

# ML0101EN-Clus-DBSCAN-weather-py-v1

September 17, 2021

## 1 Density-Based Clustering

Estimated time needed: **25** minutes

### 1.1 Objectives

After completing this lab you will be able to:

- Use DBSCAN to do Density based clustering
- Use Matplotlib to plot clusters

Most of the traditional clustering techniques, such as k-means, hierarchical and fuzzy clustering, can be used to group data without supervision.

However, when applied to tasks with arbitrary shape clusters, or clusters within cluster, the traditional techniques might be unable to achieve good results. That is, elements in the same cluster might not share enough similarity or the performance may be poor. Additionally, Density-based clustering locates regions of high density that are separated from one another by regions of low density. Density, in this context, is defined as the number of points within a specified radius.

In this section, the main focus will be manipulating the data and properties of DBSCAN and observing the resulting clustering.

Import the following libraries:

numpy as np

DBSCAN from sklearn.cluster

make\_blobs from sklearn.datasets.samples\_generator

StandardScaler from sklearn.preprocessing

matplotlib.pyplot as plt

Remember %matplotlib inline to display plots

```
[ ]: # Notice: For visualization of map, you need basemap package.
# if you dont have basemap install on your machine, you can use the following
↳ line to install it
!conda install -c conda-forge basemap matplotlib==3.1 -y
# Notice: you maight have to refresh your page and re-run the notebook after
↳ installation
```

```
[ ]: import numpy as np
      from sklearn.cluster import DBSCAN
      from sklearn.datasets.samples_generator import make_blobs
      from sklearn.preprocessing import StandardScaler
      import matplotlib.pyplot as plt
      %matplotlib inline
```

### 1.1.1 Data generation

The function below will generate the data points and requires these inputs:

centroidLocation: Coordinates of the centroids that will generate the random data.

Example: input: `[[4,3], [2,-1], [-1,4]]`

numSamples: The number of data points we want generated, split over the number of centroids (# of centroids defined in centroidLocation)

Example: 1500

clusterDeviation: The standard deviation of the clusters. The larger the number, the further the spacing of the data points within the clusters.

Example: 0.5

```
[ ]: def createDataPoints(centroidLocation, numSamples, clusterDeviation):
      # Create random data and store in feature matrix X and response vector y.
      X, y = make_blobs(n_samples=numSamples, centers=centroidLocation,
                        cluster_std=clusterDeviation)

      # Standardize features by removing the mean and scaling to unit variance
      X = StandardScaler().fit_transform(X)
      return X, y
```

Use createDataPoints with the 3 inputs and store the output into variables X and y.

```
[ ]: X, y = createDataPoints([[4,3], [2,-1], [-1,4]] , 1500, 0.5)
```

### 1.1.2 Modeling

DBSCAN stands for Density-Based Spatial Clustering of Applications with Noise. This technique is one of the most common clustering algorithms which works based on density of object. The whole idea is that if a particular point belongs to a cluster, it should be near to lots of other points in that cluster.

It works based on two parameters: Epsilon and Minimum Points

**Epsilon** determine a specified radius that if includes enough number of points within, we call it dense area

**minimumSamples** determine the minimum number of data points we want in a neighborhood to define a cluster.

```
[ ]: epsilon = 0.3
      minimumSamples = 7
      db = DBSCAN(eps=epsilon, min_samples=minimumSamples).fit(X)
      labels = db.labels_
      labels
```

### 1.1.3 Distinguish outliers

Let's Replace all elements with 'True' in core\_samples\_mask that are in the cluster, 'False' if the points are outliers.

```
[ ]: # Firts, create an array of booleans using the labels from db.
      core_samples_mask = np.zeros_like(db.labels_, dtype=bool)
      core_samples_mask[db.core_sample_indices_] = True
      core_samples_mask
```

```
[ ]: # Number of clusters in labels, ignoring noise if present.
      n_clusters_ = len(set(labels)) - (1 if -1 in labels else 0)
      n_clusters_
```

```
[ ]: # Remove repetition in labels by turning it into a set.
      unique_labels = set(labels)
      unique_labels
```

### 1.1.4 Data visualization

```
[ ]: # Create colors for the clusters.
      colors = plt.cm.Spectral(np.linspace(0, 1, len(unique_labels)))
```

```
[ ]: # Plot the points with colors
      for k, col in zip(unique_labels, colors):
          if k == -1:
              # Black used for noise.
              col = 'k'

          class_member_mask = (labels == k)

          # Plot the datapoints that are clustered
          xy = X[class_member_mask & core_samples_mask]
          plt.scatter(xy[:, 0], xy[:, 1], s=50, c=[col], marker=u'o', alpha=0.5)

          # Plot the outliers
          xy = X[class_member_mask & ~core_samples_mask]
          plt.scatter(xy[:, 0], xy[:, 1], s=50, c=[col], marker=u'o', alpha=0.5)
```

## 1.2 Practice

To better understand differences between partitional and density-based clustering, try to cluster the above dataset into 3 clusters using k-Means.

Notice: do not generate data again, use the same dataset as above.

```
[ ]: # write your code here
```

[Click here for the solution](#)

```
from sklearn.cluster import KMeans
k = 3
k_means3 = KMeans(init = "k-means++", n_clusters = k, n_init = 12)
k_means3.fit(X)
fig = plt.figure(figsize=(6, 4))
ax = fig.add_subplot(1, 1, 1)
for k, col in zip(range(k), colors):
    my_members = (k_means3.labels_ == k)
    plt.scatter(X[my_members, 0], X[my_members, 1], c=col, marker='o', alpha=0.5)
plt.show()
```

Weather Station Clustering using DBSCAN & scikit-learn

DBSCAN is especially very good for tasks like class identification in a spatial context. The wonderful attribute of DBSCAN algorithm is that it can find out any arbitrary shape cluster without getting affected by noise. For example, this following example cluster the location of weather stations in Canada. <Click 1> DBSCAN can be used here, for instance, to find the group of stations which show the same weather condition. As you can see, it not only finds different arbitrary shaped clusters, can find the denser part of data-centered samples by ignoring less-dense areas or noises.

Let's start playing with the data. We will be working according to the following workflow:

1. Loading data
  - Overview data
  - Data cleaning
  - Data selection
  - Clusteing

### 1.2.1 About the dataset

Environment Canada

Monthly Values for July - 2015

Name in the table

Meaning

Stn\_Name

Station Name</font

Lat

Latitude (North+, degrees)

Long  
Longitude (West - , degrees)  
Prov  
Province  
Tm  
Mean Temperature (°C)  
DwTm  
Days without Valid Mean Temperature  
D  
Mean Temperature difference from Normal (1981-2010) (°C)  
Tx  
Highest Monthly Maximum Temperature (°C)  
DwTx  
Days without Valid Maximum Temperature  
Tn  
Lowest Monthly Minimum Temperature (°C)  
DwTn  
Days without Valid Minimum Temperature  
S  
Snowfall (cm)  
DwS  
Days without Valid Snowfall  
S%N  
Percent of Normal (1981-2010) Snowfall  
P  
Total Precipitation (mm)  
DwP  
Days without Valid Precipitation  
P%N  
Percent of Normal (1981-2010) Precipitation  
S\_G  
Snow on the ground at the end of the month (cm)

Pd

Number of days with Precipitation 1.0 mm or more

BS

Bright Sunshine (hours)

DwBS

Days without Valid Bright Sunshine

BS%

Percent of Normal (1981-2010) Bright Sunshine

HDD

Degree Days below 18 °C

CDD

Degree Days above 18 °C

Stn\_No

Climate station identifier (first 3 digits indicate drainage basin, last 4 characters are for sorting alphabetically).

NA

Not Available

### 1.2.2 1-Download data

To download the data, we will use **!wget** to download it from IBM Object Storage.

**Did you know?** When it comes to Machine Learning, you will likely be working with large datasets. As a business, where can you host your data? IBM is offering a unique opportunity for businesses, with 10 Tb of IBM Cloud Object Storage: [Sign up now for free](#)

```
[ ]: !wget -O weather-stations20140101-20141231.csv https://cf-courses-data.s3.us.
    ↪cloud-object-storage.appdomain.cloud/
    ↪IBMDeveloperSkillsNetwork-ML0101EN-SkillsNetwork/labs/Module%204/data/
    ↪weather-stations20140101-20141231.csv
```

### 1.2.3 2- Load the dataset

We will import the .csv then we creates the columns for year, month and day.

```
[ ]: import csv
import pandas as pd
import numpy as np

filename='weather-stations20140101-20141231.csv'

#Read csv
```

```
pdf = pd.read_csv(filename)
pdf.head(5)
```

### 1.2.4 3-Cleaning

Let's remove rows that don't have any value in the **Tm** field.

```
[ ]: pdf = pdf[pd.notnull(pdf["Tm"])]
pdf = pdf.reset_index(drop=True)
pdf.head(5)
```

### 1.2.5 4-Visualization

Visualization of stations on map using basemap package. The matplotlib basemap toolkit is a library for plotting 2D data on maps in Python. Basemap does not do any plotting on its own, but provides the facilities to transform coordinates to a map projections.

Please notice that the size of each data points represents the average of maximum temperature for each station in a year.

```
[ ]: from mpl_toolkits.basemap import Basemap
import matplotlib.pyplot as plt
from pylab import rcParams
%matplotlib inline
rcParams['figure.figsize'] = (14,10)

llon=-140
ulon=-50
llat=40
ulat=65

pdf = pdf[(pdf['Long'] > llon) & (pdf['Long'] < ulon) & (pdf['Lat'] > llat) &
    ↪(pdf['Lat'] < ulat)]

my_map = Basemap(projection='merc',
                  resolution = 'l', area_thresh = 1000.0,
                  llcrnrlon=llon, llcrnrlat=llat, #min longitude (llcrnrlon) and
    ↪latitude (llcrnrlat)
                  urcrnrlon=ulon, urcrnrlat=ulat) #max longitude (urcrnrlon) and
    ↪latitude (urcrnrlat)

my_map.drawcoastlines()
my_map.drawcountries()
# my_map.drawmapboundary()
my_map.fillcontinents(color = 'white', alpha = 0.3)
my_map.shadedrelief()

# To collect data based on stations
```

```

xs,ys = my_map(np.asarray(pdf.Long), np.asarray(pdf.Lat))
pdf['xm']= xs.tolist()
pdf['ym']=ys.tolist()

#Visualization1
for index,row in pdf.iterrows():
    # x,y = my_map(row.Long, row.Lat)
    my_map.plot(row.xm, row.ym,markerfacecolor =([1,0,0]), marker='o',
    ↪markersize= 5, alpha = 0.75)
#plt.text(x,y,stn)
plt.show()

```

### 1.2.6 5- Clustering of stations based on their location i.e. Lat & Lon

DBSCAN from sklearn library can runs DBSCAN clustering from vector array or distance matrix. In our case, we pass it the Numpy array Clus\_dataSet to find core samples of high density and expands clusters from them.

```

[ ]: from sklearn.cluster import DBSCAN
import sklearn.utils
from sklearn.preprocessing import StandardScaler
sklearn.utils.check_random_state(1000)
Clus_dataSet = pdf[['xm', 'ym']]
Clus_dataSet = np.nan_to_num(Clus_dataSet)
Clus_dataSet = StandardScaler().fit_transform(Clus_dataSet)

# Compute DBSCAN
db = DBSCAN(eps=0.15, min_samples=10).fit(Clus_dataSet)
core_samples_mask = np.zeros_like(db.labels_, dtype=bool)
core_samples_mask[db.core_sample_indices_] = True
labels = db.labels_
pdf["Clus_Db"]=labels

realClusterNum=len(set(labels)) - (1 if -1 in labels else 0)
clusterNum = len(set(labels))

# A sample of clusters
pdf[["Stn_Name", "Tx", "Tm", "Clus_Db"]].head(5)

```

As you can see for outliers, the cluster label is -1

```

[ ]: set(labels)

```

### 1.2.7 6- Visualization of clusters based on location

Now, we can visualize the clusters using basemap:



```
[ ]: from mpl_toolkits.basemap import Basemap
import matplotlib.pyplot as plt
from pylab import rcParams
%matplotlib inline
rcParams['figure.figsize'] = (14,10)

my_map = Basemap(projection='merc',
                  resolution = 'l', area_thresh = 1000.0,
                  llcrnrlon=llon, llcrnrlat=llat, #min longitude (llcrnrlon) and
↳latitude (llcrnrlat)
                  urcrnrlon=ulon, urcrnrlat=ulat) #max longitude (urcrnrlon) and
↳latitude (urcrnrlat)

my_map.drawcoastlines()
my_map.drawcountries()
#my_map.drawmapboundary()
my_map.fillcontinents(color = 'white', alpha = 0.3)
my_map.shadedrelief()

# To create a color map
colors = plt.get_cmap('jet')(np.linspace(0.0, 1.0, clusterNum))

#Visualization1
for clust_number in set(labels):
    c=([0.4,0.4,0.4]) if clust_number == -1 else colors[np.int(clust_number)]
    clust_set = pdf[pdf.Clus_Db == clust_number]
    my_map.scatter(clust_set.xm, clust_set.ym, color =c, marker='o', s= 20,
↳alpha = 0.85)
    if clust_number != -1:
        cenx=np.mean(clust_set.xm)
        ceny=np.mean(clust_set.ym)
        plt.text(cenx,ceny,str(clust_number), fontsize=25, color='red',)
        print ("Cluster "+str(clust_number)+', Avg Temp: '+ str(np.
↳mean(clust_set.Tm)))
```

### 1.2.8 7- Clustering of stations based on their location, mean, max, and min Temperature

In this section we re-run DBSCAN, but this time on a 5-dimensional dataset:

```
[ ]: from sklearn.cluster import DBSCAN
import sklearn.utils
from sklearn.preprocessing import StandardScaler
sklearn.utils.check_random_state(1000)
Clus_dataSet = pdf[['xm', 'ym', 'Tx', 'Tm', 'Tn']]
```

```

Clus_dataSet = np.nan_to_num(Clus_dataSet)
Clus_dataSet = StandardScaler().fit_transform(Clus_dataSet)

# Compute DBSCAN
db = DBSCAN(eps=0.3, min_samples=10).fit(Clus_dataSet)
core_samples_mask = np.zeros_like(db.labels_, dtype=bool)
core_samples_mask[db.core_sample_indices_] = True
labels = db.labels_
pdf["Clus_Db"]=labels

realClusterNum=len(set(labels)) - (1 if -1 in labels else 0)
clusterNum = len(set(labels))

# A sample of clusters
pdf[["Stn_Name", "Tx", "Tm", "Clus_Db"]].head(5)

```

### 1.2.9 8- Visualization of clusters based on location and Temperture

```

[ ]: from mpl_toolkits.basemap import Basemap
import matplotlib.pyplot as plt
from pylab import rcParams
%matplotlib inline
rcParams['figure.figsize'] = (14,10)

my_map = Basemap(projection='merc',
                  resolution = 'l', area_thresh = 1000.0,
                  llcrnrlon=llon, llcrnrlat=llat, #min longitude (llcrnrlon) and
↳ latitude (llcrnrlat)
                  urcrnrlon=ulon, urcrnrlat=ulat) #max longitude (urcrnrlon) and
↳ latitude (urcrnrlat)

my_map.drawcoastlines()
my_map.drawcountries()
#my_map.drawmapboundary()
my_map.fillcontinents(color = 'white', alpha = 0.3)
my_map.shadedrelief()

# To create a color map
colors = plt.get_cmap('jet')(np.linspace(0.0, 1.0, clusterNum))

#Visualization1
for clust_number in set(labels):
    c=([0.4,0.4,0.4]) if clust_number == -1 else colors[np.int(clust_number)]
    clust_set = pdf[pdf.Clus_Db == clust_number]

```

```

my_map.scatter(clust_set.xm, clust_set.ym, color =c, marker='o', s= 20,
↳alpha = 0.85)
if clust_number != -1:
    cenx=np.mean(clust_set.xm)
    ceny=np.mean(clust_set.ym)
    plt.text(cenx,ceny,str(clust_number), fontsize=25, color='red',)
    print ("Cluster "+str(clust_number)+'', Avg Temp: '+' str(np.
↳mean(clust_set.Tm)))

```

Want to learn more?

IBM SPSS Modeler is a comprehensive analytics platform that has many machine learning algorithms. It has been designed to bring predictive intelligence to decisions made by individuals, by groups, by systems – by your enterprise as a whole. A free trial is available through this course, available here: [SPSS Modeler](#)

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## 1.2.10 Thank you for completing this lab!

## 1.3 Author

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### 1.3.1 Other Contributors

Joseph Santarcangelo

## 1.4 Change Log

Date (YYYY-MM-DD)	Version	Changed By	Change Description
2020-11-03	2.1	Lakshmi	Updated url of csv
2020-08-27	2.0	Lavanya	Moved lab to course repo in GitLab

##

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