

Lista 04
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1- $\min \sum_{i=1}^m b_i y_i$
 Sujeito a $\sum_{j=1}^n a_{ji} y_j \geq c_i \quad y_j \geq 0$

2- a) $\text{Max } z = 60x + 30y + 20w$
 Escrevaninha $\rightarrow x$ Sujeito a: $8x + 6y + 2w \leq 48$
 Mesa $\rightarrow y$ $3x + 2y + w \leq 20$
 Cadeira $\rightarrow w$ $2x + 2y + w \leq 8$
 $x \geq 0, y \geq 0, w \geq 0$

b) $\text{Min } z = 48x_2 + 20y_2 + 8w_2$
 Sujeito a: $8x_2 + 3y_2 + 2w_2 \leq 60$
 $6x_2 + 2y_2 + 2w_2 \leq 30$
 $2x_2 + y_2 + w_2 \leq 20$

3- a) $\text{Min } z = 24y_1 + 30y_2 + 9y_3$
 Sujeito a: $8y_1 + 5y_2 + y_3 \geq 4$ $y_1, y_2, y_3 \geq 0$
 $3y_1 + 6y_2 + 2y_3 \geq 3$

Base	y_1	y_2	y_3	y_4	y_5	b			
y_4	-8	-5	-1	1	0	-4	$-\frac{9}{-1}$	$-\frac{20}{-5}$	$-\frac{24}{-8}$
y_5	-3	-6	-2	0	1	-3	$\frac{9}{5}$	$\frac{20}{6}$	$\frac{24}{3}$
z	-24	-30	-9	0	0	0			

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Base	y_1	y_2	y_3	y_4	y_5	b
y_1	1	$\frac{5}{8}$	$\frac{1}{8}$	$-\frac{1}{8}$	0	$\frac{1}{2}$
y_5	0	$-\frac{3}{8}$	$-\frac{1}{8}$	$-\frac{3}{8}$	1	$-\frac{3}{2}$
2	0	-15	-6	-3	0	12

Resultado:

$$Z = 1.92 \quad x_1 = 3/11$$

11 $x^2 - 2^6/11$

4320

$$-6 - \left(\frac{+15}{-8} \right) = \frac{-48 + 15}{8} = \frac{-33}{8}$$

b)

Base	x_1	x_2	x_3	x_4	x_5	b
x_3	1	2	1	0	0	7
x_4	-1	1	0	1	0	0
x_5	6	2	0	0	1	21
z	-4	3	0	0	0	0

↑
Pivot

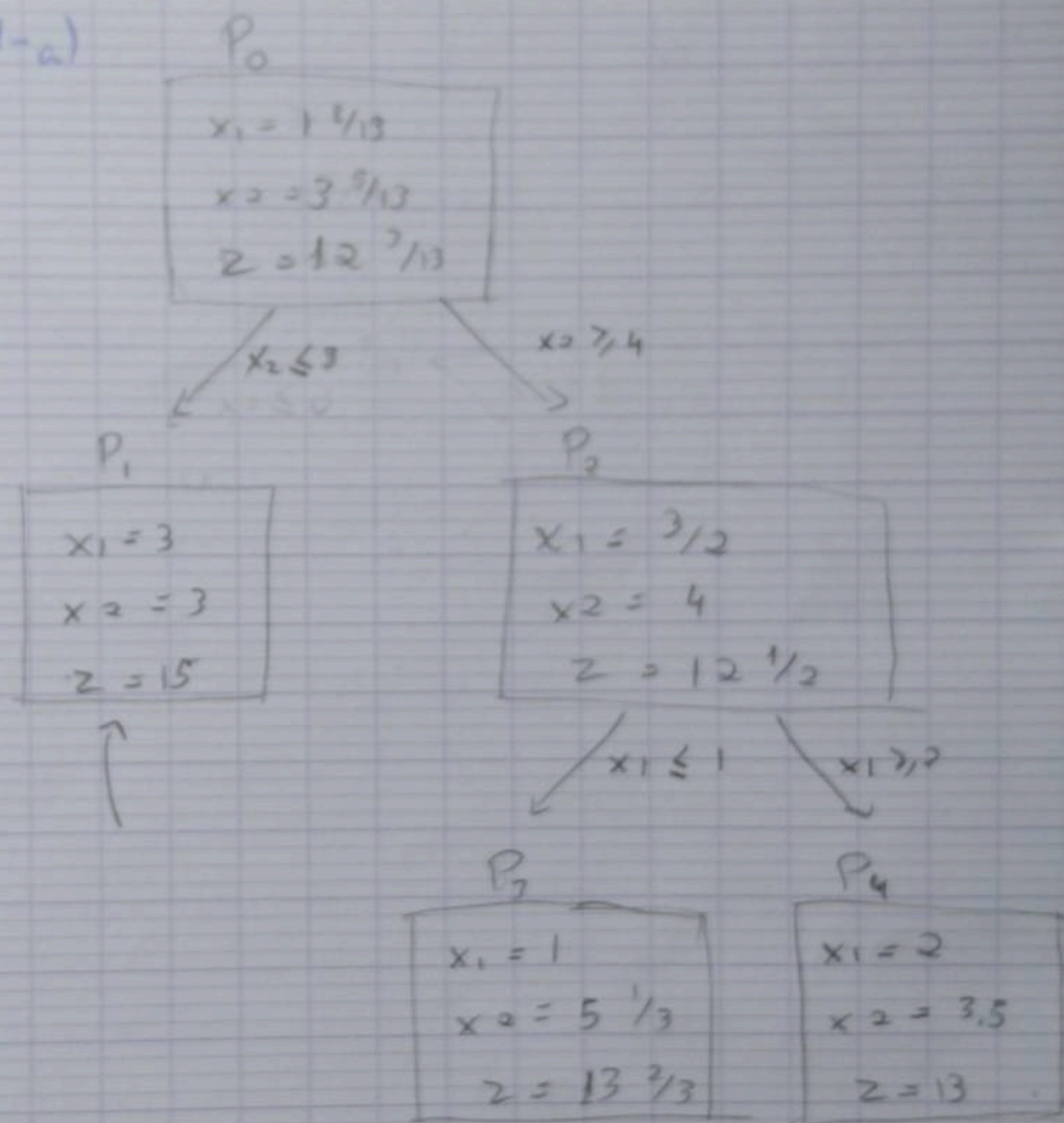
Recs / Teds:

$$z = 77/10$$

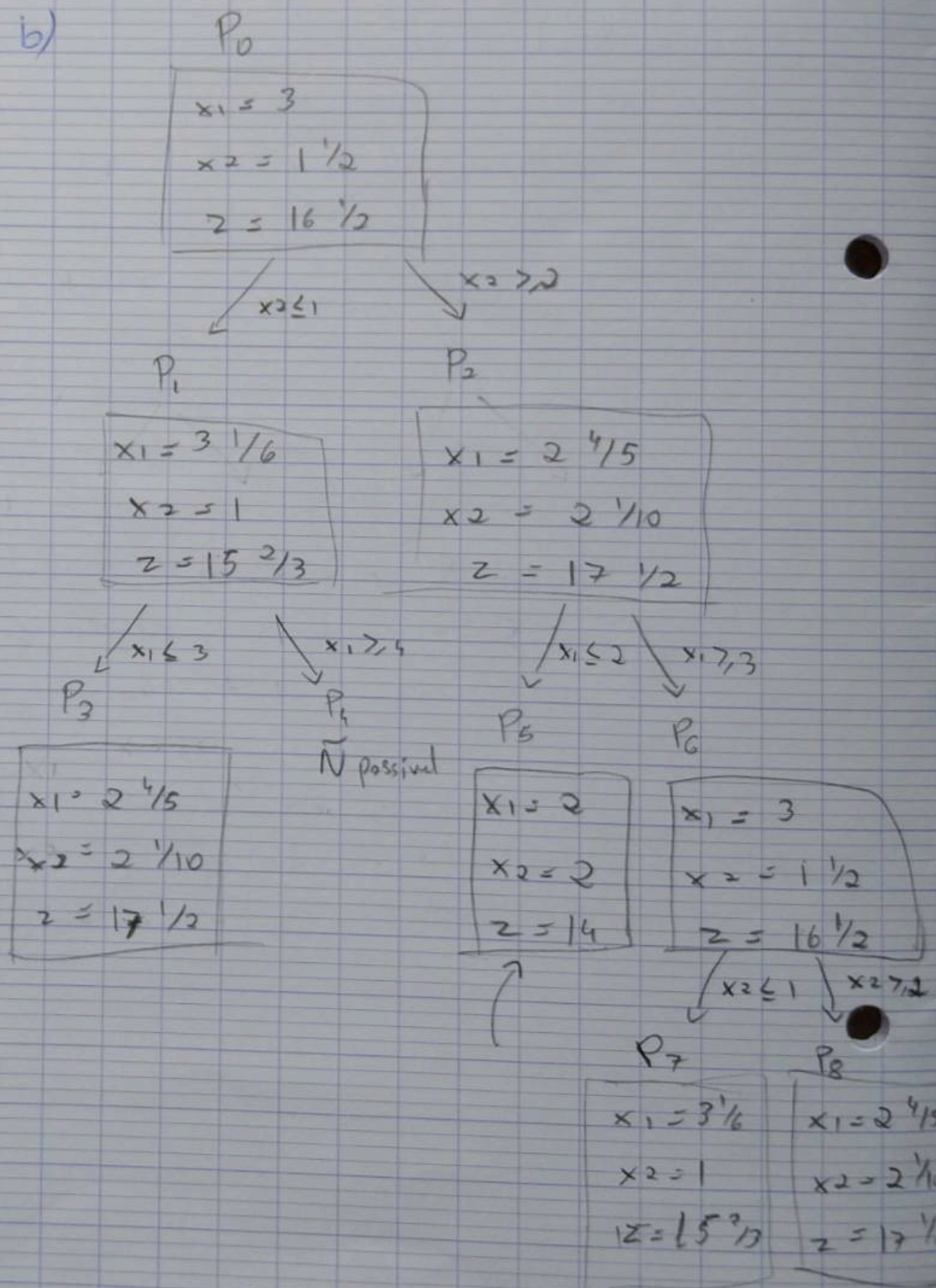
$$x_1 = 14/5$$

$$22 \div 21 \text{ } 10$$

4-a)



b)



```

c = [4, 3] # coeficientes da função objetivo
A = [[1, 2], [-1, 1],[6, 2]] #matriz de coeficientes das restrições
b = [7, 0, 21] #termos independentes

x0_bounds = (None, None) # x0 é irrestrito
x1_bounds = (None, None) # x1 >= -3

# Método padrão: simplex.

res = linprog(c, A_ub=A, b_ub=b, bounds=(x0_bounds, x1_bounds),
              options={"disp": True})

# https://docs.scipy.org/doc/scipy/reference/generated/scipy.optimize.linprog.html

```

Primal Feasibility	Dual Feasibility	Duality Gap	Step	Path Parameter	Objective
1.0	1.0	1.0	-	1.0	0.0
0.09313359053441	0.09313359053441	0.09313359053441	0.9108684373378	0.09313359053441	-50.93386936733
0.003126752651709	0.00312675265224	0.00312675265224	0.9755250943072	0.003126752652234	-178.750367743
1.991954954122e-07	1.991955014268e-07	1.991955013226e-07	0.9999372108747	1.991955014262e-07	-3163956.66125
9.957976721724e-12	9.959775084999e-12	9.959355315096e-12	0.9999499999999	9.959775084981e-12	-63279335171.1

The algorithm terminated successfully and determined that the problem is unbounded.
Iterations: 4

```

c = [3, 2] # coeficientes da função objetivo
A = [[8, 3], [5, 6],[1, 2]] #matriz de coeficientes das restrições
b = [24, 30, 9] #termos independentes

x0_bounds = (None, None) # x0 é irrestrito
x1_bounds = (None, None) # x1 >= -3

# Método padrão: simplex.

res = linprog(c, A_ub=A, b_ub=b, bounds=(x0_bounds, x1_bounds),
              options={"disp": True})

# https://docs.scipy.org/doc/scipy/reference/generated/scipy.optimize.linprog.html

```

Primal Feasibility	Dual Feasibility	Duality Gap	Step	Path Parameter	Objective
1.0	1.0	1.0	-	1.0	0.0
0.1260566912391	0.1260566912391	0.1260566912391	0.878095960448	0.1260566912391	4.120907833124
0.008949518955858	0.008949518955849	0.008949518955849	0.9333252902334	0.008949518955849	-18.972647047
4.53455694337e-06	4.53455735413e-06	4.534557353868e-06	0.9996952283899	4.534557354136e-06	-86981.48053483
2.267316987811e-10	2.267282005605e-10	2.267280423593e-10	0.9999499999266	2.26728200561e-10	-1739732648.596

The algorithm terminated successfully and determined that the problem is unbounded.
Iterations: 4