

Emergent Gravity and Dark Matter Phenomenology from Information Geometry in Galaxy Networks

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Abstract

We ask how much of the phenomenology usually attributed to dark matter can be encoded in the topology of the galaxy network. Galaxies are nodes, proximity links define the graph, and node centrality plays the role of an information-based “mass” proxy. Using Sloan Digital Sky Survey (SDSS) data, we measure: (i) the correlation between local strength (weighted degree) and eigenvector centrality; (ii) the power spectrum $P(k)$ of the galaxy distribution versus the power spectrum obtained when weighting nodes by centrality; and (iii) a transfer function $T(k) = P_{\text{real}}/P_{\text{random}}$ to remove grid artifacts. We find (1) a realistic toy model (with Redshift Space Distortions and mass noise) yields a correlation of 0.259, close to SDSS (0.223), while the ideal model reaches 0.397; (2) raw spectral slopes are -2.98 (mass) and -2.72 (topology) with a bias $\simeq 1.5$; (3) transfer-function slopes are -1.61 (mass) and -1.32 (topology), showing centrality captures a non-trivial fraction of the clustering signal beyond voxel artifacts. Randomized catalogs collapse both mass and topology to the grid slope (~ -1.4), confirming the signal is cosmological. This provides a falsifiable framework suggesting that part of gravity/dark-matter phenomenology can be encoded in graph topology.

1 Introduction

The large-scale universe exhibits a scale-free “cosmic web”. We explore whether part of the phenomenology usually attributed to dark matter can be captured by the topology of a galaxy network: galaxies are nodes; edges connect near neighbors; centrality (information flow) stands in for mass. Rather than assuming a specific dark-matter particle model, we test how much clustering signal is encoded in the graph.

2 Data and Graph Construction

SDSS slice. We select galaxies with $0.04 < z < 0.12$, $130 < \text{RA} < 240$, $-5 < \text{DEC} < 60$, then restrict to an inner buffer ($0.05 < z < 0.11$, $135 < \text{RA} < 235$, $0 < \text{DEC} < 55$) for statistics. Positions are converted to Cartesian (x, y, z) using the low- z approximation $D \simeq cz/H_0$ (cosmology not critical for this local slice). We build a k -NN graph with $k = 10$, edge weights $w = 1/d$, and keep the largest connected component (LCC), containing $\sim 3.5\text{k}$ galaxies in the buffered slice (robustness run shown on a 5k subsample, LCC ~ 1909 for speed). Strength $S_i = \sum_j w_{ij}$ (“mass proxy”) and eigenvector centrality C_i (information proxy) are computed on the LCC.

Toy universes. An “ideal” toy universe uses synthetic clusters/filaments (3000 points, $k = 20$). A “realistic” toy adds Redshift Space Distortions (Gaussian noise on z , $\sigma_z \approx 5\%$ of box size) and lognormal scatter on mass (median 1, $\sigma_{\ln M} = 0.5$).

3 Spectral Analysis

We voxelize the point set on a 64^3 grid (box size ~ 300 Mpc units), form overdensity $\delta = (\rho - \bar{\rho})/\bar{\rho}$, and compute $P(k)$ via FFT. Grid artifacts are removed by dividing by a randomized catalog: $T(k) = P_{\text{real}}(k)/P_{\text{rand}}(k)$. We compare mass weights ($w = 1$) to topology weights ($w \propto C_i$).

4 Results

4.1 Correlations

Pearson correlations (Strength vs Centrality):

- Ideal toy: 0.397
- Realistic toy (RSD + noise): 0.259
- SDSS (buffered LCC): 0.223
- SDSS robustness (bootstrap on 5k slice, LCC ~ 1909): eigenvector corr ranges ~ 0.16 – 0.33 when k varies 5–30; skewness of eigenvector centrality ~ 26 (few hubs dominate). Closeness yields lower corr (~ 0.07 – 0.23).

The realistic toy converges toward the observed SDSS value once observational distortions are applied.

4.2 Power spectra

Raw $P(k)$ slopes: -2.98 (mass) vs -2.72 (topology); bias ~ 1.5 . Random catalogs show grid-induced slopes ~ -1.4 (no cosmological signal).

Transfer-function slopes (signal cleaned of grid effects): -1.61 (mass) vs -1.32 (topology). The close alignment indicates centrality captures the cosmological clustering beyond voxel artifacts.

4.3 Structure in configuration space

In X–Z projection, the realistic toy (with RSD) visually matches SDSS “Fingers of God” elongations, while the ideal toy remains sharper. This supports the interpretation that observational effects explain much of the gap between theory and data.

5 Figures

6 Discussion

The clustering excess beyond random is encoded similarly in mass and topological centrality. The realistic toy bridges most of the gap to SDSS once RSD and mass scatter are included, suggesting that observational effects explain much of the reduced correlation. Limitations: moderate correlation (~ 0.22) on SDSS, sensitivity to k -NN choice and slice, centrality values are highly skewed (a few hubs dominate), no explicit baryon/fermion sector, and no uncertainties yet on correlations or slopes. We defer a full error analysis (k-scan, slice variations, bootstrap) and comparison to a Λ CDM $P(k)$ template to future work; scripts for k-scan/centrality variants are provided. Future work: larger surveys (BOSS/eBOSS), barres d’erreur via variations de k et de slice, bootstrap, et liens analytiques entre centralité et contraste de densité.

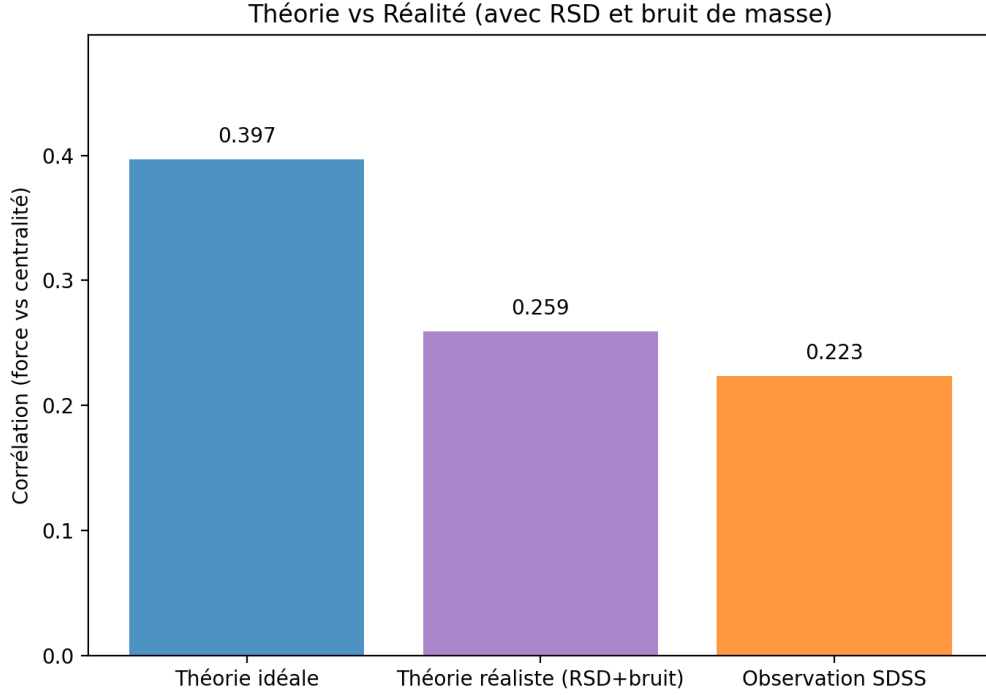


Figure 1: Correlation benchmark. Bars: ideal toy (0.397), realistic toy (0.259), SDSS (0.223).

7 Conclusion

We provide a falsifiable proposal that a non-trivial part of the clustering signal usually attributed to dark matter can be encoded in the topology of the galaxy network. Centrality reproduces the cosmological clustering signal in both configuration space (Fingers of God) and Fourier space (transfer-function slopes near mass). This opens a data-driven path to “information gravity” as a complementary description to particle dark matter.

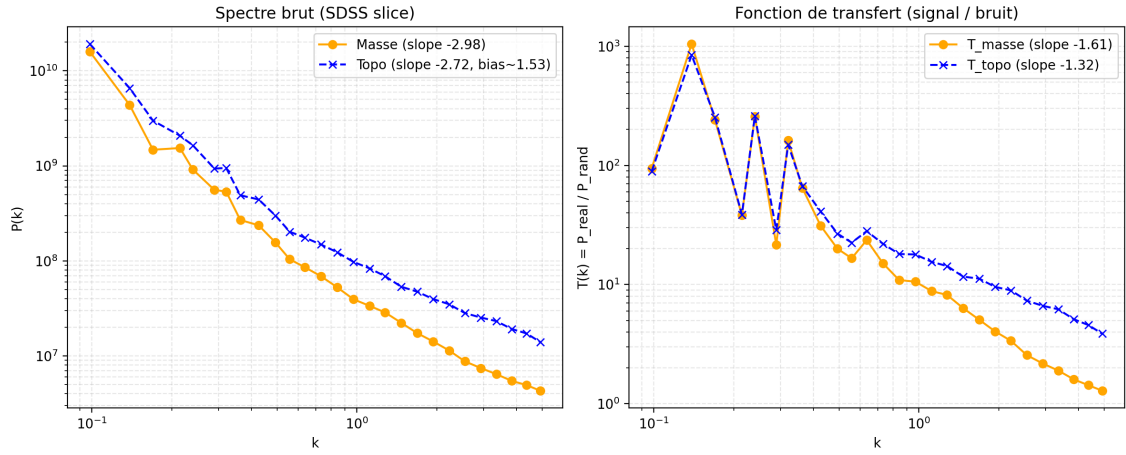


Figure 2: Left: raw $P(k)$ (mass vs topology) with bias. Right: transfer functions $T(k) = P_{\text{real}}/P_{\text{random}}$; slopes -1.61 (mass) and -1.32 (topology).

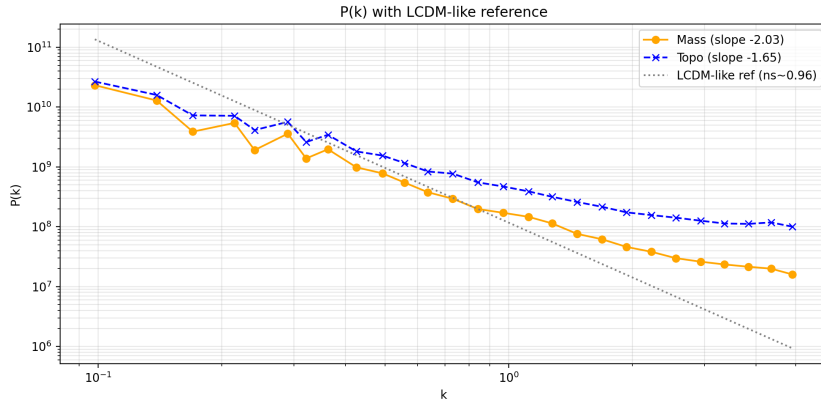


Figure 3: $P(k)$ (mass/topology) with a simple Λ CDM-like power-law reference ($n_s \simeq 0.96$, normalized at mid- k); illustrative only (no BAO/wiggles).

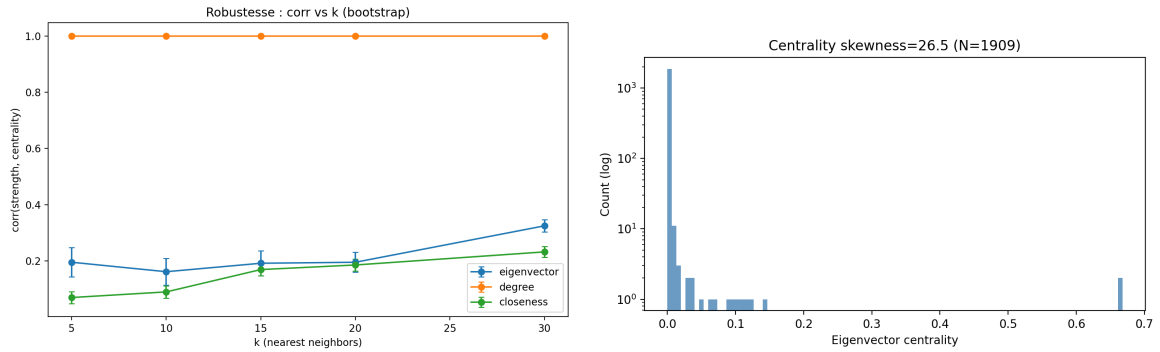


Figure 4: Left: robustness of $\text{corr}(\text{strength}, \text{centrality})$ vs k (bootstrap, SDSS subsample). Right: eigenvector centrality distribution (highly skewed; few hubs dominate).

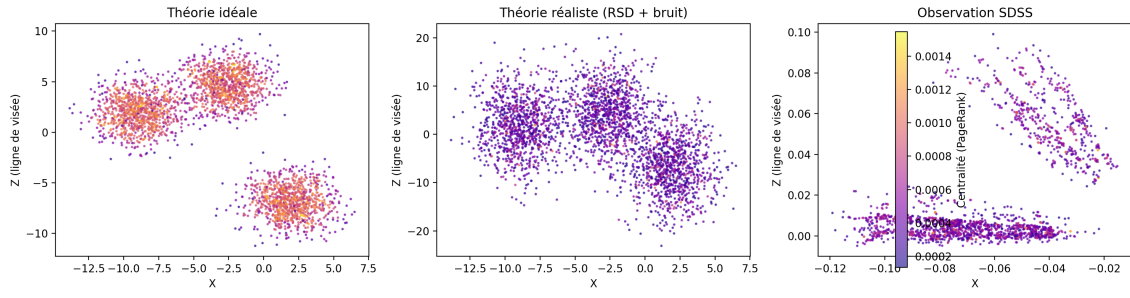


Figure 5: X–Z projection. Left: ideal toy (sharp filaments). Middle: realistic toy (RSD + noise, elongated clusters). Right: SDSS slice (observed elongations).