```
MotorCommunicatorInterface
# mc
# port
# socketId
# nibbleTranslational
# nibbleRotary
+ linearMovement()
+ rotate()
+ ~MotorCommunicatorInterface()
# driverInit()
# switchedNibbleT()
# switchedNibbleR()
# openPort()
# frameInit()
# sendPort()
# closePort()
      MotorComRS01Impl
     + MotorComRS01Impl()
     + linearMovement()
     + rotate()
     # driverInit()
```