Fundamentals of Artificial Intelligence Exercise 3: Constraint Satisfaction Problems

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Recap: Constraint Satisfaction Problems (CSP)

CSP tuple (X, D, C)

- $X = \{X_1, \dots, X_n\}$ is a set of variables
- $D = \{D_1, \dots, D_n\}$ is a set of domains, where each domain D_i is the set of allowable values $\{v_1, \dots, v_k\}$ for variable X_i
- $C = \{C_1, \dots, C_m\}$ is a set of constraints (can be unary, binary or higher-order (n-ary))

Goal: Assign a value to each variable such that all constraints are satisfied

Recap: Backtracking Search

```
function Recursive-Backtracking (assignment, csp) returns sol./failure
if assignment is complete then return assignment
var \leftarrow Select-Unassigned-Variable(csp)
for each value in Order-Domain-Values(var, assignment, csp) do
   if value is consistent with assignment given Constraints[csp] then
       add \{var = value\} to assignment
       inferences \leftarrow Inference(csp.var.value)
       if inferences \neq failure then
           add inferences to assignment
           result \leftarrow Recursive-Backtracking(assignment.csp)
           if result \neq failure then return result
           remove inferences from assignment
       remove \{var = value\} from assignment
return failure
```

Important heuristics:

- Variable Selection
- Value Selection
- Inference

Recap: Variable Selection and Value Selection Heuristics

Variable Selection

- Minium Remaining Values (MRV): choose variable with the fewest possible values first
- **Degree heuristics**: choose variable that is involved in the largest number of constraints on other unassigned variables (highest degree)

Value Selection

• Least Constraining Value: choose value that rules out the fewest choices for neighboring values in the constraint graph

Recap: Inference in CSP

Inference techniques

- Forward checking (after each assignment): inconsistent values of neighboring variables are removed.
- Arc consistency algorithm (after each assignment or as pre-processing): inconsistent values of all variables are removed.

Arc consistency of a variable

 X_i is arc-consistent with X_j , if for every value in the domain D_i there exists a value in D_j satisfying the binary constraint of the arc (X_i, X_j) .

Example: Constraint: $Y = X^2$, Domains $D_X = \{0, 1, 2, 3\}$ and $D_Y = \{0, 1, 2, 3, 4, 5, 6, 7, 8, 9\}$

 \rightarrow Question: (X, Y_i) and/or (Y, X) arc-consistent?

Tweedback code: znnk (twbk.de/znnk)

Arc Consistency Algorithm

```
function AC-3 (csp, queue) returns failure or the reduced csp otherwise
inputs: csp: a binary CSP, queue: a queue of arcs (X_i, X_i)
while queue is not empty do
   (X_i, X_i) \leftarrow \text{Remove-First}(queue)
   if Remove-Inconsistent-Values(X_i, X_i) then
       if size of Domain(X_i) = 0 then return failure
       for each X_k in Neighbors [X_i] \setminus \{X_i\} do
          add (X_k, X_i) to queue
return csp
```

function Remove-Inconsistent-Values (X_i, X_i) **returns** true iff succeeds

```
removed ← false
for each x in Domain [X_i] do
   if no value y in Domain[X_i] allows (x,y) to satisfy the constraint of (X_i,X_i)
       then delete x from Domain[X_i]; removed \leftarrow true
return removed
```

Problem 3.1: Turning n-ary constraints into binary constraints

Suppose that we have
$$CSP = (X, D, E^1)$$
 with
$$X = \{A, B, C\},$$

$$D = \{\mathsf{dom}(A), \mathsf{dom}(B), \mathsf{dom}(C)\},$$

 $E = \{\langle (A, B, C), A + B = C \rangle\},\$

where each domain can be $\{0, 1, \dots, 9\}$ for example.

¹the symbol E is taken from German word Einschränkung.

Draw the constraint hypergraph for the CSP. Based on the number of variables involved, what is the type of the constraint?

$$X = \{A, B, C\},\$$

$$D = \{dom(A), dom(B), dom(C)\},\$$

$$E = \{\langle (A, B, C), A + B = C \rangle\},\$$

We can eliminate the higher-order constraint in E by replacing the constraint node \square with a new variable node Z. What is the domain for variable Z? What is the new constraint set E' after introducing the new variable Z?

$$X = \{A, B, C\},$$

$$D = \{dom(A), dom(B), dom(C)\},$$

$$E = \{\langle (A, B, C), A + B = C \rangle\},$$

$$dom(\xi) = \langle \xi_1, \xi_2, \xi_3 \rangle \quad Z_1 = dom(A) \quad (A) \quad (B) \quad (B) \quad (B) \quad (C) = dom(C)$$

$$E = \langle (\xi_1, K), \xi_1 = K \rangle \quad (C_{22}, B), \quad (C_{23}, C), \quad (C_{23}, C), \quad (C_{23}, C) \quad (C_{23}, C), \quad (C_{23}, C), \quad (C_{23}, C) \quad (C_{23}, C), \quad (C_{23}$$

 $X = \{A, B, C\},\$

Modify CSP' such that it only contains binary constraints and formally express the new CSP'' = (X'', D'', E'').

$$CSP'' = (X'', D'', E'').$$

$$X = \{A, B, C\},$$

$$D = \{dom(A), dom(B), dom(C)\},$$

$$E = \{((A, B, C), A + B = C)\},$$

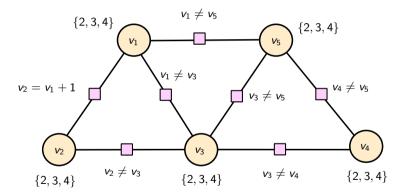
$$CSP'' = (X'', D'', E'').$$

$$CSP'' = (X'', D'',$$

Taking inspiration from previous solutions, how can you generally turn a *n*-ary constraint into binary constraints?

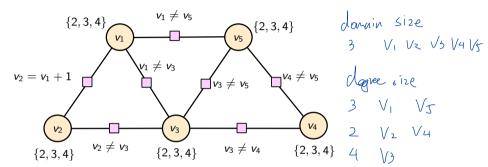
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Consider the constraint satisfaction problem in the figure below.



 \rightarrow only binary constraints.

Problem 3.2.1: Sort variables by domain size and by degree



Problem 3.2.2: Perform Backtracking Search by Hand

Variable selection:

Variable to expand next: apply minimum-remaining-values (MRV) heuristic; if there is a tie, use degree heuristics; if there is a tie again, choose the variable with the lower index.

Value selection:

Value to assign next: use least-constraining-value heuristics; if there is a tie, choose number 3; if this is not possible choose the lowest value.

Inference:

After each assignment: perform forward checking as inference. Backtrack if you find an inconsistency.

Problem 3.2.2: Perform Backtracking Search by Hand

| | | | degree | | | | | backtrack to | | | | |
|---|--------------|----------------------|-------------|------------|-----------------------|-----------------------|-------|--------------------------|------------|------------------|--------------------|--|
| step | assign | v_1 | V 2 | V 3 | <i>V</i> ₄ | <i>V</i> ₅ | v_1 | V 2 | V 3 | <i>V</i> 4 | V 5 | |
| 2 | / | 234 | 234 | 234 | 234 | 234 | 3 | 2 | 4 | 2 | 3 | _ |
| 1 | V3 /2 | xe 3 24 | 24 | | 24 | 24 | 2 | 1 | _ | (| 2 | |
| 2 | (V) :" | dex / | Ø | | | | | • | | _ | | 2 |
| 5 | V1=4 | / | ϕ | | | | | | | | | |
| (| 1037= | 2 34 | 34 | / | 34 | 34 | 2 | ι | _ | ı | ۷ | |
| 2 | √ ‡ = | 3 / | 4 | | 34 | 4 | _ | 0 | _ | ر {2, 3, 4 | | $\gamma_1 \neq \nu_5$ |
| 3 | V5= tie | 4 / | 4 | / | > | | _ | - <i>O</i> _{v2} | $= v_1 +$ | 0 | | $\neq v_3$ $v_3 \neq v_5$ $v_4 \neq v_5$ |
| | | ightarrow Degree $-$ | | 4 | 1/2 = 4 | | | | | | \ | |
| Value: least constr. value $\rightarrow 3 \rightarrow$ lowest value Inference: forward checking | | | | | | | | | | | | |
| | | _ | | ্ | 5 V4 = 3 | | | | | 4} ^{v2} | ≠ v ₃ ∫ | $\{2,3,4\}$ $v_3 \neq v_4$ $\{2,3,4\}$ |
| I weedba | ack code | e: znnk (twł | ok.de/znnkj |) | | | | | 12, 3, | 41 | ι | 2,5,7, |

Problem 3.2.3: Perform Backtracking Search by Hand

Variable selection:

Variable to expand next: apply minimum-remaining-values (MRV) heuristic; if there is a tie, use degree heuristics; if there is a tie again, choose the variable with the lower index.

Value selection:

Value to assign next: use least-constraining-value heuristics; if there is a tie, choose number 3; if this is not possible choose the lowest value.

Inference:

After each assignment: perform arc consistency algorithm. Backtrack if you find an inconsistency.

Problem 3.2.3: Perform Backtracking Search by Hand

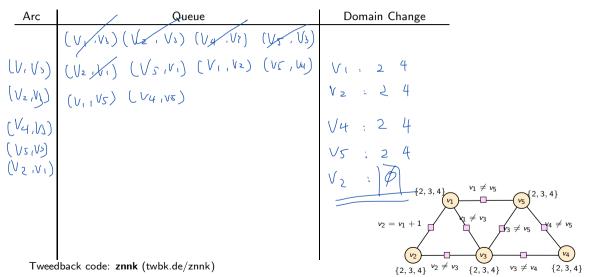
| | | curre | nt domains | ; | | | d | egree | <u>:</u> | | backtrack to |
|---------------|-------------------------------|-------------|------------|-----|-----------------|-------|-------------------------|-----------------------|-----------------|-----------------------|-------------------------------|
| step assign | v_1 | V 2 | V 3 | V4 | V 5 | v_1 | v ₂ | <i>V</i> ₃ | <i>V</i> 4 | <i>V</i> ₅ | |
| 0 / | 234 | 234 | 234 | 234 | 2341 | } | 2 | 4 | 2 | 3 | |
| 1 /3=3 | 24 | 24 | / | 24 | 2 4 | 2 | ι | _ | 1 | 2 | |
| 1 N3=5 | 3 | 4 | / | 3 | 4 | 2 | 1 | _ | | 1 2 | (|
| 2 V,-> | / | 4 | | 3 | 4 | - | D | _ | | 1 1 | |
| 3 V4=3 | | 4 | | | 4 | _ | - 0 | | | - 0 | |
| 4 Vz=4 | | | | | $ \leftarrow $ | _ | | _ | _ | - ō |) L ≠ v ₅ |
| 5 VT=4 | | | | , | | | _ | <u> </u> | [2, 3, <u>4</u> | | |
| | | | | | | | <i>v</i> ₂ : | = v ₁ + | 1 | \r_ ≠ | $v_3 \neq v_5$ $v_4 \neq v_5$ |
| Variable: MRV | ightarrow Degree $ ightarrow$ | lower index | | | | | | | < | _ ' | |

Value: least constr. value \rightarrow 3 \rightarrow lowest value

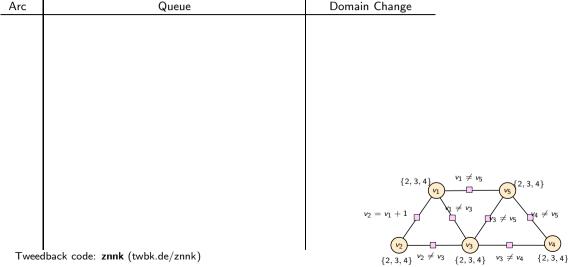
Inference: arc consistency algorithm

{2, 3, 4}

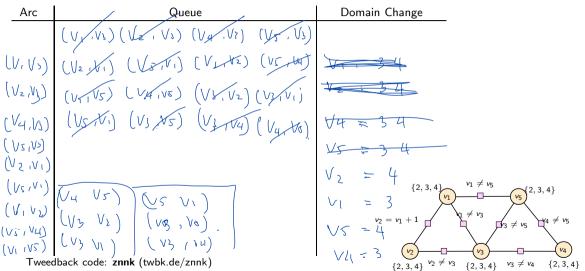
Problem 3.2.3: Perform Backtracking Search by Hand (AC-3)



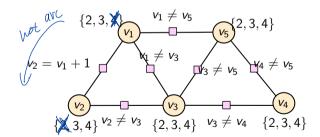
Problem 3.2.3: Perform Backtracking Search by Hand (AC-3)



Problem 3.2.3: Perform Backtracking Search by Hand (AC-3)



Consider the constraint satisfaction problem at its initial state. Is the CSP arc consistent? Is this a convenient initial condition if we plan to apply backtracking search? Describe the domains after the arc consistency algorithm has been applied to the CSP as a preprocessing step.



Tweedback code: znnk (twbk.de/znnk)

New, arc-consistent CSP:

Problem 3.2.5: Backtracking Search after Preprocessing

Variable selection:

Variable to expand next: apply minimum-remaining-values (MRV) heuristic; if there is a tie, use degree heuristics; if there is a tie again, choose on randomly.

Value selection:

Value to assign next: use least-constraining-value heuristics; if there is a tie, choose choose one randomly.

Inference:

After each assignment: perform arc consistency algorithm. Backtrack if you find an inconsistency.

Assume the data structure of the queue is a set, i.e., if we add an element to the queue which is already in the queue, the element will not be added a second time (each element is unique).

Problem 3.2.5: Backtracking Search after Preprocessing

| | | | 1 | (| degree | backtrack to | | | | | | |
|------|--------|-------|------------|-----------------------|------------|-----------------------|-------|------------|------------|------------|------------|--|
| step | assign | v_1 | V 2 | <i>V</i> ₃ | <i>V</i> 4 | <i>V</i> ₅ | v_1 | V 2 | V 3 | <i>V</i> 4 | V 5 | |
| 0 | \ | 23 | 34 | 234 | 234 | 234 | 3 | 2 | 4 | 2 | 3 | |

Variable: MRV → Degree → randomly Value: least constr. value → randomly Inference: arc consistency algorithm Tweedback code: znnk (twbk.de/znnk)

 $v_{2} = v_{1} + 1$ $v_{1} \neq v_{3}$ $v_{3} \neq v_{5}$ $v_{3} \neq v_{5}$ $v_{4} \neq v_{5}$ $v_{3} \neq v_{5}$ $v_{4} \neq v_{5}$ $v_{3} \neq v_{4}$ $v_{4} \neq v_{5}$ $v_{2} \neq v_{3}$ $v_{3} \neq v_{4}$ $v_{3} \neq v_{4}$ $v_{4} \neq v_{5}$ $v_{5} \neq v_{5}$

Problem 3.2.5: Backtracking Search after Preprocessing (AC-3)

| Arc Queue Domain Change | |
|---|-----------|
| (N21N1) (N3/N2) (N3/N3) (N4/N3) (N4/N3) N3=34 | |
| | |
| $(V_L)^{(l)}$ | |
| $\begin{pmatrix} \Lambda^{2} & \Lambda^{1} \\ (\Lambda^{2} & \Lambda_{2} \end{pmatrix} = \begin{pmatrix} \Lambda^{4} & \Lambda^{2} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda_{1} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda^{2} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda^{2} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda^{2} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda^{2} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda^{2} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda^{2} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda^{2} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda^{2} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} & \Lambda^{2} \end{pmatrix} = \begin{pmatrix} \Lambda^{3} & \Lambda^{2} \\ (\Lambda^{2} &$ | |
| (V), (V2) (V4, (V3)) V3=4 | |
| (1242) | |
| (64, 61/ | |
| $\{2,3\}$ $v_1 \neq v_5$ $v_2 \neq v_3$ | {2, 3, 4} |
| $v_2 = v_1 + 1$ v_3 $v_3 \neq v_3$ $v_3 \neq v_4$ | V5 |
| To continue to control (both) do (control | |

Tweedback code: znnk (twbk.de/znnk)

For each of the previous performances of backtracking search with a different inference compare the number of iterations and the number of times you needed to backtrack.

Forward checking (3.2.2):

Arc Consistency Algorithm (3.2.3):

Arc Consistency Algorithm after preprocessing (3.2.5):