# CPC COOPERATIVE PATENT CLASSIFICATION

## G PHYSICS

(NOTES omitted)

# **INSTRUMENTS**

G01 MEASURING; TESTING

(NOTES omitted)

# G01D MEASURING NOT SPECIALLY ADAPTED FOR A SPECIFIC VARIABLE; ARRANGEMENTS FOR MEASURING TWO OR MORE VARIABLES NOT COVERED IN A SINGLE OTHER SUBCLASS; TARIFF METERING APPARATUS; MEASURING OR TESTING NOT OTHERWISE PROVIDED FOR

### NOTES

- 1. This subclass covers:
  - devices for indicating or recording the results of measurements, not peculiar to variables covered by a single other subclass:
  - analogous apparatus but in which the input is not a variable to be measured, e.g. a hand operation;
  - · details of measuring instruments, which are of general interest;
  - measurement transducers not adapted solely for the measurement of a single specified variable and not provided for elsewhere, i.e. means for converting the output of a sensing member to another variable where the form or nature of the sensing member does not constrain the means for converting;
  - · measuring or testing not otherwise provided for.
- 2. Attention is drawn to the Notes following the title of class G01.

## **WARNING**

3/021

• • {using purely analogue techniques}

In this subclass non-limiting references (in the sense of paragraph 39 of the Guide to the IPC) may still be displayed in the scheme.

1/00	Measuring arrangements giving results other than momentary value of variable, of general application (G01D 3/00 takes precedence; in tariff metering apparatus G01D 4/00; transducers not specially adapted for a specific variable G01D 5/00)	3/022 3/024 3/028	<ul> <li>• {having an ideal characteristic, map or correction data stored in a digital memory}</li> <li>• for range change; Arrangements for substituting one sensing member by another</li> <li>• mitigating undesired influences, e.g. temperature,</li> </ul>
1/02	<ul> <li>giving mean values, e.g. root means square values (measuring root mean square values of currents or voltages G01R 19/02)</li> </ul>	3/032	pressure  • affecting incoming signal, e.g. by averaging; gating undesired signals
1/04 1/06 1/08	<ul> <li>giving integrated values (giving mean values G01D 1/02)</li> <li>by intermittent summation</li> <li>over fixed periods of time</li> </ul>	3/036 3/0365	<ul> <li>on measuring arrangements themselves</li> <li>{the undesired influence being measured using a separate sensor, which produces an influence related signal}</li> </ul>
1/10 1/12 1/14	<ul> <li>giving differentiated values</li> <li>giving a maximum or minimum of a value</li> <li>giving a distribution function of a value, i.e. number of times the value comes within specified ranges of</li> </ul>	3/06 3/063	<ul> <li>with provision for operation by a null method</li> <li>{Comparing the measuring value with a reference value which periodically or incidentally scans the measuring range}</li> </ul>
1/16	<ul><li>amplitude</li><li>giving a value which is a function of two or more values, e.g. product or ratio</li></ul>	3/066	<ul> <li>• {Balancing a force which represents the measuring value, by means of a reference force}</li> <li>• with provision for safeguarding the apparatus, e.g.</li> </ul>
1/18	<ul> <li>with arrangements for signalling that a predetermined value of an unspecified parameter has been exceeded (G01D 1/14 takes precedence)</li> </ul>	3/10	against abnormal operation, against breakdown <ul><li>with provision for switching-in of additional or auxiliary indicators or recorders</li></ul>
3/00	Indicating or recording apparatus with provision for the special purposes referred to in the subgroups	4/00	<b>Tariff metering apparatus</b> (in taximeters <u>G07B 13/00</u> ; apparatus actuated by coins, cards or the like with meter-controlled dispensing of liquid, gas, or
3/02	<ul> <li>with provision for altering or correcting the law of variation</li> </ul>	4/002	electricity G07F 15/00) • {Remote reading of utility meters}

4/004	<ul> <li>{Remote reading of utility meters to a fixed location}</li> </ul>	5/142 {using Hall-effect devices (measuring magnetic variables using Hall-effect or other
4/006	Remote reading of utility meters to a non-fixed location, i.e. mobile location}	galvanomagnetic devices <u>G01R 33/06</u> )} 5/145 {influenced by the relative movement
4/000		between the Hall device and magnetic fields
4/008	<ul> <li>{Modifications to installed utility meters to enable remote reading}</li> </ul>	(see G01R 33/06)}
4/02	Details	5/147 {influenced by the movement of a third
		element, the position of Hall device and
4/04	. Resetting-mechanisms, e.g. for indicating	the source of magnetic field being fixed in
1/06	members	respect to each other}
4/06	. Arrangement of clutches between driving and	5/16 by varying resistance
	indicating member, e.g. of hysteresis clutch	5/165 by relative movement of a point of contact
4/00	(G01D 4/04 takes precedence)	{or actuation} and a resistive track
4/08	Transfer of indication from a counter into a	5/1655 {more than one point of contact or
4/10	summing counter	actuation on one or more tracks}
4/10	<ul> <li>Maximum indicating or recording apparatus, i.e.</li> <li>where the tariff for a period is based on a maximum</li> </ul>	5/18 by varying effective impedance of discharge
	demand within that period	tubes or semiconductor devices
4/12		5/183 {Sensing rotation or linear movement using
4/12	Apparatus for indicating or recording progressive maximum	strain, force or pressure sensors}
4/1.4		
4/14	<ul> <li>Fixed-demand indicating or recording apparatus, i.e. where indication is made when</li> </ul>	, ,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,
	a predetermined quantity has been consumed	5/20 by varying inductance, e.g. by a movable armature
	during a time interval greater or less than a	
	predetermined time interval	5/2006 {by influencing the self-induction of one or more coils (G01D 5/22 takes precedence)}
4/16	Apparatus for indicating or recording maximum or	5/2013 {by a movable ferromagnetic element, e.g.
4/10	minimum load hours	a core (G01D 5/2033 takes precedence)
4/18	Apparatus for indicating or recording	5/202 {by movable a non-ferromagnetic
4/10	overconsumption with opposing torque which	conductive element (G01D 5/2033 takes
	comes into effect when a predetermined level is	precedence)}
	exceeded, e.g. subtraction meters	5/2026 {constituting a short-circuiting element}
	-	5/2033 {controlling the saturation of a magnetic
5/00	Mechanical means for transferring the output of a	circuit by means of a movable element,
	sensing member; Means for converting the output	e.g. a magnet}
	of a sensing member to another variable where	5/204 {by influencing the mutual induction
	the form or nature of the sensing member does not	between two or more coils (G01D 5/22 takes
	constrain the means for converting; Transducers	precedence)}
	not specially adapted for a specific variable	5/2046 {by a movable ferromagnetic element, e.g.
	(G01D 3/00 takes precedence; specially adapted for apparatus giving results other than momentary value	a core}
	of variable G01D 1/00)	5/2053 {by a movable non-ferromagnetic
		conductive element}
	<u>NOTE</u>	5/206 {constituting a short-circuiting element}
	The subgroups of this main group are	5/2066 {by movement of a single coil with respect
	distinguished by the means which is of major	to a single other coil}
	importance. Thus the mere application of other	5/2073 {by movement of a single coil with respect
	means for giving a final indication does not affect	to two or more coils}
	the classification.	5/208 {using polyphase currents}
<b>5</b> /0.0		5/2086 {by movement of two or more coils with
5/02	using mechanical means	respect to two or more other coils}
5/04	using levers; using cams; using gearing	5/2093 {using polyphase currents}
5/06	• acting through a wall or enclosure, e.g. by	5/22 differentially influencing two coils
	bellows, by magnetic coupling	5/2208 {by influencing the self-induction of the
5/08	Reducing the effects of friction, e.g. by applying	coils}
	vibrations	5/2216 {by a movable ferromagnetic element,
5/10	Applying external forces to increase force	e.g. a core}
	available for operation of indicating or recording	5/2225 {by a movable non-ferromagnetic
	part	conductive element}
5/12	• using electric or magnetic means (G01D 5/06 takes	5/2233 {constituting a short-circuiting
# 13 # =	precedence)	element}
5/125	• • {characterised by a first part whose movement	5/2241 {by controlling the saturation of a
	represents the measuring value, and by a second	magnetic circuit by means of a movable
	part which is moved by an external force in order	element, e.g. a magnet}
E /1 A	to follow the movement of the first part}	5/225 {by influencing the mutual induction
5/14	influencing the magnitude of a current or voltage	between the two coils}
		between the two cons

5/2258 {by a movable ferromagnetic ele	
ì	The state of the s
e.g. core}	marks}
5/2266 (specially adapted circuits the	
5/2275 {by a movable non-ferromagnet	c separate encoders}
conductive element}	5/246 by varying the duration of individual pulses
5/2283 {constituting a short-circuiting	5/247 using time shifts of pulses
element}	5/248 by varying pulse repetition frequency
5/2291 {Linear or rotary variable different	
transformers (LVDTs/RVDTs) have	C 1
	c/2.52 · · · · (Tube buenn)
a single primary coil and two seconds	dary 5/2495 {Pseudo-random code}
coils}	5/2497 {Absolute encoders ( <u>G01D 5/2454</u> takes
5/24 by varying capacitance	precedence)}
5/2403 • • • • {by moving plates, not forming part	of the 5/25 . Selecting one or more conductors or channels
capacitor itself, e.g. shields}	from a plurality of conductors or channels, e.g. by
5/2405 {by varying dielectric}	closing contacts
5/241 by relative movement of capacitor el	
5/2412 {by varying overlap}	
5/2415 {adapted for encoders}	5/2515 {with magnetically controlled switches, e.g.
the state of the s	by movement of a magnet}
5/2417 {by varying separation}	5/252 a combination of conductors or channels
5/242 by carrying output of an electrodynamic	· · · · · · · · · · · · · · · · · · ·
e.g. a tachodynamo	by movement of a magnet}
5/243 influencing the phase or frequency of ac	5/26 • characterised by optical transfer means, i.e. using
5/244 influencing characteristics of pulses or pu	
trains; generating pulses or pulse trains	5/262 • • {with optical projection of a pointer or a scale}
5/24404 {Interpolation using high frequency sig	
5/24409 {Interpolation using memories}	(G01D 5/28, G01D 5/32, G01D 5/39 and
5/24414 {Encoders having selectable interpolati	
factors}	adjustment thereof}
5/24419 • • • {Interpolation not coverd by groups	5/266 • • {by interferometric means (G01D 5/353 takes
<u>G01D 5/24404</u> , <u>G01D 5/24409</u> or	precedence)}
<u>G01D 5/24414</u> }	5/268 • • {using optical fibres ( <u>G01D 5/28</u> - <u>G01D 5/38</u>
5/24423 {Mounting means or means for restrain	ing take precedence)}
during shipping (G01D 5/24442 takes	5/28 with deflection of beams of light, e.g. for direct
precedence)}	optical indication (G01D 5/40 takes precedence;
5/24428 • • • {Error prevention}	{mechanical adjustment G01D 5/264})
5/24433 {by mechanical means}	5/285 { using a movable mirror}
	The second secon
scale}	5/305 {controlling the movement of a following
5/24442 {by mounting means}	part}
5/24447 • • • {by energy backup}	5/32 with attenuation or whole or partial obturation of
5/24457 {Failure detection}	beams of light (G01D 5/40 takes precedence {;
5/24461 {by redundancy or plausibility}	mechanical adjustment G01D 5/264})
5/24466 Comparison of the error value to a	5/34 the beams of light being detected by photocells
5/24466 {Comparison of the error value to a threshold}	
threshold}	5/341 {controlling the movement of a following
threshold} 5/24471 {Error correction}	5/341 {controlling the movement of a following part}
threshold} 5/24471 {Error correction} 5/24476 {Signal processing}	5/341 {controlling the movement of a following part} 5/342 {the sensed object being the obturating part}
threshold} 5/24471 {Error correction} 5/24476 {Signal processing	5/341 {controlling the movement of a following part} 5/342 {the sensed object being the obturating part} 5/344 {using polarisation (G01D 5/35303 takes
threshold} 5/24471 {Error correction} 5/24476 {Signal processing (G01D 5/2448 - G01D 5/24495 take precedence)}	5/341 {controlling the movement of a following part} 5/342 {the sensed object being the obturating part} 5/344 {using polarisation (G01D 5/35303 takes precedence)}
threshold} 5/24471 {Error correction} 5/24476 {Signal processing	5/341 {controlling the movement of a following part} 5/342 {the sensed object being the obturating part} 5/344 {using polarisation (G01D 5/35303 takes precedence)}  or 5/345 {Polarising encoders}
threshold} 5/24471 {Error correction} 5/24476 {Signal processing (G01D 5/2448 - G01D 5/24495 take precedence)}	5/341 {controlling the movement of a following part} 5/342 {the sensed object being the obturating part} 5/344 {using polarisation (G01D 5/35303 takes precedence)}
threshold}  5/24471 {Error correction}  5/24476 {Signal processing (G01D 5/2448 - G01D 5/24495 take precedence)}  5/2448 {Correction of gain, threshold, offset phase control}	5/341 {controlling the movement of a following part} 5/342 {the sensed object being the obturating part} 5/344 {using polarisation (G01D 5/35303 takes precedence)}  or 5/345 {Polarising encoders}
threshold}  5/24471 {Error correction}  5/24476 {Signal processing (G01D 5/2448 - G01D 5/24495 take precedence)}  5/2448 {Correction of gain, threshold, offset phase control}  5/24485 {using other sensors}	5/341 {controlling the movement of a following part}  5/342 {the sensed object being the obturating part}  5/344 {using polarisation (G01D 5/35303 takes precedence)}  or 5/345 {Polarising encoders}  5/347 using displacement encoding scales  5/34707 {Scales; Discs, e.g. fixation, fabrication,
threshold}  5/24471 {Error correction}  5/24476 {Signal processing (G01D 5/2448 - G01D 5/24495 take precedence)}  5/2448 {Correction of gain, threshold, offset phase control}  5/24485 {using other sensors}  5/2449 {using hard-stored calibration data}	5/341 {controlling the movement of a following part} 5/342 {the sensed object being the obturating part} 5/344 {using polarisation (G01D 5/35303 takes precedence)}  or 5/345 {Polarising encoders} 5/347 using displacement encoding scales 5/34707 {Scales; Discs, e.g. fixation, fabrication, compensation}
threshold}  5/24471 {Error correction}  5/24476 {Signal processing (G01D 5/2448 - G01D 5/24495 take precedence)}  5/2448 {Correction of gain, threshold, offset phase control}  5/24485 {using other sensors}  5/2449 {using hard-stored calibration data}  5/24495 {using previous values}	5/341 {controlling the movement of a following part}  5/342 {the sensed object being the obturating part}  5/344 {using polarisation (G01D 5/35303 takes precedence)}  or 5/345 {Polarising encoders}  5/347 using displacement encoding scales  5/34707 {Scales; Discs, e.g. fixation, fabrication, compensation}  5/34715 {Scale reading or illumination devices}
threshold}  5/24471 {Error correction}  5/24476 {Signal processing (G01D 5/2448 - G01D 5/24495 take precedence)}  5/2448 {Correction of gain, threshold, offset phase control}  5/24485 {using other sensors}  5/2449 {using hard-stored calibration data}  5/24495 {using previous values}  5/245 using a variable number of pulses in a taken and the stored calibration data}	5/341 {controlling the movement of a following part}  5/342 {the sensed object being the obturating part}  5/344 {using polarisation (G01D 5/35303 takes precedence)}  or 5/345 {Polarising encoders}  5/347 using displacement encoding scales  5/34707 {Scales; Discs, e.g. fixation, fabrication, compensation}  5/34715 {Scale reading or illumination devices}  rain 5/34723 {involving light-guides}
threshold}  5/24471 {Error correction}  5/24476 {Signal processing (G01D 5/2448 - G01D 5/24495 take precedence)}  5/2448 {Correction of gain, threshold, offset phase control}  5/24485 {using other sensors}  5/2449 {using hard-stored calibration data}  5/24495 {using previous values}  5/245 using a variable number of pulses in a total size of the stored calibration data}  5/2451 {Incremental encoders (G01D 5/24545)}	5/341 {controlling the movement of a following part}  5/342 {the sensed object being the obturating part}  5/344 {using polarisation (G01D 5/35303 takes precedence)}  or 5/345 {Polarising encoders}  5/347 using displacement encoding scales  5/34707 {Scales; Discs, e.g. fixation, fabrication, compensation}  5/34715 {Scale reading or illumination devices}  rain 5/34723 {involving light-guides}  takes 5/3473 {Circular or rotary encoders}
threshold}  5/24471 {Error correction}  5/24476 {Signal processing (G01D 5/2448 - G01D 5/24495 take precedence)}  5/2448 {Correction of gain, threshold, offset phase control}  5/24485 {using other sensors}  5/2449 {using hard-stored calibration data}  5/24495 {using previous values}  5/245 using a variable number of pulses in a telephone for the stored calibration data}  5/2451 {Incremental encoders (G01D 5/24545 precedence)}	5/341 {controlling the movement of a following part}  5/342 {the sensed object being the obturating part}  5/344 {using polarisation (G01D 5/35303 takes precedence)}  or 5/345 {Polarising encoders}  5/347 using displacement encoding scales  5/34707 {Scales; Discs, e.g. fixation, fabrication, compensation}  5/34715 {Scale reading or illumination devices}  ain 5/34723 {involving light-guides}  5/3473 {Circular or rotary encoders}  5/34738 {Axles; Driving or coupling means}
threshold}  5/24471 {Error correction}  5/24476 {Signal processing (G01D 5/2448 - G01D 5/24495 take precedence)}  5/2448 {Correction of gain, threshold, offset phase control}  5/24485 {using other sensors}  5/2449 {using previous values}  5/2445 {using a variable number of pulses in a t 5/2451 {Incremental encoders (G01D 5/2452 precedence)}  5/2452 {incorporating two or more tracks	5/341 {controlling the movement of a following part}  5/342 {the sensed object being the obturating part}  5/344 {using polarisation (G01D 5/35303 takes precedence)}  or 5/345 {Polarising encoders}  5/347 using displacement encoding scales  5/34707 {Scales; Discs, e.g. fixation, fabrication, compensation}  5/34715 {Scale reading or illumination devices}  5/34723 {involving light-guides}  5/34738 {Circular or rotary encoders}  5/34738 {Axles; Driving or coupling means}  having 5/34746 {Linear encoders}
threshold}  5/24471 {Error correction}  5/24476 {Signal processing (G01D 5/2448 - G01D 5/24495 take precedence)}  5/2448 {Correction of gain, threshold, offset phase control}  5/24485 {using other sensors}  5/2449 {using hard-stored calibration data}  5/24495 {using previous values}  5/2451 {Incremental encoders (G01D 5/2454 precedence)}  5/2452 {incorporating two or more tracks an (n, n+1,) relationship}	5/341 {controlling the movement of a following part}  5/342 {the sensed object being the obturating part}  5/344 {using polarisation (G01D 5/35303 takes precedence)}  or 5/345 {Polarising encoders}  5/347 using displacement encoding scales  5/34707 {Scales; Discs, e.g. fixation, fabrication, compensation}  5/34715 {Scale reading or illumination devices}  states 5/34723 {involving light-guides}  5/34738 {Circular or rotary encoders}  5/34746 {Axles; Driving or coupling means}  5/34753 {Carriages; Driving or coupling means}
threshold}  5/24471 {Error correction}  5/24476 {Signal processing (G01D 5/2448 - G01D 5/24495 take precedence)}  5/2448 {Correction of gain, threshold, offset phase control}  5/24485 {using other sensors}  5/2449 {using previous values}  5/2445 {using a variable number of pulses in a t 5/2451 {Incremental encoders (G01D 5/2452 precedence)}  5/2452 {incorporating two or more tracks	5/341 {controlling the movement of a following part}  5/342 {the sensed object being the obturating part}  5/344 {using polarisation (G01D 5/35303 takes precedence)}  or 5/345 {Polarising encoders}  5/347 using displacement encoding scales  5/34707 {Scales; Discs, e.g. fixation, fabrication, compensation}  5/34715 {Scale reading or illumination devices}  states 5/34723 {involving light-guides}  5/34738 {Circular or rotary encoders}  5/34746 {Axles; Driving or coupling means}  5/34753 {Carriages; Driving or coupling means}
threshold}  5/24471 {Error correction}  5/24476 {Signal processing (G01D 5/2448 - G01D 5/24495 take precedence)}  5/2448 {Correction of gain, threshold, offset phase control}  5/24485 {using other sensors}  5/2449 {using hard-stored calibration data}  5/24495 {using previous values}  5/2451 {Incremental encoders (G01D 5/2454 precedence)}  5/2452 {incorporating two or more tracks an (n, n+1,) relationship}	5/341 {controlling the movement of a following part}  5/342 {the sensed object being the obturating part}  5/344 {using polarisation (G01D 5/35303 takes precedence)}  or 5/345 {Polarising encoders}  5/347 using displacement encoding scales  5/34707 {Scales; Discs, e.g. fixation, fabrication, compensation}  5/34715 {Scale reading or illumination devices}  5/34723 {involving light-guides}  5/34738 {Circular or rotary encoders}  5/34746 {Axles; Driving or coupling means}  5/34753 {Carriages; Driving or coupling means}
threshold}  5/24471 {Error correction}  5/24476 {Signal processing (G01D 5/2448 - G01D 5/24495 take precedence)}  5/2448 {Correction of gain, threshold, offset phase control}  5/24485 {using other sensors}  5/2449 {using hard-stored calibration data}  5/24495 {using previous values}  5/2451 {Incremental encoders (G01D 5/2450 precedence)}  5/2452 {incorporating two or more tracks an (n, n+1,) relationship}  5/2454 {Encoders incorporating incremental}	5/341 {controlling the movement of a following part}  5/342 {the sensed object being the obturating part}  5/344 {using polarisation (G01D 5/35303 takes precedence)}  or 5/345 {Polarising encoders}  5/347 using displacement encoding scales  5/34707 {Scales; Discs, e.g. fixation, fabrication, compensation}  5/34715 {Scale reading or illumination devices}  ain 5/34723 {involving light-guides}  5/3473 {Circular or rotary encoders}  5/34738 {Axles; Driving or coupling means}  having 5/34746 {Linear encoders}  5/34753 {Carriages; Driving or coupling means}  and 5/34761 {Protection devices, e.g. caps; Blowing devices}
threshold}  5/24471 {Error correction}  5/24476 {Signal processing (G01D 5/2448 - G01D 5/24495 take precedence)}  5/2448 {Correction of gain, threshold, offset phase control}  5/24485 {using other sensors}  5/2449 {using hard-stored calibration data}  5/24495 {using previous values}  5/245 using a variable number of pulses in a transfer of the stored calibration data}  5/2451 {Incremental encoders (G01D 5/245-precedence)}  5/2452 {incorporating two or more tracks an (n, n+1,) relationship}  5/2454 {Encoders incorporating incremental absolute signals}  5/2455 {with incremental and absolute tracks an and absolute tracks an and absolute tracks and a	5/341 {controlling the movement of a following part}  5/342 {the sensed object being the obturating part}  5/344 {using polarisation (G01D 5/35303 takes precedence)}  or 5/345 {Polarising encoders}  5/347 using displacement encoding scales  5/34707 {Scales; Discs, e.g. fixation, fabrication, compensation}  5/34715 {Scale reading or illumination devices}  rain 5/34723 {involving light-guides}  takes 5/3473 {Circular or rotary encoders}  5/34738 {Axles; Driving or coupling means}  having 5/34746 {Carriages; Driving or coupling means}  5/34761 {Protection devices, e.g. caps; Blowing devices}  cks on 5/34769 {Sealing means}
threshold}  5/24471 {Error correction}  5/24476 {Signal processing (G01D 5/2448 - G01D 5/24495 take precedence)}  5/2448 {Correction of gain, threshold, offset phase control}  5/24485 {using other sensors}  5/2449 {using hard-stored calibration data}  5/24495 {using previous values}  5/245 using a variable number of pulses in a treatment of the stored calibration data}  5/2451 {Incremental encoders (G01D 5/2450 precedence)}  5/2452 {incorporating two or more tracks an (n, n+1,) relationship}  5/2454 {Encoders incorporating incremental absolute signals}	5/341 {controlling the movement of a following part}  5/342 {the sensed object being the obturating part}  5/344 {using polarisation (G01D 5/35303 takes precedence)}  or 5/345 {Polarising encoders}  5/347 using displacement encoding scales  5/34707 {Scales; Discs, e.g. fixation, fabrication, compensation}  5/34715 {Scale reading or illumination devices}  ain 5/34723 {involving light-guides}  5/3473 {Circular or rotary encoders}  5/34738 {Axles; Driving or coupling means}  having 5/34746 {Linear encoders}  5/34753 {Carriages; Driving or coupling means}  and 5/34761 {Protection devices, e.g. caps; Blowing devices}

5/34784 { with only analogue scales or both	5/35383 {using multiple sensor devices using
analogue and incremental scales}	multiplexing techniques}
5/34792 { with only digital scales or both digital and incremental scales}	5/35387 { using wavelength division multiplexing}
5/34794 {Optical encoders using the Vernier	5/3539 {using time division multiplexing}
principle, i.e. incorporating two or	5/35393 {using frequency division multiplexing}
more tracks having a (n, n+1,) relationship}	5/35396 {using other forms of multiplexing}
5/353 influencing the transmission properties of an	5/36 Forming the light into pulses
optical fibre	5/363 {Direction discrimination}
5/35303 • • • • • {using a reference fibre, e.g.	5/366 {Particular pulse shapes}
interferometric devices}	5/38 by diffraction gratings
5/35306 {using an interferometer arrangement}	5/39 • Canning a visible indication of the measured value and reproducing this indication at the
5/35309 {using multiple waves interferometer}	remote place, e.g. on the screen of a cathode ray
5/35312 {using a Fabry Perot}	tube {(mechanical adjustment <u>G01D 5/264)</u> }
5/35316 {using a Bragg gratings}	5/40 specially adapted for use with infrared light
5/35319 {using other multiple wave	{(mechanical adjustment G01D 5/264)}
interferometer}	5/42 • using fluid means
5/35322 {using interferometer with one loop with several directions of circulation of	5/425 {characterised by a first part whose movement
the light, e.g. Sagnac interferometer}	represents the measuring value, and by a second
5/35325 { using interferometer with two	part which is moved by an external force in order to follow the movement of the first part}
arms in reflection, e.g. Mickelson	5/44 . using jets of fluid
interferometer}	5/46 by deflecting or throttling the flow
5/35329 {using interferometer with two arms	5/48 • using wave or particle radiation means (G01D 5/26
in transmission, e.g. Mach-Zender	takes precedence)
interferometer}	5/485 • • {using magnetostrictive devices}
5/35332 {using other interferometers}	5/50 • derived from a radioactive source
5/35335 { Aspects of emitters or receivers used by an interferometer in an optical fibre	5/52 detected by a counter tube
sensor arrangement (using multiple	5/54 . using means specified in two or more of groups
sensor devices using multiplexing	G01D 5/02, G01D 5/12, G01D 5/26, G01D 5/42,
techniques <u>G01D 5/35383</u> )}	and <u>G01D 5/48</u>
5/35338 {using other arrangements than	<u>NOTES</u>
interferometer arrangements}	1. For a combination of two or more of the
5/35341 {Sensor working in transmission}	means specified, the first applicable one of the
5/35345 {using Amplitude variations to detect the measured quantity}	subgroups below takes precedence over any
5/35348 {using stimulated emission to detect	others of these groups.  2. Classification is made in this group only
the measured quantity}	if no other group can be selected as being
5/35351 {using other means to detect the	predominantly applicable.
measured quantity}	
5/35354 {Sensor working in reflection}	5/56 • using electric or magnetic means
5/35358 (using backscattering to detect the	5/58 • using optical means, i.e. using infrared, visible or ultraviolet light
measured quantity}	5/60 . using fluid means
5/35361 { using elastic backscattering to detect the measured quantity, e.g.	5/62 . using wave or particle radiation means not
using Rayleigh backscattering}	covered by group G01D 5/58
5/35364 {using inelastic backscattering}	7/00 Indicating massured values
to detect the measured quantity,	<ul><li>7/00 Indicating measured values</li><li>7/002 • {giving both analog and numerical indication}</li></ul>
e.g. using Brillouin or Raman	7/005 • {Indication of measured value by colour change}
backscattering}	7/007 • {Indication of measured value by teorida change}
5/35367 (using reflected light other than	7/02 • Indicating value of two or more variables
backscattered to detect the measured quantity}	simultaneously
5/3537 {Optical fibre sensor using a particular	7/04 using a separate indicating element for each
c.ccc. • • • • •   Oparent fibre betteen diffigure particular	variable
arrangement of the optical fibre itself}	
	7/06 Luminous indications projected on a common
arrangement of the optical fibre itself} 5/35374 {Particular layout of the fiber} 5/35377 {Means for amplifying or modifying the	7/06 Luminous indications projected on a common screen
arrangement of the optical fibre itself} 5/35374 {Particular layout of the fiber} 5/35377 {Means for amplifying or modifying the measured quantity}	<ul> <li>7/06 Luminous indications projected on a common screen</li> <li>7/08 using a common indicating element for two or</li> </ul>
arrangement of the optical fibre itself}  5/35374 {Particular layout of the fiber}  5/35377 {Means for amplifying or modifying the measured quantity}  5/3538 {using a particular type of fiber, e.g.	<ul> <li>7/06 Luminous indications projected on a common screen</li> <li>7/08 using a common indicating element for two or more variables</li> </ul>
arrangement of the optical fibre itself} 5/35374 {Particular layout of the fiber} 5/35377 {Means for amplifying or modifying the measured quantity}	<ul> <li>7/06 Luminous indications projected on a common screen</li> <li>7/08 using a common indicating element for two or</li> </ul>

9/00	Recording measured values	11/10	. Elements for damping the movement of parts
9/005	• {Solid-state data loggers}	11/12	using fluid damping
9/007	• • {Data loggers attached to transport containers for	11/14	<ul> <li>using magnetic induction damping</li> </ul>
	perishable products, e.g. food or medicines}	11/16	<ul> <li>Elements for restraining, or preventing the</li> </ul>
9/02	• Producing one or more recordings of the values of a		movement of, parts, e.g. for zeroising (caging of
0./0.4	single variable	11/10	moving parts when not in use <u>G01D 11/20</u> )
9/04	• • with provision for multiple or alternative	11/18	• Springs (G01D 11/06 takes precedence)
0/06	recording	11/20	Caging devices for moving parts when not in use
9/06	Multiple recording, e.g. duplicating	11/22	. automatically actuated
9/08	<ul> <li>giving both graphical and numerical recording</li> </ul>	11/24	• Housings {; Casings for instruments}
9/10	the recording element, e.g. stylus, being	11/245	{Housings for sensors}
9/10	controlled in accordance with the variable, and	11/26	Windows; Cover glasses; Sealings therefor
	the recording medium, e.g. paper roll, being	11/28	• Structurally-combined illuminating devices
	controlled in accordance with time	11/30	<ul> <li>Supports specially adapted for an instrument;</li> <li>Supports specially adapted for a set of instruments</li> </ul>
9/12	recording occurring continuously	11/305	• • {Panel mounting of instruments}
9/14	with provision for altering speed of recording	11/303	• • (I alief mounting of instruments)
	medium in accordance with the magnitude of	13/00	Component parts of indicators for measuring
	the variable to be recorded		arrangements not specially adapted for a specific
9/16	• • recording occurring at separated intervals, e.g.		variable
	by chopper bar	13/02	. Scales; Dials
9/18	recording element actuated only upon change	13/04	Construction
	in value of variable	13/06	• • • Moving bands ( <u>G01D 13/10</u> takes precedence)
9/20	the recording element, e.g. stylus, being	13/08	Rotating drums ( <u>G01D 13/10</u> takes precedence)
	controlled in accordance with time and the	13/10	• • • with adjustable scales; with auxiliary scales,
	recording medium, e.g. paper roll, being controlled in accordance with the variable	10/10	e.g. vernier
9/22	recording occurring continuously	13/12	Graduation
9/24	• • • recording occurring at separated intervals, e.g.	13/14	for rotations of more than 360 degrees
)12 <del>4</del>	by chopper bar	13/16	with staggered markings
9/26	• either the recording element, e.g. stylus, or	13/18	with raised or recessed markings
), <b>2</b> 0	the recording medium, e.g. paper roll, being	13/20	with luminescent markings
	controlled in accordance with both time and the	13/22	• Pointers, e.g. settable pointer
	variable	13/24	for indicating a maximum or minimum
9/28	<ul> <li>Producing one or more recordings, each recording</li> </ul>	13/26	<ul> <li>adapted to perform a further operation, e.g. making electrical contact</li> </ul>
	being of the values of two or more different	13/265	• • • {Pointers which conduct light}
	variables (G01D 9/38, G01D 9/40 take precedence)	13/28	<ul><li> (Foliates which conduct right)</li><li> with luminescent markings</li></ul>
9/285	• • {producing additional marks (e.g. reference lines		• • with familiescent markings
0/20	time marks)}	15/00	Component parts of recorders for measuring
9/30	<ul> <li>there being a separate recording element for each variable, e.g. multiple-pen recorder</li> </ul>		arrangements not specially adapted for a specific variable
9/32	there being a common recording element for two	15/005	
7132	or more variables	15/003	<ul><li>{Effaceable recording}</li><li>Styli or other recording elements acting to</li></ul>
9/34	the variables being recorded in a predetermined	13/02	mechanically deform or perforate the recording
7/51	sequence		surface (printing recording elements G01D 15/20)
9/36	in separate columns	15/04	acting to punch holes in the recording surface
9/38	Producing one or more recordings, each recording	15/06	Electric recording elements, e.g. electrolytic
	being produced by controlling the recording	15/08	• for spark erosion
	element, e.g. stylus, in accordance with one variable	15/10	Heated recording elements acting on heatsensitive
	and controlling the recording medium, e.g. paper	10, 10	layers
	roll, in accordance with another variable	15/12	Magnetic recording elements
9/40	Producing one or more recordings, each recording	15/14	• Optical recording elements; Recording elements
	being produced by controlling either the recording		using X-or nuclear radiation
	element, e.g. stylus or the recording medium, e.g. paper roll, in accordance with two or more variables	15/16	. Recording elements transferring recording material,
9/42	Recording indications of measuring instruments by		e.g. ink, to the recording surface (printing recording
9/42	photographic means, e.g. of counters		elements <u>G01D 15/20</u> )
	photographic means, e.g. or counters	15/18	Nozzles emitting recording material
11/00	Component parts of measuring arrangements	15/20	• Recording elements for printing with ink or for
	not specially adapted for a specific variable		printing by deformation or perforation of the
11.05	( <u>G01D 13/00</u> , <u>G01D 15/00</u> take precedence)	15/00	recording surface, e.g. embossing
11/02	Bearings or suspensions for moving parts	15/22	Chopper bars for bringing recording element into     contact with recording surface.
11/04	. Knive-edge bearings	15/24	contact with recording surface  Drives for recording elements and surfaces not
11/06	• Strip or thread suspensions, e.g. in tension	13/24	covered by G01D 5/00
11/08	Elements for balancing moving parts		2010104 07 <u>301D 3100</u>

15/26 15/28	<ul><li>operating by clockwork</li><li>Holding means for recording surfaces; Guiding</li></ul>	2205/14	• • by converting the linear movement into a rotary movement
	means for recording surfaces; Exchanging means for recording surfaces	2205/18	• using magnetic means not otherwise provided for in this subclass
15/30	for foldable strip charts	2205/20	Detecting rotary movement
15/32	for circular charts	2205/22	by converting the rotary movement into a linear
15/34	Recording surfaces		movement
15/342	• • {of circular shape}	2205/24	using magnetic means not otherwise provided for
15/345	• • {of cylindrical shape}		in this subclass
15/347	{Strip or Tape}	2205/26	Details of encoders or position sensors specially
18/00	Testing or calibrating apparatus or arrangements		adapted to detect rotation beyond a full turn of 360°, e.g. multi-rotation
	provided for in groups <u>G01D 1/00</u> - <u>G01D 15/00</u>	2205/28	• • The target being driven in rotation by additional
18/001	• {Calibrating encoders}		gears
18/002	• {Automatic recalibration ( <u>G01D 18/008</u> takes	2205/40	<ul> <li>Position sensors comprising arrangements for</li> </ul>
10/004	precedence)}		concentrating or redirecting magnetic flux
18/004	• • {Continuous recalibration}	2205/50	Grounding or electrostatically shielding a position
18/006	• • {Intermittent recalibration}		sensor or encoder
18/008 <b>21/00</b>	<ul> <li>{with calibration coefficients stored in memory}</li> <li>Measuring or testing not otherwise provided for</li> </ul>	2205/60	Means for precisely aligning or centering the disk of a rotary encoder, e.g. fitting jigs
21/00	Measuring two or more variables by means not	2205/70	Position sensors comprising a moving target with
21/02	covered by a single other subclass		particular shapes, e.g. of soft magnetic targets
	covered by a single other subclass	2205/73	Targets mounted eccentrically with respect to the
2204/00	Indexing scheme relating to details of tariff-		axis of rotation
	metering apparatus	2205/77	Specific profiles
2204/10	Analysing; Displaying	2205/771	Toothed profiles
2204/12	• Determination or prediction of behaviour, e.g.	2205/772	Sawtooth profiles
	likely power consumption or unusual usage	2205/773	Spiral profiles
	patterns	2205/774	• • Profiles with a discontinuity, e.g. edge or
2204/125	Utility meter reading systems specially adapted		stepped profile
	for determining the environmental impact of	2205/775	Tapered profiles
	user behaviour	2205/776	Cam-shaped profiles
2204/14	Displaying of utility usage with respect to time,	2205/777	• • • Whorl-shaped profiles
	e.g. for monitoring evolution of usage or with respect to weather conditions	2205/80	Manufacturing details of magnetic targets for magnetic encoders
2204/16	Displaying of utility pricing or cost	2205/85	Determining the direction of movement of an
2204/18	Remote displaying of utility meter readings		encoder, e.g. of an incremental encoder
2204/20	Monitoring; Controlling	2205/90	• Two-dimensional encoders, i.e. having one or two
2204/22	. Arrangements for detecting or reporting faults,		codes extending in two directions
	outages or leaks	2205/95	Three-dimensional encoders, i.e. having codes
2204/24	• Identification of individual loads, e.g. by		extending in three directions
	analysing current/voltage waveforms	2207/00	
2204/26	Remote utility meter reading systems with	2207/00	Indexing scheme relating to details of indicating
	control function, i.e. reading systems including	2207/10	measuring values
	mechanisms for turning on/off the supply	2207/10	Displays which are primarily used in aircraft or  display aircraft angelife information.
2204/28	Processes or tasks scheduled according to the	2207/20	display aircraft-specific information  Displays for vehicles in which information is
	power required, the power available or the power	2207/20	superimposed on an external view, e.g. heads-up
2201/20	price		displays or enhanced reality displays
2204/30	Remote utility meter reading systems specially	2207/30	<ul> <li>Displays providing further information, in addition</li> </ul>
	adapted for metering the generated energy or power	2207/30	to measured values, e.g. status
2204/35	Monitoring the performance of renewable		to measured values, e.g. status
2201110	electricity generating systems, e.g. of solar panels	2213/00	Indexing scheme relating to constructional details
2204/40	Networks; Topology		of indicators
2204/43	. Identification of a specific meter	2213/10	Drivers for gauges
2204/45	Utility meters networked together within a single building	2213/20	Gauges having a single pointer and two or more scales
2204/47	Methods for determining the topology or	2210/00	Indexing scheme valeting to date the effective
	arrangement of meters in a network	2218/00	Indexing scheme relating to details of testing or
2205/00	Indexing scheme relating to details of means for	2219/10	calibration  Testing of sensors or measuring errongements
2200/00	transferring or converting the output of a sensing member	2218/10	Testing of sensors or measuring arrangements
2205/10	Detecting linear movement		

2205/10 • Detecting linear movement