

UN-LOCKED ZIG

SYNCHRONIZING CODE WITHOUT LOCKS

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Motivation

- Have you ever cooked with others?
 - ▶ It's horrible!
- You need to coordinate who does what and when
 - ▶ Otherwise, you get in each other's way
- Same problem in programming



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Concurrent Programming

```
fun Stack(comptime T: type) type {  
> return struct {  
> > backing: std.ArrayList(T),  
  
> > pub fn push(self: *Stack, value: T) void {  
> > > // try self.backing.append(value);  
> > > const len = self.backing.items.len;  
> > > self.backing.items.ptr[len] = value;  
> > > self.backing.items.len = len + 1;  
> > }  
> };  
}
```

Concurrent Programming

```
fun Stack(comptime T: type) type {  
  > return struct {  
    > > backing: std.ArrayList(T),  
    > > lock: std.Thread.Mutex,  
  
    > > pub fn push(self: *Stack, value: T) void {  
    > > > // try self.backing.append(value);  
    > > > self.lock.lock();  
    > > > const len = self.backing.items.len;  
    > > > self.backing.items.ptr[len] = value;  
    > > > self.backing.items.len = len + 1;  
    > > > self.lock.unlock();  
    > > }  
  > };  
}
```

Beyond Mutual Exclusion

- A Mutex is easy to understand and use
 - ▶ Just grab it and you're safe!
- But for more complex interactions, there are also more complex tools
 - Semaphores
 - Non-blocking Locks
 - Read-Write Locks
 - Reentrant Locks
 - Phases/Barriers
 - ...

The hidden Costs of Locks

Locks seem simple and safe

- But can easily create bottlenecks
- And add additional failure modes
- ▶ Easy to stop thinking about implications

What if we could achieve thread safety without ever forcing a thread to wait?



The hidden Costs of Locks

A selection of additional failure modes

- **Contention**
Multiple threads try to acquire a lock leads to performance degradation.
- **Starvation**
When many threads compete for a lock, some threads may never get it.
- **Priority Inversion**
A lower-priority thread holds a lock needed by a higher-priority thread.
- **Composability**
Locks don't compose well, suggesting the addition of coarser-grained ones.

Agenda

What's
up with
Locks?

Lock-free
Coding

Un-Locking
Zig



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How to synchronize without Locks?

The critical section should be so small that no other thread could interrupt it.



Our work horse: Compare and Swap (CAS)

```
fn cas(pointer: *T, expected: T, new: T) bool {  
> if (pointer.* != expected) {  
> > return false;  
> }  
> pointer.* = new;  
> return true;  
> }
```

“Look at this memory address. If it still contains the value I expected, then — and only then — update it to my new value.”

Building upon CAS

- We can now utilize CAS to actually set a value atomically

```
var current_val: T = atomic_load(ptr);  
var new_val: T = compute(current_val);  
while (!cas(ptr, current_val, new_val)) {  
  > current_val = atomic_load(ptr);  
  > new_val = compute(current_val);  
}
```

- Often, this logic is wrapped into atomic variables
- ▶ They then provide atomic methods for getting, setting, and updating the value



Levels of Freedom

Obstruction Free

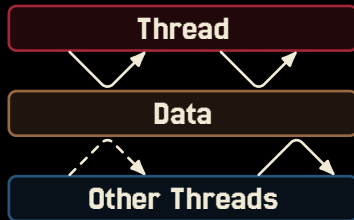
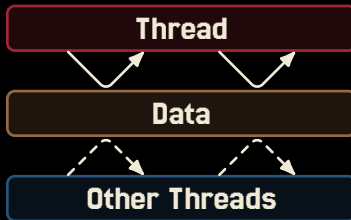
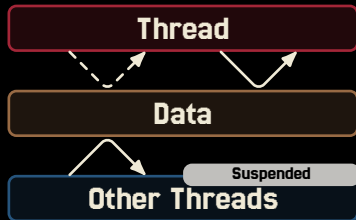
- Weakest Guarantee
- Thread will proceed if all other threads stop

Lock Free

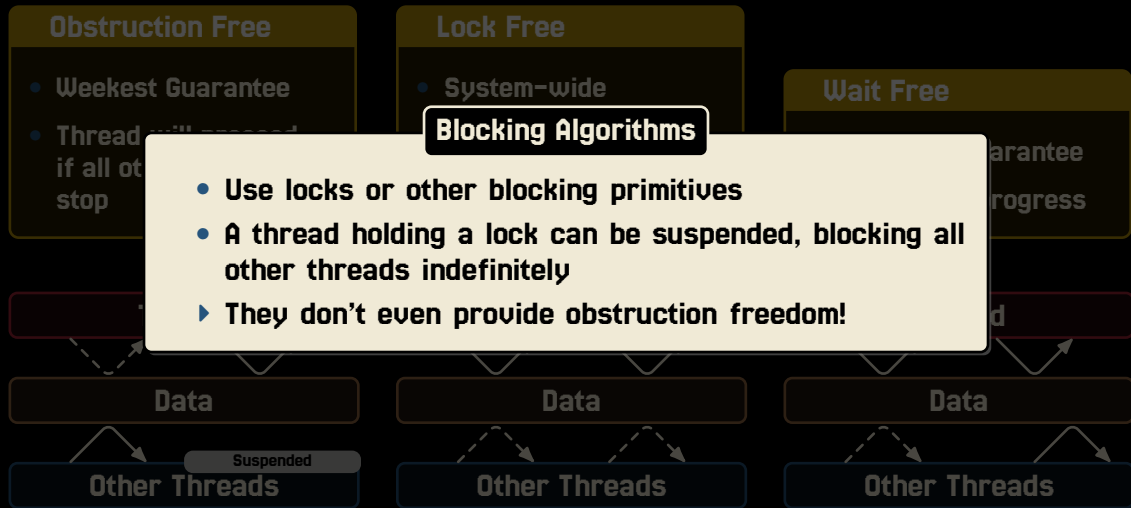
- System-wide progress
- At least one thread makes progress

Wait Free

- Strongest Guarantee
- Per-thread progress



Levels of Freedom



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Un-Locking Zig — Atomic Operations

- Our CPUs support atomic operations withing their instruction sets
 - test-and-set, fetch-and-increment, compare-and-swap, ...
 - LOCK XCHG, LOCK XADD, LOCK CMPXCHG, ...
- ▶ Lock-free programming is enabled by the hardware itself
- Zig provides access to these atomic operations via built-in functions

```
@cmpxchgWeak(comptime T: type, ptr: *T, expected_value: T, new_value: T, success_order: AtomicOrder, fail_order: AtomicOrder) ?T
@cmpxchgStrong(comptime T: type, ptr: *T, expected_value: T, new_value: T, success_order: AtomicOrder, fail_order: AtomicOrder) ?T
```

Un-Locking Zig — Atomic Variables

- **Zig provides atomic types in `std.atomic`**
 - ▶ `std.atomic.Value`
- **It provides wrappers around Zig's atomic built-ins**

```
const std = @import("std");  
const atomic = std.atomic;
```

```
var counter: atomic.Value(u32) = atomic.Value(u32).init(0);  
counter.fetchAdd(1, .SeqCst);
```


Un-Locking Zig — Atomic Variables

- **Zig provides atomic types in `std.atomic`**
 - ▶ `std.atomic.Value`
- **It provides wrappers around Zig's atomic built-ins**

```
const std = @import("std");  
const atomic = std.atomic;
```

```
var counter := atomic.Value(u32) = atomic.Value(u32).init(0);  
@atomicRmw(u32, &counter, .Add, 1, .SeqCst);
```

Let's look at some Code — Push

```
pub fn push(self: *Self, value: T) !void {  
  > var new_head = try self.allocator.create(Node);  
  > new_head.* = Node{  
  >   > .value = value,  
  >   > .next = null,  
  > };  
  
  > while (true) {  
  >   > const old_head = self.top.load(.acquire);  
  >   > new_head.next = old_head;  
  >   > if (self.top.cmpxchgWeak(old_head, new_head, .release, .←  
  >     acquire) == null) {  
  >     > return;  
  >   > }  
  > }  
}
```

Let's look at some Code — Push

```
pub fn push(self: *Self, value: T) !void {  
    > var new_head = try self allocator.create(Node);  
    > new_head.* = Node{  
    > > .value = value,  
    > > .next = null,  
    > };
```

Why is next not atomic?

```
    > while (true) {  
    > > const old_head = self. (.acquire);  
    > > new_head.next = old_head;  
    > > if (self.top.cmpxchgWeak(old_head, new_head, .release, .←  
    > > > acquire) == null) {  
    > > > return;  
    > > }  
    > }  
}
```



Let's look at some Code — Pop

```
pub fn pop(self: *Self) ?T {  
  > while (true) {  
  >   > const old_head = self.top.load(.acquire) orelse {  
  >   >   > return null;  
  >   > };  
  >   > const new_head = old_head.next;  
  >   > if (self.top.cmpxchgWeak(old_head, new_head, .release, .←  
  >   >   acquire) == null) {  
  >   >   > const value = old_head.value;  
  >   >   > self allocator.destroy(old_head);  
  >   >   > return value;  
  >   > }  
  > }  
}
```

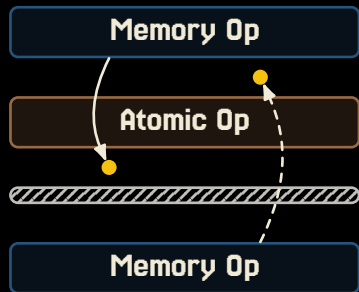
Why does CAS take so many parameters?

```
const data = 42;           while (!data_ready) {}  
const data_ready = true;   use(data);
```

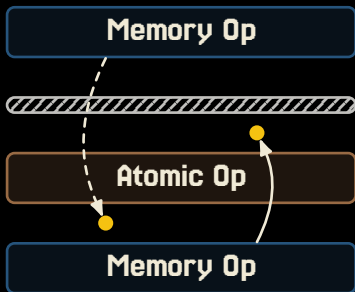
- **This seems to work, right?**
 - ▶ **Wrong! There is no clear dependency between `data_ready` and `data`**
 - ▶ **The compiler and the CPU might reorder instructions :)**
- **By introducing memory barriers, we can prevent this reordering**
 - ▶ **Since different operations have different requirements, we need to specify them individually**

Bringing Order to Chaos

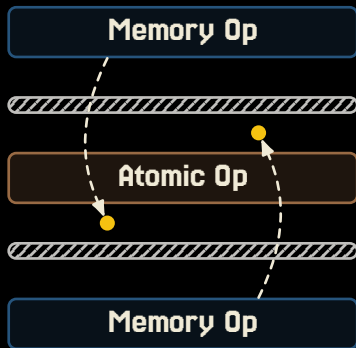
Acquire



Release



AcqRel



Bringing Order to Chaos

Acquire

Release

AcqRel

```
@cmpxchgWeak(comptime T: type,  
  ptr: *T,  
  expected_value: T,  
  new_value: T,  
  success_order: AtomicOrder,  
  fail_order: AtomicOrder  
) ?T
```

```
@cmpxchgStrong(comptime T: type,  
  ptr: *T,  
  expected_value: T,  
  new_value: T,  
  success_order: AtomicOrder,  
  fail_order: AtomicOrder  
) ?T
```

- The success order is enforced when the the actual and expected values match
- Fail order is enforced when they don't

Memory Op

The Problem with ~~ABDA~~ ABA



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The Solution to ~~ABBA~~ ABA

💡 DCAS

Double CAS; not supported on most hardware.

```
cas(ptr, ep, ap,  
    ver, ev, av);
```

Not to be confused with a wide CAS!

💡 Pointer Tagging

Only delay the problem, but can be practical.

On 8-byte aligned systems, 3 bits are free!
We can just put the version there.

Then we don't need DCAS!

💡 Hazard Pointers

Safe memory reclamation, but complex to implement.

Don't modify the CAS; prevent the "A back to A" part.

Pretty much manual garbage collection.

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When Locks are good enough



Simplicity

- When performance is not critical
- When few threads access a resource a few times

Coordination

- When threads need to wait for each other
- When complex interactions are needed

When Lock-Free shines

Performance

- Better performance under oversubscription
- Better suited for real-time and low-latency systems

Robustness

- No unpredictable blocking delays
- No deadlocks, livelocks, or priority inversions

Conclusion

- ✓ Locks have real — often hidden — costs
- ✓ Non-blocking algorithms utilize atomic operations to achieve thread safety
- ✓ A CAS inside a loop is the building block of many algorithms
- ✓ While non-blocking algorithms have actual advantages, they also come with their own challenges

Don't be afraid to use locks, but don't limit yourself to them either!



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