view_frames Result

Broadcaster: /robot_state_publisher

Average rate: 10000.000 Hz

Buffer length: 0.000 sec

camera_rgb_frame

ecent transform: 0.000 (1936.583 sec old)

camera_rgb_optical_frame

Broadcaster: /robot_state_publisher Average rate: 10000.000 Hz

Most recent transform: 0.000 (1936.583 sec old)
Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher

Average rate: 10000.000 Hz

Buffer length: 0.000 sec

camera_laser_optical_frame

Broadcaster: /robot_state_publisher

Average rate: 10000.000 Hz

Most recent transform: 0.000 (1936.583 sec old)

Buffer length: 0.000 sec

Broadcaster: /robot_state_publisher

Average rate: 10000.000 Hz

Buffer length: 0.000 sec

camera_depth_optical_frame

Broadcaster: /robot_state_publisher

Average rate: 10000.000 Hz

Buffer length: 0.000 sec

camera_laser_frame