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HW6

$$1. \nabla f = \begin{pmatrix} 4x_1^3 + 6x_1^2 - 4x_1x_2 \\ -2x_1^2 + 8x_2 \end{pmatrix}$$

$$\nabla^2 f = \begin{pmatrix} 12x_1^2 + 12x_1 - 4x_2 & -4x_1 \\ -4x_1 & 8 \end{pmatrix}$$

For stationary points, $\nabla f = 0 \Leftrightarrow 4x_2^2 = x_1^2$ and $3x_1^2(x_1 + 2) = 0$

So stationary points $x_1^* = (0, 0)$ $x_2^* = (-2, 1)$

$$\nabla^2 f(x_1^*) = \begin{pmatrix} 0 & 0 \\ 0 & 8 \end{pmatrix}$$

$$\nabla^2 f(x_2^*) = \begin{pmatrix} 20 & 8 \\ 8 & 8 \end{pmatrix}$$

$$\text{tr}(\nabla^2 f(x_1^*)) = 28 > 0 \quad \det(\nabla^2 f(x_2^*)) = 160 - 64 > 0.$$

\rightarrow Hessian positive definite, x_2^* local minimizer.

$$f(\pm|t|, 0) = t^4(2 \pm |t|)t^2$$

$$\nabla^2 f^2(x_1^*) \text{ satisfy SONC} = |t|^3(|t| + 2)$$

$\rightarrow x_1^*$ a degenerate saddle

Point

2. (a) $f(x) = \left(\frac{1}{4}x_1^2 - x_2^2 - 2 \right)$

$\nabla^2 f(x) = \begin{pmatrix} \frac{1}{2}x_1 & -2x_2 \\ -2x_2 & -2x_1 + 2x_2^2 \end{pmatrix}$

$\nabla f(x) = 0 \rightarrow 2x_2(2x_2^2 - x_1) = 0$

① $x_2 = 0 \rightarrow x_1 = \pm 2\sqrt{2}$

② $x_1 = 2x_2^2 \rightarrow x_2^4 - x_2^2 - 2 = 0 \rightarrow x_2^2 = 2 \text{ or } -1 \rightarrow x_2 = \pm\sqrt{2}, x_1 = 4$

f has 4 stationary points $\bar{x}_1 = (2\sqrt{2}, 0)$ $\bar{x}_2 = (-2\sqrt{2}, 0)$ $\bar{x}_3 = (4, \sqrt{2})$ $\bar{x}_4 = (4, -\sqrt{2})$

(b) $\nabla^2 f(\bar{x}_1) = \begin{pmatrix} \sqrt{2} & 0 \\ 0 & -4\sqrt{2} \end{pmatrix}$ $\nabla^2 f(\bar{x}_2) = \begin{pmatrix} -\sqrt{2} & 0 \\ 0 & 4\sqrt{2} \end{pmatrix}$

eigen value $\sqrt{2}$ $-4\sqrt{2}$ $-\sqrt{2}$ $4\sqrt{2} \rightarrow \nabla^2 f(\bar{x}_2)$ indefinite, \bar{x}_2 saddle point

$\nabla^2 f(\bar{x}_1)$ indefinite $\rightarrow \bar{x}_1$ saddle point.

$\nabla^2 f(\bar{x}_3) = \begin{pmatrix} 2 & -2\sqrt{2} \\ -2\sqrt{2} & 10 \end{pmatrix}$

$\nabla^2 f(\bar{x}_4) = \begin{pmatrix} 2 & 2\sqrt{2} \\ 2\sqrt{2} & 10 \end{pmatrix}$

$\text{tr}(\nabla^2 f(\bar{x}_3)) = \text{tr}(\nabla^2 f(\bar{x}_4)) = 18 > 0$

$\det(\nabla^2 f(\bar{x}_3)) = \det(\nabla^2 f(\bar{x}_4)) = 32 - 8 = 24 > 0$

So $\nabla^2 f(\bar{x}_3)$ $\nabla^2 f(\bar{x}_4)$ are positive

definite $\rightarrow \bar{x}_3, \bar{x}_4$ are strict

local minimizer (second order sufficient condition)

3. (a) $\nabla g_1(x) = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$ $\nabla g_2(x) = \begin{pmatrix} 0 \\ 1 \end{pmatrix}$ $\nabla g_3(x) = \begin{pmatrix} -2x_1 \\ -2x_2 \end{pmatrix}$

$$g_1(\bar{x}) = g_2(\bar{x}) = -1 < 0 \quad g_3(\bar{x}) = 0$$

So $A(x) = \{3\}$, $\nabla g_3(\bar{x}) = (0, -2)^T \neq 0 \rightarrow$ LICQ satisfied at \bar{x} .

(b) \bar{x} is feasible $g_1(\bar{x}), g_2(\bar{x}) < 0 \rightarrow \bar{\lambda}_1 = \bar{\lambda}_2 = 0$

For $\bar{\lambda}_3$, $\nabla f(\bar{x}) + \nabla g_3(\bar{x})\bar{\lambda}_3 = \begin{pmatrix} 3\bar{x}_1^2 + 2 - 2\bar{x}_3 \\ -4\bar{x}_1\bar{x}_2 + 2\bar{x}_3 \end{pmatrix} + \bar{\lambda}_3 \begin{pmatrix} 0 \\ -2 \end{pmatrix} = \begin{pmatrix} 0 \\ 2 - 2\bar{\lambda}_3 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$

So $\bar{\lambda}_3 = 1$ while $\bar{\lambda}_1 = \bar{\lambda}_2 = 0 \rightarrow$ valid for Lagrange multipliers.

Complementarity condition is satisfied obviously

$\rightarrow (\bar{x}, \bar{\lambda})$ is KKT triple, \bar{x} is KKT point

4. (a) Lagrangian function $L(x_1, x_2, x_3, \lambda) = x_1 + 2x_2 + 4x_3 + \lambda \left(\frac{4}{x_1} + \frac{2}{x_2} + \frac{1}{x_3} - 1 \right)$

Main condition $1 - \frac{4\lambda}{x_1^2} \geq 0 \quad 2 - \frac{2\lambda}{x_2^2} \geq 0 \quad 4 - \frac{\lambda}{x_3^2} \geq 0$

Dual feasibility $\lambda \geq 0$

Complementarity $x_1 \left(1 - \frac{4\lambda}{x_1^2} \right) = 0 \quad x_2 \left(2 - \frac{2\lambda}{x_2^2} \right) = 0 \quad x_3 \left(4 - \frac{\lambda}{x_3^2} \right) = 0 \quad \lambda \left(\frac{4}{x_1} + \frac{2}{x_2} + \frac{1}{x_3} - 1 \right) = 0$

Primal feasibility $\frac{4}{x_1} + \frac{2}{x_2} + \frac{1}{x_3} \leq 1, \quad x_1, x_2, x_3 > 0$

(b) From Primal feasibility condition, we have $x_1, x_2, x_3 \neq 0$.

So For Complementarity condition

$$x_1^2 = 4\lambda, \quad x_2^2 = \lambda, \quad x_3^2 = \frac{\lambda}{4}$$

Plug in $x_1 = 2\sqrt{\lambda}, \quad x_2 = \sqrt{\lambda}, \quad x_3 = \frac{\sqrt{\lambda}}{2}$ into $\frac{4}{x_1} + \frac{2}{x_2} + \frac{1}{x_3} = 1$

we have $\lambda = 36$

So KKT condition has 1 solution

$$x_1 = 12, \quad x_2 = 6, \quad x_3 = 3$$

5 (a) dual variable for $\sum_{i=1}^n x_i \leq p : \lambda_0 \geq 0$. for $x_i \geq 0, \forall i, \lambda_i \geq 0$ for each
 KKT condition Main condition $-\frac{1}{\sigma_i + x_i} + \lambda_0 - \lambda_i = 0 \quad i = 1, 2, \dots, n$

Dual feasibility $\lambda_0 \geq 0, \lambda_i \geq 0$

Complementarity $\lambda_0 (\sum_{i=1}^n x_i - p) = 0 \quad \lambda_i x_i = 0$

Primal feasibility $\sum_{i=1}^n x_i \leq p \quad x_i \geq 0$

(b) $x_1, x_3 > 0$, by complementarity condition, we have $\lambda_1 = \lambda_3 = 0$

main condition $\lambda_0 = \frac{1}{\sigma_1 + x_1} = \frac{2}{5} \rightarrow \lambda_2 = \frac{1}{\sigma_2} + \lambda_0 = \frac{1}{15}$

\rightarrow ~~$\lambda_0 = \frac{2}{5}$~~ $\lambda_0 = \frac{2}{5}, \lambda_1 = 0, \lambda_2 = \frac{1}{15}, \lambda_3 = 0$, which all satisfy
 KKT condition.

$\rightarrow (\frac{1}{2}, 0, \frac{3}{2})$ is a KKT point.