

Image Segmentation using Graph Cuts

A very simple yet useful model for image segmentation is the following: the foreground is modelled as having a constant grey level μ_1 and the background as being constant equal to μ_0 . The segmentation task is to find a curve γ such that the region Γ inside the curve is foreground and the exterior is background. See Figure 1. Finding the best possible curve results in an optimization problem and is the topic of this computer session.

A simple version of the Mumford-Shah functional takes the length of γ into account:

$$E(\gamma) = \lambda \text{length}(\gamma) + \iint_{\Gamma} (I(\mathbf{x}) - \mu_1)^2 d\mathbf{x} + \iint_{\Omega \setminus \Gamma} (I(\mathbf{x}) - \mu_0)^2 d\mathbf{x} \quad (1)$$

We would like to find the curve γ which minimizes $E(\gamma)$. We will do this with a discrete approximation of E . From now on, we view I as a discrete image with n pixels. Let θ be an indicator variable for the foreground, i.e.:

$$\theta_i = \begin{cases} 1, & \text{if } i \text{ is foreground} \\ 0, & \text{if } i \text{ is background} \end{cases} \quad (2)$$

Let i and j be two image pixel locations. We say that i is a neighbor of j if they are adjacent, either horizontally or vertically. We write this as $j \in \mathcal{N}_i$.

```
M=5; %Width of image
N=6; %Height of image
n = M*N; %Number of image pixels
Neighbors = edges4connected(M,N);
i=Neighbors(:,1);
j=Neighbors(:,2);
A = sparse(i,j,1,n,n);
```

This creates a matrix A such that $A_{ij} \neq 0 \iff j \in \mathcal{N}_i$. We can plot this 5×6 image along with the neighborhood structure with

```
[X Y] = ndgrid(1:M,1:N);
draw_graph(X(:),Y(:),A)
```

We can now approximate (1) by

$$E(\theta) = \frac{\lambda}{2} \sum_{i=1}^n \sum_{j \in \mathcal{N}_i} \mathbb{I}(\theta_i \neq \theta_j) + \sum_{i=1}^n \theta_i (I(i) - \mu_1)^2 + \sum_{i=1}^n (1 - \theta_i) (I(i) - \mu_0)^2. \quad (3)$$

\mathbb{I} is the indicator function, i.e. $\mathbb{I}(\theta_i \neq \theta_j)$ is equal to 1 if θ_i and θ_j are different. Thus the first double summation counts the total number of separated neighbors.

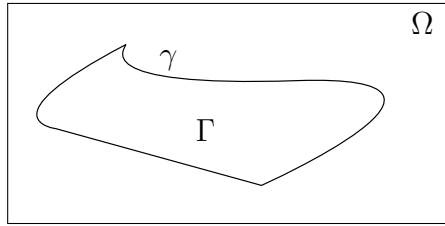


Figure 1: Image segmentation

Minimizing (3) is an example of a minimum cut problem (see lecture notes). There exists very efficient methods to solve it exactly. We will use the software written by Boykov and Kolmogorov, which is ubiquitous in the image analysis community. The first task is to load an image (feel free to use your own favourite one).

```
I = imread('cameraman.tif');
I = double(I)/255;
[M N] = size(I);
n = M*N; %Number of image pixels
```

Next, choose some values for μ_1 , μ_0 and λ to specify what foreground and background looks like and to decide how important a short curve length is.

```
mu0 = ???
mu1 = ???
lambda = ???
```

Create the neighbors and the sparse matrix in the same manner as before. Set $A_{ij} = \lambda \iff j \in \mathcal{N}_i$. (Don't try to draw this graph with `draw_graph` – it's too big)

```
A = ???
```

Now we handle the other two sums in (3). They will be represented with s and t connections in the graph (see the lecture notes to refresh your memory). In the software package we are going to use, these are represented as a separate $n \times 2$ matrix:

```
T = [ (I(:)-mu1).^2 (I(:)-mu0).^2 ];
T = sparse(T);
```

Finally, we solve the minimum cut problem:

```
tic
[E Theta] = maxflow(A,T);
Theta = reshape(Theta,M,N);
Theta = double(Theta);
toc
```

And we can now view the output:

```
imshow(Theta);
```

Write a function so that you may easily try the code with different values of the parameters:

```
function Lab = segment_image(I,mu0,mu1,lambda)
    ...
end
```

If time permits

Construct a scheme to automatically find good values of μ_0 and μ_1 by iterating the following scheme:

1. Segment the image using μ_0 and μ_1
2. Set μ_0 and μ_1 to the mean of their respective region