MotorCommunicatorInterface # mc # port # socketId # nibbleTranslational # nibbleRotary + linearMovement() + rotate() + ~MotorCommunicatorInterface() # driverInit() # switchedNibbleT() # switchedNibbleR() # openPort() # frameInit() # sendPort() # closePort() MotorComPS01Impl + MotorComPS01Impl() + linearMovement() # driverInit()