

Exercise 5

Exercise 4

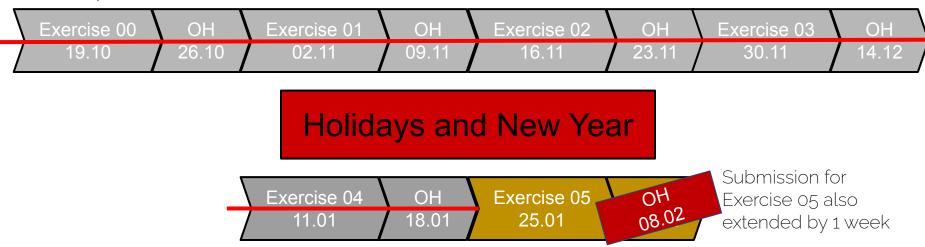
• 1 week extension due to submission problems

 please download the exercise folder again if you could not complete the exercise

 please reevaluate the exercise if you have gotten a low score of around 60/100 points

About the Exercise Session

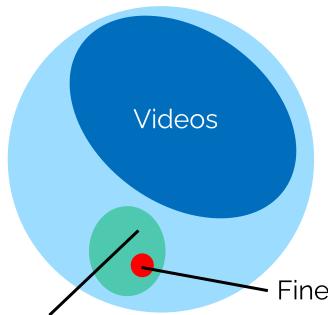
 2 weeks for each exercise + Office hours (OH) for questions in between



Deadline always 23:59 CET on due date

Recap: Unsupervised Segmentation

Real image data



- only a small part of the available image data is labelled
- only a small part of the labelled data has fine grained (pixel-level) annotations
- the vast majority of data is unlabelled

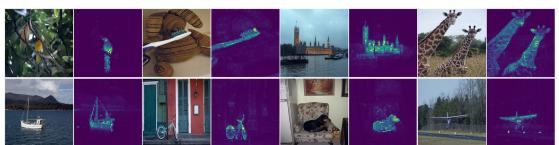
=> try to leverage all available data for your task

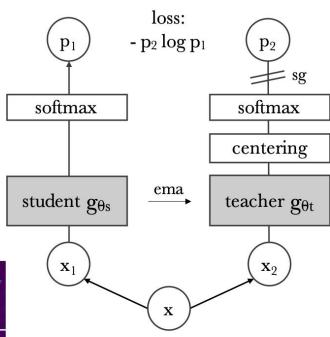
Fine Annotation

Coarse Annotation (e.g. image-level labels)

Recap: DINO

- You already used pretrained unsupervised
 (self-supervised) features
- get good results with little training effort on downstream tasks



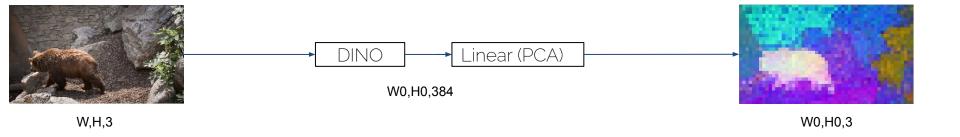


Caron et al. "Emerging Properties in Self-Supervised Vision Transformers"

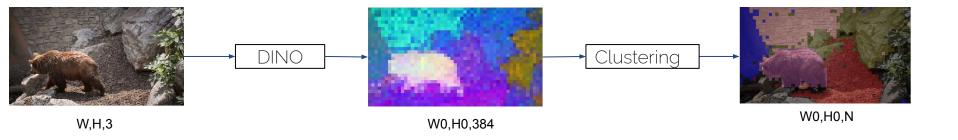
Exercise 5

- Object Segmentation via Clustering algorithms
- No supervision available
- Pretrained powerful image embeddings (learned with self-supervision)
- Comparing different methods for unsupervised clustering
 - k-Means
 - Gaussian Mixture Models
 - Spectral Clustering

DINO: Self Supervised Learning



Exercise 5: No Supervision



$$E(\{\boldsymbol{\mu}_1,\ldots\boldsymbol{\mu}_K\},\boldsymbol{Z}) = \sum_{i=1}^N \sum_{k=1}^K z_{ik} d(\boldsymbol{x}_i,\boldsymbol{\mu}_k)$$

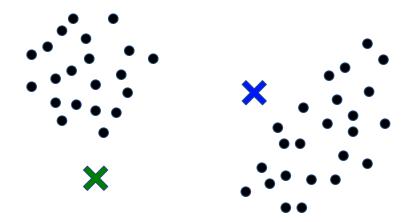
$$\min_{\boldsymbol{Z}} E(\{\boldsymbol{\mu}_1,\ldots\boldsymbol{\mu}_K\},\boldsymbol{Z})$$

 $z_i k = \begin{cases} 1 & \text{if } k = \arg\min_j \|\boldsymbol{x}_i - \boldsymbol{\mu}_j\|^2 \\ 0 & \text{else.} \end{cases}$

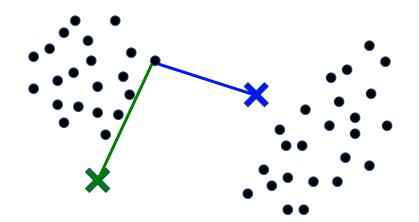
$$\mu_k = \frac{1}{N_k} \sum_{i=1}^{N} z_{ik} \boldsymbol{x}_i, \quad \text{where } N_k = \sum_{i=1}^{N} z_{ik}$$

 $D_i^2 = \min\{\|oldsymbol{x}_i - oldsymbol{\mu}_1\|^2, \dots, \|oldsymbol{x}_i - oldsymbol{\mu}_k\|^2\}$

O. initialize the centers

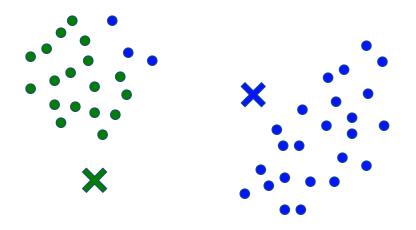


1. calculate the distance to the centers

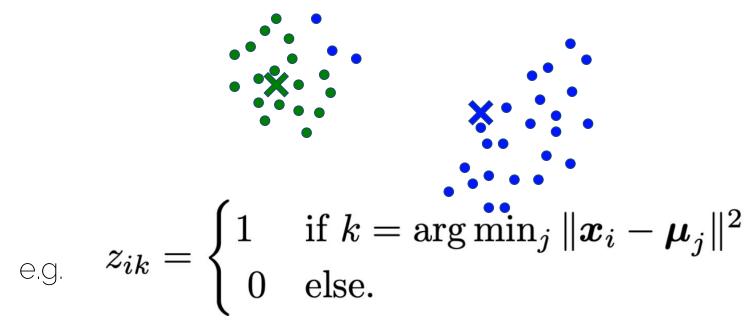


eg
$$D_i^2 = \min\{\|m{x}_i - m{\mu}_1\|^2, \dots, \|m{x}_i - m{\mu}_k\|^2\}$$

2. assign datapoints to centers based on distance

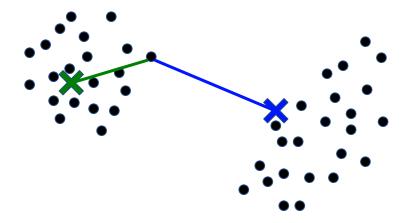


3. calculate new centers

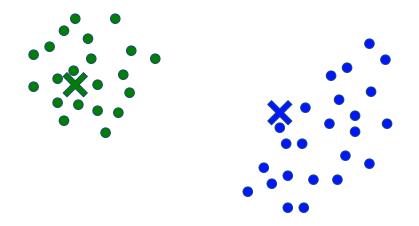


CV3DST

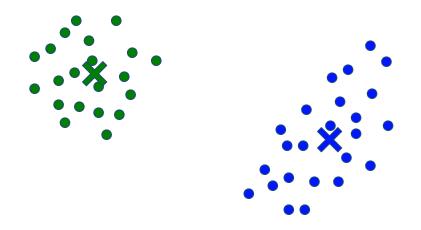
1. calculate the distance to the centers



2. assign datapoints to centers based on distance



3. calculate new centers



k-Means in formulas

Cost Function
$$E(\{\boldsymbol{\mu}_1,\ldots\boldsymbol{\mu}_K\},\boldsymbol{Z}) = \sum_{i=1}^{N} \sum_{k=1}^{N} z_{ik} d(\boldsymbol{x}_i,\boldsymbol{\mu}_k)$$

Objective

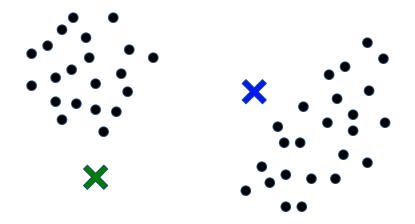
$$\min_{\boldsymbol{Z}} E(\{\boldsymbol{\mu}_1, \dots \boldsymbol{\mu}_K\}, \boldsymbol{Z})$$

1. Assign points
$$z_{ik} = \begin{cases} 1 & \text{if } k = \arg\min_j \|\boldsymbol{x}_i - \boldsymbol{\mu}_j\|^2 \\ 0 & \text{else.} \end{cases}$$

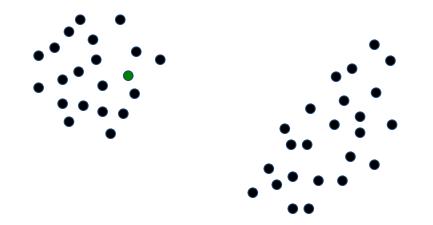
centroids

2. Recalculate centroids
$$\mu_k = \frac{1}{N_k} \sum_{i=1}^N z_{ik} \boldsymbol{x}_i$$
, where $N_k = \sum_{i=1}^N z_{ik}$

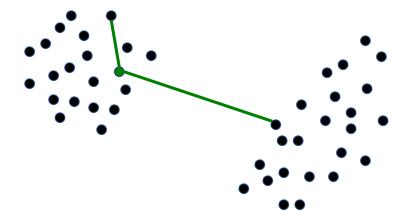
How to initialize the centers?



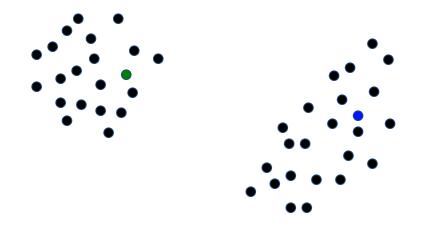
1. choose a random datapoint as the first center



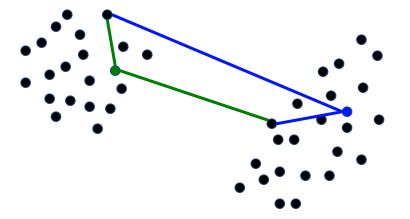
2. compute the minimum distance of all datapoint to all centers



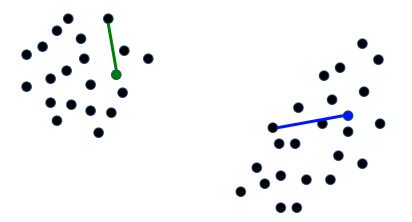
3. choose the next centroid from a categorical sampling



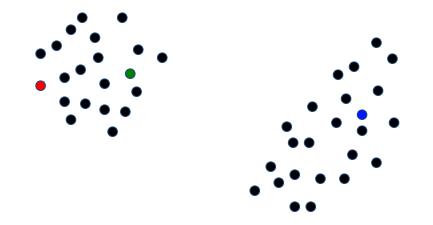
2. compute the minimum distance of all datapoint to all centers



2. compute the minimum distance of all datapoint to all centers

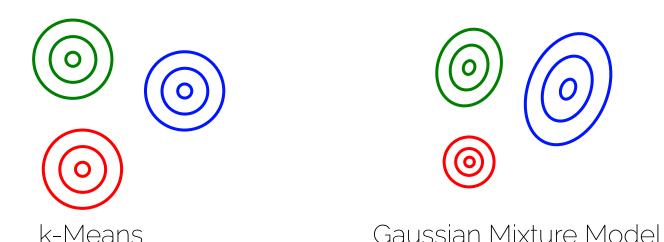


3. choose the next centroid from a categorical sampling



Gaussian Mixture Models

- K-Means is limited in its expressiveness
- Can we add additional degrees of freedom to our model to more accurately represent our data?



Difference

- k-Means models the probability of a datapoint belonging to a class only on the centroids of the clusters
- Gaussian Mixture Models model the probability as

$$p(z_{ik} = 1) = \frac{\pi_k \mathcal{N}(\boldsymbol{x}_i | \boldsymbol{\mu}_k, \boldsymbol{\Sigma}_k)}{\sum_{j=1}^K \pi_j \mathcal{N}(\boldsymbol{x}_i | \boldsymbol{\mu}_j, \boldsymbol{\Sigma}_j)}$$

• GMMs are equivalent to k-Means if all responsibilities are equal and the covariances are identity matrices

GMMs calculate the parameters

- GMMs are commonly solved by using the expectation-maximization algorithm
- E-step

$$p(z_{ik} = 1) = \frac{\pi_k^{(t)} \mathcal{N}(\boldsymbol{x}_i | \boldsymbol{\mu}_k^{(t)}, \boldsymbol{\Sigma}_k^{(t)})}{\sum_{j=1}^K \pi_j^{(t)} \mathcal{N}(\boldsymbol{x}_i | \boldsymbol{\mu}_j^{(t)}, \boldsymbol{\Sigma}_j^{(t)})}$$

• M-Step Responsibilities
$$N_k = \sum_{i=1}^N p(z_{ik} = 1) \qquad \boldsymbol{\mu}_k^{(t+1)} = \frac{1}{N_k} \sum_{i=1}^N p(z_{ik} = 1) \boldsymbol{x}_i$$
 Centroids
$$\boldsymbol{\Sigma}^{(t+1)} = \frac{1}{N_k} \sum_{i=1}^N p(z_{ik} = 1) \boldsymbol{x}_i$$

$$oldsymbol{\Sigma}_k^{(t+1)} = rac{1}{N_k} \sum_{i=1}^N p(z_{ik} = 1) (oldsymbol{x}_i - oldsymbol{\mu}_k^{(t+1)}) (oldsymbol{x}_i - oldsymbol{\mu}_k^{(t+1)})^ op \qquad \pi_k^{(t+1)} = rac{N_k}{N}$$

Covariances

Mixing Coefficients

Spectral Clustering

- spectral clustering is a unsupervised segmentation methods build upon spectral graph theory
- given a undirected graph

$$G = (V, E)$$

with its adjacency matrix

$$W = w(u, v) : (u, v) \in E$$

we can segment the graph based on the eigenvalues and eigenvectors of the Laplacian

$$L=D-W$$
 where D s the row-wise sum of W

How to cluster?

- foreground-background segmentation
 - 1. Calculate the eigenvectors of the Laplacian
 - 2. Select the **second** eigenvector
 - 3. Threshold the eigenvector
- there are more ways to cluster for
 - object localization
 - multi-class segmentation

We refer you to the original paper/code for more details

But we are working with images?

- Construct an adjacency matrix from the image
- We follow <u>Deep Spectral Methods</u>

$$W_{\mathrm{knn}}(u,v) = \begin{cases} 1 - \|\psi(u) - \psi(v)\|, & u \in \mathrm{KNN}_{\psi}(v), \\ 0, & \text{otherwise,} \end{cases}$$

$$W_{ ext{feat}} = oldsymbol{f} oldsymbol{f}^{ op} \odot (oldsymbol{f} oldsymbol{f}^{ op} > 0)$$
 $W = W_{ ext{feat}} + \lambda W_{ ext{knn}}$

and have a image- and learning-based part

Melas-Kyriazi et al., Deep Spectral Methods: A Surprisingly Strong Baseline for Unsupervised Semantic Segmentation and Localization, CVPR 2022

Image based adjacency

$$W_{\mathrm{knn}}(u,v) = \begin{cases} 1 - \|\psi(u) - \psi(v)\|, & u \in \mathrm{KNN}_{\psi}(v), \\ 0, & \text{otherwise,} \end{cases}$$

$$\psi(u) = (\cos(c_H(u)), \sin(c_H(u)), c_S(u), c_V(u), p_x(u), p_y(u))$$
 color values from the HSV color space (p_x, p_y)

Feature based adjacency

$$W_{ ext{feat}} = oldsymbol{f} oldsymbol{f}^ op \odot (oldsymbol{f} oldsymbol{f}^ op > 0)$$

- $m{f}$ deep image feature e.g. DINO
- as the deep image features restrict the resolution, we have to adapt the resolution of the image-based adjacency
- ullet this also reduces the size of W significantly
- additional post processing steps (e.g. CRFs) increases resolution and can improve results even further

Downsides

- low resolution of the segmentation without post-processing
- k-Means and GMMs are initialization dependent
 -> k-means++ does not solve it completely
- number of clusters is a hyperparameter to tune
 spectral clustering is able to adapt on the fly

Links

- Test server: <u>https://cv3dst.cvai.cit.tum.de/login</u>
- If you have trouble registering <u>https://forms.gle/yZkZiDiyHxWuNqQG7</u>
- Data for Exercise 04: <u>https://vision.in.tum.de/webshare/g/cv3dst/exercise_05.zip</u>

Links for the individual datasets

- MOT
 https://vision.in.tum.de/webshare/g/cv3dst/datasets/MO
 T16.zip
- market <u>https://vision.in.tum.de/webshare/g/cv3dst/datasets/market.zip</u>
- obj_seg
 https://vision.in.tum.de/webshare/g/cv3dst/datasets/obj_seg.zip
- reid_gnn https://vision.in.tum.de/webshare/g/cv3dst/datasets/reid _gnn.zip