Dynamic Memory Allocation

ARQCP Course

Arquitetura de Computadores Licenciatura em Engenharia Informática

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Disclaimer

Material and Slides

Some of the material/slides are adapted from various:

- Presentations found on the internet;
- Books;
- Web sites;
- .

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Outline

- Memory
- 2 Dynamic Memory Allocation in C
- 3 Dynamic Memory Allocators

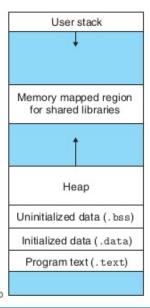
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Memory

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Program Memory Layout (address space)

- Every byte of memory in a program's memory space has an associated address.
- Everything the program needs to run is in its memory space, and different types of entities reside in different parts of a program's memory space.



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Allocating Memory

```
#define N 5
int s_array[N];
long xpto;
char a='2';
int get_max(int *v, int n){
 int i=0;
 int max = v[0];
 for(i=1;i<n;i++) {
  if(v[i] > max)
  max = v[i];
 return max;
int main(){
 int vec[N];
 int max = 0;
 max = get_max(vec,N);
 return 0;
```

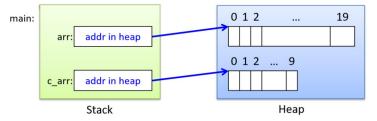
- Static global data
 - Fixed size at compile-time
 - Entire lifetime of the program (loaded from executable)
- Stack-allocated data
 - Local/temporary variables
 - Known lifetime (deallocated on function return)
- For instance, what if your declared array size becomes insufficient or is more than required?

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Dynamic Memory Allocation (I)

- Memory allocated **on the fly** during run time
- Dynamically allocated memory occupies the heap memory region of a program's address space.
- For dynamic memory allocation, pointers are crucial

```
int main() {
  int *arr;
  char *c_arr;
  arr = malloc(sizeof(int) * 20);// allocate an array of 20 ints on the heap:
  c_arr = malloc(sizeof(char) * 10);// allocate an array of 10 chars on the heap
  return 0;
}
```



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Dynamic Memory Allocation (II)

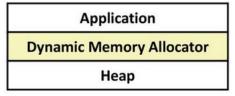
- It's important to remember that **heap memory is anonymous memory**, where "anonymous" means that addresses in the heap are not bound to variable names.
- Declaring a named program variable allocates it on the stack or in the data part of program memory.
- The allocation and deallocation of blocks from the heap follow **no set rules**, in contrast to the stack;
- Blocks may be allocated at any moment and released at any time.
- Numerous custom heap allocators are available to tune heap performance for various usage patterns, but this makes it much more difficult to track which parts of the heap are allocated or free at any given time.



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Dynamic Memory Allocation (III)

- Programmers use dynamic memory allocators to User stack acquire virtual memory at run time
 - For data structures whose size (or lifetime) is known only at runtime
 - Manage the heap of a program's virtual memory

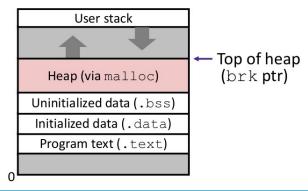


- Types of allocators
 - **Explicit allocator**: programmer allocates and frees space
 - **Example:** malloc and free in C.
 - Implicit allocator: programmer only allocates space (no free)
 - Example: garbage collection in Java, Caml, and Lisp

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Dynamic Memory Allocation (IV)

- Allocator organizes heap as a collection of variable- sized blocks, which are either allocated or free
 - Allocator requests pages in the heap region;
 - Virtual memory hardware and OS kernel allocate these pages to the program
 - Application objects (arrays, variables and so on) are typically smaller than pages, so the allocator manages blocks within pages



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Dynamic Memory Allocation in C

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Library

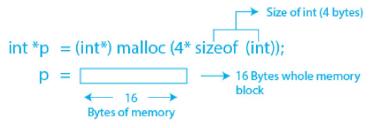
- Need to #include <stdlib.h>
- void* malloc(size_t size)
 - Allocates the requested memory and returns a pointer to it.
- void *calloc(size_t nitems, size_t size)
 - Allocates the requested memory and returns a pointer to it.
- void *realloc(void *ptr, size_t size)
 - Attempts to resize the memory block pointed to by ptr that was previously allocated with a call to calloc or malloc.
- void free(void *ptr)
 - Deallocates the memory previously allocated by a call to calloc, malloc, or realloc.
- Data types
 - void * (void pointer)
 - It is a pointer that has no associated data type with it.
 - It can hold an address of any type and can be type casted to any type.
 - size_t
 - It is an unsigned integer type

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malloc

```
ptr = (castType*) malloc(size)
```

- It takes a single argument, which is the number of bytes to allocate, and returns a pointer to the beginning of the allocated memory.
- The memory allocated by malloc is not initialized, so it contains garbage values.
- It returns a pointer to the first byte of the allocated memory, or NULL if the request for memory could not be fulfilled.

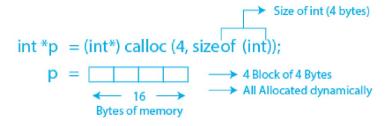


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calloc

```
ptr = (castType*)calloc(n, size);
```

- It is used to allocate memory for an array of elements of a certain data type and **initializes all bits to zero**.
- The function takes two arguments: the number of elements in the array and the size of each element.
- It returns a pointer to the first byte of the allocated memory, or NULL if the request for memory could not be fulfilled.



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realloc

```
ptr = realloc(ptr, newSize);
```

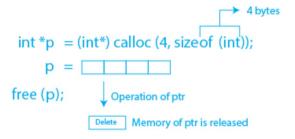
- Itis used to change the size of a previously allocated memory block.
- It takes two arguments: a pointer to the memory block that you want to resize and the new size of the memory block.
- If the new size is larger than the original size, the function may move the memory block to a new location in order to accommodate the increased size.
- If the new size is smaller than the original size, the function will truncate the memory block to the new size.

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free

free(ptr);

- It is used to deallocate memory that has already been allocated using the malloc, calloc, or realloc functions.
- Releasing the memory block indicated to by the address provided to it, it makes more allocations possible.
- To stop memory leaks in your program, you must utilize free on dynamically allocated memory.



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Allocating

■ To allocate heap memory, call malloc (or calloc), passing in the total number of bytes of contiguous heap memory to allocate.

```
#include <stdlib.h>
int main() {
  int *p;
  p = (int *) malloc(sizeof(int)); // allocate heap memory for storing an int
  if (p != NULL) {
   *p = 6; // the heap memory p points to gets the value 6
  }
  ...
  return 0;
}
```

■ Use the sizeof operator to compute the number of bytes to request.

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Deallocating

■ When a program no longer needs the heap memory it dynamically allocated with malloc, it should explicitly deallocate the memory by calling the free function.

```
#include <stdlib.h>
int main() {
  int *p;
    ...
    free(p);
    p = NULL;
    return 0;
}
```

 \blacksquare It is also a good idea to set the pointer's value to ${\tt NULL}$ after calling free,

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Dynamically Allocated Arrays

```
int i;
int s_array[20];
int *d_array;
d_array = malloc(sizeof(int) * 20);
if (d_array == NULL) {
    printf("Error: malloc failed\n");
    exit(1);
}
for (i=0; i < 20; i++) {
    s_array[i] = i;
    d_array[i] = i;
}
free(d_array);
d_array = NULL;</pre>
```

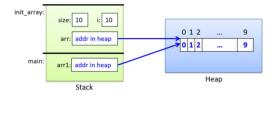
- After dynamically allocating heap space for an array, a program can access the array through the pointer variable.
 - Because the pointer variable's value represents the base address of the array in the heap, we can use the same syntax to access elements in dynamically allocated arrays as we use to access elements in statically declared arrays.
- When a program is finished using a dynamically allocated array, it should call free to deallocate the heap space.

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Pointers to Heap Memory and Functions

- When passing a dynamically allocated array to a function, the pointer variable argument's value is passed to the function (i.e., the base address of the array in the heap is passed to the function).
 - Thus, when passing either statically declared or dynamically allocated arrays to functions, the parameter gets exactly the same value —the base address of the array in memory.

```
int main(void) {
   int *arr1;
   arr1 = malloc(sizeof(int) * 10);
   ...
   init_array(arr1, 10);
   ...
}
void init_array(int *arr, int size) {
   int i;
   for (i = 0; i < size; i++) {
      arr[i] = i;
   }
}</pre>
```



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Allocating Memory for an Array in a Function

```
int main(void) {
  int *arr1 = NULL;
  int r = arr_alloc(&arr1, 10);
   ...
  free (arr1);
}
```

```
int main(void) {
  int *arr1 = NULL;
  int arr1 = arr_alloc(10);
    ...
  free (arr1);
}
```

```
int arr_alloc(int **p, int n) {
  int res = 1;
  *p = malloc(sizeof(int) * n);
  if (*p == NULL) {
    printf("malloc error\n");
    res = 0;
  }
  return res;
}
```

```
int * arr_alloc(int n) {
  int *p = malloc(sizeof(int) * n);
  return p;
}
```

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Reallocating Memory for an Array

```
int i, *p;
 /* allocate block of n ints */
p = (int*) malloc(n*sizeof(int));
 /* check for allocation error */
if (p == NULL) {
 perror("malloc");
  exit(0);
 /* initialize int array */
 for (i=0; i<n; i++)</pre>
 p[i] = i;
 /\star add space for m ints to end of p block \star/
p = (int*) realloc(p, (n+m)*sizeof(int));
 /* check for allocation error */
if (p == NULL) {
 perror("realloc");
 exit(0);
 /* initialize new spaces */
for (i=n; i < n+m; i++)
 p[i] = i;
 /* print new array */
for (i=0; i<n+m; i++)
 printf("%d\n", p[i]);
 free(p);
```

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Reallocating Memory for an Array in a Function

```
int main(void) {
   int *arr1 = NULL;
   int r = arr_alloc(&arr1, 10);
    ...
   r = arr_realloc(&arr1, 10);
   ...
   free (arr1);
}
```

```
int arr_realloc(int **p, int n) {
  int res = 1;
  *p = (int*) realloc(*p, (n+m) *sizeof(int));
  if (*p == NULL) {
    printf("malloc error\n");
    res = 0;
  }
  return res;
}
```

```
int main(void) {
   int *arr1 = NULL;
   ...
   int arr1 = arr_alloc(10);
   ...
   arr1 = arr_realloc(10);
   ...
   free (arr1);
}
```

```
int* arr_alloc(int *p, int n) {
  int *rp = (int*) realloc(p, (n+m)*sizeof(
          int));
  return rp;
}
```

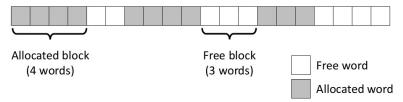
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Dynamic Memory Allocators

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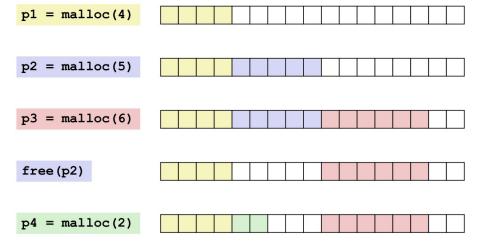
Assumption & Notation

- Let us assume that memory is divided into 32 bits (4 bytes) word.
 - Memory is word addressed (words are int-sized)
 - E.g. malloc(4) will be equivalent to malloc(4*sizeof(int))
- Allocations will be in sizes that are a multiple of boxes (i.e., multiples of 4 bytes).

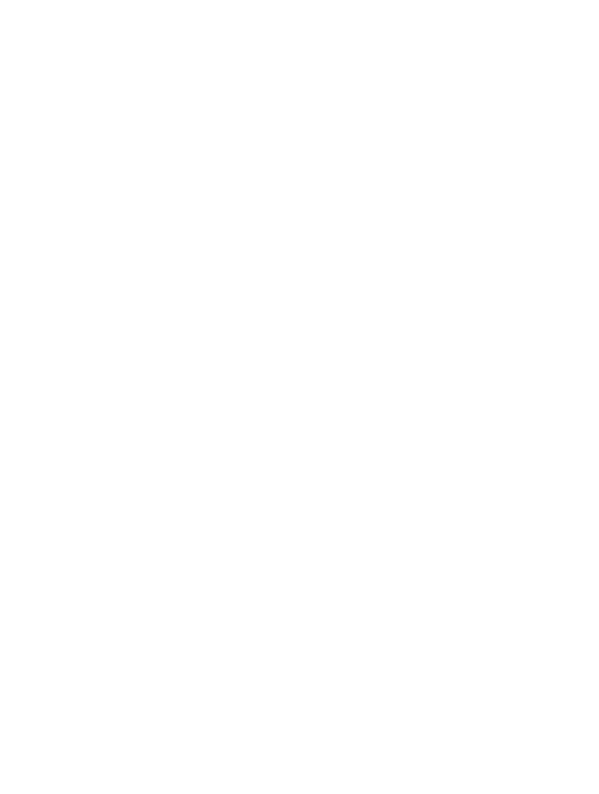


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Allocating and freeing blocks



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Performance

- Goals:
 - Given some sequence of malloc and free requests $R_0, R_1, ..., R_k, R_{k+1}$, maximize throughput and peak memory utilization
 - These goals are often conflicting
- **Aggregate payload** P_k :
 - malloc(p) results in a block with a payload of p bytes
 - After request R_k has completed, the aggregate payload P_k is the sum of currently allocated payloads
- \blacksquare Current heap size H_k
 - Assume H_k is monotonically non-decreasing
 - Allocator can increase size of heap using sbrk

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Performance

Throughput

- Number of completed requests per unit time
- Example:
 - If 5000 malloc calls and 5000 free calls completed in 10 seconds, then throughput is 1000 operations/second

Peak Memory Utilization

- Defined as $U_k = (\max_{i \le k} P_i)/H_k$ after k + 1 requests
- Goal: maximize utilization for a sequence of requests

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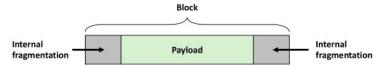
Fragmentation

- Poor memory utilization is caused by **fragmentation**
- Sections of memory are not used to store anything useful, but cannot satisfy allocation requests
- Two types: internal and external

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Internal Fragmentation

- For a given block, internal fragmentation occurs if payload is smaller than the block
 - It is the difference between de block size minus payload size



- Causes:
 - Padding for alignment purposes
 - Overhead of maintaining heap data structures (inside block, outside payload)

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External Fragmentation

- For the heap, external fragmentation occurs when allocation/free pattern leaves "holes" between blocks
 - That is, the aggregate payload is non-continuous
 - Can cause situations where there is enough aggregate heap memory to satisfy request, but no single free block is large enough



Depends also on the pattern of future requests

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Applications & Allocators

- Applications
 - Can issue arbitrary sequence of malloc and free requests
 - Must never access memory not currently allocated
 - Must never free memory not currently allocated
 - Also must only use free with previously malloc'ed blocks
- Allocators
 - Cannot control number or size of allocated blocks
 - Must respond immediately to malloc requests
 - i.e., cannot reorder or buffer requests
 - Must allocate blocks from free memory
 - i.e., can only place allocated blocks in free memory
 - Must align blocks so they satisfy all alignment requirements
 - Can manipulate and modify only free memory
 - Cannot move the allocated blocks
 - i.e., defragmentation is not allowed

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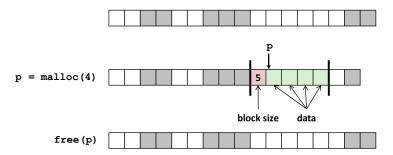
Implementation Issues

- How do we know how much memory to free given just a pointer?
- How do we **keep track of the free blocks**?
- How do we pick a block to use for allocation (when many might fit)?
- What do we do with the extra space when allocating a structure that is smaller than the free block it is placed in?
- How do we reinsert a freed block into the heap?

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Knowing How Much to Free

- Standard method
 - Keep the length of a block in the word preceding the data
 - This word is often called the header field or header
 - Requires an extra word for every allocated block



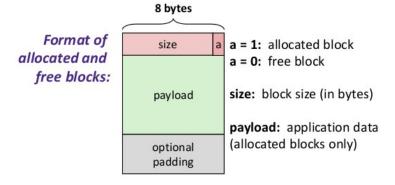
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Keeping Track of Free Blocks (I)

- 1 Implicit free list using length links all blocks using math
 - No actual pointers, and must check each block if allocated or free



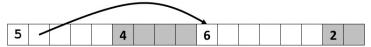
For each block we need both size and allocation status



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Keeping Track of Free Blocks (II)

Explicit free list among only the free blocks, using pointers



- **3** Segregated free list
 - Different free lists for different size "classes"
- 4 Blocks sorted by size
 - Can use a **balanced binary tree** (e.g., red-black tree) with pointers within each free block, and the length used as a key

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