# Linear Algebra Part I

## This is a minimal lecture to get you started

3blue1brown lecture series

Cheatsheet

Notebook

Some things are better read/watched

Too much lecture content is bad

Flipped learning: questions at end of lecture

#### **Functions**

#### **Example 1**

$$f(x) = x^2$$

$$f: \mathbb{R} \to \mathbb{R}^+$$

Domain: all real numbers

Range: all positive real numbers

#### Example 2

$$+(x,y) = x + y$$

$$f: \mathbb{R} \times \mathbb{R} \to \mathbb{R}$$

Domain: all pairs of real numbers

Range: all real numbers

#### **Terminology**

Domain: set of possible inputs

Range: set of possible outputs

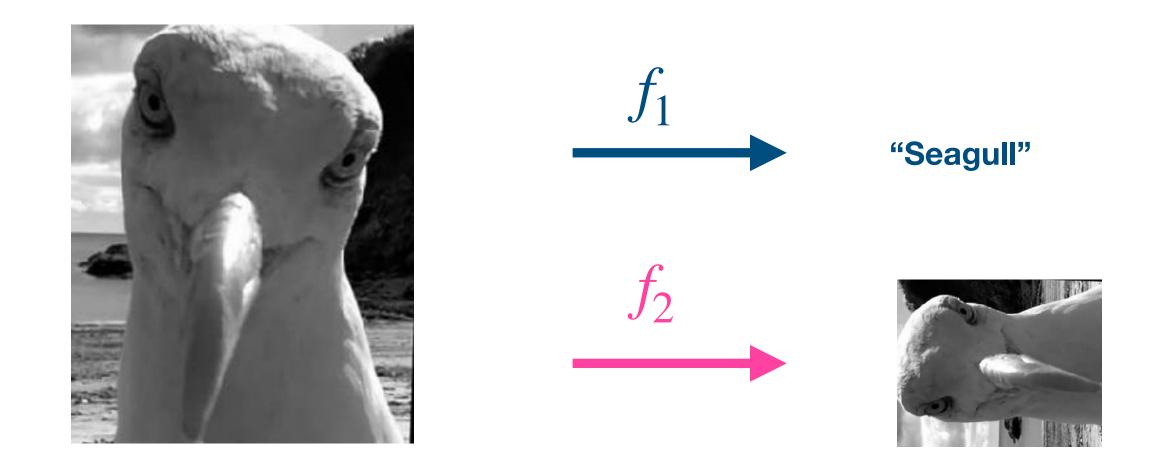
Examples express transformations/relationships between numbers

# Recap

#### **Functions**

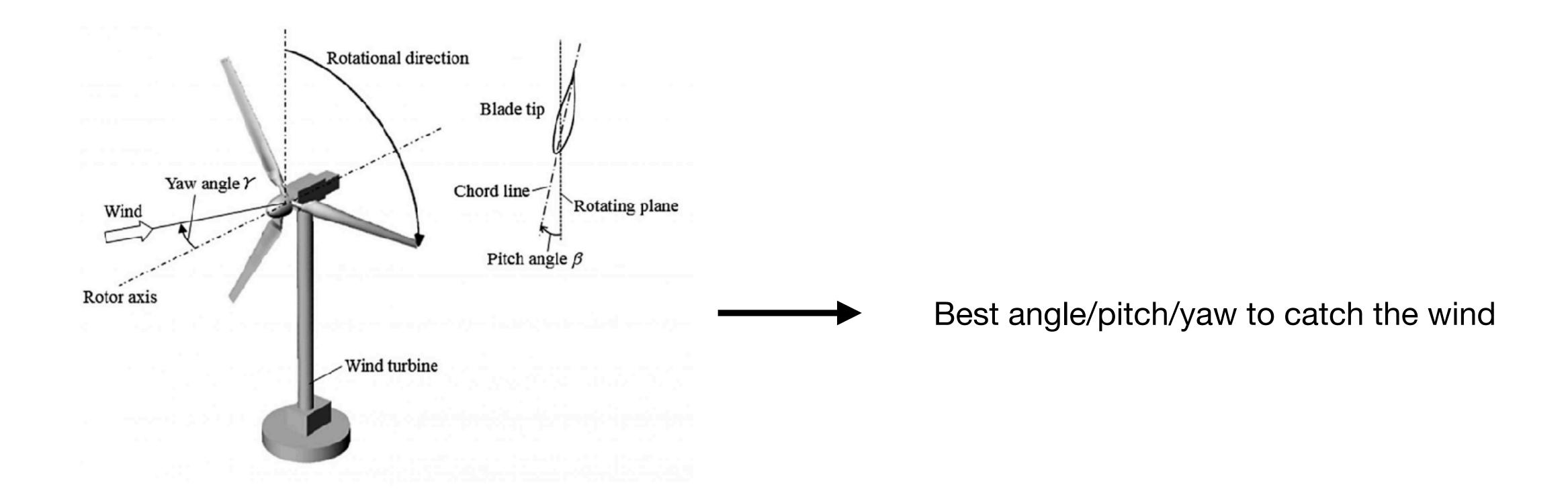
 $f_1: images \rightarrow strings (text)$ 

 $f_2$ : images  $\rightarrow$  images

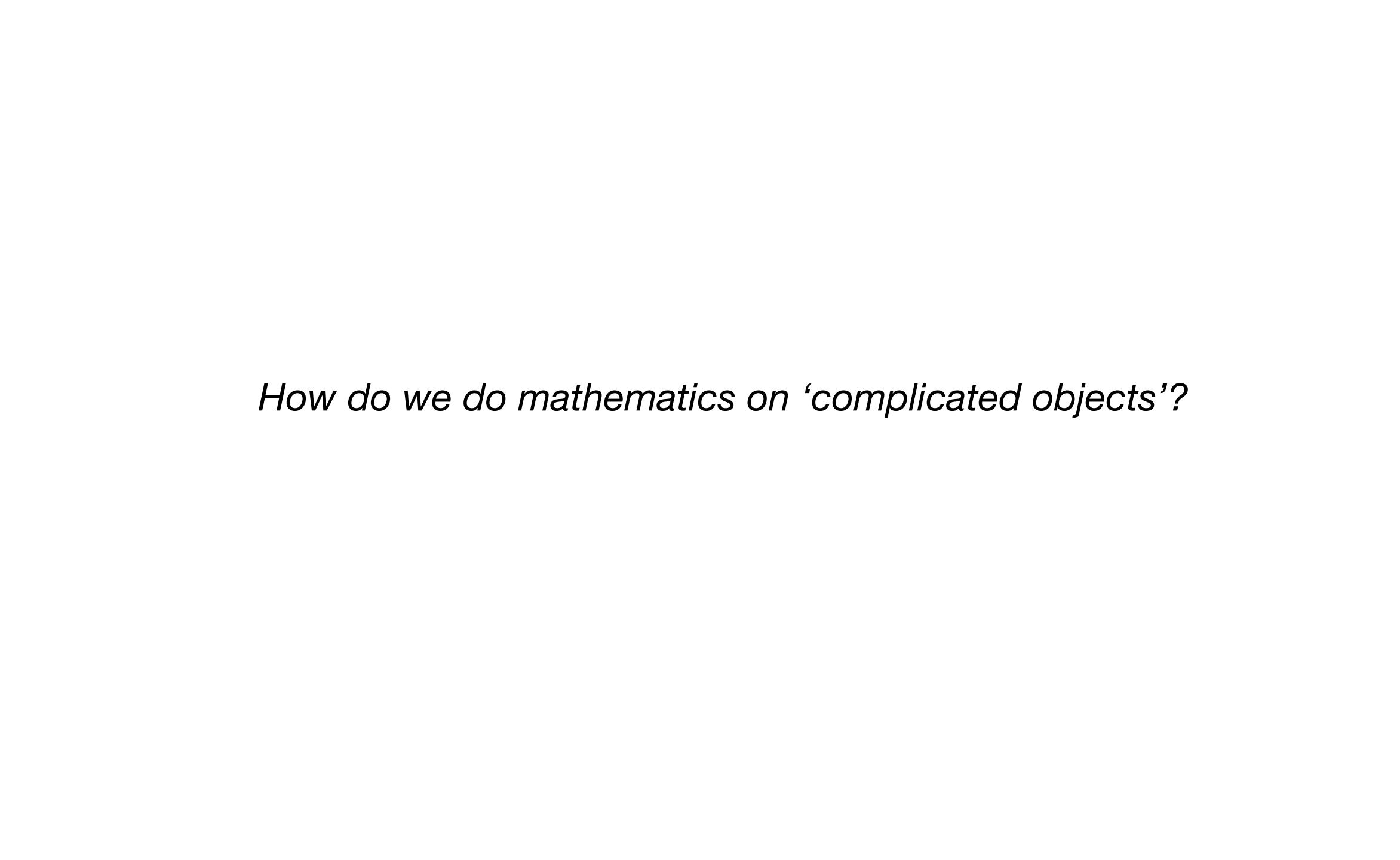


Real life: transformations / relationships between more complicated objects

#### **Functions**

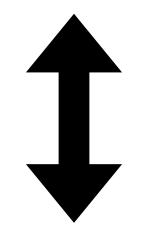


Real life: transformations / relationships between more complicated objects



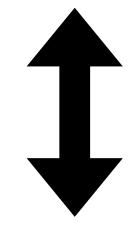
# Complicated objects often boil down to collections arrays of numbers



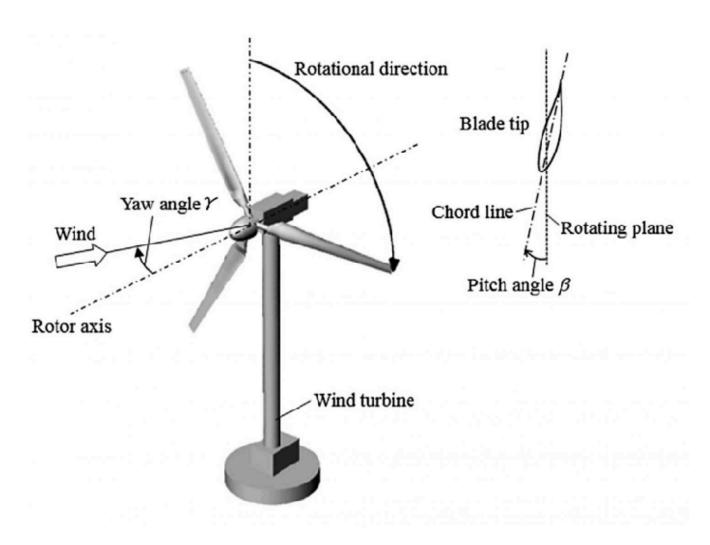


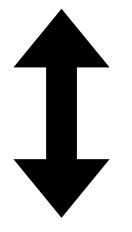
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Lots of numbers!



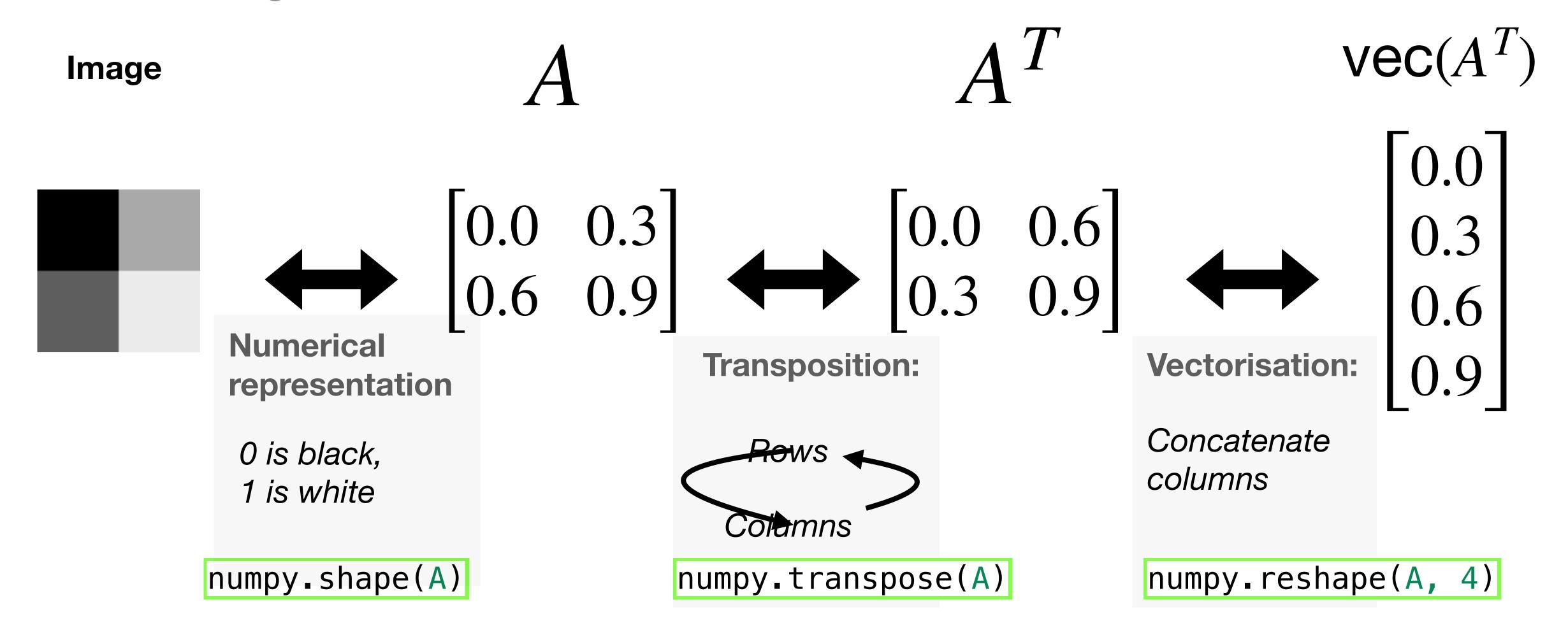


Windspeed, Wind direction, Motor torque, Yaw angle

...

## Arrays have a shape

Which we change as convenient!



## Arrays have a shape

Which we change as convenient!

#### The number 4

A scalar: no shape

numpy.shape(4)

#### The array [4]

An array containing one element: the number 4

numpy.shape([4])

Not the same!!!

# Shapes have a tensor dimension

#### **Vector (1d-array)**

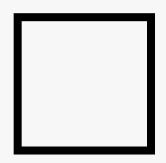
 $[0.0 \quad 0.3 \quad 0.6 \quad 0.9]$ 

#### Matrix (2d-array)

 0.0
 0.3

 0.6
 0.9

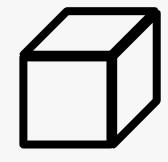
Rows and columns



#### 3-Tensor (3d-array)

$$\begin{bmatrix}
0.0 & 0.3 \\
0.6 & 0.9
\end{bmatrix}
\begin{bmatrix}
0.0 & 0.3 \\
0.6 & 0.9
\end{bmatrix}
\begin{bmatrix}
0.0 & 0.3 \\
0.6 & 0.9
\end{bmatrix}$$

Rows, columns,....layers?



A[3,7,2] - accessing element in 3d array

numpy.reshape([4], (1,1,1,1,1))

- how many dimensions?

# Shapes have a tensor dimension

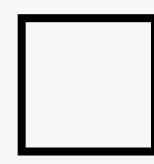
#### **Vector (1d-array)**

$$[0.0 \quad 0.3 \quad 0.6 \quad 0.9]$$

A.shape = (4,)

#### Matrix (2d-array)

Rows and columns

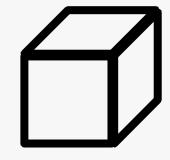


A.shape = (2,2)

#### 3-Tensor (3d-array)

$$\begin{bmatrix}
0.0 & 0.3 \\
0.6 & 0.9
\end{bmatrix}
\begin{bmatrix}
0.0 & 0.3 \\
0.6 & 0.9
\end{bmatrix}
\begin{bmatrix}
0.0 & 0.3 \\
0.6 & 0.9
\end{bmatrix}$$

Rows, columns,....layers?



A.shape = (2,2,3)

Dimension is:

len(A.shape)

# Confusing terminology alert

**Vector (1d-array)** 

 $[0.0 \quad 0.3 \quad 0.6 \quad 0.9]$ 

Python/Julia: - tensor/array dimension is 1

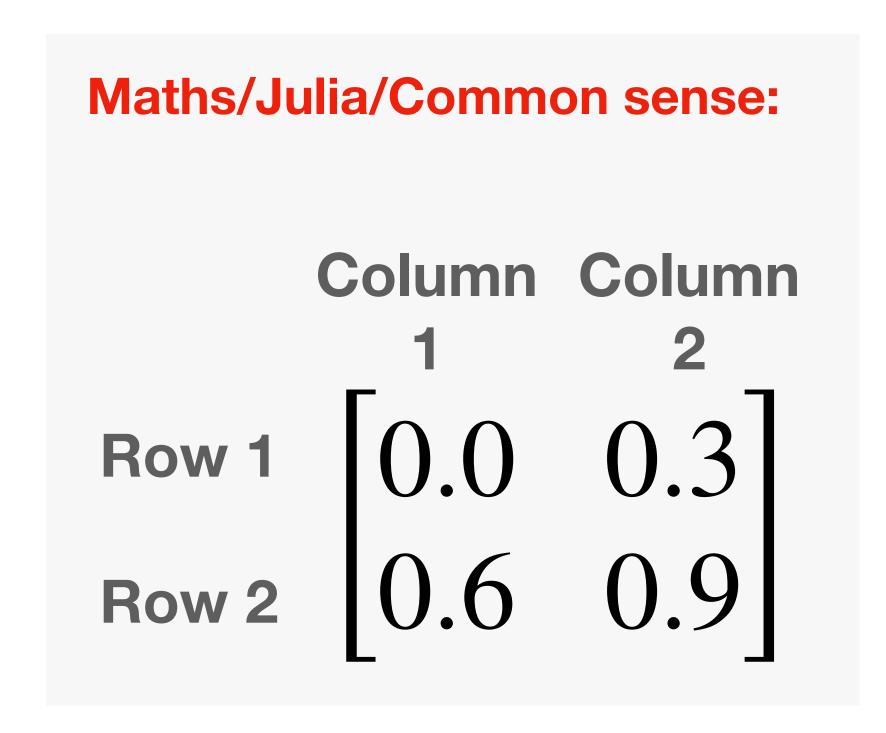
- length is 4

Mathematician: - It's a 4-dimensional vector.

- A vector is a 1d tensor (i.e. array)
  - Vector's length depends on its entries

# Array indexing alert

#### **Avoid incredible Python frustration!!!**



Python: Column Column 0 1 Row 0 
$$\begin{bmatrix} 0.0 & 0.3 \\ 0.6 & 0.9 \end{bmatrix}$$

$$A_{21} = 0.6$$

$$A[1,0] = 0.6$$

Ingredients to do maths on arrays?

Let's look back to how we do maths on numbers!

#### Addition/subtraction

is straightforward!

- Only makes sense on vectors with same shape

- Otherwise, just like for numbers!

$$\begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} + \begin{bmatrix} w \\ x \\ y \\ z \end{bmatrix} = \begin{bmatrix} a+w \\ b+x \\ c+y \\ d+z \end{bmatrix}$$

$$\begin{bmatrix} a & b \\ c & d \end{bmatrix} - \begin{bmatrix} w & x \\ y & z \end{bmatrix} = \begin{bmatrix} a - w & b - x \\ c - y & d - z \end{bmatrix}$$

## Scaling

is straightforward!

- Multiply an array (of any shape) by a scalar (number / field element)

$$\begin{bmatrix} a \\ b \\ c \\ d \end{bmatrix} = \begin{bmatrix} x * a \\ x * b \\ x * c \\ x * d \end{bmatrix}$$

$$\begin{bmatrix} 1 \\ -3 \\ 4 \end{bmatrix} = \begin{bmatrix} -3 \\ -12 \\ 6 \end{bmatrix}$$

## **Dot product**

...also called inner product

$$\frac{a}{c} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}$$

$$\frac{x}{x} = \begin{bmatrix} w \\ x \\ y \end{bmatrix}$$

$$a^{T}x = [a, b, c, d] \begin{bmatrix} w \\ x \\ y \end{bmatrix}$$

#### Also denoted

$$\langle \underline{a}, \underline{x} \rangle$$

$$a \cdot x$$

$$= aw + bx + cy + dz \in \mathbb{R}$$

#### Pause

In Marimo: build two vectors and two matrices.

Take the dot products of the vectors. Subtract the matrices from each other

## What's the point of a matrix?

Two ways to look at a matrix

$$\begin{bmatrix} 4 & 2 & 5 \\ -3 & 6 & 1 \end{bmatrix}$$
 - Two row vectors

$$\begin{bmatrix} 4 & 2 & 5 \\ -3 & 6 & 1 \end{bmatrix}$$
 - Three column vectors

## Matrix multiplication transforms vectors

$$\begin{bmatrix} 4 & 2 & 5 \\ -3 & 6 & 1 \end{bmatrix} \quad \begin{bmatrix} 2 \\ 4 \\ 3 \end{bmatrix} = ?$$

Do this in Marimo now

## Matrix multiplication transforms vectors

Inner product of each row vector in the matrix, with the vector

$$\begin{bmatrix} 4 & 2 & 5 \\ -3 & 6 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 4 \\ 3 \end{bmatrix} = \begin{bmatrix} 8+8+15 \\ -6+24+3 \end{bmatrix}$$

- Requirement: number of matrix columns = length of vector
- Outcome: length of new vector = number of rows in matrix

#### **Alternative**

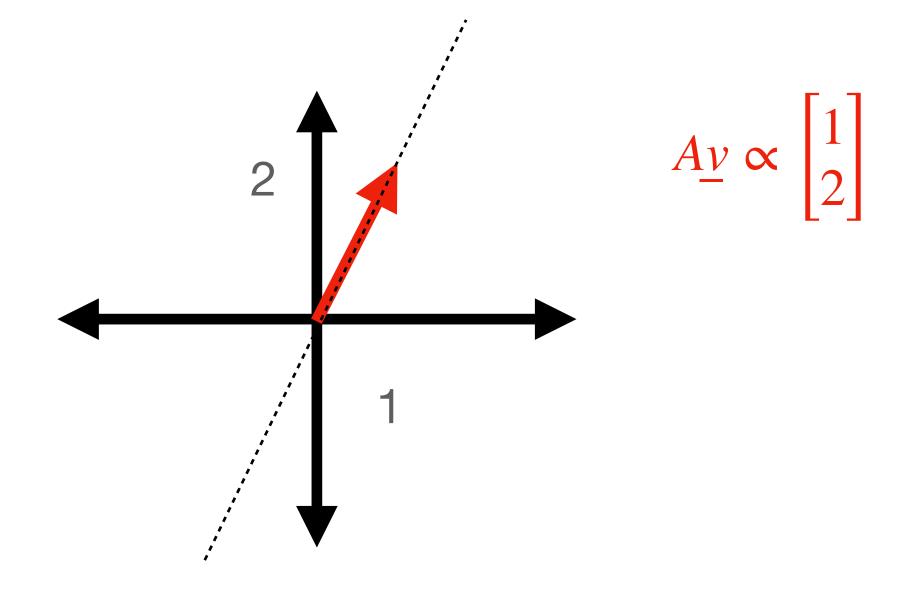
$$\begin{bmatrix} 4 & 2 & 5 \\ -3 & 6 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 4 \\ 3 \end{bmatrix} = 2 \begin{bmatrix} 4 \\ -3 \end{bmatrix} + 4 \begin{bmatrix} 2 \\ 6 \end{bmatrix} + 3 \begin{bmatrix} 5 \\ 1 \end{bmatrix}$$

- Requirement: number of matrix columns = length of vector
- Outcome: length of new vector = number of rows in matrix

# What can you say about this matrix?

$$\begin{bmatrix} 1 & 2 & 3 \\ 2 & 4 & 6 \end{bmatrix} \begin{bmatrix} v_1 \\ v_2 \\ v_3 \end{bmatrix}$$

All input vectors are pushed onto this line



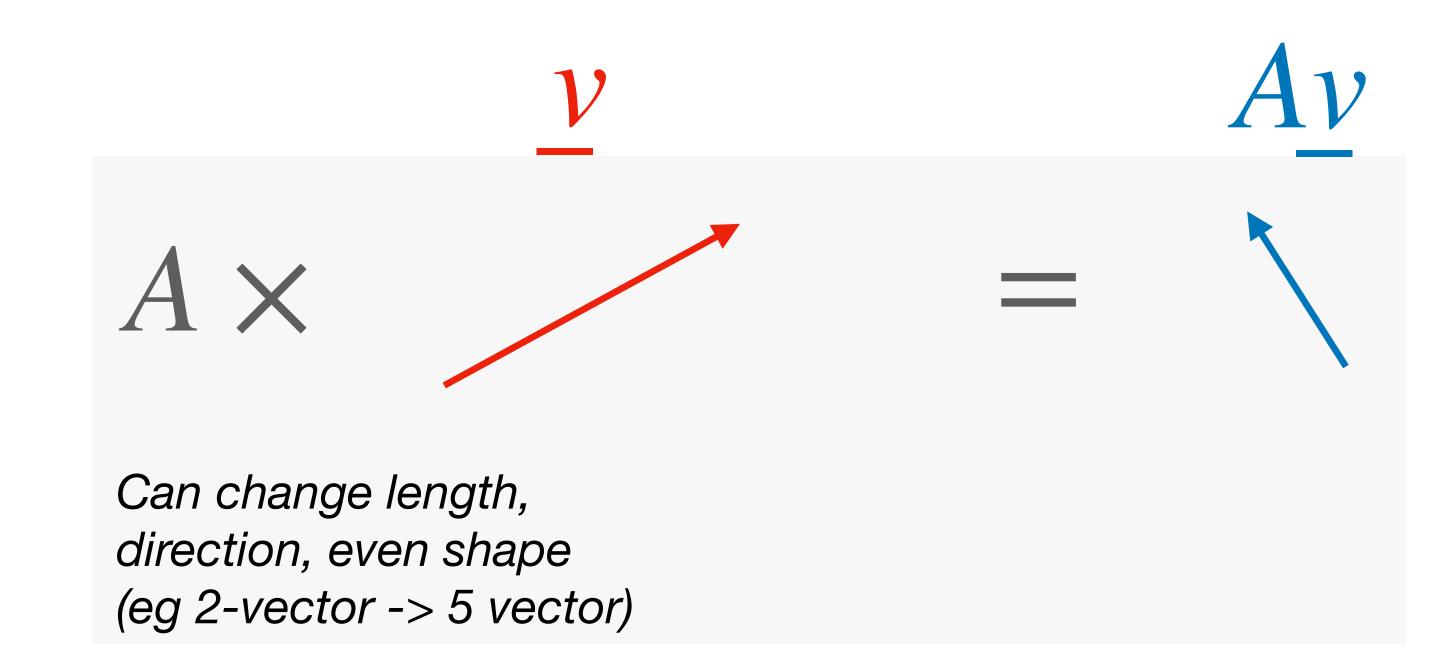
#### Matrices transform vectors

...by matrix multiplication

$$f(\underline{v}) = (\underline{A}\underline{v}) \qquad \text{Vector}$$
Vector

Matrix

Use np.matmul to transform your vector by your matrix in marimo

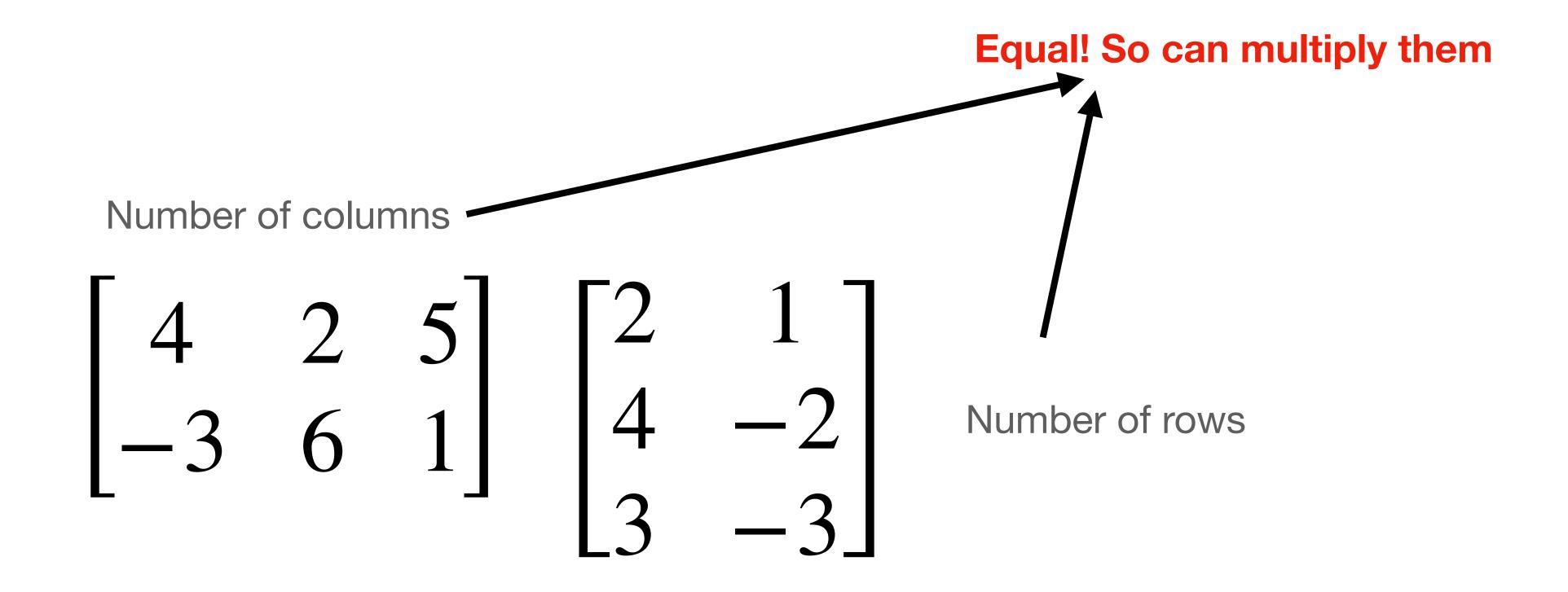


#### Square matrix properties

$$\begin{bmatrix} 4 & 2 & 5 \\ -3 & 6 & 1 \\ 1 & 3 & -2 \end{bmatrix} \begin{bmatrix} 2 \\ 4 \\ 3 \end{bmatrix} = \begin{bmatrix} \bullet \\ \bullet \end{bmatrix}$$

Input and output vectors have same shape

## When can we multiply matrices?



a) Figure out the shape of the output

(m x n) matrix multiplied by (n x p) matrix = (m x p) matrix

**Requirement**: Number of columns (A) = Number of rows (B)

a) Figure out the shape of the output

$$\begin{bmatrix} 4 & 2 & 5 \\ -3 & 6 & 1 \end{bmatrix} \begin{bmatrix} 2 & 1 \\ 4 & -2 \\ 3 & -3 \end{bmatrix} = \begin{bmatrix} \bullet & \bullet \\ \bullet & \bullet \end{bmatrix}$$

Outcome: Number of rows (A) x Number of columns (B)

 $C_{ii}$  Depends on  $i^{th}$  row and  $j^{th}$  column

b) Inner product of each row vector of A with each column vector of B

$$\begin{array}{c|ccccc}
A & B & C \\
\hline
 \begin{bmatrix} 4 & 2 & 5 \\ -3 & 6 & 1 \end{bmatrix} & \begin{bmatrix} 2 & 1 \\ 4 & -2 \\ 3 & -3 \end{bmatrix} & = \begin{bmatrix} (8+8+15) & (4-4-15) \\ (-6+24+3) & (-3-12-3) \end{bmatrix} \\
& = \begin{bmatrix} 31 & -15 \\ 21 & -18 \end{bmatrix} \\
C_{ij} = \langle A_{i,\bullet}, B_{\bullet,j} \rangle$$

ith row ith column

Question: Is this allowable?

$$\begin{bmatrix} 2,3 \end{bmatrix} \begin{bmatrix} 4 & 2 & 5 \\ -3 & 6 & 1 \end{bmatrix} = [\bullet, \bullet, \bullet]$$

#### **Verify yourself:**

$$\left( \begin{bmatrix} 2,3 \end{bmatrix} \begin{bmatrix} 4 & 2 & 5 \\ -3 & 6 & 1 \end{bmatrix} \right)^{T} = \begin{bmatrix} 4 & -3 \\ 2 & 6 \\ 5 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ 3 \end{bmatrix}$$

## Law of matrix transposition

$$(A\nu)^T = \nu^T A^T$$

Transposition swaps the multiplication order

## Important: non-commutativity of multiplication

i.e.  $AB \neq BA$  unlike scalars

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix} = ?$$

$$\begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} = ?$$

Different row/column vectors!

# The identity matrix

 $I_n$  is an  $(n \times n)$  matrix with ones on the diagonal

$$I_3 = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

$$I_{3} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \qquad I_{n} = \begin{bmatrix} 1 & 0 & \dots & 0 \\ 0 & 1 & 0 & \vdots \\ \vdots & 0 & \ddots & \vdots \\ 0 & \dots & \dots & 1 \end{bmatrix}$$

#### **Exercise:**

$$\begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix} = ?$$

$$\begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix} = ?$$

# The identity matrix

 $I_n$  is an  $(n \times n)$  matrix with ones on the diagonal

$$AI = IA = A$$

- analogous to the number 1 in scalar multiplication

$$x(1) = 1(x) = x$$

#### The scalar inverse

$$f(x) = 4x$$

$$g(x) = \frac{1}{4}x$$

$$g \circ f(x) = \frac{1}{4}(4x) = 1x = x$$

$$\frac{1}{4}$$
 is the inverse of 4

 $f \circ g$  is the identity function:  $f \circ g(x) = 1(x)$ 

## The matrix inverse (for square matrices)

numpy linalg inv(A)

Inverse of A is  $A^{-1}$  implies:

$$AA^{-1} = A^{-1}A = I$$

$$\Rightarrow AA^{-1}x = x$$

**Example** (verify yourself)

$$\begin{bmatrix} -2.5 & 1.5 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix} = \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix} \begin{bmatrix} -2.5 & 1.5 \\ 2 & -1 \end{bmatrix} = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}$$

...is useful

Problem: find 
$$a, b$$

$$\begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} 7 \\ 13 \end{bmatrix}$$

Cancels to identity! 
$$\begin{bmatrix} -2.5 & 1.5 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} 2 & 3 \\ 4 & 5 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} -2.5 & 1.5 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} 7 \\ 13 \end{bmatrix}$$

$$\begin{bmatrix} a \\ b \end{bmatrix} = \begin{bmatrix} -2.5 & 1.5 \\ 2 & -1 \end{bmatrix} \begin{bmatrix} 7 \\ 13 \end{bmatrix} = \begin{bmatrix} 2 \\ 1 \end{bmatrix}$$

...is useful

General problem: find  $\underline{x}$ , given y

$$A\underline{x} = \underline{y}$$

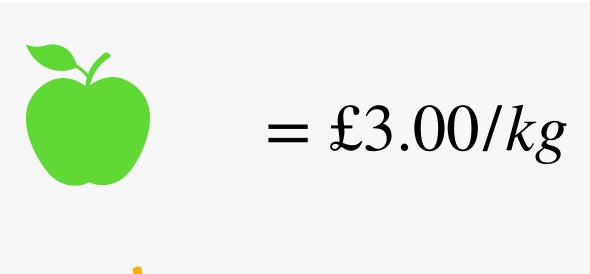
$$\Rightarrow A^{-1}A\underline{x} = \underline{x} = A^{-1}y$$

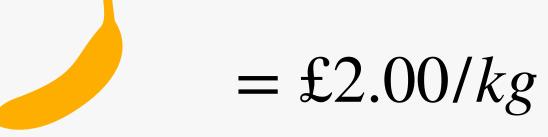
This is called a matrix equation

toy application

$$\frac{x}{2}$$

$$\begin{bmatrix} £3.00/kg & £2.00/kg \\ 1 & 1 \end{bmatrix} \begin{bmatrix} a & kg \\ b & kg \end{bmatrix} = \begin{bmatrix} £12 \\ 5kg \end{bmatrix}$$





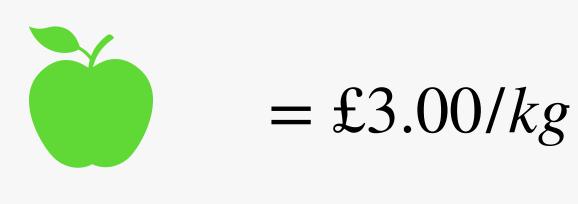


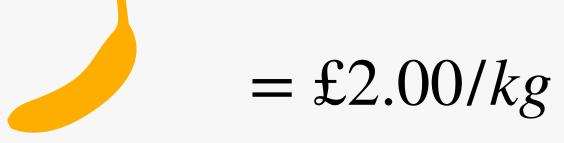
- Number of rows of A is number of constraints
- Number of columns of A is number of free variables

toy application

$$\frac{x}{A^{-1}} \qquad \frac{y}{2}$$

$$\begin{bmatrix} a & kg \\ b & kg \end{bmatrix} = \begin{bmatrix} 1 & kg/\pounds & -2 \\ -1 & kg/\pounds & 3 \end{bmatrix} \begin{bmatrix} £12 \\ 5kg \end{bmatrix} = \begin{bmatrix} 2 & kg \\ 3 & kg \end{bmatrix}$$







- Number of rows of A is number of constraints
- Number of columns of A is number of free variables

...doesn't always exist!

$$A\underline{x} = \underline{y}$$

$$\Rightarrow A^{-1}A\underline{x} = \underline{x} = A^{-1}y$$

Proof by contradiction: inverse can't exist

$$\begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix}^{-1} \begin{bmatrix} 0 \\ 0 \end{bmatrix}? \dots \text{but} \qquad \begin{bmatrix} a & b \\ c & d \end{bmatrix} \begin{bmatrix} 0 \\ 0 \end{bmatrix} = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

...doesn't always exist!

#### **Square matrices**

**Invertible matrices** 

$$Ax = 0 \Rightarrow x = 0$$

Non-invertible matrices

$$A\underline{x} = \underline{0}$$
 for nonzero  $\underline{x}$ 

$$A \times$$

## Important note on array algebra

$$A\underline{x} = \underline{y}$$

$$\Rightarrow A^{-1}A\underline{x} = \underline{x} = A^{-1}y$$

$$A^{-1}A\underline{x} = \underline{x} \neq A\underline{x}A^{-1}$$

#### **Equation manipulation:**

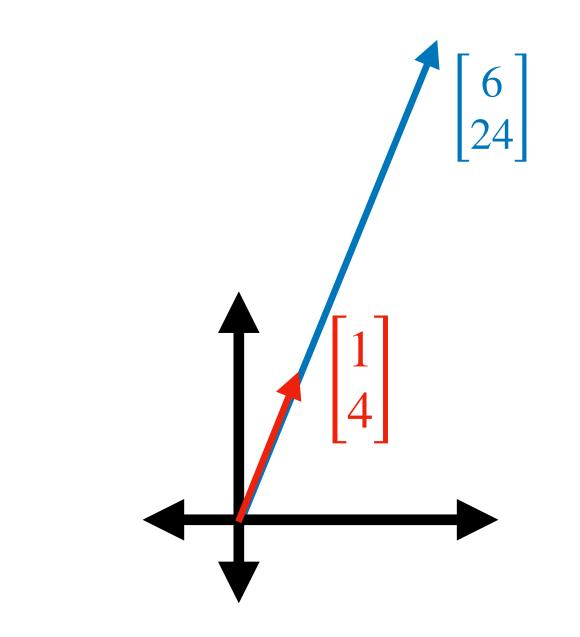
- Can do same thing to both sides of the equation (like scalar algebra)
- Except, left multiplication and right multiplication are different

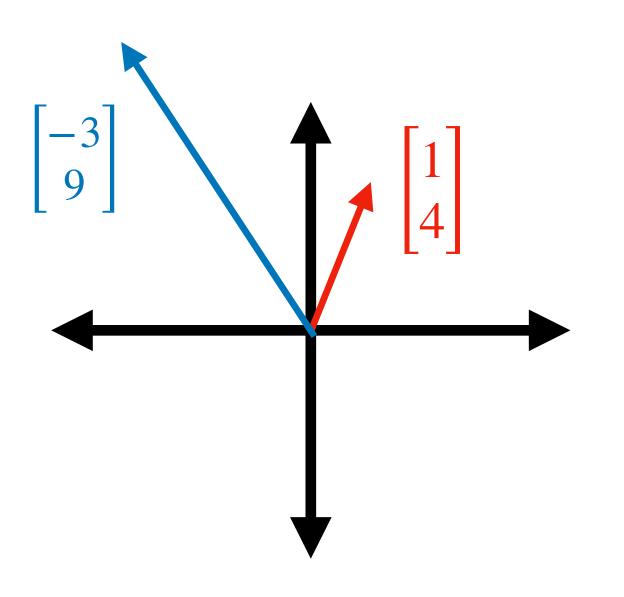
$$\begin{bmatrix} -6 & 3 \\ 4 & 5 \end{bmatrix} \begin{bmatrix} 1 \\ 4 \end{bmatrix} = ? \qquad = \begin{bmatrix} 6 \\ 24 \end{bmatrix} = 6 \begin{bmatrix} 1 \\ 4 \end{bmatrix}$$

- Pure scaling, no rotation

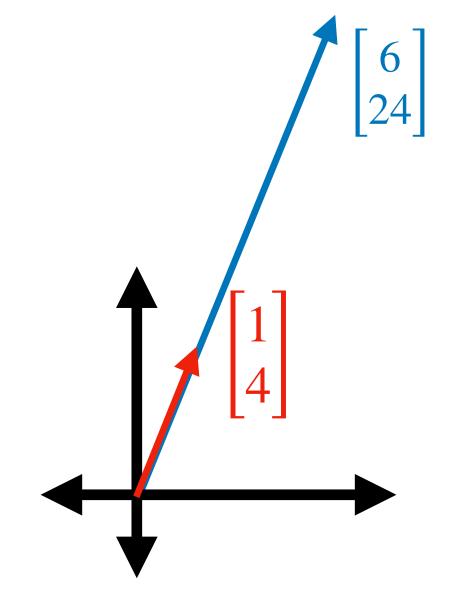
$$\begin{bmatrix} -6 & 3 \\ 4 & 5 \end{bmatrix} \begin{bmatrix} 1 \\ 1 \end{bmatrix} = ? = \begin{bmatrix} -3 \\ 9 \end{bmatrix}$$

- Scaling and rotation

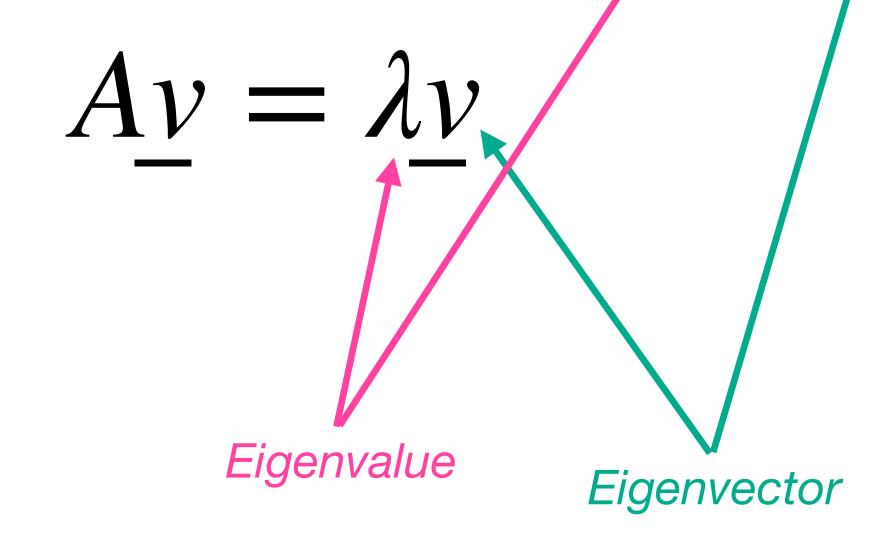




$$\begin{bmatrix} -6 & 3 \\ 4 & 5 \end{bmatrix} \begin{bmatrix} 1 \\ 4 \end{bmatrix} = ? \qquad = \begin{bmatrix} 6 \\ 24 \end{bmatrix} = 6$$



- Pure scaling, no rotation



- Eigenvectors of a matrix are those that don't rotate under transformation

numpy.linalg.eig(A)

Exercise: find eigenvectors of

$$egin{bmatrix} d_1 & 0 \ 0 & d_2 \end{bmatrix}$$

