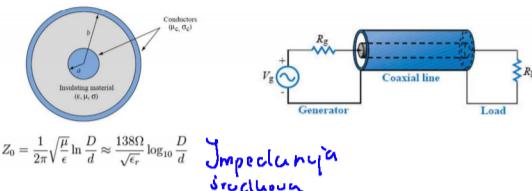


Nykiac 1

$\nabla D = \rho$		$\nabla B = 0$	
$\nabla \times E = -\frac{\partial B}{\partial t}$		$\nabla \times H = J + \frac{\partial D}{\partial t}$	
$\nabla \times E = 0$		$\nabla \cdot H = j$	
		$\nabla \cdot D = \rho$	
		$\nabla \cdot B = 0$	

$\nabla D = \rho$	prawo Gaussa	$\nabla B = 0$	brak ładunków magnetycznych
$\nabla \times H = j + \frac{\partial D}{\partial t}$	prawo Ampera	$\nabla \times E = -\frac{\partial B}{\partial t}$	prawo Faradaya



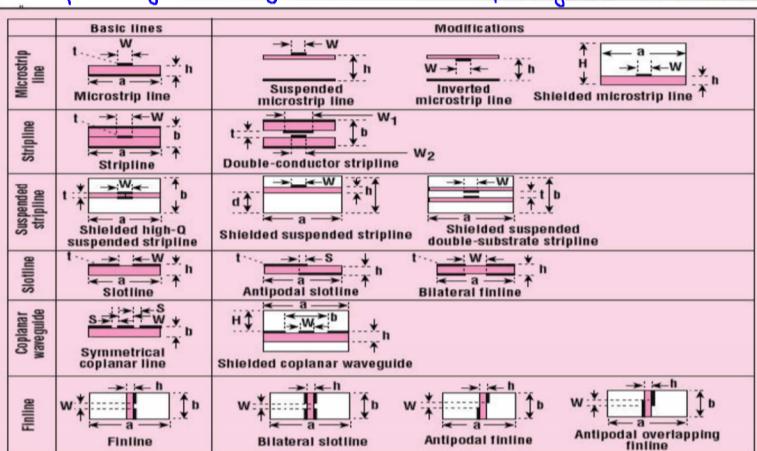
Impedancia struktury

$$Z_0 = \frac{1}{2\pi} \sqrt{\frac{\mu}{\epsilon}} \ln \frac{D}{d} \approx \frac{138\Omega}{\sqrt{\epsilon_r}} \log_{10} \frac{D}{d}$$

$E_{eff} = \frac{\epsilon_r + 1}{2} + \frac{\epsilon_r - 1}{2} \frac{1}{\sqrt{1 + 12d/W}}$

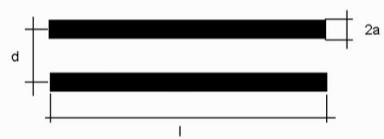
$$Z_f = \begin{cases} \frac{60}{\sqrt{E_{eff}}} \ln \left(\frac{8d}{W} + \frac{w}{4d} \right) & dla \quad W/d \leq 1 \\ \frac{120\pi}{\sqrt{E_{eff}} [w/d + 1.393 + 0.667 \ln(w/d + 1.444)]} & dla \quad W/d \geq 1 \end{cases}$$

Poziomowy budowy układów mikrofalowych



Warunki kierzystwozawodności

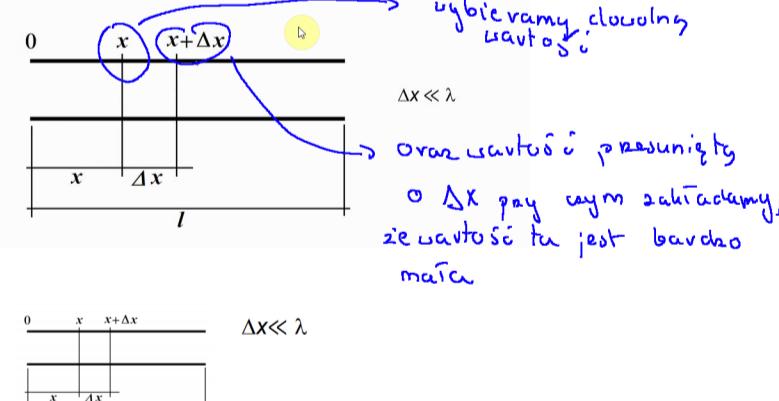
- All physical (real) structures are structures with distributed parameters
- if the quasi-stationary condition is not met $d \ll \lambda$, the structure can only be analyzed with the use of electromagnetic field theory methods



- For one-dimensional structures i.e.: in which one of three dimensions does not fulfill the quasi-stationary condition the analysis with circuit theory can be introduced

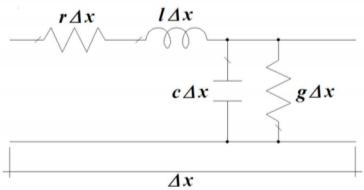
Długość fali jest znaczenie węższa od cięciwości fali której przenoszą

- For one-dimensional structures we build a model which we call transmission line



- For section Δx we can introduce a model consisting of lumped elements which are:
- inductor L_Δ - which represents magnetic field
 - capacitor C_Δ - which represents electric field
 - resistor R_Δ - which represents losses in conductors
 - conductor G_Δ - which represents losses in dielectrics

reprezentuje straty w dielektryku (izolatorze między liniami)

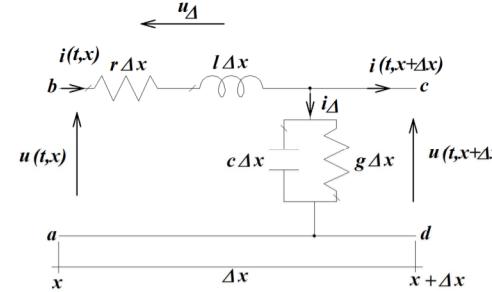


$$r [\Omega/m] \stackrel{\text{def}}{=} \lim_{\Delta x \rightarrow 0} \frac{R_\Delta}{\Delta x}$$

$$l [H/m] \stackrel{\text{def}}{=} \lim_{\Delta x \rightarrow 0} \frac{L_\Delta}{\Delta x}$$

$$g [S/m] \stackrel{\text{def}}{=} \lim_{\Delta x \rightarrow 0} \frac{G_\Delta}{\Delta x}$$

We create a transmission line by cascading to get $n \Delta x = l$
where n - number of elementary subsections



Now we can apply Kirchoff's laws to our model

According to II Kirchhoff's law for abcd loop:

$$u(t,x) = u_\Delta + u(t,x + \Delta x)$$

where

$$u_\Delta = r\Delta x i(t,x) + l\Delta x \frac{\partial}{\partial t} i(t,x)$$

$$u(t,x) - u(t,x + \Delta x) = r\Delta x i(t,x) + l\Delta x \frac{\partial}{\partial t} i(t,x)$$

Voltage function $u(t,x+\Delta x)$ can be expanded in Taylor series around x

$$u(t,x + \Delta x) = u(t,x) + \frac{\partial u(t,x)}{\partial x} \Delta x + \dots$$

Since Δx is small the higher order terms can be neglected

Taylor's theorem: for function $f(x)$ differentiable on the section (a,b) $n+1$ times

We can for arbitrary point x of the section write

$$f(x) = f(a) + \frac{x-a}{1!} f'(a) + \frac{(x-a)^2}{2!} f''(a) + \dots + \frac{(x-a)^n}{n!} f^{(n)}(a) + R_n(x,a)$$

Voltage function $u(t,x+\Delta x)$ can be expanded in Taylor series around x

$$u(t,x + \Delta x) = u(t,x) + \frac{\partial u(t,x)}{\partial x} \Delta x + \dots$$

Since Δx is small the higher order terms can be neglected

$$u(t,x) - u(t,x + \Delta x) = r\Delta x i(t,x) + l\Delta x \frac{\partial}{\partial t} i(t,x)$$

$$-\frac{\partial u(t,x)}{\partial x} \Delta x = r\Delta x i(t,x) + l\Delta x \frac{\partial}{\partial t} i(t,x)$$

$$\text{Finally we get } -\frac{\partial u(t,x)}{\partial x} = ri(t,x) + l \frac{\partial}{\partial t} i(t,x)$$

For c node we can write, according to the I Kirchhoff's law

$$i(t,x) = i_\Delta + i(t,x + \Delta x)$$

$$i_\Delta = g\Delta x u(t,x + \Delta x) + c\Delta x \frac{\partial}{\partial t} u(t,x + \Delta x)$$

Applying Taylor's expansion of a function $u(t,x+\Delta x)$ we get

$$i_\Delta = g\Delta x u(t,x) + g \frac{\partial}{\partial x} u(t,x) \Delta x^2 + c\Delta x \frac{\partial}{\partial t} u(t,x) + c \frac{\partial^2}{\partial t \partial x} u(t,x) \Delta x^2$$

Terms with Δx^2 are neglected, hence we get

$$i_\Delta = g\Delta x u(t,x) + c\Delta x \frac{\partial}{\partial t} u(t,x)$$

Putting the resulting equation

$$i_\Delta = g\Delta x u(t,x) + c\Delta x \frac{\partial}{\partial t} u(t,x)$$

To the initial equation

$$i(t,x) = i_\Delta + i(t,x + \Delta x)$$

And applying once again Taylor's expansion of $i(t,x+\Delta x)$

$$i(t,x + \Delta x) = i(t,x) + \frac{\partial i(t,x)}{\partial x} \Delta x + \dots$$

we get

$$-\frac{\partial i(t,x)}{\partial x} = gu(t,x) + c \frac{\partial}{\partial t} u(t,x)$$

Równanie telegrafistów

$$-\frac{\partial u(t,x)}{\partial x} = ri(t,x) + l \frac{\partial}{\partial t} i(t,x)$$

$$-\frac{\partial i(t,x)}{\partial x} = gu(t,x) + c \frac{\partial}{\partial t} u(t,x)$$

- Solution of Telegraphers' equations is difficult without assuming the shape of voltages and currents

- Steady state of transmission line is possible i.e. under assumption that voltages and currents are sinusoidal

opisując nam sposób propagacji sygnału optycznego położenie się punktu i napięcia w linii transmisyjnej.

For a given point x we can write

$$u(x,t) = \sqrt{2} U_{sk}(x) \sin(\omega t + \phi(x)) = \text{Im}[\sqrt{2} U e^{j\phi}]$$

$$i(x,t) = \sqrt{2} I_{sk}(x) \sin(\omega t + \phi(x)) = \text{Im}[\sqrt{2} I e^{j\phi}]$$

where

$U = U_{sk}(x) e^{j\phi(x)}$ are complex rms values of voltage and current

Going back to Telegrapher's equations

$$-\frac{\partial u(t,x)}{\partial x} = ri(t,x) + l \frac{\partial}{\partial t} i(t,x) \quad -\frac{\partial i(t,x)}{\partial x} = gu(t,x) + c \frac{\partial}{\partial t} u(t,x)$$

$$-\text{Im}[\sqrt{2} \frac{\partial u}{\partial x} e^{j\phi}] = \text{Im}[\sqrt{2} r i e^{j\phi}] + \text{Im}[\sqrt{2} j \omega U e^{j\phi}]$$

$$-\text{Im}[\sqrt{2} \frac{\partial i}{\partial x} e^{j\phi}] = \text{Im}[\sqrt{2} g U e^{j\phi}] + \text{Im}[\sqrt{2} j \omega I e^{j\phi}]$$

Ordinary derivatives

Differentiation in time

$$-\text{Im}[\sqrt{2} \frac{du}{dx} e^{j\phi}] = \text{Im}[\sqrt{2} r i e^{j\phi}] + \text{Im}[\sqrt{2} j \omega U e^{j\phi}]$$

$$-\text{Im}[\sqrt{2} \frac{di}{dx} e^{j\phi}] = \text{Im}[\sqrt{2} g U e^{j\phi}] + \text{Im}[\sqrt{2} j \omega I e^{j\phi}]$$

Skiping Im and dividing by $\sqrt{2} e^{j\phi}$

Równanie telegrafistów dla ciągostanu statycznego

$\frac{du}{dx} = (r + j\omega l)U$

$\frac{di}{dx} = (g + j\omega c)I$

Wykorzystanie binarsowej charakterystyki

To remember:

- Equations of transmission line in a steady state for sinusoidal excitation
- U, I complex rms values, which are functions of x (distance for the beginning of line)

introduce new quantity
 $\gamma^2 = (g + j\omega)(r + j\omega)$
 Final version of the equations

$$\frac{d^2U}{dx^2} - \gamma^2 U = 0$$

$$\frac{d^2I}{dx^2} - \gamma^2 I = 0$$

These are ordinary differential equations of II order for which the general solutions are known, we have:

$$U = A_1 ch(\gamma x) + B_1 sh(\gamma x)$$

$$I = A_2 ch(\gamma x) + B_2 sh(\gamma x)$$

Since the general solution is the solution of the system of 2 ordinary differential equations of the first order, only two constants are independent

Finally we can write:

$$U = Ach(\gamma x) + Bsh(\gamma x)$$

$$I = -\frac{1}{Z_f} [Bch(\gamma x) + A sh(\gamma x)]$$

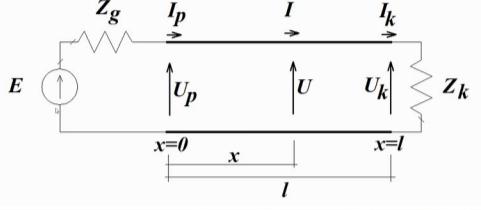
where

$$Z_f = \sqrt{\frac{r + j\omega}{g + j\omega}}$$

impedancia
falsa

Constants A and B are calculated from initial conditions

Lets consider a section of the length l in a circuit below



$$U = Ach(\gamma x) + Bsh(\gamma x)$$

$$I = -\frac{1}{Z_f} [Bch(\gamma x) + A sh(\gamma x)]$$

For $x = 0$ \rightarrow $U_p = U$

$$U = U_p \quad I = I_p$$

Putting to the equations we get

$$U_p = A$$

$$I_p = -\frac{1}{Z_f} B$$

Finally we get the solutions

$$U = U_p ch(\gamma x) - Z_f l_p sh(\gamma x)$$

$$I = I_p ch(\gamma x) - \frac{U_p}{Z_f} sh(\gamma x)$$

Similar solutions we can write measuring distance from the end of the line:

$$U = U_k ch(\gamma y) + Z_f l_k sh(\gamma y)$$

$$I = I_k ch(\gamma y) + \frac{U_k}{Z_f} sh(\gamma y)$$

Physical interpretation of Z_f

$$U = U_k ch(\gamma y) + Z_f l_k sh(\gamma y)$$

$$I = I_k ch(\gamma y) + \frac{U_k}{Z_f} sh(\gamma y)$$

Assuming $y = l$ we get

$$U_p = U_k ch(\gamma l) + Z_f l_k sh(\gamma l)$$

$$I_p = I_k ch(\gamma l) + \frac{U_k}{Z_f} sh(\gamma l)$$

Assuming, that the line is loaded with impedance Z_k : $U_k = I_k Z_k$

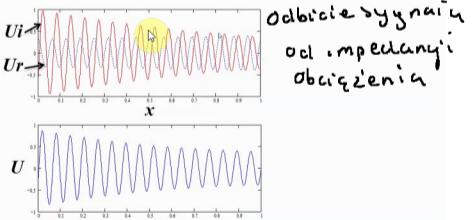
$$U_p = U_k ch(\gamma l) + \frac{Z_f}{Z_k} U_k sh(\gamma l) \quad \longrightarrow \quad U_p = U_k (ch(\gamma l) + \frac{Z_f}{Z_k} sh(\gamma l))$$

$$I_p = U_k ch(\gamma l) + \frac{U_k}{Z_k} sh(\gamma l) \quad \longrightarrow \quad I_p = U_k (\frac{1}{Z_k} ch(\gamma l) + \frac{1}{Z_f} sh(\gamma l))$$

We can therefore write the voltage and current in a line

$$U = U_i + U_r \quad I = I_i + I_r$$

As a sum of incident and reflected waves in every point of time and every point in a line



Calculating the ratios of voltages and currents of transmitted and reflected waves

$$\frac{U_i}{I_i} = \frac{0.5(U_p + I_p Z_f)}{0.5(I_p + \frac{U_p}{Z_f}) e^{-\gamma x}} = \frac{Z_f (I_p + \frac{U_p}{Z_f})}{I_p + \frac{U_p}{Z_f}} = Z_f$$

$$\frac{U_r}{I_r} = \frac{0.5(U_p - I_p Z_f)}{0.5(I_p - \frac{U_p}{Z_f}) e^{\gamma x}} = \frac{Z_f (I_p - \frac{U_p}{Z_f})}{I_p - \frac{U_p}{Z_f}} = -Z_f$$

Współczynnik odbicia

Reflection coefficient is defined as an amplitude ratio of reflected to the transmitted wave

$$\Gamma_U = \frac{U_r}{U_i} = \frac{U_k - I_k Z_f}{U_k + I_k Z_f} e^{-2\gamma y}$$

Since at the end of a line $y = 0$, $U_k = I_k Z_k$ hence

$$\Gamma_{Uk} = \frac{Z_k - Z_f}{Z_k + Z_f} \quad - \text{the reflection coefficient at the end of a line}$$

We can express the reflection coefficient with the reflection coefficient at the end of a line

$$\Gamma_U = \Gamma_{Uk} e^{-2\gamma l}$$

$$\text{Reflection coefficient for current: } \Gamma_I = \frac{I_r}{I_i} = \frac{I_k - \frac{U_k}{Z_f}}{I_k + \frac{U_k}{Z_f}} e^{-2\gamma l} = \frac{I_k Z_f - U_k}{I_k Z_f + U_k} e^{-2\gamma l} = -\Gamma_U$$

Taking that equality we assume that

$$\Gamma = \Gamma_U$$

$$\Gamma = \Gamma_k e^{-2\gamma y}$$

Writing reflection coefficient Γ_k in exponential form

$$\Gamma_k = |\Gamma_k| e^{j\Theta_k}$$

We get

$$\Gamma = |\Gamma_k| e^{j\Theta_k} e^{-2\gamma y} = |\Gamma_k| e^{-2\alpha y} e^{j(\Theta_k - 2\beta y)}$$

$|\Gamma| = |\Gamma_k| e^{-2\alpha y}$ Magnitude of reflection coefficient takes the largest value at the end of a line

Since $\Gamma_k = \frac{Z_k - Z_f}{Z_k + Z_f}$ It can take the following values:

Since $\Gamma_k = \frac{Z_k - Z_f}{Z_k + Z_f}$ It can take the following values:

for $Z_k = 0 \quad \Gamma = -1$
 for $Z_k = Z_f \quad \Gamma = 0$
 for $Z_k = \infty \quad \Gamma = 1$
 $0 \leq |\Gamma| \leq 1$

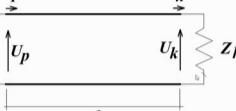
rozważanie na koncu
(catheodic reflection)

Input impedance – by def. – ratio of voltage to current at the beginning of a line

$$Z_w = \frac{U_p}{I_p}$$

Alternatively we can express input impedance with reflection coefficient

$$Z_w = \frac{U_p}{I_p} = Z_f \frac{Z_k + Z_f th(\gamma l)}{Z_f + Z_k th(\gamma l)}$$



$$Z_w = \frac{U_p}{I_p} = Z_f \frac{1 + \Gamma_k e^{-2\gamma l}}{1 - \Gamma_k e^{-2\gamma l}}$$

Impedancia wejściowa zależy od impedancji obciążenia i zależy od parametrów linii

Rozkład napięcia i prądu skuterennego

Lets investigate the distribution of an rms values for voltages and currents along the line

From the expressions

$$U = U_i (1 + \Gamma)$$

$$U = 0.5(U_k + I_k Z_f) e^{j\gamma y} (1 + \Gamma_k e^{-2\gamma l})$$

And the expression $U_{ik} = 0.5(U_k + I_k Z_f)$

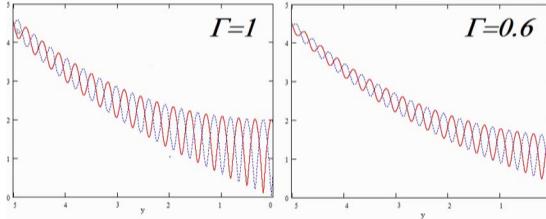
$$U = U_{ik} e^{j\gamma y} (1 + \Gamma_k e^{-2\gamma l})$$

moduł 2 wartości bezwzględnej

We calculate the magnitude of the expression $|U| = \sqrt{U U^*}$

$$|U| = U_{ik} e^{\alpha y} \sqrt{1 + 2\Gamma_k e^{-2\alpha y} \cos(\Theta_k - 2\beta y) + \Gamma_k^2 e^{-4\alpha y}}$$

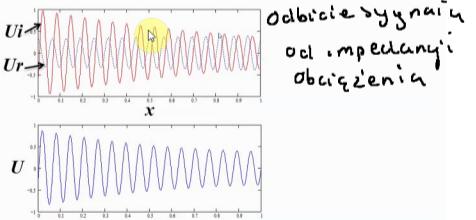
$$|U| = \frac{I_{ik}}{Z_f} e^{\alpha y} \sqrt{1 - 2\Gamma_k e^{-2\alpha y} \cos(\Theta_k - 2\beta y) + \Gamma_k^2 e^{-4\alpha y}}$$



We can therefore write the voltage and current in a line

$$U = U_i + U_r \quad I = I_i + I_r$$

As a sum of incident and reflected waves in every point of time and every point in a line



Calculating the ratios of voltages and currents of transmitted and reflected waves

$$\frac{U_i}{I_i} = \frac{Z_f (I_p + \frac{U_p}{Z_f})}{I_p + \frac{U_p}{Z_f}} = Z_f$$

$$\frac{U_r}{I_r} = \frac{Z_f (I_p - \frac{U_p}{Z_f})}{I_p - \frac{U_p}{Z_f}} = -Z_f$$

Współczynnik odbicia

Reflection coefficient is defined as an amplitude ratio of reflected to the transmitted wave

$$\Gamma_U = \frac{U_r}{U_i} = \frac{U_k - I_k Z_f}{U_k + I_k Z_f} e^{-2\gamma y}$$

Since at the end of a line $y = 0$, $U_k = I_k Z_k$ hence

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We can express the reflection coefficient with the reflection coefficient at the end of a line

$$\Gamma_U = \Gamma_{Uk} e^{-2\gamma l}$$

$$\text{Reflection coefficient for current: } \Gamma_I = \frac{I_r}{I_i} = \frac{I_k - \frac{U_k}{Z_f}}{I_k + \frac{U_k}{Z_f}} e^{-2\gamma l} = \frac{I_k Z_f - U_k}{I_k Z_f + U_k} e^{-2\gamma l} = -\Gamma_U$$

Taking that equality we assume that

$$\Gamma = \Gamma_U$$

Since $\Gamma_k = \frac{Z_k - Z_f}{Z_k + Z_f}$ It can take the following values:

$$\Gamma$$

We get

$$\Gamma = |\Gamma_k| e^{j\Theta_k} e^{-2\gamma y} = |\Gamma_k| e^{-2\alpha y} e^{j(\Theta_k - 2\beta y)}$$

$|\Gamma| = |\Gamma_k| e^{-2\alpha y}$ Magnitude of reflection coefficient takes the largest value at the end of a line

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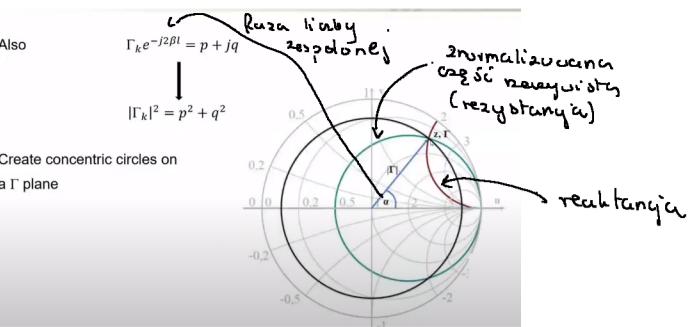
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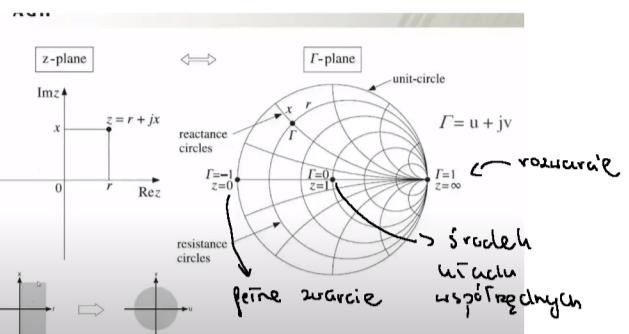
$$\Gamma = |\Gamma_k| e^{j\Theta_k} e^{-2\gamma y} = |\Gamma_k| e^{-2\alpha y} e^{j(\Theta_k - 2\beta y)}$$

$|\Gamma| = |\Gamma_k| e^{-2\alpha y}$ Magnitude of reflection coefficient takes the largest value at the



Wykres Smitha to transformacja

2 ukladu hspotygodnych



Opis macierzy linii transmisyjnej

ABCD matrix

$$\begin{bmatrix} U_1 \\ I_1 \end{bmatrix} = A \begin{bmatrix} U_2 \\ I_2 \end{bmatrix}$$

$$A = ABCD = \begin{bmatrix} a_{11} & a_{12} \\ a_{21} & a_{22} \end{bmatrix}$$

$$U_1 = a_{11}U_2 - a_{12}I_2$$

$$I_1 = a_{21}U_2 - a_{22}I_2$$

From transmission line equations

$$U_p = U_k ch(\gamma l) + Z_f I_k sh(\gamma l)$$

$$I_p = I_k ch(\gamma l) + \frac{U_k}{Z_f} sh(\gamma l)$$

$$U_1 = a_{11}U_2 - a_{12}I_2$$

$$I_1 = a_{21}U_2 - a_{22}I_2$$

$$I_k = -I_2$$

$$I_p = I_1$$

$$U_p = U_1$$

$$U_k = U_2$$

$$U_1 = a_{11}U_2 - a_{12}I_2$$

$$I_1 = a_{21}U_2 - a_{22}I_2$$

$$I_k = -I_2$$

$$I_p = I_1$$

$$U_p = U_1$$

$$U_k = U_2$$

$$U_p = U_k ch(\gamma l) + Z_f I_k sh(\gamma l)$$

$$I_p = I_k ch(\gamma l) + \frac{U_k}{Z_f} sh(\gamma l)$$

$$U_1 = U_2 ch(\gamma l) + Z_f I_2 sh(\gamma l)$$

$$I_1 = U_2 \frac{1}{Z_f} sh(\gamma l) - I_2 ch(\gamma l)$$

$$U_p = U_1$$

$$U_k = U_2$$

$$\left[\begin{array}{c} U_1 \\ I_1 \end{array} \right] = \left[\begin{array}{cc} ch(\gamma l) & Z_f sh(\gamma l) \\ \frac{1}{Z_f} sh(\gamma l) & ch(\gamma l) \end{array} \right] \left[\begin{array}{c} U_2 \\ I_2 \end{array} \right]$$

Wszystko dla modulu wagi hego (wronice strony)

Stąd funkcje sh i ch

Ugryzne Macierze reprezentacyjne (Scattering Matrix, Macierz S)

- In electrical circuits we use impedance/admittance description which utilize coefficients of voltage-current equations

- Impedance / admittance matrices may not exist for every passive circuit

- A description with scattering matrix has been introduced

- Scattering parameters are not directly related to voltages and currents but are related to their linear combination

- Every linear and passive circuit can be described with scattering matrix

- Scattering matrix is defined in conditions of ports loaded with given impedances

- Convenient description in microwave frequency range where the power transfer is considered instead of voltage / current description



Let us consider one-port

We define incident parameter

$$a = a_{11}U + a_{12}I$$

$$b = a_{21}U + a_{22}I$$

a_{ij} - Arbitrary constants, can be chosen depending on the considered problem, typically they are chosen as a way to get simple description of power

We assume

$$a_{11} = a_{21} = \frac{1}{2\sqrt{R_0}}$$

$$a_{12} = -a_{22} = \frac{\sqrt{R_0}}{2}$$

R₀ - Arbitrary real value called normalization constant, the dimension is Ω

a = a₁₁U + a₁₂I

$$b = a_{21}U + a_{22}I$$

$$a_{12} = -\frac{\sqrt{R_0}}{2}$$

We get

$$a = \frac{1}{2} \left(\frac{U}{\sqrt{R_0}} + I\sqrt{R_0} \right) = \frac{1}{2} \left(\frac{U + R_0 I}{\sqrt{R_0}} \right)$$

$$b = \frac{1}{2} \left(\frac{U}{\sqrt{R_0}} - I\sqrt{R_0} \right) = \frac{1}{2} \left(\frac{U - R_0 I}{\sqrt{R_0}} \right)$$

Normalizing voltage and current

$$u = \frac{U}{\sqrt{R_0}}$$

$$i = I\sqrt{R_0}$$

We get

$$a = \frac{1}{2}(u + i)$$

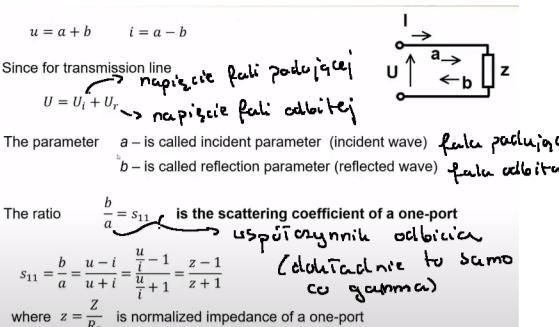
$$b = \frac{1}{2}(u - i)$$

Fale produkcyjne

By adding we get

$$u = a + b$$

$$i = a - b$$



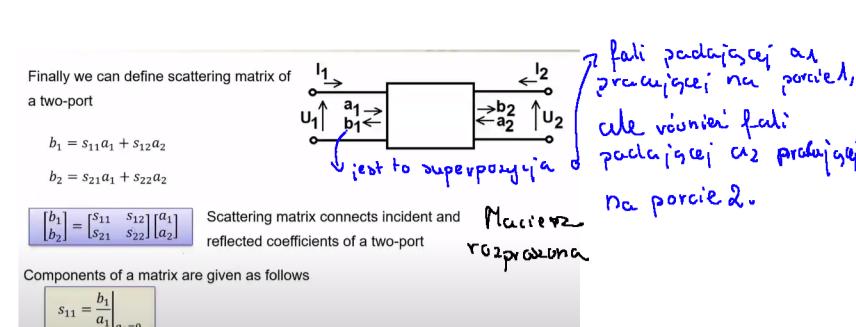
$$s_{11} = \frac{b}{a} = \frac{u - i}{u + i} = \frac{\frac{u}{\sqrt{R_0}} - \frac{i}{\sqrt{R_0}}}{\frac{u}{\sqrt{R_0}} + \frac{i}{\sqrt{R_0}}} = \frac{z - 1}{z + 1} \Leftrightarrow \Gamma_k = \frac{Z_k - Z_f}{Z_k + Z_f}$$

One can notice that for a passive one-port, i.e. $\text{Re}[Z] \geq 0$ absolute value $|s_{11}| \leq 1$

$$|s_{11}|^2 = \frac{(Re(z-1))^2 + Im^2 z}{(Re(z+1))^2 + Im^2 z}$$

Hence for $\text{Re}[Z] \geq 0$ absolute value $|s_{11}|^2 \leq 1$

therefore also $|s_{11}| \leq 1$ - this is the condition of passivity of a one-port necessary and sufficient



$$s_{11} = \frac{b_1}{a_1} \Big|_{a_2=0}$$

Macierz S wieze nam fale produkcyjne

2 falkami odbitymi lub falkami produkcyjnymi

Jesli produkty fale produkcyjne a to fale produkcyjne i odbite, jednorazem tworzą fale produkcyjne i odbite, bo istnieje możliwość, że duchovnik jest w trakcie transmisji 2 portu i na port 2

$$s_{11} = \frac{b_1}{a_1} \Big|_{a_2=0}$$

Assumption that $a_2 = 0$ means that $u_2 = -i_2$

$$a_2 = \frac{1}{2}(u_2 + i_2)$$

hence $\frac{U_2}{\sqrt{R_{02}}} = -i_1 \sqrt{R_{02}}$

$$\frac{U_2}{-i_2} = R_{02}$$

$$s_{11} = \frac{b_1}{a_1} \Big|_{a_2=0}$$

Therefore s_{11} is an input reflection coefficient of a two-port

$$s_{11} = \frac{b_1}{a_1} = \frac{z_1 - 1}{z_1 + 1} = \frac{z_1 - R_{01}}{z_1 + R_{01}}$$

From the second equation $b_2 = s_{21}a_1 + s_{22}a_2$

$$s_{21} = \frac{b_2}{a_1} \Big|_{a_2=0}$$

Wspolczynnik transmisijski

$$s_{21} = \frac{b_2}{a_1} \Big|_{a_2=0}$$

$$s_{21} = \frac{b_2}{a_1} = \frac{1}{2} \left(\frac{U_2}{\sqrt{R_{02}}} - i_1 \sqrt{R_{02}} \right)$$

$$s_{21} = \frac{1}{2} \left(\frac{U_1}{\sqrt{R_{01}}} + i_1 \sqrt{R_{01}} \right)$$

Taking into account that $I_1 = \frac{E_g - U_1}{R_{01}}$ $I_2 = \frac{-U_2}{R_{02}}$

$$s_{21} = \frac{U_2}{E_g \sqrt{R_{02}}} \text{ therefore } s_{21}^2 = \frac{P_2}{P_{av}}$$

P₂ power dissipated in the resistor R₀₂

$$s_{21}^2 = \frac{P_2}{P_{av}} \text{ Transducer power gain}$$

Każdy wątpliwym podniesiony do kwadratu informuje nas o mocy

Similarly for excitation of output port

$$s_{22} = \frac{b_2}{a_2} \Big|_{a_1=0} = \frac{z_2 - 1}{z_2 + 1} \text{ Wspolczynnik odbitej po drugiej stronie} \rightarrow aby zmniejszyć należałoby odbić się bez odbioru$$

$$s_{22} = \frac{b_2}{a_2} \Big|_{a_1=0} = 2 \frac{U_1}{E_g \sqrt{R_{01}}} \text{ Stosunek napięć wejściowych modyfikowany przez reakcję charakterystyczną na wątpliwych odbitach}$$

$$s_{22}^2 = \frac{P_{22}}{P_{av2}}$$

Power reflected towards the source

$$s_{22}^2 = \frac{P_{22}}{P_{av2}} \text{ Power reflected towards the source}$$

Reverse transducer power gain

$$s_{12}^2 = \frac{P_{12}}{P_{av2}}$$

Wzmocnienie (tłumienie) mocy odbiorczej (2 portu 2)

$$s_{12}^2 = \frac{P_{12}}{P_{av2}} \text{ mocy dostarczanej na port 2}$$

Power delivered to a two-port

$$P_1 - power delivered to the input$$

$$P_2 - power delivered to output$$

$$P = P_1 + P_2 = a^* a - b^* b$$

Power delivered to a two-port

$$P_1 - power delivered to the input$$

$$P_2 - power delivered to output$$

$$P = P_1 + P_2 = a^* a - b^* b$$

Knowing that $b = Sa$

$$P = a^* t a - b^* t b = a^* t a - S^* t S a$$

$$P = a^* t a - b^* t b = a^* t a - S^* t S a$$

For lossless two-ports $P = 0$, hence for $a \neq 0$

$$1 - S^* t S = 0$$

$S^* t S = 1$ Scattering matrix of a lossless network is unitary

Należy pamiętać, że macierz jest lewostronna

$$S^$$

Technika mikroprocesorowa - uklad II

linia transmisyjna

$$Z_f = \sqrt{\frac{r+j\omega L}{g+j\omega C}} = \sqrt{\frac{L}{C}}$$

Impedancja falowej linii jest zaleziona od częstotliwości

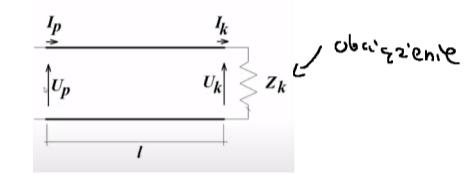
$\alpha = 0$ // częstotliwość rezywista $\gamma \rightarrow$ stała, propagująca

$$\beta = j\beta = j\omega \sqrt{\frac{L}{C}}$$

$$V_f = \frac{\omega}{\beta} = \frac{1}{\sqrt{LC}} - \text{prędkość falowej}$$

Jeśli napiszemy i przed określając funkcje trygonometryczne dającą cosinus to oznacza że linia transmisyjna jest bezstratna, w przewornym typieku przyjmując punkty hiperboliczne (ch, sh)

Impedancja wejściowa od strony generatora



$$U_p = U_k \cos(\beta l) + j Z_f I_k \sin(\beta l)$$

$$I_p = I_k \cos(\beta l) + j \frac{U_k}{Z_f} \sin(\beta l)$$

$$Z_w = \frac{U_p}{I_p} = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)}$$

częstość wejściowa γ

Standing wave distribution

$$|U| = U_{ik} e^{i\alpha y} \sqrt{1 + 2\Gamma_k e^{-2\alpha y} \cos(\Theta_k - 2\beta y) + \Gamma_k^2 e^{-4\alpha y}}$$

$$|I| = \frac{I_{ik}}{Z_f} e^{i\alpha y} \sqrt{1 - 2\Gamma_k e^{-2\alpha y} \cos(\Theta_k - 2\beta y) + \Gamma_k^2 e^{-4\alpha y}}$$

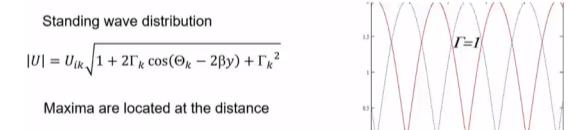
$\alpha = 0$

$$|U| = U_{ik} \sqrt{1 + 2\Gamma_k \cos(\Theta_k - 2\beta y) + \Gamma_k^2}$$

$$|I| = \frac{I_{ik}}{Z_f} \sqrt{1 - 2\Gamma_k \cos(\Theta_k - 2\beta y) + \Gamma_k^2}$$

No dependency

Standing wave distribution



Maxima are located at the distance

$$\cos(\Theta_k - 2\beta y) = 1$$

$$\Theta_k - 2\beta y = 2\pi k$$

$$y_{max,k} = \frac{1}{2\beta} (\Theta_k - 2\pi k) \quad k = 0, 1, 2, \dots$$

$$y_{min,k} = \frac{1}{2\beta} (\Theta_k - \pi(2k+1)) \quad k = 0, 1, 2, \dots$$

Wysiękanie maksimum i minimum w tym samym miejscu

Standing wave distribution

$$|U| = U_{ik} \sqrt{1 + 2\Gamma_k \cos(\Theta_k - 2\beta y) + \Gamma_k^2}$$

The distance between minimum and maximum

$$y_{max} - y_{min} = \frac{1}{2\beta} (\Theta_k - 2\pi k) - y_{min} = \frac{1}{2\beta} (\Theta_k - \pi(2k+1)) = \frac{\pi}{2\beta} = \frac{\lambda}{4}$$

The distance between two consecutive minima

$$y_{min,k} - y_{min,k+1} = \frac{\lambda}{4} = \frac{V_f}{2f} \quad \text{a dla } \epsilon_r = 1 \quad y_{min,k} - y_{min,k+1} = \frac{\lambda}{4} = \frac{c}{2f}$$

Odczytujemy pomiędzy szczeblem minimum i maksymum to połowę częstotliwości fali $\frac{1}{2}$

Standing wave distribution

$$|U| = U_{ik} \sqrt{1 + 2\Gamma_k \cos(\Theta_k - 2\beta y) + \Gamma_k^2}$$

Stojące fale stojące

$$\text{SWR} = \rho = \frac{1 + |\Gamma_k| e^{-2\alpha y}}{1 - |\Gamma_k| e^{-2\alpha y}}$$

$$\alpha = 0$$

$$\text{SWR} = \rho = \frac{1 + |\Gamma_k|}{1 - |\Gamma_k|} = \frac{U_{max}}{U_{min}}$$

Standing wave ratio in lossless line does not depend on y and can be used for measurement of reflection coefficient

1. Transmission line loaded with matched load $Z_k = Z_f$

Reflection coefficient
odbiór
 $\Gamma_k = \frac{Z_k - Z_f}{Z_k + Z_f} = 0$ Reflected wave does not exists

Standing wave ratio

$$VSWR = \rho = \frac{1 + |\Gamma_k|}{1 - |\Gamma_k|} = \frac{U_{max}}{U_{min}} = 1$$

najniższa wartość jaką można uzyskać

2. Transmission line shorted at the end $Z_k = 0$

Reflection coefficient

$$\Gamma_k = \frac{Z_k - Z_f}{Z_k + Z_f} = -1$$

Input impedance

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

impedancja wejściowa linii bezstratnej

3. Transmission line open at the end $Z_k = \infty$

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = -j Z_f \cot(\beta l)$$

Input impedance

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

impedancja wejściowa linii bezstratnej

4. Transmission line shorted at the end $Z_k = 0$

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

Input impedance

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

impedancja wejściowa linii bezstratnej

5. Transmission line open at the end $Z_k = \infty$

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = -j Z_f \cot(\beta l)$$

Input impedance

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

impedancja wejściowa linii bezstratnej

6. Transmission line shorted at the end $Z_k = 0$

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

Input impedance

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

impedancja wejściowa linii bezstratnej

7. Transmission line open at the end $Z_k = \infty$

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = -j Z_f \cot(\beta l)$$

Input impedance

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

impedancja wejściowa linii bezstratnej

8. Transmission line shorted at the end $Z_k = 0$

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

Input impedance

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

impedancja wejściowa linii bezstratnej

9. Transmission line open at the end $Z_k = \infty$

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = -j Z_f \cot(\beta l)$$

Input impedance

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

impedancja wejściowa linii bezstratnej

10. Transmission line shorted at the end $Z_k = 0$

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

Input impedance

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

impedancja wejściowa linii bezstratnej

11. Transmission line open at the end $Z_k = \infty$

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = -j Z_f \cot(\beta l)$$

Input impedance

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

impedancja wejściowa linii bezstratnej

12. Transmission line shorted at the end $Z_k = 0$

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

Input impedance

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

impedancja wejściowa linii bezstratnej

13. Transmission line open at the end $Z_k = \infty$

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = -j Z_f \cot(\beta l)$$

Input impedance

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

impedancja wejściowa linii bezstratnej

14. Transmission line shorted at the end $Z_k = 0$

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

Input impedance

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

impedancja wejściowa linii bezstratnej

15. Transmission line open at the end $Z_k = \infty$

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = -j Z_f \cot(\beta l)$$

Input impedance

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

impedancja wejściowa linii bezstratnej

16. Transmission line shorted at the end $Z_k = 0$

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

Input impedance

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

impedancja wejściowa linii bezstratnej

17. Transmission line open at the end $Z_k = \infty$

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = -j Z_f \cot(\beta l)$$

Input impedance

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

impedancja wejściowa linii bezstratnej

18. Transmission line shorted at the end $Z_k = 0$

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

Input impedance

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = j Z_f \tan(\beta l)$$

impedancja wejściowa linii bezstratnej

19. Transmission line open at the end $Z_k = \infty$

$$Z_w = Z_f \frac{Z_k + j Z_f \tan(\beta l)}{Z_f + j Z_k \tan(\beta l)} = -j Z_f \cot(\beta l)$$

Input impedance