

## Lab 6 APPLIED LINEAR ALGEBRA FOR IT - 501032

## 1 Exercises

**Exercise 1:** Write command to find 1-norm of the following matrices:

(a) 
$$A_1 = \begin{pmatrix} 1 & -7 \\ -2 & -3 \end{pmatrix}$$
 (c)  $A_3 = \begin{pmatrix} 2 & -8 \\ 3 & 1 \end{pmatrix}$  (b)  $A_2 = \begin{pmatrix} -2 & 8 \\ 3 & 1 \end{pmatrix}$  (d)  $A_4 = \begin{pmatrix} 2 & 3 \\ 1 & -1 \end{pmatrix}$ 

Note: Do not use the built-in function (i.e. norm function) to find norm.

**Exercise 2:** Write command to find infinity-norm of the following matrices:

(a) (c) (e) 
$$B_{1} = \begin{pmatrix} 1 & -7 \\ -2 & -3 \end{pmatrix} \qquad B_{3} = \begin{pmatrix} 5 & -4 & 2 \\ -1 & 2 & 3 \\ -2 & 1 & 0 \end{pmatrix} \qquad B_{5} = \begin{pmatrix} -3 & 0 & 0 \\ 0 & 4 & 0 \\ 0 & 0 & 2 \end{pmatrix}$$
(b) 
$$B_{2} = \begin{pmatrix} 3 & 6 \\ 1 & 0 \end{pmatrix} \qquad B_{4} = \begin{pmatrix} 3 & 6 & -1 \\ 3 & 1 & 0 \\ 2 & 4 & -7 \end{pmatrix}$$

**Note:** Do not use the built-in function (i.e. norm function) to find norm.

Exercise 3: Write command to find calculate the Frobenius-norm

(a) 
$$C_{1} = \begin{pmatrix} 5 & -4 & 2 \\ -1 & 2 & 3 \\ -2 & 1 & 0 \end{pmatrix} \qquad C_{2} = \begin{pmatrix} 1 & 7 & 3 \\ 4 & -2 & -2 \\ -2 & -1 & 1 \end{pmatrix} \qquad C_{3} = \begin{pmatrix} 2 & 3 \\ 1 & -1 \end{pmatrix}$$

Note: Do not use the built-in function (i.e. norm function) to find norm.



**Exercise 4:** Let u and v be vectors in  $\mathbb{R}^2$ . For the following u and v determine the angle between the vectors.

(a) 
$$u=\left(\begin{array}{c}1\\1\end{array}\right),\qquad v=\left(\begin{array}{c}0\\1\end{array}\right)\qquad \qquad u=\left(\begin{array}{c}-2\\3\end{array}\right),\qquad v=\left(\begin{array}{c}1/2\\-1/2\end{array}\right)$$
 (b) 
$$u=\left(\begin{array}{c}1\\0\end{array}\right),\qquad v=\left(\begin{array}{c}0\\1\end{array}\right)$$

**Exercise 5:** Determine the unit vector  $\hat{u}$  for each of the following vectors.

(a) 
$$u = (2, 3)^T$$
 (c)  $u = (1/2, -1/2, 1/4)^T$  (b)  $u = (1, 2, 3)^T$  (d)  $u = (\sqrt{2}, 2, -\sqrt{2}, \sqrt{2})^T$ 

**Exercise 6:** Let  $v_1 = (1, 2, 3)^T$ ,  $s_2 = (7, 4, 3)^T$ , and  $s_3 = (2, 1, 9)^T$  be the position of three satellites. Find the Euclidean distances between satellites.

Exercise 7: Write a function to decode the encoded following message  $E = \begin{pmatrix} 80 & 98 & 99 & 85 & 106 & 94 \\ 71 & 92 & 76 & 95 & 100 & 92 \\ 124 & 163 & 140 & 160 & 176 & 161 \end{pmatrix}. \text{ Given } A = \begin{pmatrix} 1 & 2 & 3 \\ 2 & 1 & 2 \\ 3 & 2 & 4 \end{pmatrix} \text{ and lookup table }$ 

Alphabet	A	В	С	D	***	W	х	Υ	Z	
Position	1	2	3	4	***	23	24	25	26	27
Position +3	4	5	6	7		26	27	28	29	30

**Hint:** In order to decode the message D, you need to know the inverse matrix  $A^{-1}$  and then you calculate  $A^{-1}E$  to get the matrix D. Remember that the matrix D contains the message. Finally, using the above lookup table to obtain the message which can read.

Exercise 8: Using lookup table in the Exercise 8, write a function to encode the following message

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using the matrix  $A = \begin{pmatrix} 3 & 4 & 5 \\ 1 & 3 & 1 \\ 1 & 1 & 2 \end{pmatrix}$ 

**Hint:** In order to encode the message, you need to create the matrix E with lookup table and then calculate AE.

**Exercise 9:** Write a function to calculate the similarities among documents. Consider the following document-term matrix



	T1	T2	<b>T3</b>	T4	<b>T5</b>	<b>T6</b>	<b>T7</b>	<b>T8</b>
Doc1	0	4	0	0	0	2	1	3
Doc2	3	1	4	3	1	2	0	1
Doc3	3	0	0	0	3	0	3	0
Doc4	0	1	0	3	0	0	2	0
Doc5	2	2	2	3	1	4	0	2

Using the Cosine Similarity =  $\frac{Doc_i \cdot Doc_j}{\|Doc_i\|_2 \|Doc_j\|_2}$ . Cosine Similarity is used to measure the angle between two unit length.

Exercise 10: Write a function reuse the Cosine Similarity measure to retrieve the documents which is the nearest with vector  $\mathbf{q} = \begin{pmatrix} 0 & 0 & 0.7 & 0.5 & 0 & 0.3 \end{pmatrix}$ . Given the documents are represented as vectors.

	nova	galaxy	heat	actor	film	role
D1	1.0	0.5	0.3	0	0	0
D2	0.5	1.0	0	0	0	0
D3	0	1.0	0.8	0.7	0	0
D4	0	0.9	1.0	0.5	0	0
D5	0	0	0	1.0	0	1.0
D6	0	0	0	0	0.7	0
D7	0.5	0	0.7	0	0	0.9
D8	0	0.6	0	1.0	0.3	0.2