STAT-S 610: Assignment 5

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Github Repository

Here is the link for my repository: https://github.com/LuisNavarro07/Stat_Computing_A5 Note: you'll see that in my repository I have a file called "llr_functions_1.R". This was my first attempt to use the apply function. However, it did not work as expected. I updated it using the "llr_functions_3.R".

Commit History

I typed the following code into the terminal. These lines of code added the files to the main branch of my repository and commit to such changes. Hence, created a snapshot of the repository with the saved versions (until this point) of the files added.

```
## 2. Git init
git init
## 3. Git status
git status
## Create the files in R and then add them
git add benchmark_llr.R
git add llr_functions.R
git add test_llr.R
## check whether files were added
git status
## commit
git commit -m 'initial commit'
```

Speed Test 1

Typing **git checkout speed-test-1** changes you from the master branch to the speed-test-1 branch. Performs a similar action as **git switch speed-test-1**

```
git branch speed-test-1
git checkout speed-test-1
git add llr_functions_1.R
git commit -m 'speed-test-1'
```

These are the original functions that implemented the locally weighted regression.

```
### Function LLR
llr = function(x, y, z, omega) {
    fits = sapply(z, compute_f_hat, x, y, omega)
    return(fits)
}

### Function F Hat
compute_f_hat = function(z, x, y, omega) {
    Wz = make_weight_matrix(x, z, omega)
    X = make_predictor_matrix(x)
    f_hat = c(1, z) %*% solve(t(X) %*% Wz %*% X) %*% t(X) %*% Wz %*% y
    return(f_hat)
}
```

The functions below are the updated versions. I changed the name of the functions according to each speed test. For this update what I did was write how the matrix X^TW_zX looks like. This is a 2×2 matrix with the following structure. Denote W_d as a vector with the diagonal elements of W_z . So W_{di} refers to the ith element of the diagonal.

$$\begin{pmatrix} a & b \\ b & c \end{pmatrix}$$

where

$$d_1 = \sum_{i \in N} W_{di}$$

$$d_2 = \sum_{i \in N} W_{di} x_i$$

$$d_3 = \sum_{i \in N} W_{di} x_i^2$$

Similarly for the matrix X^TW_zY . This ends up being a 2×1 vector:

 $\begin{pmatrix} d_4 \\ d_5 \end{pmatrix}$

where

$$d_4 = \sum_{i \in N} W_{di} y_i$$

$$d_5 = \sum_{i \in N} W_{di} x_i y_i$$

So basically what I did was to compute manually all the matrix multiplications. I used the apply command to do the sums. Since the inner matrix is a 2×2 , the inverse can be computed easily with the determinant formula. The factor to multiply d_1, d_2, d_3 is given by:

$$\gamma = \frac{1}{d_1 d_3 - d_2^2}$$

Define $\hat{d}_j = \gamma d_j$. With these numbers the whole multiplication $(X^T W_z X)^{-1} X^T W_z Y$ is reduced to a vector

$$\begin{pmatrix} c_1 = d_4 \hat{d}_3 - d_5 \hat{d}_2 \\ c_2 = -d_4 \hat{d}_2 + d_5 \hat{d}_1 \end{pmatrix}$$

and $\hat{f}(z)$ is given by the following expression. Note that in this notation, z is a scalar.

$$\hat{f}(z) = c_1 + c_2 z$$

```
### Function LLR
llr_3 = function(x, y, z, omega) {
    fits = sapply(z, compute_f_hat_3, x, y, omega)
    return(fits)
}
### Function F Hat
compute_f_hat_3 = function(z, x, y, omega) {
    ### Change this line --> Wz = make_weight_matrix(x, z, omega) For this line
    ### --> Wz = diag(make_weight_matrix(x, z, omega))
    Wz = diag(make_weight_matrix(x, z, omega))
    X = make predictor matrix(x)
    c <- matrix_product(x, y, Wz)</pre>
    ### Change this line --> f hat = c(1, z) %*% solve(inner mat(x, Wz)) %*%
    ### t(X) %*% Wz %*% y For this lines --> f_{at} = c[1] + c[2]*z
    f_hat = c[1] + c[2] * z
    return(f_hat)
}
### Change to the f_hat line of code using apply First thing to note is that
### t(X) %*% Wz %*% X is always a 2x2 matrix, where the entries of the matrix
### are easy to compute
matrix_product <- function(x, y, Wz) {</pre>
    ### Define all the multiplications in vectorized form. In this case all
    ### should be nX1 vectors
    objects <- list(Wz, Wz * x, Wz * x * x, Wz * y, Wz * x * y)
    sums <- as.double(lapply(objects, sum))</pre>
    inv_fac \leftarrow 1/((sums[1] * sums[3]) - (sums[2]^2))
    inv val <- sums[1:3] * inv fac
    c1 <- sums[4] * inv_val[3] - sums[5] * inv_val[2]
    c2 <- -sums[4] * inv_val[2] + sums[5] * inv_val[1]
    c <- c(c1, c2)
    return(c)
}
```

Which version works faster?

Using the microbenchmark function I compare the speed of these two implementations. For simplicity, I'll stick to the following testing environment.

```
n = 15
## a very simple regression model
x = rnorm(n)
y = rnorm(x + rnorm(n))
z = seq(-1, 1, length.out = 100)
omega = 1
```

It seems to be that my implementation improves the computation speed (in average) by 4.53213 milliseconds. I think it makes sense since I am reducing computational burden by avoiding matrix multiplication.

```
summary(speedtests)[1:2, ]
```

Speed Test 2

For this second implementation I used the sweep function to simplify some calculations by defining them as objects. Sweep basically applies the same arithmetic operation to the columns (or rows) of a matrix. As explained above, most of the matrix multiplications done lead to a vector where each entry is $w_i x_i$. So I used the sweep function to create the matrix $X^T W z$, and then just multiply it by the remaining terms. The good part is that these terms appears twice in the equation so I can recycle the object. These are the updated functions.

```
### Function LLR
llr_2 = function(x, y, z, omega) {
    fits = sapply(z, compute_f_hat_2, x, y, omega)
    return(fits)
}
### Function F Hat
compute_f_hat_2 = function(z, x, y, omega) {
    ### Change this line --> Wz = make_weight_matrix(x, z, omega) For this line
    ### --> Wz = diag(make_weight_matrix(x, z, omega))
    Wz = diag(make_weight_matrix(x, z, omega))
    X = make_predictor_matrix(x)
    ### Change this line --> f_hat = c(1, z) %*% solve(t(X) %*% Wz %*% X) %*%
    ### t(X) %*% Wz %*% y Sweep Function
    xw \leftarrow sweep(t(X), MARGIN = 2, STATS = Wz, FUN = "*")
    ### Sweep Matrix
    sweep_matrix <- xw %*% X</pre>
    ### Vectorized Calculation of the Last Term
    xwy <- xw %*% y
    f_hat = c(1, z) %*% solve(sweep_matrix) %*% xwy
    return(f_hat)
}
```

Which one runs faster?

Again, I'll use the microbenchmark function to test the speed. It seems that my implementation through the sweep functions slows down the average time by 6.8860 milliseconds.

summary(speedtests)

```
## expr min lq mean median uq max
## 1 llr(x, y, z, omega) 68.5895 74.41675 81.20812 77.41370 82.52260 272.9735
## 2 llr_3(x, y, z, omega) 64.6878 70.58795 77.66713 73.36065 78.63815 199.4913
## 3 llr_2(x, y, z, omega) 74.4265 80.24955 89.30432 83.62090 90.55585 472.0293
## neval
## 1 1000
## 2 1000
## 3 1000
```

Git Log Graph

This is how it looks on my end. It shows the number of commits, and in which branch they were made.