

COMP207 Digital Prototyping Logbook

[COMP207_Assignment_Brief-2.pdf](#)

This logbook documents our progress in designing and fabricating a micro mouse robot using tools such as Fusion 360, EasyEDA, 3D printing, 3D scanning, laser cutting, and the Arduino IDE. The micro mouse must autonomously navigate a maze to reach the endpoint, using only onboard sensors and the provided base components.

We'll be following the [UK Micromouse Classic Rules](#) as our competition standard.

[Table of Contents](#)