PROGRAMMING FOR ROBOTS AND MANIPULATORS (VRM)

Faculty of Mechanical Engineering, Brno University of Technology
Institute of Automation and Computer Science
Technicka 2896/2, Brno 616 69, Czech Republic
Roman.Parak@vutbr.cz

Project no. 1

Title:

ABB RobotStudio with a name that describes a robotic solution (e.g., ABB Robotstudio - Sorting Machine).

Detailed description:

The project focuses on controlling multiple robots using the simulation tool RobotStudio ABB. The robot on Table No.1 will communicate with another robot on Table No.2 using a conveyor belt. The main goal of the project will be to create a sorting production line. A more detailed description of the project will be discussed with the lecturer.

Note 1: It will be possible to create your own production line design, but in accordance with certain principles!

Note 2: It will be possible to create a team (max. 3 members), but with a reduction of the maximum score!

Language:

Comments: Czech, Slovak, English (recommended)
Variables, functions, and other.: English

Form:

RobotStudio Pack & Go file (.rspag)

Location:

GitHub

Important Dates:

Assignment: 22.2.2021
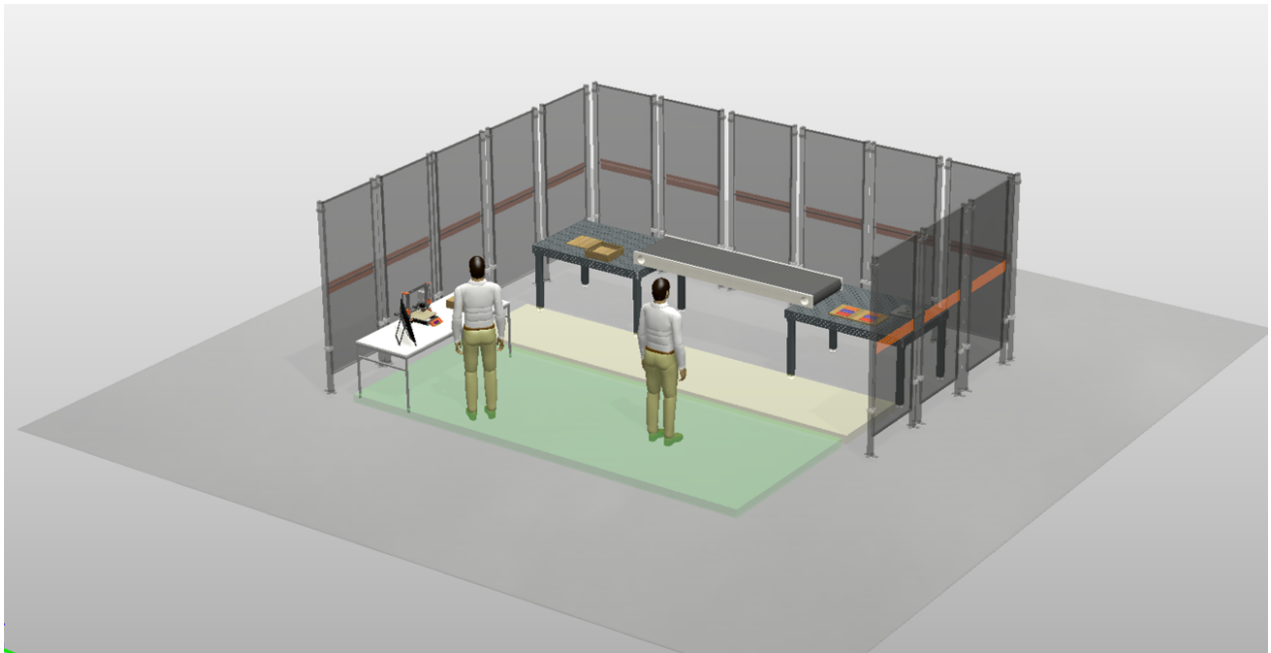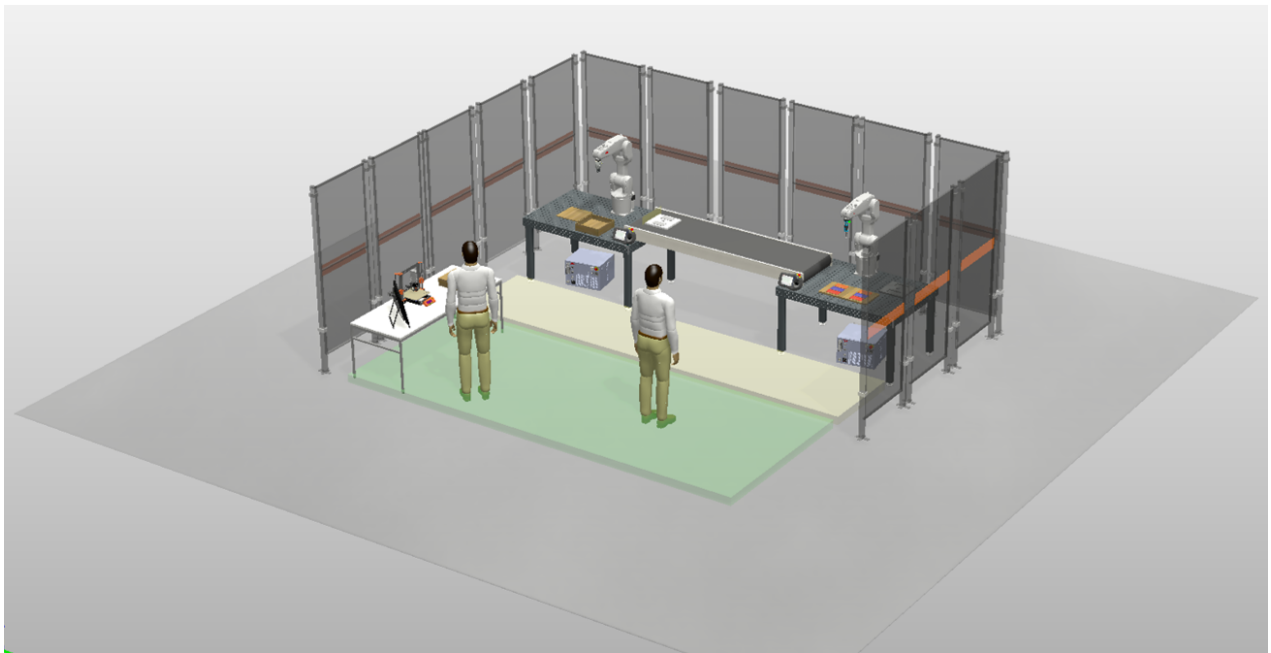Deadline: 22.3.2021

Maximum Score:

30 points

Figure 1: Project no. 1 - Template

Figure 2: Project no. 1 - Possible result