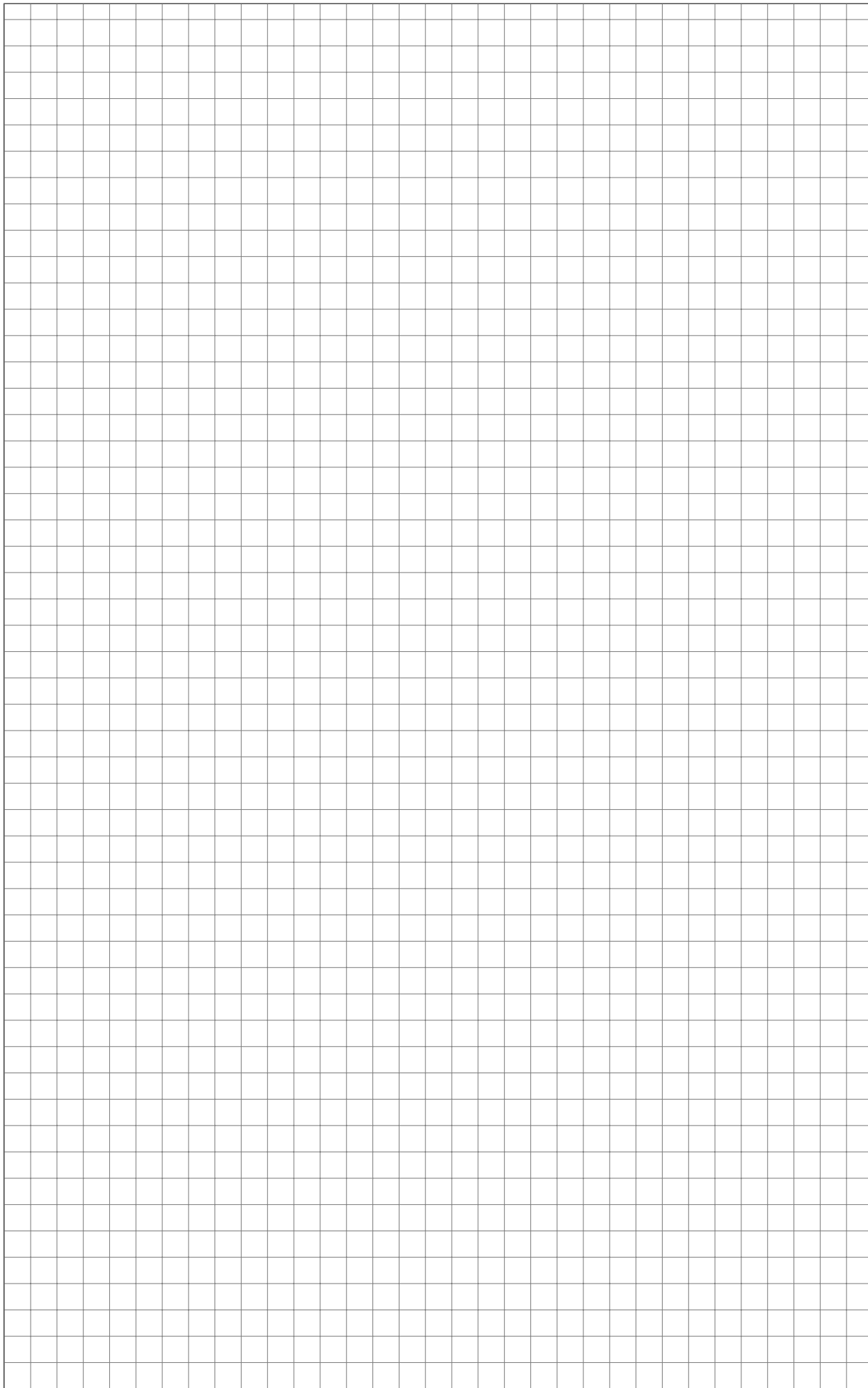


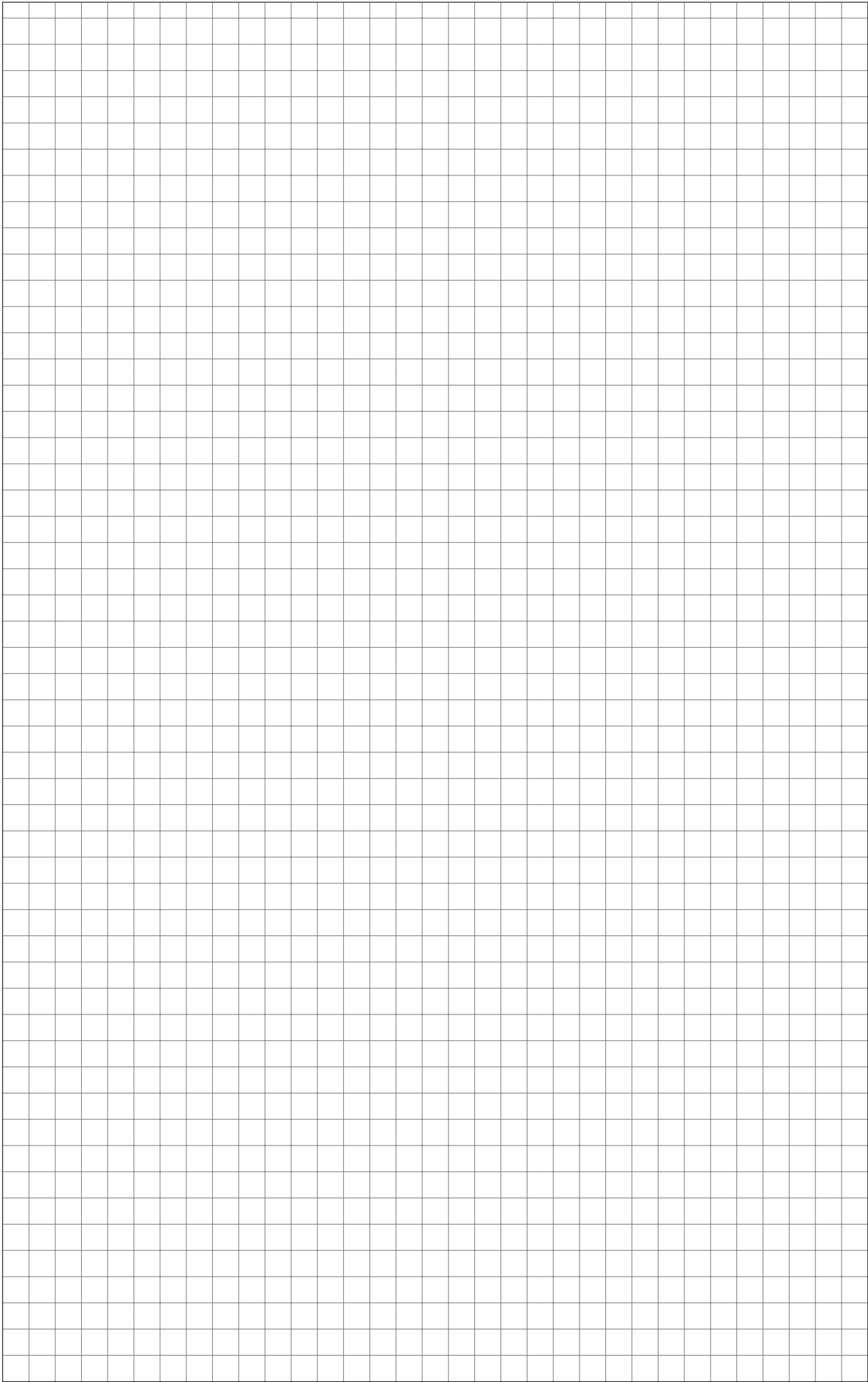
This image shows a full page of blank graph paper. The background is a very light gray, and it is covered by a precise grid of thin, medium-gray lines. The grid consists of small, equal-sized squares that extend across the entire area of the page, leaving no margins or other markings.



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