

# Multidisciplinary Design and Optimization of a Distributed Electric Propulsion UAV with Hybrid-Electric Power Architecture

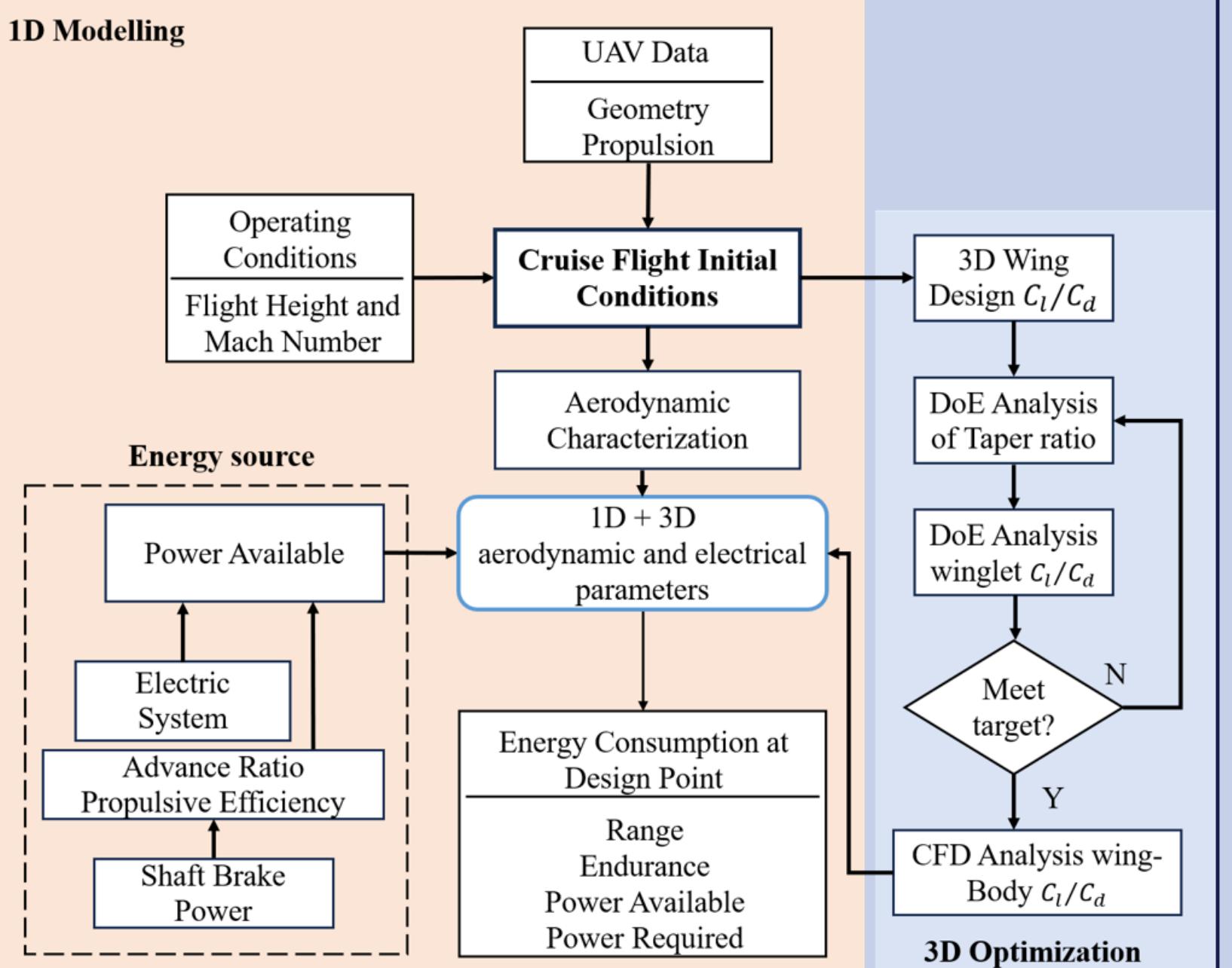
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## Background

In order to meet the key target of zero-emission aviation for cleaner and environmentally sustainable air transport, there is an increasing demand for novel propulsion architectures. For electric propulsion systems, one key challenge is the long endurance of flights. This project focuses on 3 key target;

1. Design and implement a **distributed-electric propulsion (DEP)** system for high  $C_l/C_d$  value.
2. Develop a mathematical model for estimating the performance of DEP using **hybrid-electric architecture**.
3. Optimize the **endurance** of the UAV using the mathematical model and CFD results

## Methodology



## Aircraft Dynamics

### Nonlinear State-Space Model for DEP Aircraft

#### Aerodynamic Forces

Aerodynamic force coefficients (simplified):

$$C_X = C_{X0} + C_{X\alpha}\alpha + C_{m\delta_e}\delta_e$$

$$C_Y = C_{Y0} + C_{Y\beta}\beta + C_{n\delta_r}\delta_r$$

$$C_Z = C_{Z0} + C_{Z\alpha}\alpha + C_{m\delta_e}\delta_e$$

$$F_x^{\text{aero}} = \bar{q}_{\text{avg}} S C_X, \quad F_y^{\text{aero}} = \bar{q}_{\text{avg}} S C_Y, \quad F_z^{\text{aero}} = \bar{q}_{\text{avg}} S C_Z$$

#### Aerodynamic Moments

Moment coefficients:

$$C_l = C_{l0} + C_{l\beta}\beta + C_{l\alpha}\frac{pb}{2V} + C_{ls\delta_a}\delta_a$$

$$C_m = C_{m0} + C_{m\alpha}\alpha + C_{m\beta}\frac{qc}{2V} + C_{ms\delta_e}\delta_e$$

$$C_n = C_{n0} + C_{n\beta}\beta + C_{n\alpha}\frac{rb}{2V} + C_{ns\delta_r}\delta_r$$

$$L^{\text{aero}} = \bar{q}_{\text{avg}} S b C_l, \quad M^{\text{aero}} = \bar{q}_{\text{avg}} S c C_m, \quad N^{\text{aero}} = \bar{q}_{\text{avg}} S b C_n$$

#### Kinematics

$$V = \sqrt{u^2 + v^2 + w^2}$$

$$\alpha = \tan^{-1} \left( \frac{w}{u} \right)$$

$$\beta = \sin^{-1} \left( \frac{v}{V} \right)$$

#### Motor Dynamics

For each motor  $j = 1, \dots, n$ :

$$\dot{i}_j = -Ri_j - k_e \omega_j + V_j$$

$$\dot{\omega}_j = \frac{k_t i_j - (\text{damping} + k_Q |\omega_j|) \omega_j}{J}$$

## Battery Model

## Electric Generator

## Gas Turbine

$$P_b = g(P_c),$$

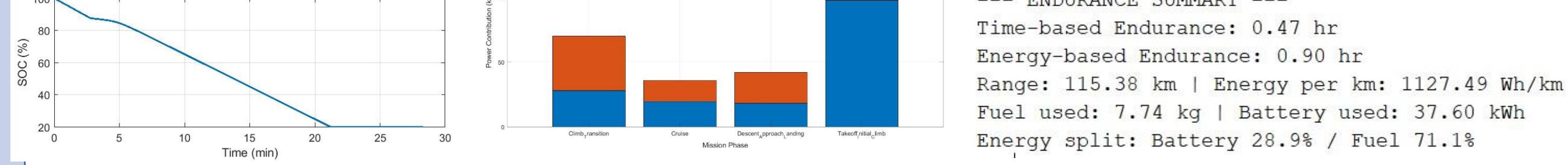
$$= \frac{U^2}{2R} \left( 1 - \sqrt{1 - \frac{4R}{U^2} P_c} \right)$$

$$P_{\text{gt}} = h_{\text{gen}}(P_{\text{gen}}(t), \omega_{\text{gen}}(t)),$$

$$= \nu_2(\omega_{\text{gen}}) P_{\text{gen}}^2 + \nu_1(\omega_{\text{gen}}) P_{\text{gen}} + \nu_0(\omega_{\text{gen}})$$

$$\dot{m} = -\varphi = -f(P_{\text{gt}}(t), \omega_{\text{gt}}(t))$$

## Validation of Energy Management Model for Hybrid-Electric Propulsion



--- ENDURANCE SUMMARY ---

Time-based Endurance: 0.47 hr

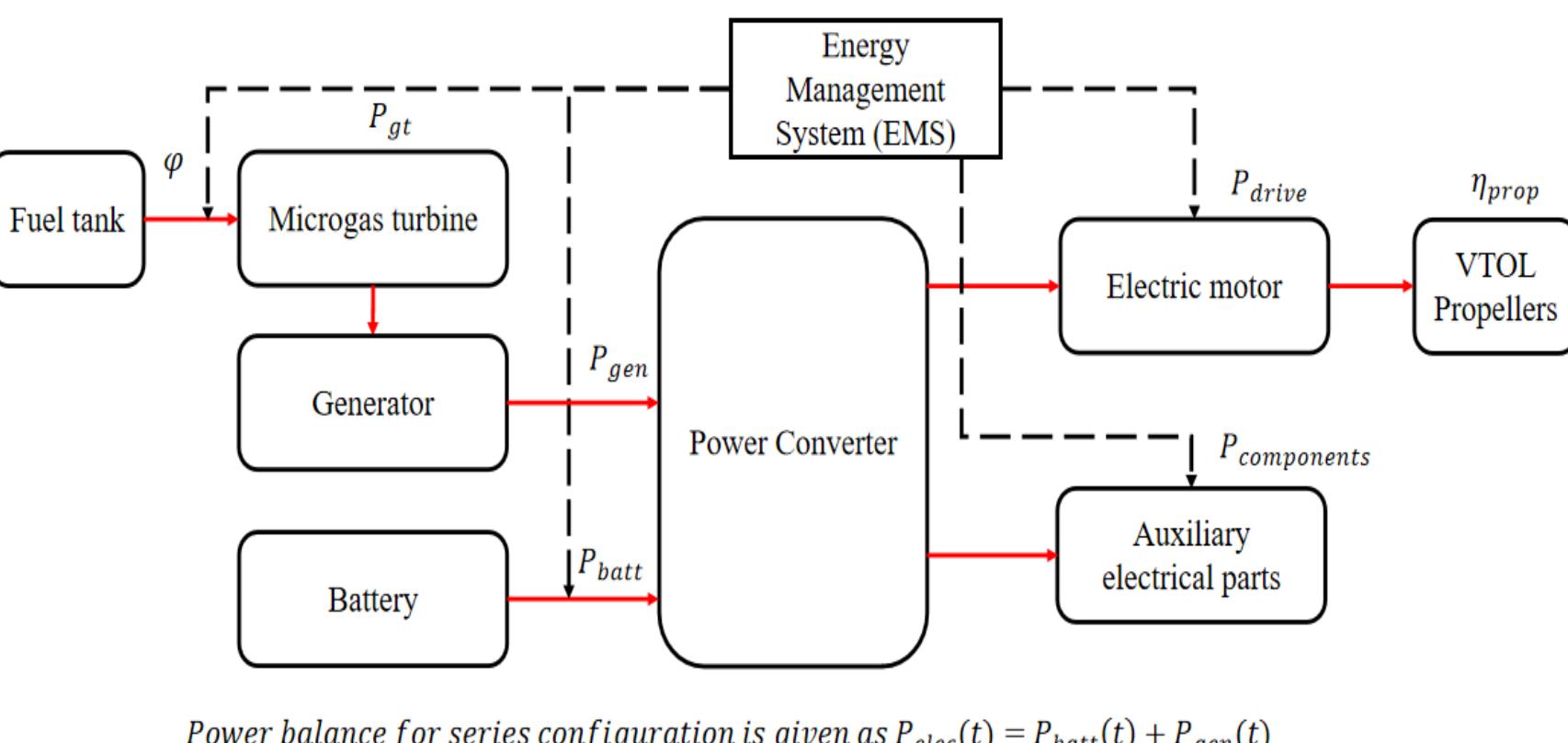
Energy-based Endurance: 0.90 hr

Range: 115.38 km | Energy per km: 1127.49 Wh/km

Fuel used: 7.74 kg | Battery used: 37.60 kWh

Energy split: Battery 28.9% / Fuel 71.1%

## Hybrid-Electric Architecture



## Conclusion and Further Work

- An experimental aircraft for DEP and HEP architecture for long range and endurance has been design and numerically validated. Experimental test will be carried out to compare results.
- An Energy management model using MPC strategy for DEP architecture with HEP has been completed for accurate prediction of range and endurance. Using the NASA Maxwell X-57 for validation, prediction – 0.9hrs, experiments - 1.1hrs.
- By modifying the aerodynamic design, battery/generator capacity and the power distribution, an aircraft with an energy-based endurance of **2.1hrs** increased to **3.8hrs**, thus, about 80% increase.