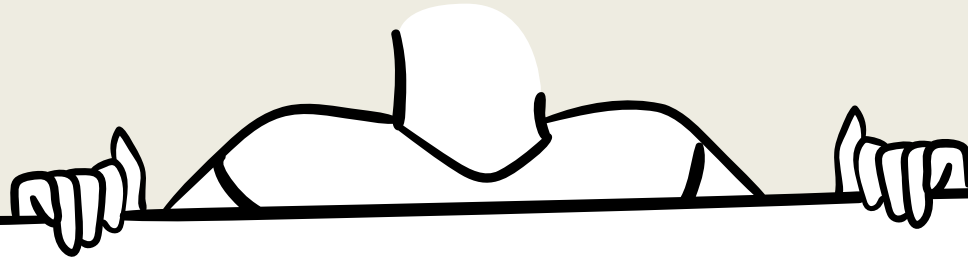


A simple ML model

MACHINE LEARNING

Dr. Temitayo Olugbade

Learning outcome



After working through this mini-video,

- ❑ you'll see how one of the simplest machine learning models (linear regression) works.

Lecture outline

- ❑ The basic linear model
- ❑ How learning happens in ML



Recall from Week 1b mini-video

1. The most basic element of **machine learning** is a **model** that learns from data.
2. With **supervised learning**, data has both **features/input x** & **labels/output y** .
3. When the label/output are real valued or continuous, it is a **regression** task. Otherwise, it is **classification**.
4. An important goal in machine learning is **generalizability** to data not seen by the model during its training.

The basic linear model

- ❑ The basic linear model
- ❑ How learning happens in ML



Basic linear model

is a function $f(\mathbf{x})$ defined as

$$f(\mathbf{x}) = \mathbf{x}\mathbf{w} + b = \hat{\mathbf{y}}$$

where


- \mathbf{x} – features (i.e. model input)
- $\hat{\mathbf{y}}$ – real/continuous-valued predicted labels (i.e. model output)
- \mathbf{w}, b – weights, bias (these are model parameters)

Basic linear model

is a function $f(\mathbf{x})$ defined as

$$f(\mathbf{x}) = \mathbf{x}\mathbf{w} + b = \hat{\mathbf{y}}$$

implies
'supervised
learning'



where

- \mathbf{x} – features (i.e. model input)
- $\hat{\mathbf{y}}$ – real/continuous-valued predicted labels (i.e. model output)
- \mathbf{w}, b – weights, bias (these are model parameters)

implies
'regression'



Applying the model to toy data

$$\begin{aligned} f(\mathbf{x}) = \hat{\mathbf{y}} &= \mathbf{x}\mathbf{w} + b \\ &= x_1w_1 + x_2w_2 + \cdots + x_Dw_D + b \end{aligned}$$

see alternative math expressions in last slide pages

Applying the model to toy data

$$f(\mathbf{x}) = \hat{\mathbf{y}} = \mathbf{x}\mathbf{w} + b = x_1w_1 + x_2w_2 + \cdots + x_Dw_D + b$$

Temperature (°C)	Relative humidity (%)	Wind speed (km/h)	Rain (mm)	Fire weather index
23	21	10	0	0
40	89	6	1	30
35	60	23	15	15

Applying the model to toy data

$$f(\mathbf{x}) = \hat{\mathbf{y}} = \mathbf{x}\mathbf{w} + b = x_1w_1 + x_2w_2 + \cdots + x_Dw_D + b$$

Temperature (°C)	Relative humidity (%)	Wind speed (km/h)	Rain (mm)	Fire weather index
23	21	10	0	0
40	89	6	1	30
35	60	23	15	15

$$\begin{bmatrix} \hat{y}_1 \\ \hat{y}_2 \\ \hat{y}_{N=3} \end{bmatrix} = \begin{bmatrix} 23 & 21 & 10 & 0 \\ 40 & 89 & 6 & 1 \\ 35 & 60 & 23 & 15 \end{bmatrix} \times \begin{bmatrix} w_1 \\ w_2 \\ w_3 \\ w_D \end{bmatrix} + \begin{bmatrix} b \\ b \\ b \end{bmatrix}$$

Applying the model to toy data

$$f(\mathbf{x}) = \hat{\mathbf{y}} = \mathbf{x}\mathbf{w} + b = x_1w_1 + x_2w_2 + \cdots + x_Dw_D + b$$

$$\begin{bmatrix} \hat{y}_1 \\ \hat{y}_2 \\ \hat{y}_{N=3} \end{bmatrix} = \begin{bmatrix} 23 & 21 & 10 & 0 \\ 40 & 89 & 6 & 1 \\ 35 & 60 & 23 & 15 \end{bmatrix} \times \begin{bmatrix} w_1 \\ w_2 \\ w_3 \\ w_4 \end{bmatrix} + \begin{bmatrix} b \\ b \\ b \end{bmatrix}$$

$$\Rightarrow \hat{y}_1 = 23w_1 + 21w_2 + 10w_3 + 0w_4 + b$$

$$\hat{y}_2 = 40w_1 + 89w_2 + 6w_3 + 1w_4 + b$$

$$\hat{y}_3 = 35w_1 + 60w_2 + 23w_3 + 15w_4 + b$$

Applying the model to toy data

$$f(\mathbf{x}) = \hat{\mathbf{y}} = \mathbf{x}\mathbf{w} + b = x_1w_1 + x_2w_2 + \cdots + x_Dw_D + b$$

$$\begin{bmatrix} \hat{y}_1 \\ \hat{y}_2 \\ \hat{y}_{N=3} \end{bmatrix} = \begin{bmatrix} 23 & 21 & 10 & 0 \\ 40 & 89 & 6 & 1 \\ 35 & 60 & 23 & 15 \end{bmatrix} \times \begin{bmatrix} w_1 \\ w_2 \\ w_3 \\ w_D \end{bmatrix} + \begin{bmatrix} b \\ b \\ b \end{bmatrix}$$

$$\Rightarrow \hat{y}_1 = 23w_1 + 21w_2 + 10w_3 + 0w_4 + b$$

$$\hat{y}_2 = 40w_1 + 89w_2 + 6w_3 + 1w_4 + b$$

$$\hat{y}_3 = 35w_1 + 60w_2 + 23w_3 + 15w_4 + b$$

but what are the best values of \mathbf{w} and b , i.e. the optimal model parameters?

How learning happens in ML

❑ The basic linear model

❑ **How learning happens in ML**



Learning the optimal model parameters

- The optimal model parameters would minimize the error between the model prediction $\hat{\mathbf{y}}$ and the true label \mathbf{y}
- Since \mathbf{y} is real/continuous-valued, one possible way to measure the model error is mean-squared error L_2 , i.e.

$$L_2 = \frac{1}{N} \sum_{n=1}^N (\hat{\mathbf{y}}_n - \mathbf{y}_n)^2$$

Learning the optimal model parameters

- The optimal model parameters would minimize the error between the model prediction $\hat{\mathbf{y}}$ and the true label \mathbf{y}
- Since \mathbf{y} is real/continuous-valued, one possible way to measure the model error is **mean-squared error** L_2 , i.e.

$$L_2 = \frac{1}{N} \sum_{n=1}^N (\hat{\mathbf{y}}_n - \mathbf{y}_n)^2$$

mean

squared

difference
(aka error)

Learning the optimal model parameters

- The optimal model parameters would minimize the error between the model prediction $\hat{\mathbf{y}}$ and the true label \mathbf{y}
- Since \mathbf{y} is real/continuous-valued, one possible way to measure the model error is mean-squared error L_2 , i.e.

$$\begin{aligned} L_2 &= \frac{1}{N} \sum_{n=1}^N (\hat{\mathbf{y}}_n - \mathbf{y}_n)^2 \\ &= \frac{1}{N} \sum_{n=1}^N (\mathbf{x}_n \mathbf{w} + b - \mathbf{y}_n)^2 \end{aligned}$$

Minimizing the error

- Error $L_2 = \frac{1}{N} \sum_{n=1}^N (\mathbf{x}_n \mathbf{w} + b - \mathbf{y}_n)^2$
- From math principles, the minimum of a function is when its gradient (derivative) is zero, so

$$0 = \frac{dL_2}{d\mathbf{w}}$$

- When you expand, apply the derivative, and make \mathbf{w} the subject of the equation

$$\mathbf{w} = (\mathbf{x}^T \mathbf{x})^{-1} \mathbf{x}^T \mathbf{y}$$

see math details (i.e. proof) in last slide pages

Minimizing the error

- Error $L_2 = \frac{1}{N} \sum_{n=1}^N (\mathbf{x}_n \mathbf{w} + b - y_n)^2$
- From math principles, the minimum of a function is when its gradient (derivative) is zero, so

$$0 = \frac{dL_2}{d\mathbf{w}}$$

- When you expand, apply the derivative, and make \mathbf{w} the subject of the equation

$$\mathbf{w} = (\mathbf{x}^T \mathbf{x})^{-1} \mathbf{x}^T \mathbf{y}$$

inverse
transpose

ML with the basic linear model

- Get training data, i.e. $(\mathbf{x}_n, \mathbf{y}_n)$ pairs, $1 \leq n \leq N$
- Choose an error metric, e.g. mean-squared error L_2
- Find the optimal model parameters, i.e. the best values for \mathbf{w}^* and b^*
- Plug this in your model and apply to obtain $\hat{\mathbf{y}}$

$$f(\mathbf{x}) = \hat{\mathbf{y}} = \mathbf{x}\mathbf{w}^* + b^*$$

ML with the basic linear model

- Get training data, i.e. $(\mathbf{x}_n, \mathbf{y}_n)$ pairs, $1 \leq n \leq N$
- Choose an error metric, e.g. mean-squared error L_2

→ **loss function**

- Find the optimal model parameters, i.e. the best values for \mathbf{w}^* and b^*

model training ←

- Plug this in your model and apply to obtain $\hat{\mathbf{y}}$

inference ↗

$$f(\mathbf{x}) = \hat{\mathbf{y}} = \mathbf{x}\mathbf{w}^* + b^*$$

→ **trained model**

Other loss function – Mean absolute error

- Mean absolute error L_1

$$L_1 = \frac{1}{N} \sum_{n=1}^N |\hat{y}_n - y_n|$$

- Demerit

Its gradient $\frac{dL_1(\mathbf{w})}{d\mathbf{w}}$ is a constant and not a function of \mathbf{w} , so the optimal \mathbf{w} can't be obtained as easily

see math details (i.e. proof) in last slide pages

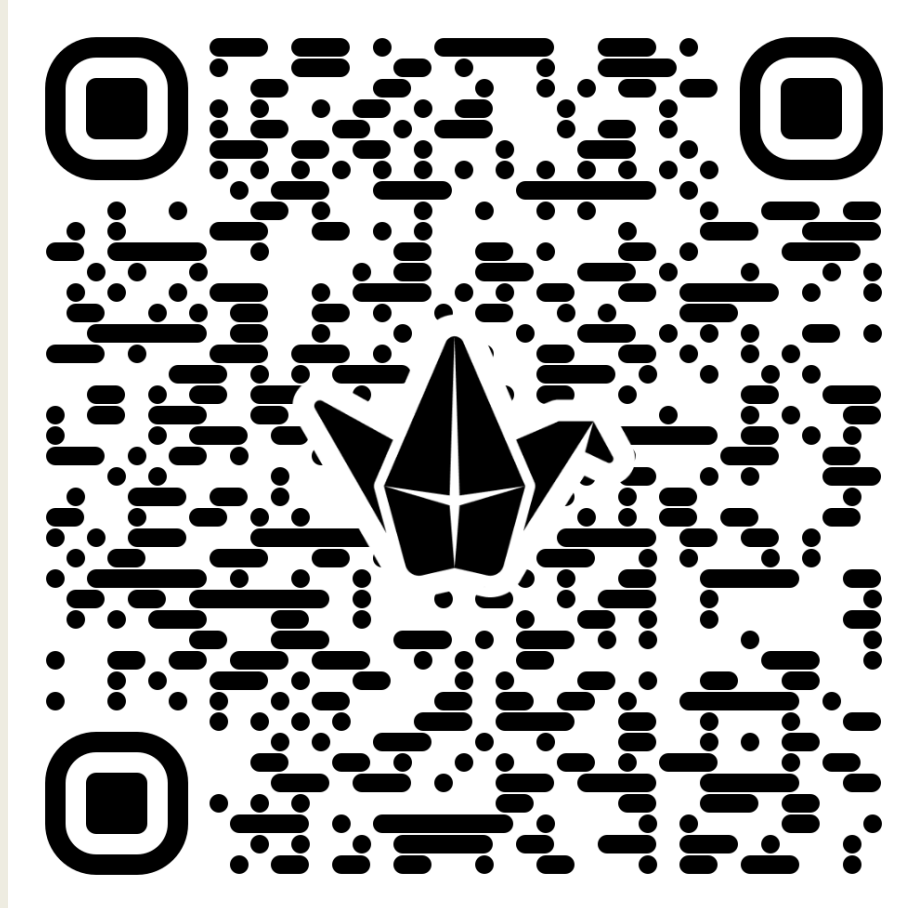
- Merit

L_1 is less influenced by outliers

Summary

1. The basic linear ML model is $f(\mathbf{x}) = \hat{\mathbf{y}} = \mathbf{x}\mathbf{w} + b$. It is a regression model. This makes this a **linear regression** model.
2. Training a ML model involves optimizing the model weights based on a **loss function**.

Any questions???



scan the QR code to ask questions

Math details and proofs

Basic linear model reframed

$$f(\mathbf{x}) = \hat{\mathbf{y}} = \mathbf{x}\mathbf{w} + b$$

- In matrix form

$$\begin{bmatrix} \hat{y}_1 \\ \vdots \\ \hat{y}_N \end{bmatrix} = \begin{bmatrix} x_{11} & \cdots & x_{1D} \\ \vdots & \ddots & \vdots \\ x_{N1} & \cdots & x_{ND} \end{bmatrix} \times \begin{bmatrix} w_1 \\ \vdots \\ w_D \end{bmatrix} + \begin{bmatrix} b \\ \vdots \\ b \end{bmatrix}$$

- Rewriting to absorb b in \mathbf{w}

$$f(\mathbf{x}) = \hat{\mathbf{y}} = \mathbf{x}\mathbf{w}$$

$$\begin{bmatrix} \hat{y}_1 \\ \vdots \\ \hat{y}_N \end{bmatrix} = \begin{bmatrix} x_{11} & \cdots & x_{1D} & 1 \\ \vdots & \ddots & \vdots & \\ x_{N1} & \cdots & x_{ND} & 1 \end{bmatrix} \times \begin{bmatrix} w_1 \\ \vdots \\ w_D \\ b \end{bmatrix}$$

Minimizing the error – MATH DETAIL (1)

$$0 = \frac{dL_2(\mathbf{w})}{d\mathbf{w}}$$

if you substitute for $L_2(\mathbf{w})$ with its value

$$0 = \frac{1}{N} \times \frac{d\left(\frac{1}{N} \sum_{n=1}^N (\mathbf{x}_n \mathbf{w} + b - \mathbf{y}_n)^2\right)}{d\mathbf{w}}$$

a neater (shorthand) way to write this is

$$0 = \frac{1}{N} \times \frac{d(\|\mathbf{xw} - \mathbf{y}\|^2)}{d\mathbf{w}}$$

when you expand the numerator of the right hand side

$$0 = \frac{d((\mathbf{xw} - \mathbf{y})^T (\mathbf{xw} - \mathbf{y}))}{d\mathbf{w}}$$

Minimizing the error – MATH DETAIL (2)

$$0 = \frac{d((\mathbf{x}\mathbf{w} - \mathbf{y})^T(\mathbf{x}\mathbf{w} - \mathbf{y}))}{d\mathbf{w}}$$

when you further expand and collect like terms

$$0 = \frac{d(\mathbf{w}^T \mathbf{x}^T \mathbf{x} \mathbf{w} - 2\mathbf{w}^T \mathbf{x}^T \mathbf{y} + \mathbf{y}^T \mathbf{y})}{d\mathbf{w}}$$

when you apply the derivative with respect to \mathbf{w} to the right hand side

$$0 = 2\mathbf{x}^T \mathbf{x} \mathbf{w} - 2\mathbf{x}^T \mathbf{y}$$

when you make \mathbf{w} the subject of the formula

$$\mathbf{w} = (\mathbf{x}^T \mathbf{x})^{-1} \mathbf{x}^T \mathbf{y}$$

Derivative of the L1 loss

$$\frac{dL_1(\mathbf{w})}{d\mathbf{w}} = \frac{1}{N} \times \frac{d(|\mathbf{x}\mathbf{w} - \mathbf{y}|)}{d\mathbf{w}}$$

$$\frac{dL_1(\mathbf{w})}{d\mathbf{w}} = \frac{1}{N} \times \frac{d(\mathbf{x}\mathbf{w} - \mathbf{y})}{d\mathbf{w}}$$

$$\frac{dL_1(\mathbf{w})}{d\mathbf{w}} = \frac{1}{N} \times \mathbf{x}$$

L1 loss gradient is a constant!

→ optimal \mathbf{w} cannot be obtained analytically