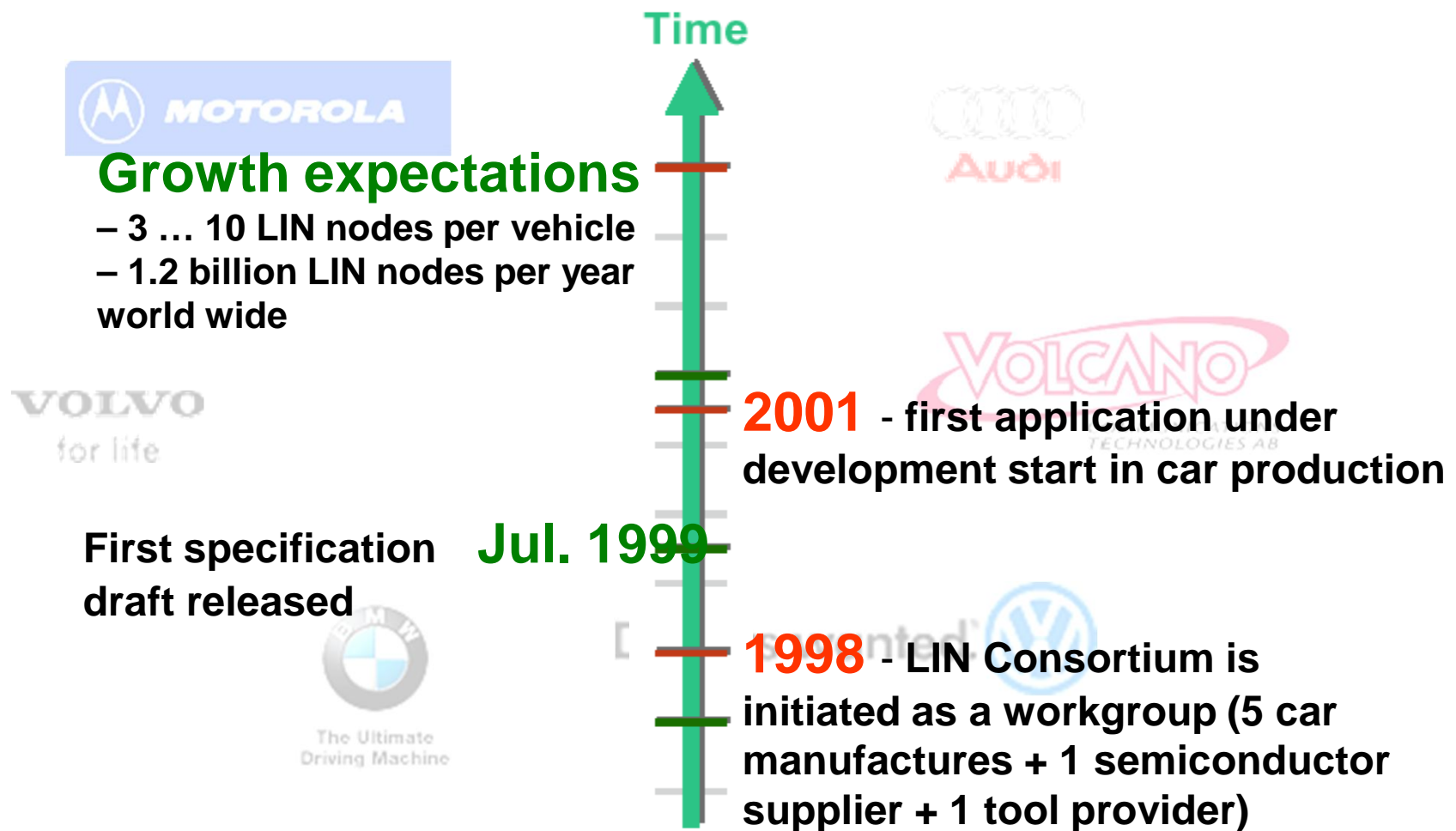


Overview

LIN Local Interconnect Network Training

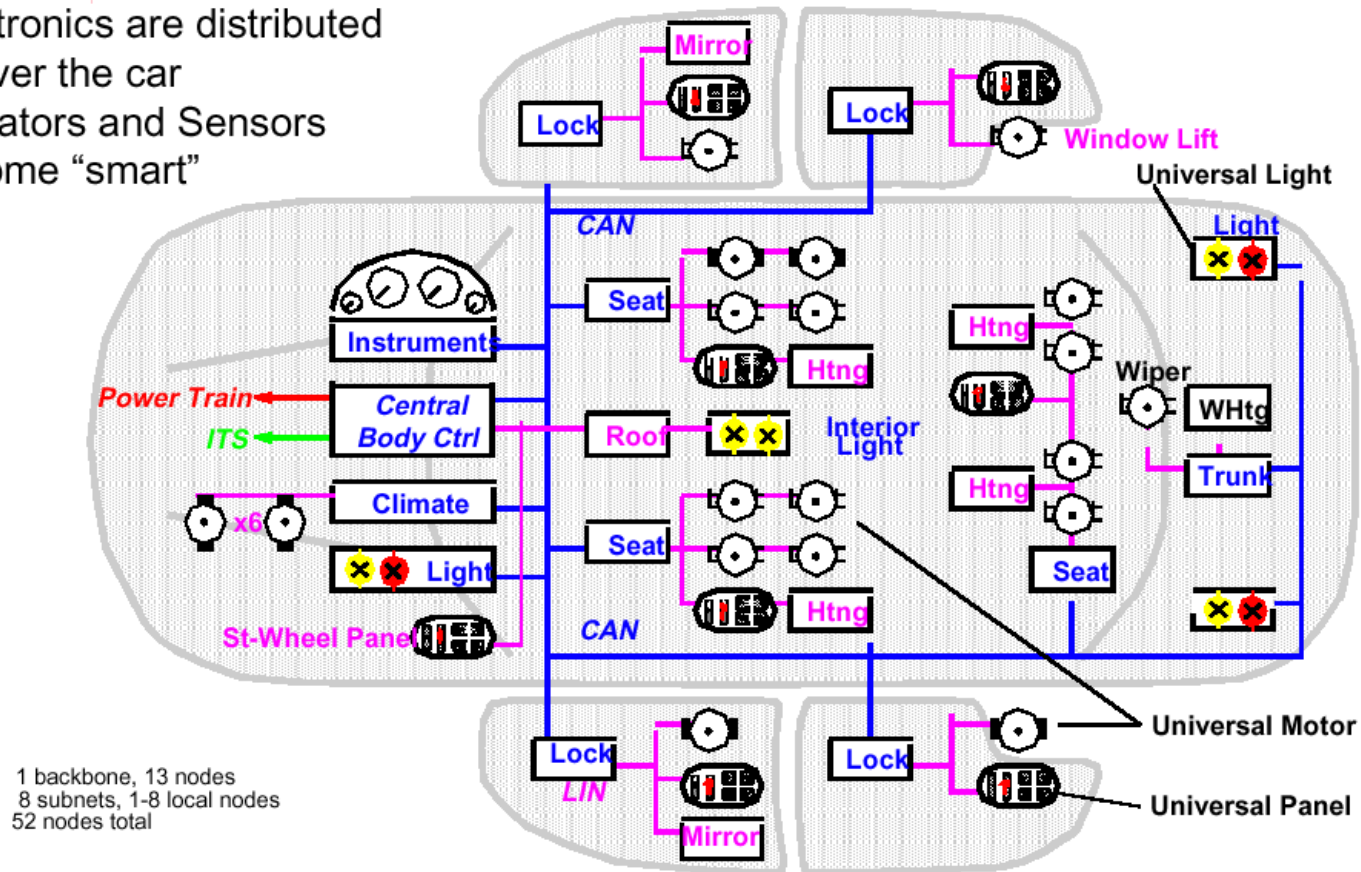
- History and Expectation
- Technical Features
- The ISO/OSI reference model and LIN
- Frames
- Message Frames
- Communication concept of LIN
- Command and Extended Frames
- Sleep mode and wake-up signal
- Error and Exception handling

History and Expectation

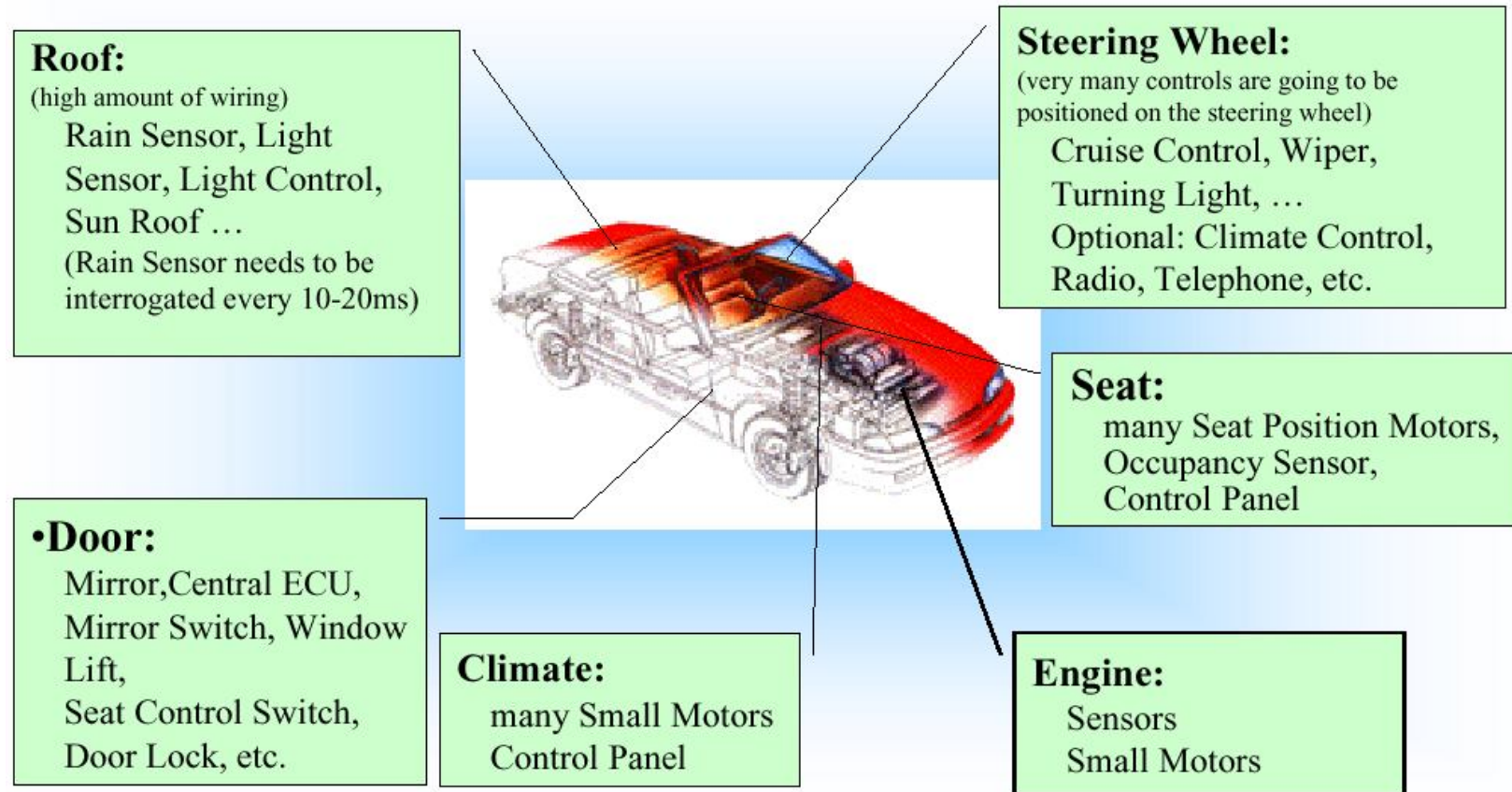


Typical example for LIN in automobiles (1)

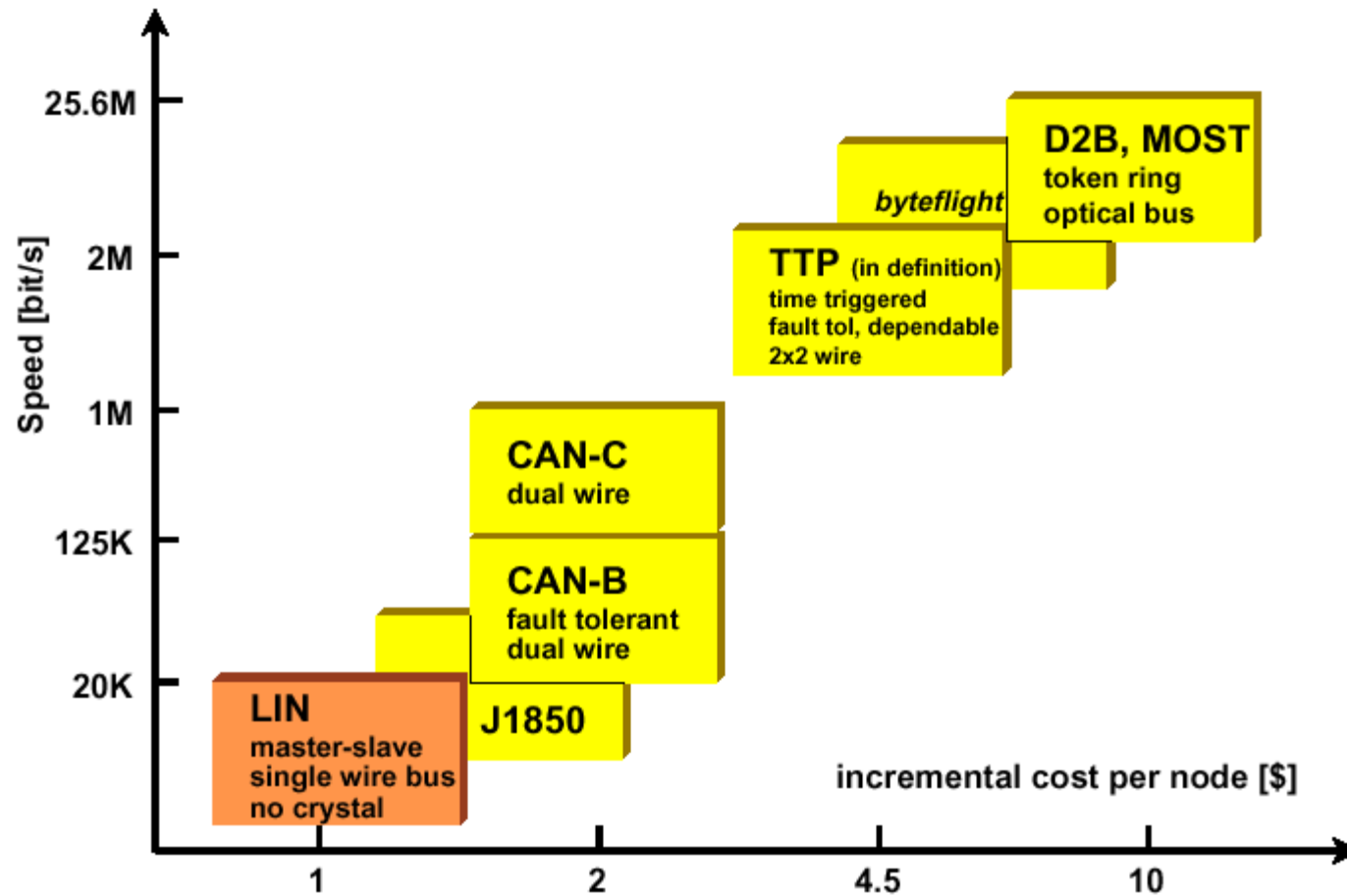
- Electronics are distributed all over the car
- Actuators and Sensors become “smart”



Typical example for LIN in automobiles (2)



Automotive Bus Systems



Overview

LIN Local Interconnect Network Training

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Technical Features(1)

- **Sub-Bus as a extension to CAN to provide connection to local network clusters**
- **Low cost single-wire implementation**
(cheaper than CAN but does not have the same reliability level as CAN)
- **Low cost silicon implementation based on common UART/SCI interface hardware**
(almost any microcontroller has necessary hardware on chip)
- **Single Master / Multiple Slave concept**
(no Arbitration is necessary)

Technical Features(2)

- **Self synchronization without quartz or ceramics resonators in slave node**

(significant cost reduction of hardware platform)

- **Speed up to 20kbit/s**

limited by the EMI of single wire transmission. Recommended Bit Rates:

Slow: 2400 bit/sec

Medium: 9600bit/sec

Fast: 19200 bit/sec

- **Guarantee of latency times for signal transmission**

- **Hot plug-in / plug-out**

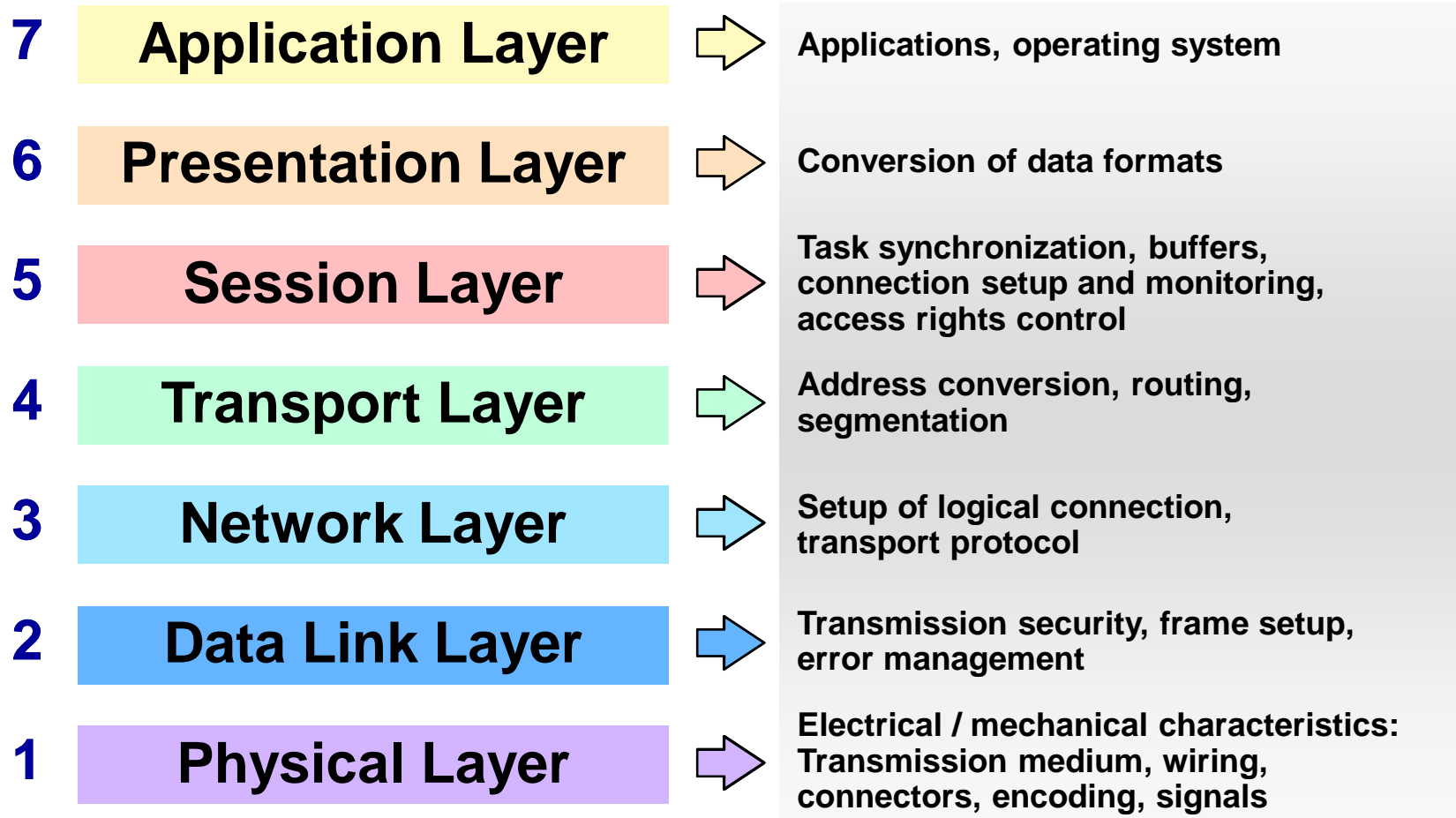
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The ISO/OSI reference model and LIN (1)

7	Application Layer	All
6	Presentation Layer	People
5	Session Layer	Seem
4	Transport Layer	To
3	Network Layer	Need
2	Data Link Layer	Data
1	Physical Layer	Processing



The ISO/OSI reference model and LIN (3)

2

Data Link Layer

LLC- Logical Link Control

is concerning with Message Filtering and Recovery Management



Acceptance Filtering, Recovery Management, Time Base Synchronization, Message Validation

MAC - Medium Access Control

is supervised by a management entity called Fault Confinement



Data Encapsulation/Decapsulation, Error Detection, Error Signaling, Serialization/Deserialization

1

Physical Layer



Bit Timing, Bit synchronization, Line Driver/Receiver

Overview

LIN Local Interconnect Network Training

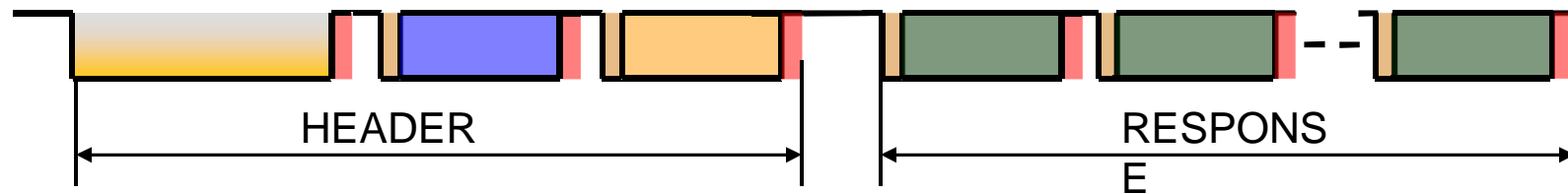
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Frames (1)

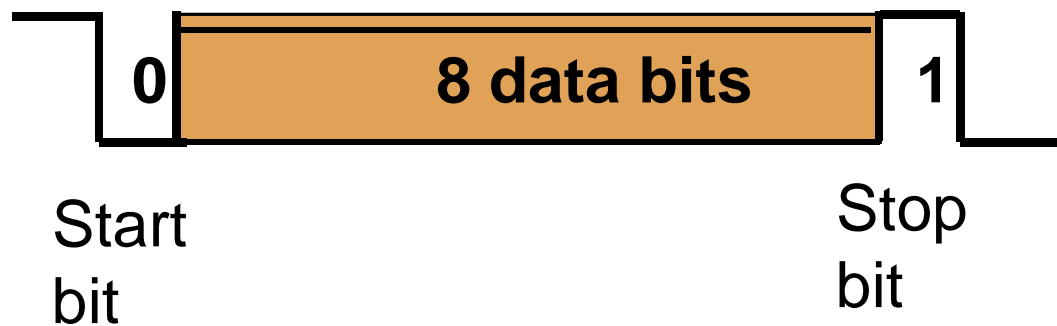
- **Frame: “Envelope” for transmission data**
- **3 different frame types :**
 - ➔ **Message Frames:** used for regular data transmission
 - ➔ **Command Frames:** used for software updates, network configuration, and diagnostic purposes
 - ➔ **Extended Frames:** are reserved to allow the embedding of user-defined message formats and future LIN formats into the current LIN protocol without violating the current LIN specification

Frames (2)

➤ Frame: Formats



➤ Byte Fields Formats: transmission with LSB first

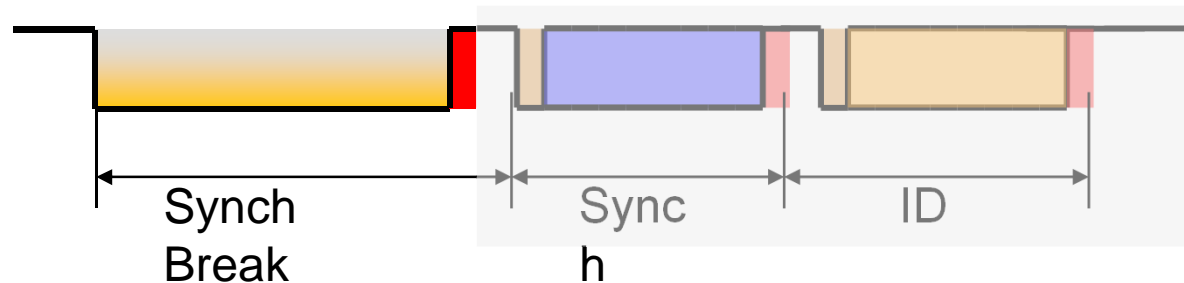


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Message Frames: Header(1)



➤ Synchronization break field

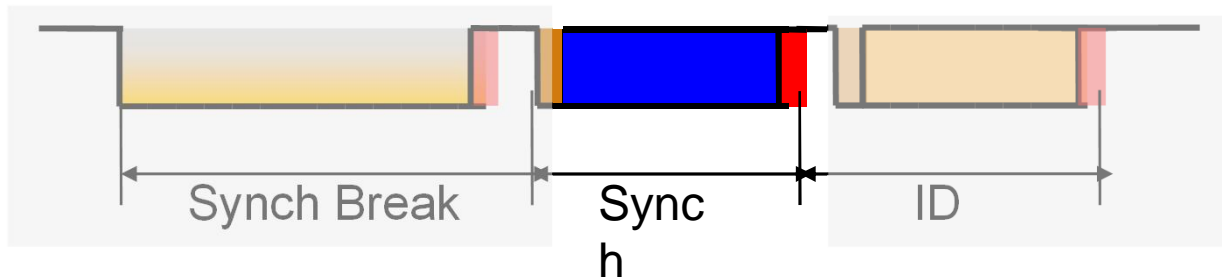
➤ identify the beginning of a message frame

➤ consists of 2 parts:

⊗ “dominant” bus value with a minimum duration of T_{SYNBRK} (13 bits)

⊗ “recessive” bus value with a minimum duration of T_{SYNDEL} (1bit)

Message Frames: Header(2)

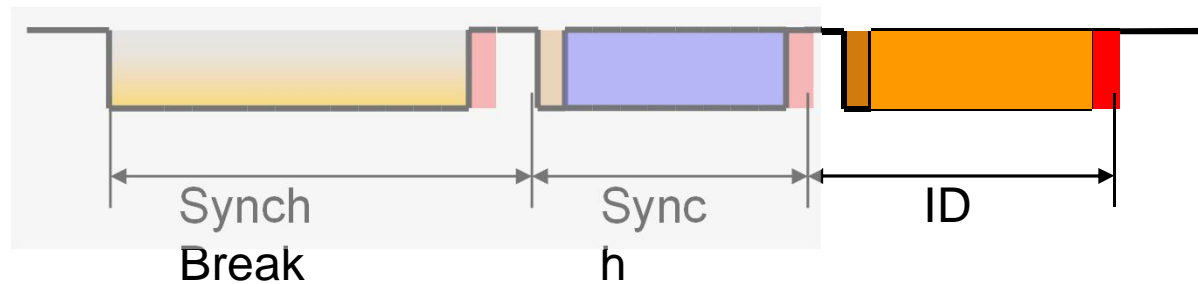


➤ Synchronization field

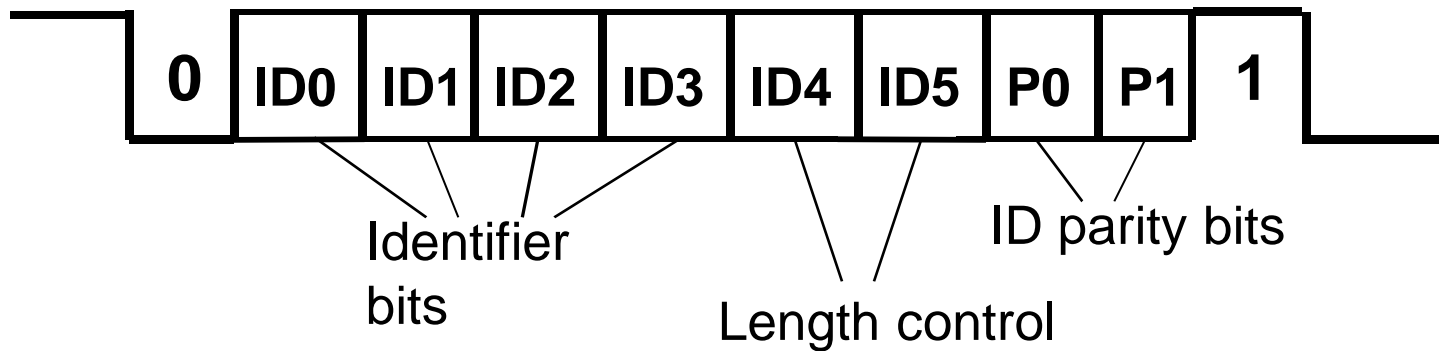
➤ contains the information for clock synchronization

➤ consists of pattern: “0x55”

Message Frames: Header(3)



➤ **Identifier field: contains the content and length of message**



Message Frames: Header(4)



- **ID0 - ID5 IDENTIFIER \Rightarrow 64 (2^6) identifiers divided in four subsets of 16 identifiers with 2, 4, 8 data fields.**

ID5	ID4	N _{DATA} (number of data fields) [byte]
0	0	2
0	1	2
1	0	4
1	1	8

- **P0 - P1 are the parity check bits of identifier**

$$P0 = ID0 \oplus ID1 \otimes ID2 \oplus ID4 \text{ (even parity)}$$

$$P1 = \overline{ID1 \oplus ID3 \otimes ID4 \oplus ID5} \text{ (odd parity)}$$

Message Frames: Response Fields



➤ Contains the data field and the checksum

↳ DATA field consists of BYTE fields

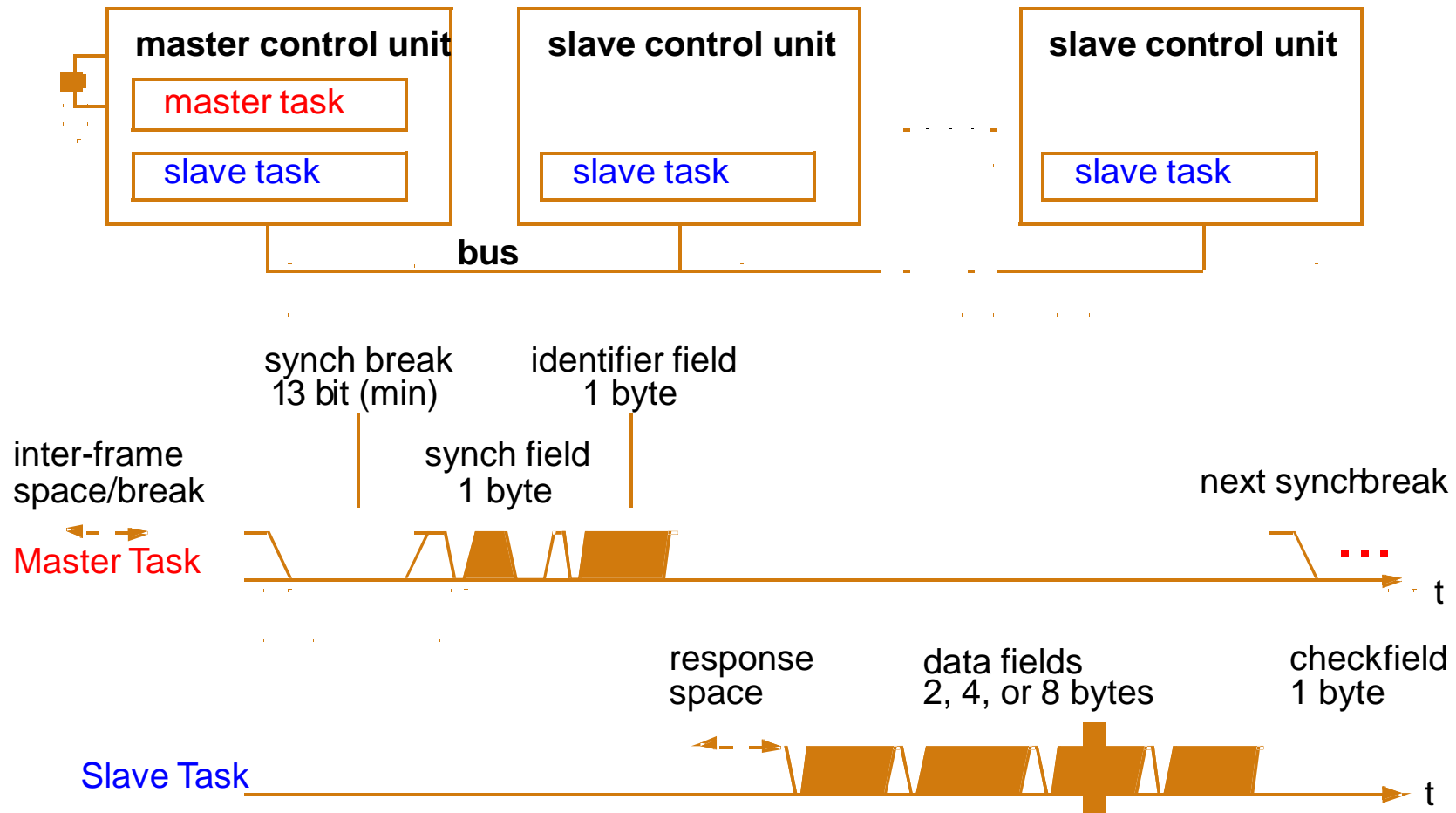
↳ CHECKSUM field contains the inverted modulo-256 sum over all data bytes calculated by “add with carry”

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Communication Concept of LIN(1)



Communication Concept of LIN(2)

Master Task

➤ Has control the whole Bus and Protocol:

- ↳ sends the header of a message

- ↳ monitors data bytes and check sum byte and evaluates them on consistency

- ↳ receives WakeUpBreak from a slave node when the bus is inactive and they request some action

- ↳ serves as a reference with it's clock base (stable clock necessary)

Communication Concept of LIN(3)

Slave Task

➤ **Is one of 2-16 members on a bus and receives or transmits data when the appropriate ID is sent by the master:**

↳ **waits for Synch Break**

↳ **synchronize on Synch Byte**

↳ **snoops for ID. According to ID slave determine what to do: receive data, transmit data or do nothing**

↳ **when transmitting sends 2, 4, or 8 data bytes and the checksum byte**

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Command and Extended Frames: Command Frames

➤ are used to broadcast general command requests for service purposes from the master to all bus participants:

↳ ID = 0x3C(0x3C) “Master request frame” to send commands and data from the master to the slave node

↳ ID = 0x3D(0x7D) “Slave response frame” that triggers one node to send data to the master node

➤ first data byte of a command frame containing the values from 0x00 to 0x7F are reserved:

↳ SLEEP MODE command - used to broadcast the sleep mode to all bus nodes: ID = 0x3C and DATA(0)=0x00

Command and Extended Frames: Extended Frames

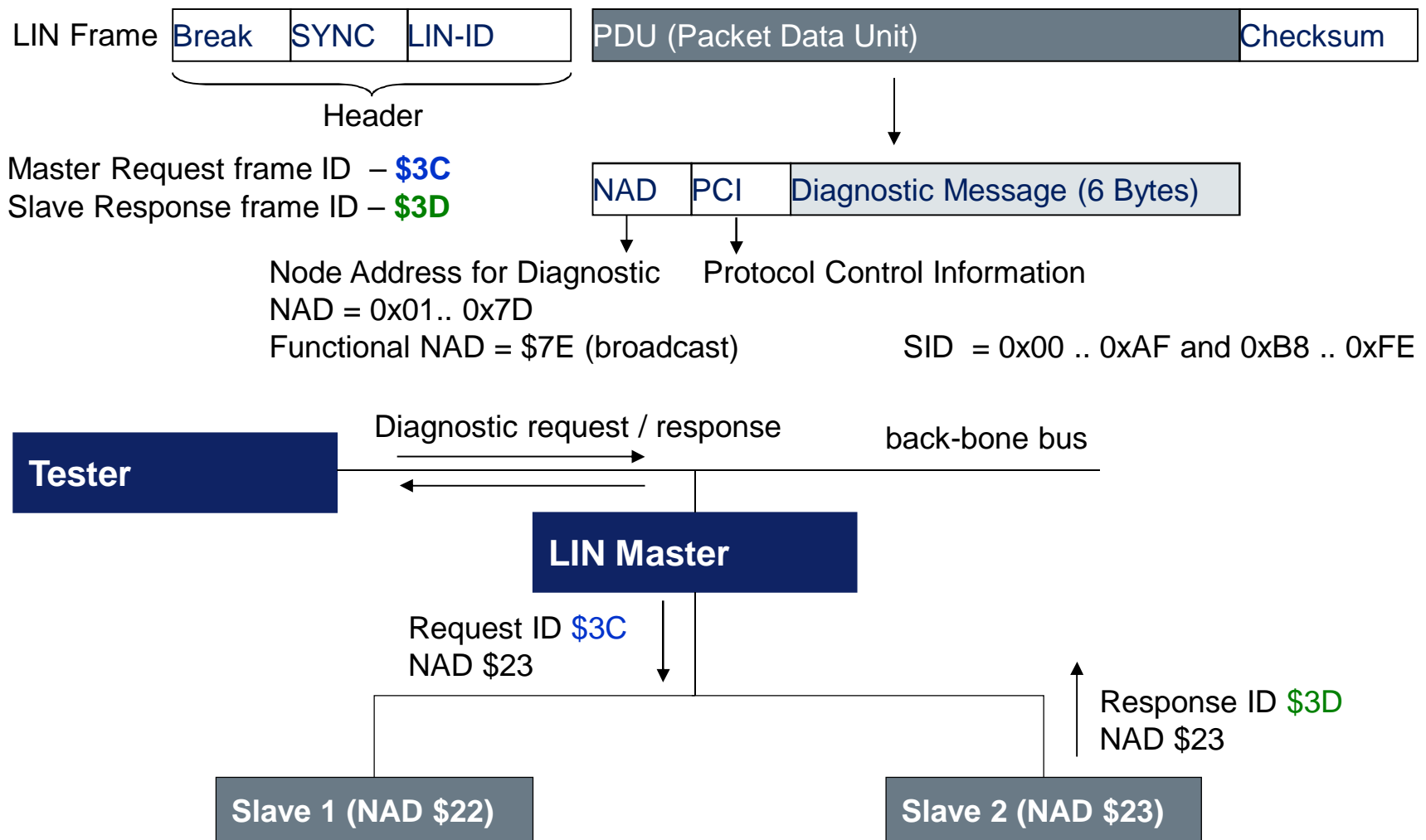
➤ are reserved to allow the embedding of user-defined message formats and future LIN formats into LIN protocol without violating the current LIN specification:

↳ ID = 0x3E(0xFE) user defined extended frame

↳ ID = 0x3F(0xBF) future LIN extension

➤ the identifier can be followed by an arbitrary number of LIN bytes fieldc

Transport protocol -Diagnostic communication on LIN



TP-Protocol Control Information

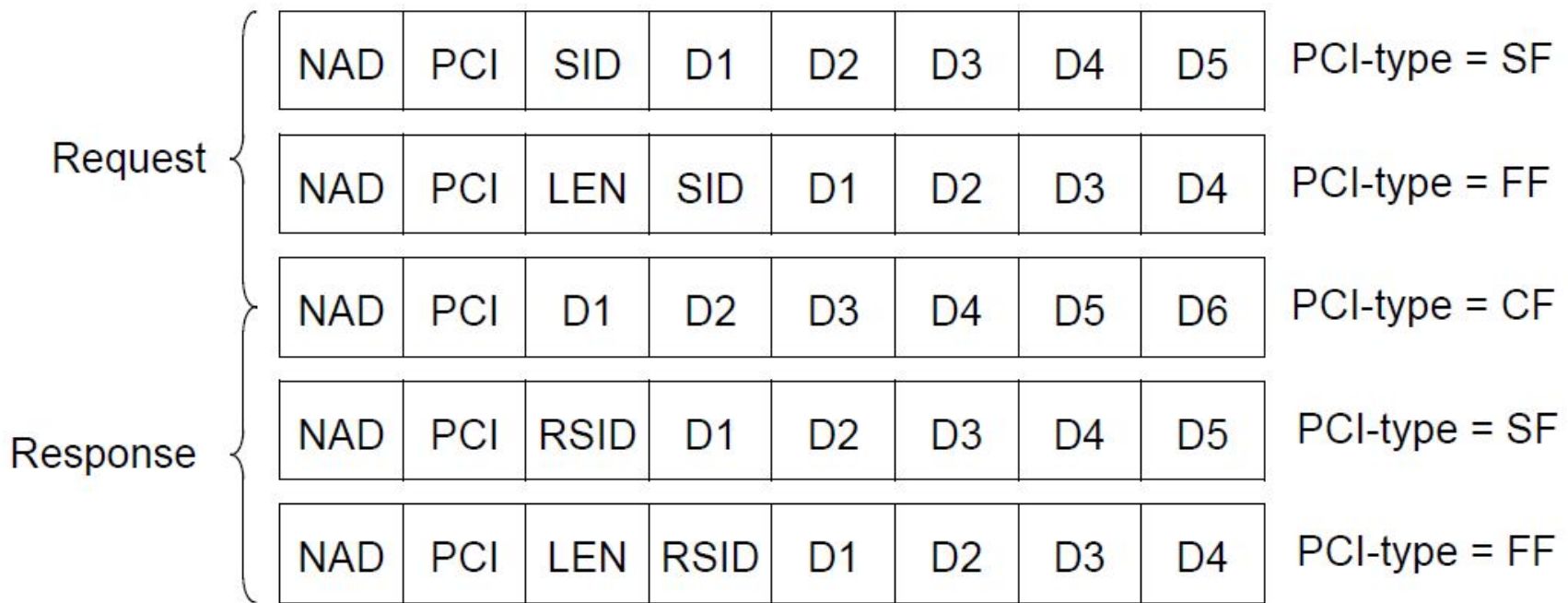


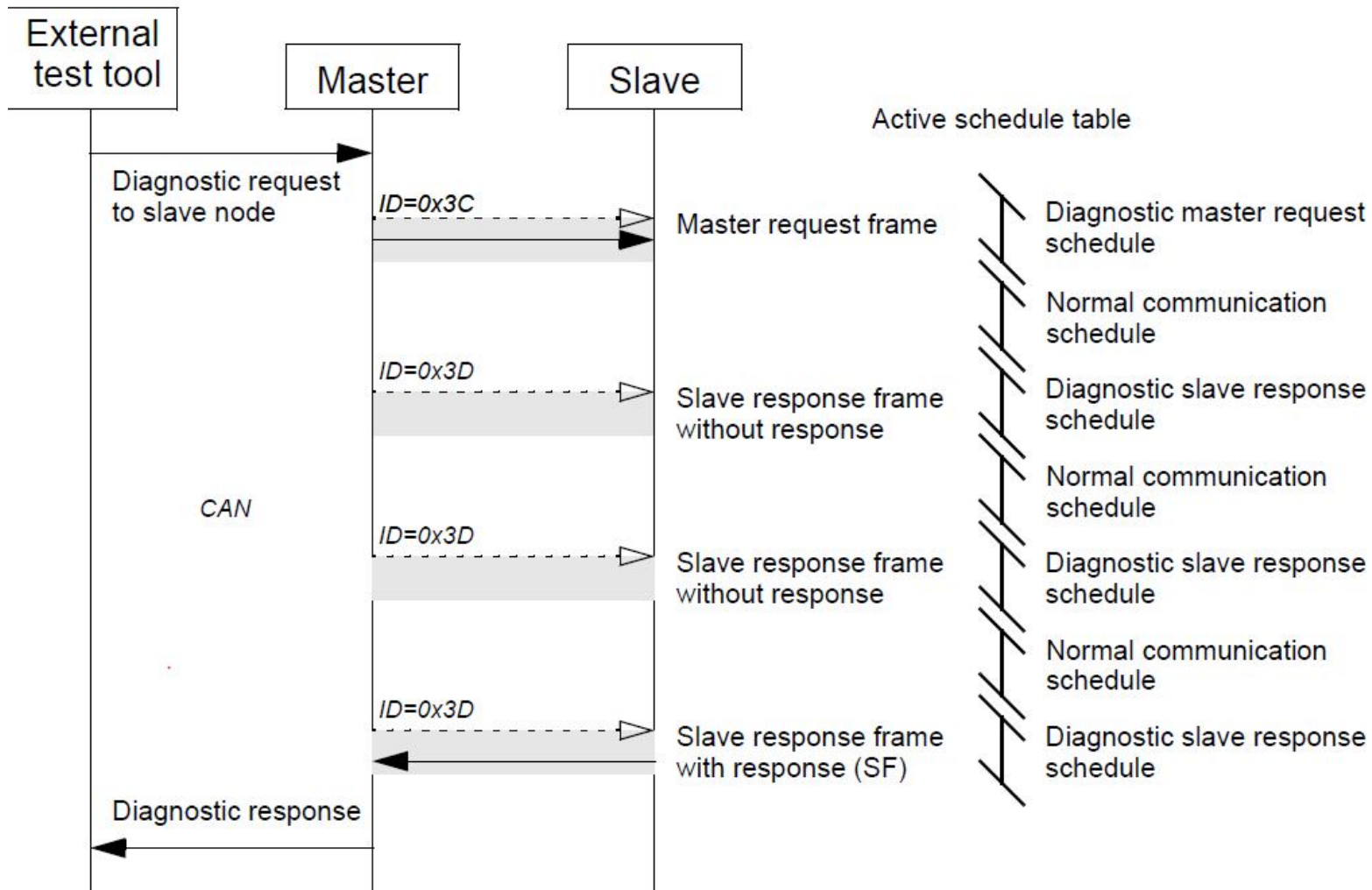
Figure 3.2: PDUs supported by the LIN transport layer.

TP-Protocol Control Information

Type	PCI type				Additional information			
	B7	B6	B5	B4	B3	B2	B1	B0
SF	0	0	0	0	Length			
FF	0	0	0	1	Length/256			
CF	0	0	1	0	Frame counter			

Table 3.1: Structure of the PCI byte.

TP-Protocol Control Information



Overview

LIN Local Interconnect Network Training

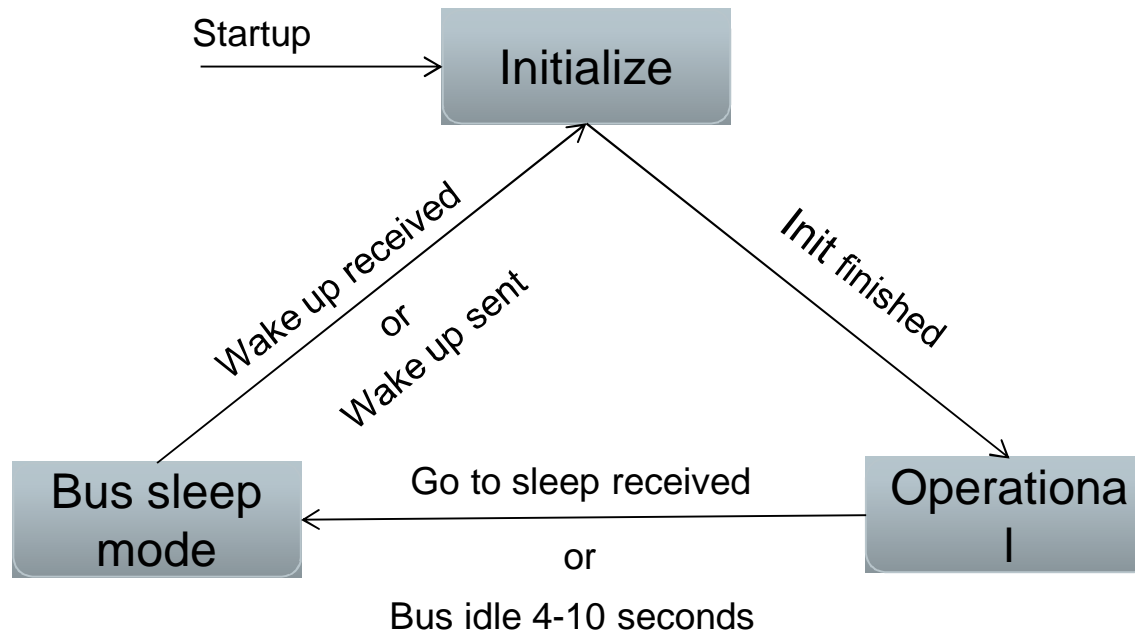
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Network management

→ Refers to:

- Wake-up
- Go to sleep

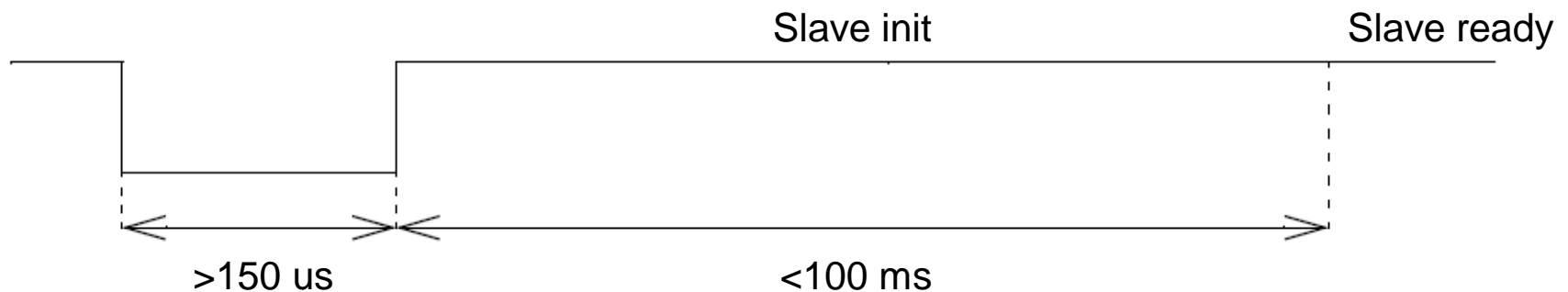
→ Slave communication state diagram:



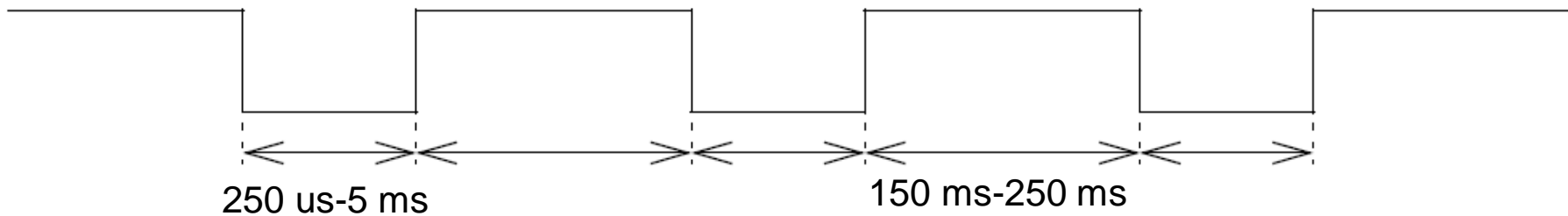
Network management

→ Wake up:

- Force the bus to dominant state for 250 μ s – 5ms
- Can be sent by any LIN node

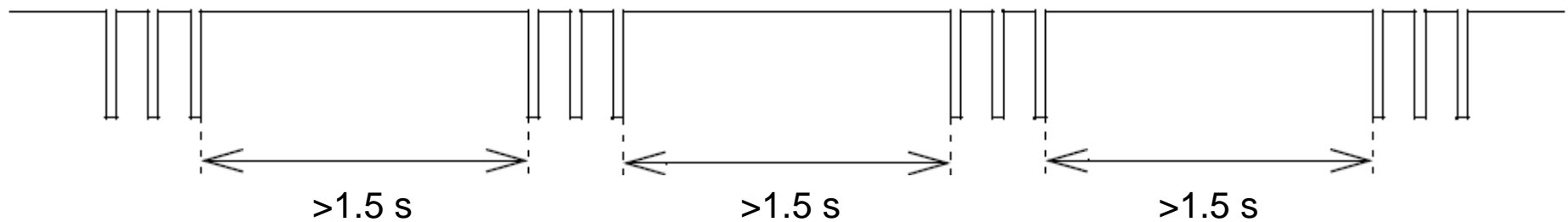


- More wake up can be requested



Network management

- After 3 failing wake up requests: minimum 1.5s wait time



→ Go to sleep:

- Done by:
 - Master request frame

0	0xF	0xF	0xF	0xF	0xF	0xF	0xF
	F	F	F	F	F	F	F

- Bus idle 4-10 seconds

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Error and exception handling

➤ Possible error types:

➤ **Bit Error**

➤ **Checksum Error**

➤ **Identifier Parity Error**

➤ **Slave Not Responding Error**

Error and exception handling(1)

Bit Errors

➤ Error description

The bit actually appearing on the bus is different that the one transmitted

➤ Method of detection

Sending unit monitors the bus while transmitting. A BIT_ERROR has to be detected at that bit time.

➤ Fault Confinement

This error is detected by - master task in master
- slave task in slave

while reading back its own transmission

Error and exception handling(2)

Checksum Errors

➤ Error description

The inverted modulo-256 sum over all received data bytes does not match with the receive checksum byte

➤ Method of detection

The sum of the inverted modulo-256 sum over all received data bytes and the checksum byte does not result in 0xFF

➤ Fault Confinement

This error is detected by:

- slave task in master when expecting or reading data from the bus**
- slave task in slave while reading from the bus**

Error and exception handling(3)

Identifier-Parity Errors

➤ Error description

The parity identifier bits does not match with the correct calculated values

➤ Method of detection

👉 Typical LIN slave application do not distinguish between an unknown but valid identifier and a corrupted identifier

➤ Fault Confinement

This error is detected by - master task in master while reading back its own transmission

- slave task in slave while reading from the bus

Error and exception handling(4)

Slave-Not-Responding Errors

➤ Error description

The message frame is not fully completed within maximum length

➤ Method of detection

A slave task waits the entire message upon transmission of the new header

➤ Fault Confinement

This error is detected by - slave task in master when expecting or reading data from the bus

- slave task in slave while reading from the bus only when a slave expects a message from another slave

Error and exception handling(5)

Inconsistent-Synch-Field Errors

➤ Error description

Synch field is different than the pattern 0x55

➤ Method of detection

Slave task detects edges of Synch field outside the given tolerance

➤ Fault Confinement

This error is detected only by slave task in slave

Error and exception handling(6)

Causes for message errors

- **Local Disturbance of Ground Potential**
- **Local Disturbance of Supply Voltage**
- **Global Electric Disturbance of the Bus Signal**
- **Unsynchronized Time Base**

