

Lukas Schäfer

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Education

M.Sc. Informatics

University of Edinburgh

09/2018 – Present

Edinburgh, United Kingdom

- Expected graduation in August 2019
- Specialisation in **Machine Learning** and **Autonomous Robotics**
- **DAAD** (German Academic Exchange Service) **graduate scholarship**
- Modules include: Reinforcement Learning, Algorithmic Game Theory and its Applications, Machine Learning and Pattern Recognition, Robotics: Science and Systems, Decision Making in Robots and Autonomous Agents

B.Sc. Computer Science, minor subject Japanese

Saarland University

10/2015 – 08/2018

Saarbrücken, Germany

- Degree classification: grade of **1.2** (German scale) equivalent to UK **1st class honours**
- BSc thesis: Domain-Dependent Policy Learning using Neural Networks in Classical Planning
- Modules include: Automated Planning, Admissible Search Enhancements, Neural Networks: Implementation and Application, Information Retrieval and Data Mining, Software Engineering, Modern Imperative Programming Languages

Abitur - Secondary School

Warndtgymnasium Geislautern, Völklingen

08/2008 – 07/2015

Geislautern, Germany

- Graduated **Abitur 1.0** with examination subjects:
Mathematics - 15, English - 12, Computer Science - 14, German - 15, History - 15
- Prices received:
 - Year's best student award of the Warndtgymnasiums Geislautern
 - Computer science and mathematics award 2015 of Saarland University
 - History award 2015 of historic society for the Saar-Region (Historischer Verein für die Saargegend e.V.)

Research

B.Sc. Dissertation, Saarland University

Foundations of Artificial Intelligence (FAI) Group

04/2018 – 07/2018

- Transferred domain-dependent policy learning neural network architecture of Action-Schema Networks to classical automated planning
- Implemented the network using Keras, slightly adjusted its training for classical planning and extended the FastDownward planning framework
- Extensive evaluation and analysis was conducted on IPC domains of varying complexity identifying limitations in generalisation and scalability
- Received best grade 1.0 twice of both reviewers

Work Experience

Programming 1 Teaching Assistant, Saarland University

Dependable Systems and Software Group

10/2016 – 03/2017

- Taught first-year students fundamental concepts of functional programming, basic complexity theory and inductive correctness proofs in weekly tutorials and office hours
- Corrected weekly tests as well as mid- and endterm exams
- Collectively created learning materials and discussed student progress as part of the whole teaching team

Volunteering

Navigation Team Member, University of Edinburgh

09/2018 – Present

HYPED – University of Edinburgh Hyperloop Society

- Working on navigation of Poddy III Hyperloop prototype including filtering data of IMUs and proximity sensors using Kalman filters to estimate location, orientation and speed of the pod
- Preliminary Design Briefing of Poddy III was approved by SpaceX for their 2019 Hyperloop competition

Lecturer and Coach, Saarland University

Mathematics Preparation Course

09/2017 – 10/2017

- Assisted the organization of the mathematics preparation course for upcoming computer science students
- Explained importance of mathematics for CS, formal languages and predicate logic to ~ 250 participants in daily lectures of the first week
- Supervised two groups to provide feedback and further assistance in daily coaching-sessions
- The course received **BESTE-award** for special student commitment 2017 of Saarland University

School Year Representative, Warndtgymnasium

08/2013 – 07/2015

- Elected committee member representing the school year
- Planned, organised school events up to graduation ceremony and negotiated with sponsors

Project Experience

Autonomous Robot Localisation, University of Edinburgh

09/2018 – 12/2018

Group Project for Robotics: Science and Systems Lecture

- Constructed a four-wheel differential steering mobile robot as group of three for autonomous localisation in a known environment using LEGO aside of technical components including a Raspberry Pi computer
- Implemented particle-filter localisation and obstacle avoidance based on IR and sonar sensors
- Robot successfully managed to navigate through the constructed arena, detect and communicate points of interest using light sensors and return back to its deployment location

Galaxy-based Search, University of Edinburgh

09/2018 – 12/2018

Group Project for Natural Computing Lecture

- Implemented the Galaxy-based Search Algorithm (GbSA) and Particle Swarm Optimisation (PSO) baseline for PCA approximation as metaheuristic optimisation algorithms
- Evaluated and analysed GbSA and its foundational research paper, showing limitations, proposing adjustments to the algorithm and proofing their positive impact on performance in an evaluation

Plagiarism Detection Tool, Saarland University

04/2017 – 07/2017

Group Project for Software Engineering Lecture

- Researched, planned and built a reliable similarity detection for text & code in Python with language-specific analysis for Python and C as a group of five
- Designed and implemented a web-based output creation, highlighting similar submissions and plagiarism
- Our software is now successfully used in our customer's lectures to detect plagiarism cases on Python code

Concurrent CDCL SAT-Solver, Saarland University

07/2017 – 09/2017

Group Project for Modern Imperative Programming Languages Seminar

- Planned and implemented a concurrent Conflict-Driven Clause Learning SAT-Solver using Rust
- Optimised literal assignment using multiple heuristic strategies, pure variable detection and handling

Skills

Programming: Python • C++ • C • Java • SML • Rust • Matlab • Bash

Markup: HTML • CSS • \LaTeX • Markdown

Technologies/ Tools: TensorFlow • Keras • NumPy • UNIX • Git • Vim

Languages: Fluent in German and English • advanced in French • beginner in Japanese

[References available on request - Last updated on December 10, 2018]