Good afternoon.

# Randomized Algorithms, Lecture 9

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May 21th 2019

### Today's Lecture

Note about Chernoff bounds

The probabilistic method, part II

Overview

Oblivious Routing Revisited

Lovasz Local Lemma

Method of conditional probabilities

### Chernoff bounds

#### Theorem

Let X be a sum of independent Poisson trials, and let  $\mu = \mathbb{E}[X]$ .

For any  $\bar{\delta}>0$  and  $\bar{\mu}\geq\mu$ .

$$\mathsf{Pr}[X > (1+ar{\delta})ar{\mu}] < \left(rac{e^{ar{\delta}}}{(1+ar{\delta})^{(1+ar{\delta})}}
ight)^{\mu}$$

For any  $0<\bar{\delta}<1$  and  $\bar{\mu}\leq\mu$ .

$$\mathsf{Pr}[X < (1-ar{\delta})ar{\mu}] < \left(rac{e^{-ar{\delta}}}{(1-ar{\delta})^{(1-ar{\delta})}}
ight)^{\!\!ar{\mu}} < e^{-rac{ar{\delta}^2ar{\mu}}{2}}$$

These versions of the Chernoff bounds are not part of the curriculum, but are quite useful. I believe you have already had one exercise where they would have been useful.

The point is that we often only have an upper or lower bound on the expectation. Thus version of the theorem essentially says that it is valid to use this bound instead of the actual value when estimating the probability.

### Chernoff bounds

# Proof $X > (1 + \bar{\delta})\bar{\mu}$ .

Let  $\bar{\mu} \geq \mu$ , and choose  $\delta$  such that  $(1 + \delta)\mu = (1 + \bar{\delta})\bar{\mu}$ . Note that  $\delta > \delta$ 

that 
$$\delta \geq \bar{\delta}$$
 
$$\Pr[X > (1 + \bar{\delta})\bar{u}] = \Pr[X > (1 + \delta)u]$$

Pr
$$[X>(1+ar{\delta})ar{\mu}]= extsf{Pr}[X>(1+\delta)\mu]$$

$$\Pr[X > (1+ar{\delta})ar{\mu}] = \Pr[X > (1+\delta)\mu]$$

$$< \left(\frac{e^{\delta}}{(1+\delta)^{(1+\delta)}}\right)^{\mu} \qquad \qquad \text{(By Chernoff)}$$

$$<\left(\frac{e^{\delta}}{(1+\delta)^{(1+\delta)}}\right)^{\mu}$$
 (By Chernoff) 
$$\left(\frac{1-\frac{1}{2}}{(1+\delta)^{(1+\delta)}}\right)^{(1+\delta)\mu}$$

$$< \left(\frac{e^{\delta}}{(1+\delta)^{(1+\delta)}}\right)^{\mu} \qquad \text{(By Chernoff)}$$

$$= \left(\frac{e^{1-\frac{1}{1+\delta}}}{1+\delta}\right)^{(1+\delta)\mu}$$

 $\leq \left( \tfrac{e^{1-\frac{1}{1+\bar{\delta}}}}{1+\bar{\delta}} \right)^{\!\! \left(1+\bar{\delta}\right)\bar{\mu}}$ 

$$\left(\frac{e^{\delta}}{\delta^{(1+\delta)}}\right)^{\mu}$$
 (By Chernoff)

 $=\left(rac{\mathrm{e}^{1-rac{1}{1+\delta}}}{1+\delta}
ight)^{(1+ar{\delta})ar{\mu}} \quad ((1+\delta)\mu=(1+ar{\delta})ar{\mu})$ 

$$\frac{e^{\delta}}{e^{(1+\delta)}}\Big)^{\mu}$$
 (By Chernoff)  $\frac{1}{e^{\frac{1}{2}}}\Big)^{(1+\delta)\mu}$ 

 $(\bar{\delta} \leq \delta)$ 

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ight)^{\!\!\mu}$  (By Chernoff)

$$\Pr[X < (1-\delta)\bar{\mu}] = \Pr[X < (1-\delta)\mu]$$

$$< \left(\frac{e^{-\delta}}{(1-\delta)^{(1-\delta)}}\right)^{\mu} \qquad \qquad \text{(By Chernoff)}$$

$$\langle (1-\delta)\mu \rangle = \Pr[\lambda < (1-\delta)\mu]$$

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### The probabilistic method: Core ideas

- 1. Any random variable X takes some value  $\leq \mathbb{E}[X]$  and some value  $\geq \mathbb{E}[X]$ .
- 2. If a random object taken from a universe U had nonzero probability of satisfying a property P, then there must be an object in U satisfying F

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## Oblivious Routing: Reminder

#### **Definition**

In an *oblivious* routing scheme, the route  $v_i$  takes to reach d(i) is independent of d(j) for all  $i \neq j$ .

#### **Theorem**

Any deterministic oblivious permutation routing scheme on a network of N nodes of out degree d uses  $\Omega(\sqrt{N/d})$  steps in the worst case.

#### Theorem

Valiant's scheme for oblivious routing on the hypercube with  $N=2^n$  nodes uses Nn random bits and expected  $\mathcal{O}(n)$  steps.

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Any randomized oblivious algorithm for permutation routing on the hypercube with  $N = 2^n$  nodes that uses k random bits runs in  $\Omega(2^{-k}\sqrt{N/n})$  steps.

#### Proof

random choice between deterministic algorithms  $\{A_1, \ldots, A_R\}$ . Since only k bits used,  $R \leq 2^k$ . Some fixed algorithm  $A_i$  is chosen with probability  $\geq \frac{1}{R} \geq 2^{-k}$  in any run. By the lower bound, there is an instance  $I_i$  on which  $A_i$  require  $t(n) = \Omega(\sqrt{N/n})$  steps. The expected number of steps when running A on  $I_i$  is at least  $2^{-k}t(n) = \Omega(2^{-k}\sqrt{N/n})$ .

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# Oblivious Routing: Corollary

### Corollary

Any randomized oblivious algorithm for permutation routing on the hypercube with  $N = 2^n$  nodes must use  $\Omega(n)$  random bits to run in expected O(n) steps.

Using the probabilistic method, we'll show

#### Theorem

For every n, there exists a randomized oblivious scheme for permutation routing on a hypercube with  $N=2^n$  nodes that use 3n random bits and expected at most 15n steps.

Most of these details are irrelevant.

$$2^{-k}\sqrt{\frac{N}{n}} \le Cn$$

$$2^{-2k}\frac{N}{n} \le C^2n^2$$

$$2^{-2k}N \le C^2n^3$$

$$2^{n-2k} \le C^2n^3 \qquad \text{(Using } N = 2^n\text{)}$$

$$n - 2k \le 3\log_2 n + \log_2 C^2$$

$$n - 3\log_2 n - \log_2 C^2 \le 2k$$

$$\frac{n - 3\log_2 n - \log_2 C^2}{2} \le k$$

$$\frac{n - 4\log_2 n}{2} \le k \qquad \text{(for } n \ge C^2\text{)}$$

$$\frac{17 - 4\log_2 17}{34}n \le k \qquad \text{(for } n \ge \max\{17, C^2\}\text{)}$$

$$k \in \Omega(n)$$

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Valiant's scheme can be seen as picking a deterministic algorithm uniformly at random from  $\mathcal{A} = \{A_i\}_{(i \in [N^N])}$ . Let  $t = N^3$ , and for  $j \in [t]$  pick  $B_j \in \mathcal{A}$  independently, uniformly at random, with replacement, and let  $\mathcal{B} = \{B_j\}_{(j \in [t])}$ . For any permutation  $\pi_i$ , let  $X_{ij} = [B_j \text{ uses } > 14n \text{ steps on } \pi_i]$  and let  $X_i = \sum_{j=1}^t X_{ij}$ . We know  $\mathbb{E}[X_{ij}] \leq \frac{1}{N}$  for all i, j, so  $\mu = \mathbb{E}[\sum_{i=1}^t X_{ij}] \leq \frac{t}{N} = N^2$ . Let  $\bar{\mu} = N^2$  and  $\bar{\delta} = 1$  then

$$\begin{split} \Pr[X_i > 2N^2] &= \Pr[X_i > (1+\bar{\delta})\bar{\mu}] \\ &< \left(\frac{e^{\bar{\delta}}}{(1+\bar{\delta})^{(1+\bar{\delta})}}\right)^{\bar{\mu}} \quad \text{(By note at beginning)} \\ &\leq e^{-\frac{\bar{\delta}^2\bar{\mu}}{4}} = e^{-\frac{N^2}{4}} \qquad \text{(By Theorem 4.3)} \\ \Pr[\cup_{i=1}^{N!} \{X_i > 2N^2\}] &\leq \sum_{i=1}^{N!} \Pr[X_i > 2N^2] \leq N! \cdot e^{-\frac{N^2}{4}} < 1 \end{split}$$

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Thus there exists such a  $\mathcal{B}$  where  $X_i \leq 2N^2$  for all  $\pi_i$ .

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Let X be the number of steps used by B on  $\pi$ . We conclude

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We need to take the max here, because we don't have the exact probability.

We don't need sup because the range for q is compact and the function we are taking max over is continuous.

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If  $n \le 4$  then N-1-6n < 0 so the maximum is obtained for q=0, and is 14n < 15n.

If  $n \ge 5$ , then the maximum is obtained for q = 2/N, and is  $14n + 4\frac{N-1-6n}{N} < 14n + 4 < 14n + n = 15n$ 

## **Oblivious Routing: Summary**

We have seen that, for every n, there exists a randomized oblivious scheme for permutation routing on the hypercube with  $N = 2^n$  nodes that use 3n random bits and expected at most 15n steps.

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We have seen that, for every n, there exists a randomized oblivious scheme for permutation routing on the hypercube with  $N = 2^n$  nodes that use 3n random bits and expected at most 15n steps.

Why is this not an efficient algorithm? Because we don't know how to construct  $\mathcal{B}$  efficiently, and we need a new one for each n (non-uniform).

Recall that for *independent* (bad) events  $\mathcal{E}_1, \ldots, \mathcal{E}_n$ , we have  $\Pr[\bigcap_{i=1}^n \overline{\mathcal{E}}_i] = \prod_{i=1}^n (1 - \Pr[\mathcal{E}_i])$ .

We will generalize this slightly, to the case where there is *some* dependencies.

An event  $\mathcal{E}_i$  is mutually independent of a set S of events, if  $\Pr[\mathcal{E}_i \mid \cap_{\mathcal{E}_j \in \mathcal{T}} \mathcal{E}_j] = \Pr[\mathcal{E}_i]$  for all  $T \subseteq S$ .

Let V be a set of events. A dependency graph for V is any digraph G = (V, E) where each  $\mathcal{E}_i \in V$  is mutually independent of  $\{\mathcal{E}_i \in V \setminus \{\mathcal{E}_i\} \mid (\mathcal{E}_i, \mathcal{E}_i) \notin E\}$ .

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Note that this holds for all  $T \subseteq S$  if and only if it holds for all for all  $T \subseteq S \cup \{\overline{\mathcal{E}}_j \mid \mathcal{E}_j \in S\}$ .

In other words, an event and its complement are equivalent in terms of dependency.

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So each event may depend on (some subset of) its neighbors, but don't have to.

#### Lemma (Lovasz Local Lemma)

Let G = (V, E) be a dependency graph for events  $\mathcal{E}_1, \ldots, \mathcal{E}_n$  in a probability space. Suppose there exists  $x_i \in [0,1]$  for  $1 \le i \le n$  such that

$$\Pr[\mathcal{E}_i] \leq x_i \prod_{(i,j) \in E} (1 - x_j)$$

Then

$$\Pr\left[\bigcap_{i=1}^n \overline{\mathcal{E}}_i\right] \geq \prod_{i=1}^n (1-x_i)$$

The proof of this is *not* part of the curriculum.

## Lovasz Local Lemma: Corollary

#### Corollary (Symmetric Lovasz Local Lemma)

Let  $\mathcal{E}_1, \ldots, \mathcal{E}_n$  be events in a probability space, with  $\Pr[\mathcal{E}_i] \leq p$  for all i. If each event is mutually independent of all other events except for at most d, and if  $ep(d+1) \leq 1$ , then  $\Pr[\bigcap_{i=1}^n \overline{\mathcal{E}}_i] > 0$ 

Proving this will be part of Assignment #6.

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A k-SAT instance is a set of logical clauses, each containing exactly k literals.

Suppose each variable in a k-SAT instance appears in at most  $\frac{2^k}{ke}$  of the m clauses. Consider a random truth assignment (like in MAX-SAT-SIMPLE) where each variable is set to TRUE independently with probability  $\frac{1}{2}$ .

Let  $\mathcal{E}_i$  be the event that clause i is unsatisfied. Then  $\Pr[\mathcal{E}_i] = p = 2^{-k}$ . This event is independent of all other  $\mathcal{E}_j$ , except those where clause i and j share a variable.

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Each clause shares variables with at most  $d = k(\frac{2^k}{ke} - 1) \le \frac{2^k}{e} - 1$  other clauses. Since  $ep(d+1) \le e(2^{-k})((\frac{2^k}{e} - 1) + 1) = 1$ , the corollary tells us that there is a satisfying assignment.

The book uses  $2^{\frac{k}{50}}$  as the upper bound on the number of clauses, because the subsequent algorithm in the book needs such a bound.

That algorithm is obsolete, since newer versions of the Algorithmic Lovasz Local Lemma work with the simpler assumptions here.

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It can only share each of the k variables that it actually contains, and each of these are present in at most  $\frac{2^k}{ke}-1$  other clauses.

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Moser and Tardos, JACM 2010:

## Theorem (Algorithmic Lovasz Local Lemma)

If the events  $\mathcal{E}_1, \ldots, \mathcal{E}_n$  in the Lovasz Local Lemma are determined by a finite set  $\mathcal{P}$  of independent random variables, and  $x_i < 1$  for all i, then there is a Las Vegas style randomized algorithm running in expected polynomial time that finds an assignment to all variables in  $\mathcal{P}$  such that  $\bigcap_{i=1}^n \overline{\mathcal{E}}_i$ .

The expected number of "steps" in the algorithm is  $\mathcal{O}\left(\sum_{i=1}^{n}\frac{x_i}{1-x_i}\right)$ , and each step is assumed to take polynomial time.

Consider the set-balancing problem: Given  $\mathbf{A} \in \{0,1\}^{n \times n}$ , find column vector  $\mathbf{b} \in \{-1,1\}^n$  minimizing  $\|\mathbf{A}\mathbf{b}\|_{\infty} = \max_i |(\mathbf{A}\mathbf{b})_i|$ .

If for each i we pick  $\mathbf{b}_i \in \{-1,1\}$  independently and uniformly at random, and let  $\mathcal{E}_i$  denote the event that  $|(\mathbf{A}\mathbf{b})_i| > 4\sqrt{n \ln n}$ , then (See Example 4.5)

$$\Pr[\mathcal{E}_i] \le \frac{2}{n^2} \implies \Pr[\cup_i \mathcal{E}_i] \le \sum_i \Pr[\mathcal{E}_i] \le \frac{2}{n}$$

$$\implies \Pr\left[\max_i |(\mathbf{Ab})_i| \le 4\sqrt{n \ln n}\right] \ge 1 - \frac{2}{n}$$

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 We will derandomize this using the *method of*

conditional probabilities.

For a node a, let  $P(a) = \Pr[\bigcup_i \mathcal{E}_i \mid a \text{ reached}]$ . Note  $P(r) \leq \frac{2}{n} < 1 \text{ for } n > 2$ .

Let c, d be children of a, then  $P(a) = \frac{P(c) + P(d)}{2}$ , so  $\min\{P(c), P(d)\} \le P(a)$ .

For each leaf  $\ell$ ,  $P(\ell) \in \{0, 1\}$ . In particular,  $P(\ell) < 1 \implies P(\ell) = 0$ .

If we can efficiently select the child minimizing  $P(\cdot)$  we are done.

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$$\begin{split} P(a) &= \Pr[\cup_i \mathcal{E}_i \mid a \text{ reached}] \\ &= \Pr[\cup_i \mathcal{E}_i \cap c \text{ reached} \mid a \text{ reached}] \\ &+ \Pr[\cup_i \mathcal{E}_i \cap d \text{ reached} \mid a \text{ reached}] \\ &= \Pr[\cup_i \mathcal{E}_i \mid c \text{ reached}] \cdot \Pr[c \text{ reached} \mid a \text{ reached}] \\ &+ \Pr[\cup_i \mathcal{E}_i \mid d \text{ reached}] \cdot \Pr[d \text{ reached} \mid a \text{ reached}] \\ &= P(c) \cdot \frac{1}{2} + P(d) \cdot \frac{1}{2} \\ &= \frac{P(c) + P(d)}{2} \end{split}$$

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If we can efficiently select the child minimizing  $P(\cdot)$  we are done. For some problems we can! But not for this one.

Define  $\widehat{P}(a) := \sum_{i=1}^{n} \Pr[\mathcal{E}_i \mid a \text{ reached}].$ 

Then  $P(a) \leq \widehat{P}(a)$  (union bound), and

- 1. P(r) <
- 2. For any node a with children c, a

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This gives us a deterministic polynomial-time approximation algorithm. For each i,

$$\Pr[\mathcal{E}_i \mid a \text{ reached}] = \frac{\Pr[\mathcal{E}_i \mid c \text{ reached}] + \Pr[\mathcal{E}_i \mid d \text{ reached}]}{2}$$

Thus

$$\widehat{P}(a) = \sum_{i=1}^{n} \Pr[\mathcal{E}_i \mid a \text{ reached}]$$

$$= \sum_{i=1}^{n} \frac{\Pr[\mathcal{E}_i \mid c \text{ reached}] + \Pr[\mathcal{E}_i \mid d \text{ reached}]}{2}$$

$$= \frac{\widehat{P}(c) + \widehat{P}(d)}{2}$$

$$\geq \min \left\{ \widehat{P}(c), \widehat{P}(d) \right\}$$

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Assume a has depth  $\ell \in [n]$ , and that all unfixed bits in **b** are set to 0.

For each i, we have  $\Pr[\mathcal{E}_i \mid a \text{ reached}] = 2^{-s} \sum_{j=t}^s {s \choose j}$ , where  $s \leq n-\ell$  is the number of bit positions selected by  $\mathbf{A}_i$  that has not yet been fixed in  $\mathbf{b}$ , and  $t = 4\sqrt{n \ln n} + 1 - |(\mathbf{A}\mathbf{b})_i|$  is the minimum number of these positions that need to be set correctly to make  $|(\mathbf{A}\mathbf{b})_i| > 4\sqrt{n \ln n}$ .

This can clearly be computed in polynomial time.

Define  $\widehat{P}(a) := \sum_{i=1}^n \Pr[\mathcal{E}_i \mid a \text{ reached}]$ .

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- ▶ We have seen a useful extension to the Chernoff Bounds.
- We saw a lower bound for randomized oblivious routing, showing a tradeoff between the amount of randomness used and the best possible expected number of steps. We also saw a non-uniform matching upper bound.
- ▶ We then saw Lovasz Local Lemma in its normal and symmetric form, and used it to show that certain restricted versions of *k*-SAT always have a satisfying assignment, and I briefly mentioned that there is an algorithmic version of Lovasz Local lemma.
- Finally, we saw how the method of conditional probabilities could be used to derandomize the set-balancing problem.
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