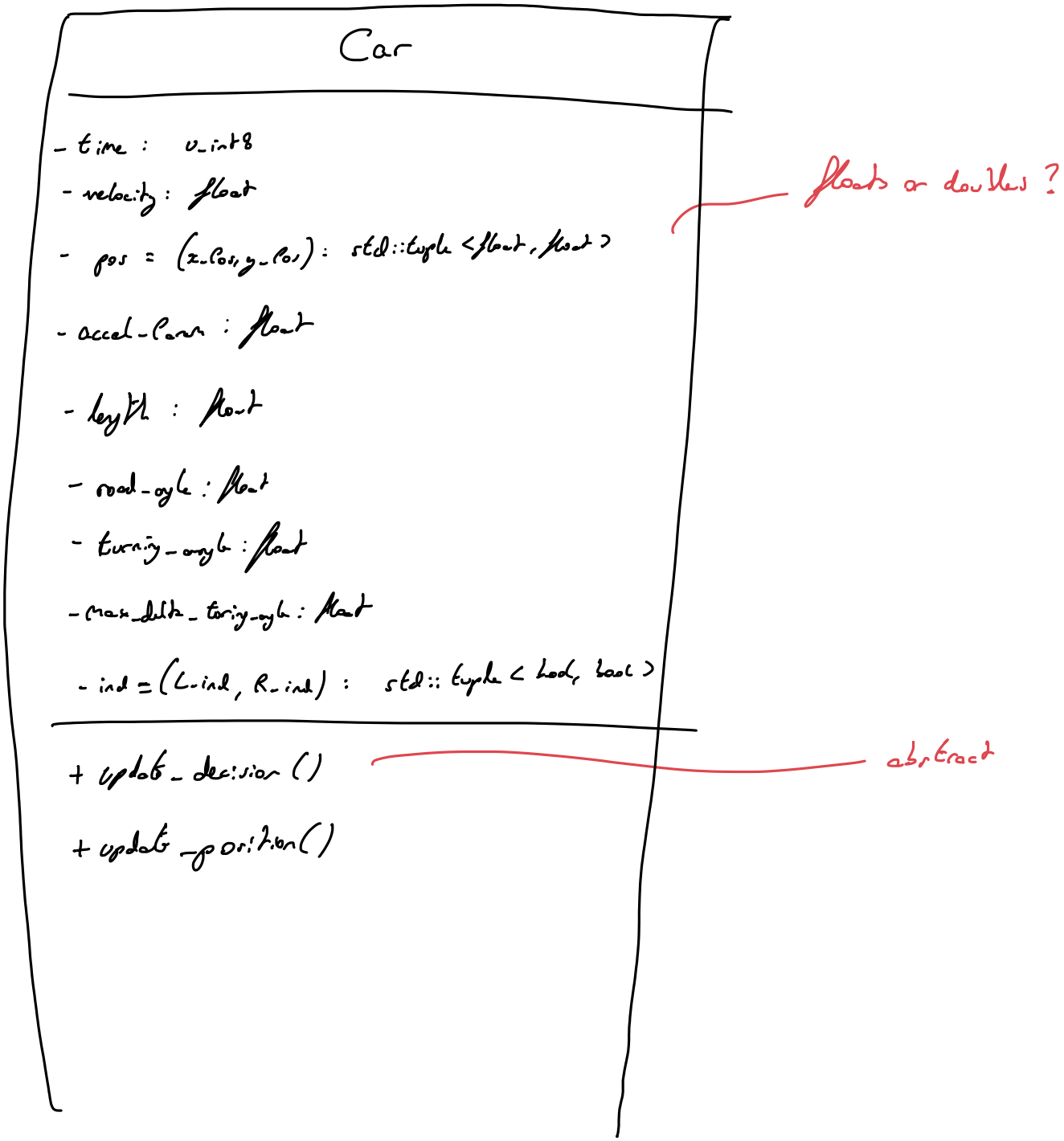
Car
- time : u_int8
- velocity : float
- pos = (x_pos, y_pos) : std::tuple <float, float>
- accel_power : float
- length : float
- road_angle : float
- turning_angle : float
- max_delta_turing_angle : float
- ind = (L_ind, R_ind) : std:: tuple < bool, bool >
+ update_decision ()
+ update_position()
floats or doubles ?
abstract

Road

- road_delim = (x_start, x_end) : std::tuple<float, float>
- lanes : std::tuple<float, ...> ~~~ 1 or 2 lanes