# CHAPTER 4 THE MEDIUM ACCESS CONTROL (MAC) SUBLAYER (介质访问子层)

- The channel allocation problem
- Multiple access protocols
- 802.3: Ethernet
- 802.11: Wireless LANs
- Data link layer switching
- 802.15: Bluetooth\*
- 802.16: Broadband wireless\*
- RFID\*

#### THE CHANNEL ALLOCATION PROBLEM

- Two types of networks:
  - ◆ Those using **point-to-point** connection.
  - ◆ Those using **broadcast** channels.
- In any broadcast network, the key issue is how to determine who gets to use the channel when there is competition for it.
  - Consider a telephone conference call.
  - ◆ Broadcast channels are sometimes referred to as multiaccess channels or random access channels.
- The protocols used to determine who goes next on a multiaccess channel belong to a *sublayer* of the data link layer called the MAC (Medium Access Control). The MAC sublayer is the bottom part of the data link layer.

#### The Channel Allocation Problem: Introduction

- 信道分配问题: How to allocate a single broadcast channel among competing users
  - Static channel allocation in LANs and MANs
    - TDM
    - FDM
  - Dynamic channel allocation in LANs and MANs
    - ALOHA
    - CSMA
    - Collision free protocols
    - Limited-contention protocols
    - • •

# The Channel Allocation Problem: **Static** channel allocation in LANs and MANs

The traditional way of allocating a single channel among multiple competing users is Frequency Division Multiplexing (FDM, 频分多路复用).

- ◆ When there is only a small and fixed number of users, each of which has a heavy (buffered) load of traffic, FDM is a simple and efficient allocation.
- ◆ When the number of senders is large and continuously varying or the traffic is bursty, FDM has some problems.

# The Channel Allocation Problem: **Static** channel allocation in LANs and MANs

- Mathematical analysis
  - Queueing model
  - $\blacksquare$  N queues  $\rightarrow$  N times worse

 Similar for other static channel allocation methods such as TDM (Time Division Multiplexing)

#### The Channel Allocation Problem:

#### **Dynamic** channel allocation in LANs and MANs

#### Five key assumptions for the channel allocation problem

- 1. Independent Traffic (独立传输). The model consists of *N* independent stations, each with a program or user that generates frames for transmission.
- 2. Single channel (单信道假设). A single channel is available for all communication.
- 3. Collision assumption (冲突假设).
- 4. Time assumption (时间假设): (a) Continuous Time.(b) Slotted Time.
- 5. Carrier assumption (载波假设): (a) Carrier Sense.(b) No Carrier Sense.

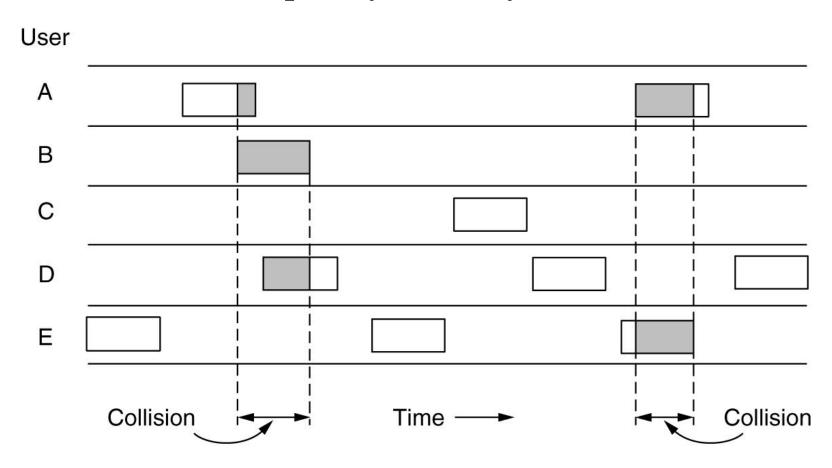
#### MULTIPLE ACCESS PROTOCOLS

- ALOHA
- Carrier Sense Multiple Access (CSMA) protocols
- Collision-free protocols
- Limited contention protocols

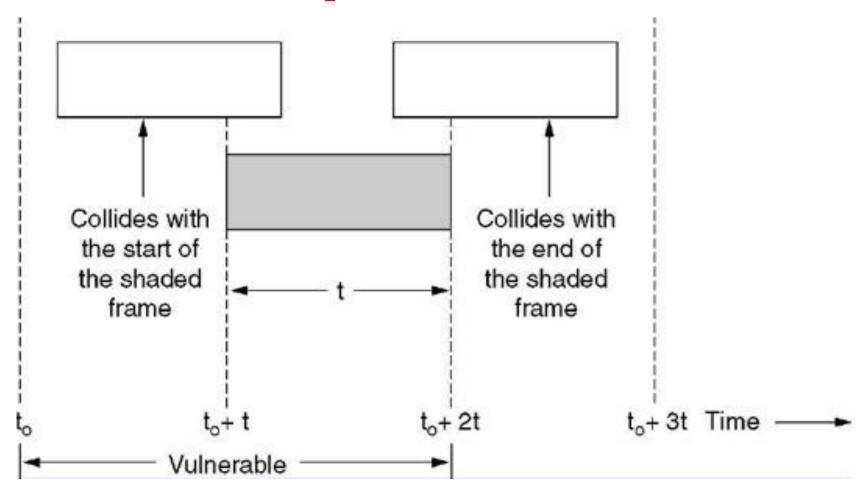
Wireless LAN Protocols

- Let users transmit whenever they have data to be sent.
  - There will be collisions and the colliding frames will be destroyed.
  - The sender just waits a random amount of time and sends it again if a frame is destroyed.

In pure ALOHA, frames are transmitted at completely arbitrary times.



Vulnerable period for the shaded frame.



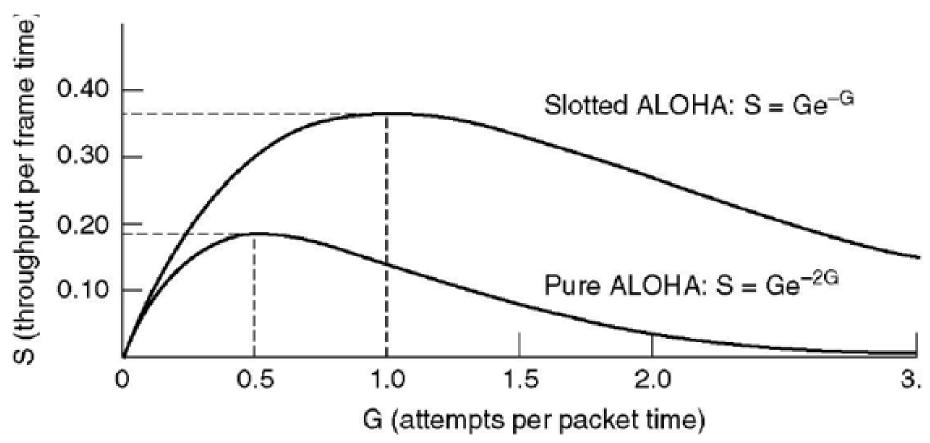
# Multiple Access Protocols: Efficiency of ALOHA

- Concepts:
  - Frame time: frame length / bit rate
  - Stations generate N (Poisson mean) new frames per frame time
  - Offered load: G (Poisson mean) transmission attempts per frame time. G includes retransmissions.
    - At low loads: G≈N
    - At high loads: G>N
  - Throughput  $S = GP_0$  where  $P_0$  is the probability that a frame does not suffer a collision.

### Multiple Access Protocols: Slotted ALOHA

- In 1972, Roberts published a method for doubling the capacity of an ALOHA system.
- **Time is slotted**. A computer is not permitted to send at any time. Instead it is required to wait for the beginning of the next slot.
- The vulnerable period is halved for Slotted ALOHA.

Throughput versus offered traffic for ALOHA systems.



### Multiple Access Protocols: Notes

- **Note**: Protocols that are perfectly valid fall into disuse for political reasons, but years later some clever person realizes that a long-discarded protocol solves his current problem.
  - → Study many protocols that are in current use.
- → Study a number of elegant protocols that are not currently in widespread use, but might easily be used in future applications.

- With stations transmitting at will, without paying attention to what the other stations are doing, there are bound to be many collisions, 不听就说→ poor channel utilization.
- If stations can detect what other stations are doing and adjust their behavior accordingly, 先听再说→ better channel utilization.
- Protocols in which stations listen for a carrier and act accordingly are called Carrier Sense Multiple Access Protocols (CSMA Protocols, 载波侦听多路访问协议).

- ■CSMA (Carrier Sense Multiple Access) without CD (Collision Detection)
  - Persistent CSMA
  - Non-persistent CSMA
  - p-persistent CSMA
- CSMA with CD

# Multiple Access Protocols: CSMA without CD: Persistent CSMA

Before sending, a station senses the channel.

- If the channel is **idle**, the station **transmits** a frame.
- If the channel is **busy**, the station **waits until** it becomes idle. Then the station transmits a frame.
- If a collision occurs, the station waits a random amount of time and starts all over again.

The protocol is called *1-persistent* because the station transmits with a probability of 1 whenever it finds the channel idle.

# Multiple Access Protocols: CSMA without CD: Persistent CSMA

#### Discussion

- This scheme seems to avoid collisions except for the rare case of simultaneous sends, but in fact it does not.
- If two stations become ready in the middle of a third station's transmission,
  - ♦ both will wait politely until the transmission ends,
  - ♦ both will then begin transmitting exactly simultaneously, resulting in a collision.
- If they were not so impatient, there would be fewer collisions.

# Multiple Access Protocols: CSMA without CD: Persistent CSMA

#### Discussion (Cont)

- propagation delay has an important effect on collisions
  - ◆ There is a chance that just after a station begins sending, another station will become ready to send and sense the channel.
  - ◆ If the first station's signal has not yet reached the second one, the latter will sense an idle channel and will also begin sending, resulting in a collision.
  - ◆ This chance depends on the number of frames that fit on the channel, or the bandwidth-delay (BD) product of the channel
    - ◆ Low BD product → small chance of collision
    - ◆ Large BD product → high chance of collision
- Better than ALOHA.

### Multiple Access Protocols: CSMA without CD: Non-persistent CSMA

- Before sending, a station senses the channel.
  - ◆ If the channel is **idle**, the station **transmits** a frame.
  - ◆ If the channel is **in use**, the station <u>does not</u> continually sense it. Instead, it **waits a random period of time** and then repeats the algorithm.
  - ◆ If a collision occurs, the station waits a random amount of time and starts all over again.
- Discussion
  - ◆ Better channel utilization than 1-persistent CSMA (less greedy)
  - ◆ Longer delays than 1-persistent CSMA

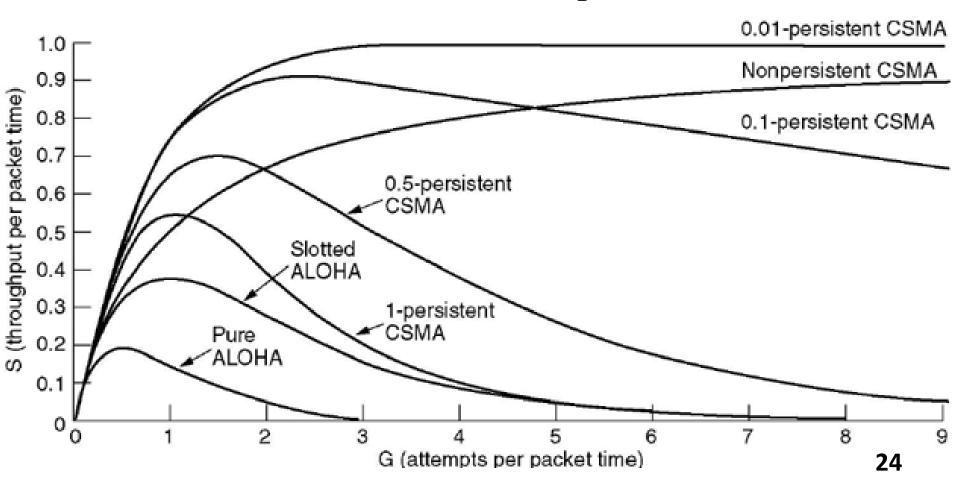
# Multiple Access Protocols: CSMA without CD: p-persistent CSMA

- Applied to slotted channels
- Before sending, a station senses the channel:
  - If the channel is **idle**, it **transmits with a probability** p. With a probability q=1-p, it defers until the next slot.
  - If that slot is also idle, it either transmits or defers again, with probabilities p and q.
  - This process is repeated until either the frame has been transmitted or another station has begun transmitting.
  - If the channel is **busy**, it **waits until the next slot** and applies the above algorithm.

IEEE 802.11 uses a refinement of p-persistent CSMA

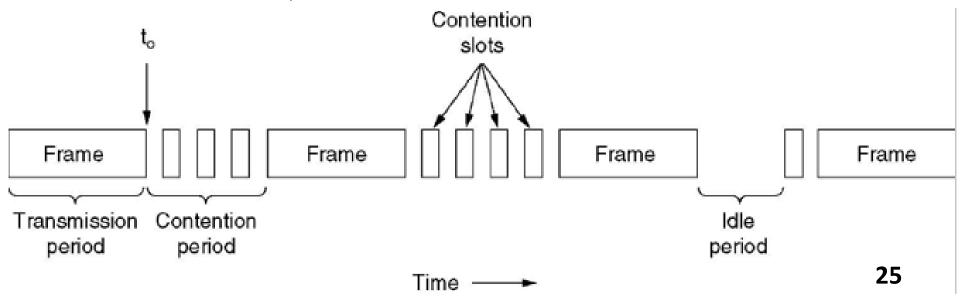
# Multiple Access Protocols: CSMA without CD: Comparison

Comparison of the channel utilization versus load for various random access protocols.



### Multiple Access Protocols: CSMA with CD

- CSMA/CD (Carrier Sense Multiple Access with Collision Detection)
  - is an improvement over CSMA without CD.
  - As soon as stations detect a collision, they stop their transmissions.
- CSMA/CD can be in one of three states: contention, transmission, or idle.

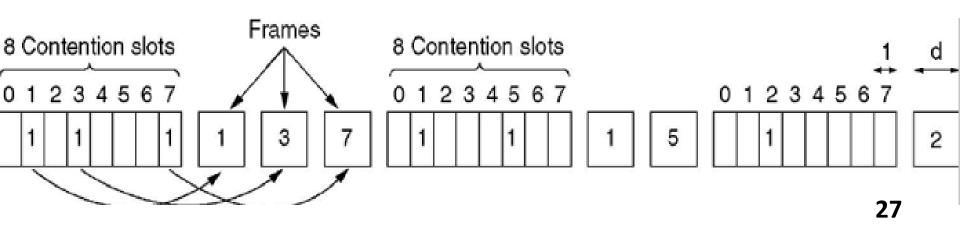


#### Multiple Access Protocols: CSMA with CD

- How long will it take to detect collisions?
  - ◆ The time for transmitting one full frame?
  - ◆ The time for transmitting from one end to the other end of the cable?
  - In the worst case, a station cannot be sure that it has seized the channel until it has transmitted for  $2\tau$  without hearing a collision. Here  $\tau$  is the time for a signal to propagate between the two farthest stations.

# Multiple Access Protocols: Collision free protocols: A Bit-Map Protocol

- Each contention period consists of exactly *N* slots.
- In general, station i inserts 1 in time slot i in order to send data.
- After all *N* slots have passed by, each station has complete knowledge of which stations wish to transmit. Then they begin transmitting in numerical order. Since everyone agrees on who goes next, there will never be any collisions.
- After the last ready station has transmitted its frame, another *N* bit contention period is begun.



#### Collision free protocols: A Bit-Map Protocol

- Notations:
  - The time unit is one contention bit
  - *N*: contention period
  - *d*: data frame length
- At low load:
  - Delay for low-numbered stations: 0.5N + 1N = 1.5N
  - $\blacksquare$  Delay for high-numbered stations: 0.5*N*
  - $\rightarrow$  The mean delay for all stations is N.
  - $\rightarrow$  The efficiency: d/(N+d).
- At high load:
  - the *N* bit contention period is distributed over *N* frames, yielding an overhead of only 1 bit per frame,
  - $\rightarrow$  the efficiency: d/(d+1).

#### Collision free protocols: Token Passing

- Token passing
  - The token represents permission to send.
  - If a station has a queued frame when it receives the token, it can send that frame before it passes the token to the next station.
  - If a station has no queued frame, it simply passes the token
- Two kinds of token passing
  - Token ring
  - Token bus

#### Collision free protocols: Token Ring

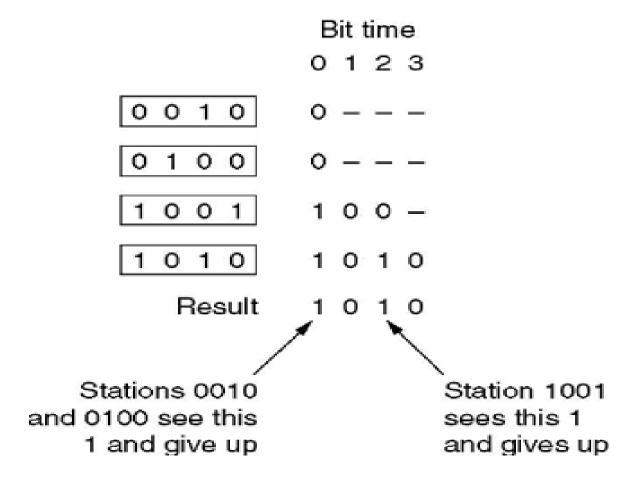
- For a *token ring* protocol, the stations are connected one to the next in a single ring.
- Passing the token to the next station then simply consists of receiving the token in from one direction and transmitting it out in the other direction.
- This way they will circulate around the ring and reach whichever station is the destination.
- Since all positions in the cycle are equivalent, there is no bias for low- or high-numbered stations.
- Examples: 802.5 (1980s), FDDI (1990s), RPR
   (Resilient Packet Ring, 802.17) (2000s), ...

#### Collision free protocols: Binary Countdown

- A station wanting to use the channel now broadcasts its address as a binary bit string, starting with the high-order bit. All addresses are assumed to be the same length.
- The bits in each address position from different stations are BOOLEAN ORed together by the channel when they are sent at the same time.
- To avoid conflicts, an arbitration rule must be applied: as soon as a station sees that a high-order bit position that is 0 in its address has been overwritten with a 1, it gives up.

Collision free protocols: Binary Countdown

The binary countdown protocol. A dash indicates silence.



#### Multiple Access Protocols: Limited-Contention protocols

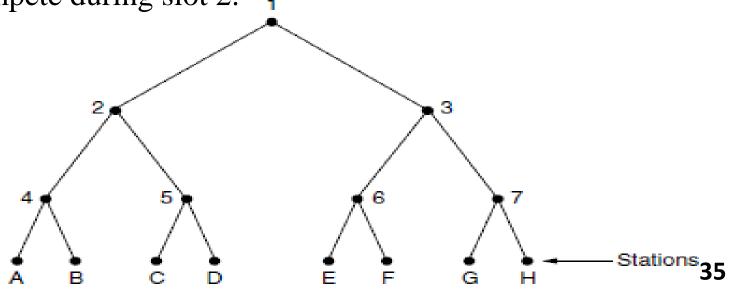
- Methods with contention
  - *Under low load*, the contention method (i.e., pure or slotted ALOHA, CSMA) is preferable due to its low delay.
  - *Under high load*, the contention method becomes increasingly less efficient.
- Methods without contention
  - Under low load, the collision-free method has high delay.
  - Under high load, the collision-free method becomes increasingly more efficient.
  - → Limited-Contention Protocols

# Multiple Access Protocols: Limited-Contention protocols

- What we need is a way to assign stations to slots dynamically
  - With many stations per slot when the load is low
  - With a few stations per slot when the load is high.
- Adaptive Tree Walk Protocol (自适应树搜索协议)

#### Multiple Access Protocols: Adaptive Tree Walk

- the stations as the leaves of a binary tree
- lack In **slot 0**, all stations are permitted to try to acquire the channel.
- ◆ If one of them does so, fine.
- ◆ If there is a **collision**, then during slot 1 only those **stations falling** under node 2 in the tree may **compete**.
- ◆ If one of them acquires the channel, the slot following the frame is reserved for stations under node 3.
- ◆ If there is **collision** under node 2 for slot 1, **stations under node 4** may compete during slot 2. ₁

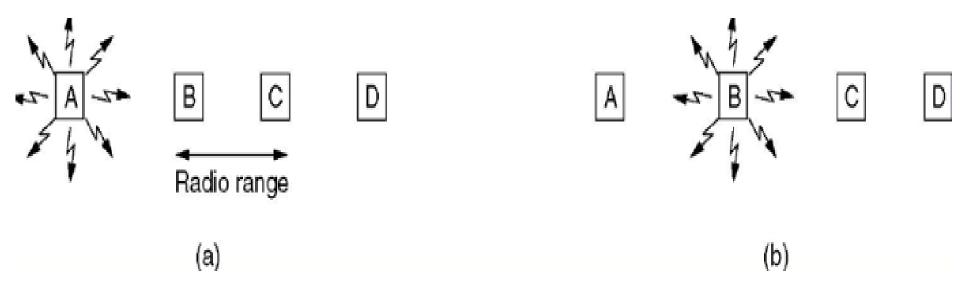


### Multiple Access Protocols: Adaptive Tree Walk

- Adaptive Tree Walk Protocol
  - ◆ At what level in the tree should the search begin?
  - ◆ The heavier the load, the farther down the tree the search should begin.
  - igoplus Begin at  $i = \log_2 q$  where q is the estimate of the number of ready stations.
  - ◆ Numerous improvements to the basic algorithm have been discovered (Bersekas and Gallager, 1992)

#### Multiple Access Protocols: Wireless LAN Protocols

- Hidden station problem (隐藏终端问题)
- Exposed station problem (暴露终端问题)



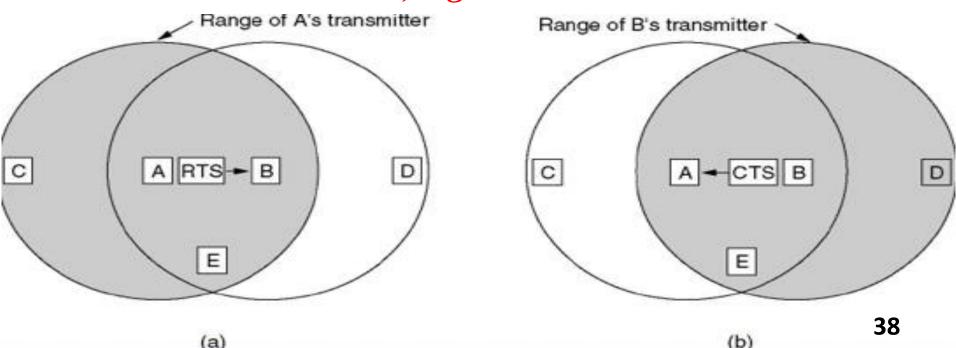
■ The problem is that **before starting a transmission**, a station really wants to know whether or not there is activity around the receiver not the sender.

#### Multiple Access Protocols: Wireless LAN Protocols

The MACA (Multiple Access with Collision Avoidance) protocol. A sending an RTS to B, B responding with a CTS to A.

- 1. D: A's hidden terminal, hear CTS and stop data
- 2. E: hear RTS and CTS, stop data
- 3. C: A's exposed terminal, hear RTS, wait until CTS, can transmit data

#### Collision can still occur, e.g. RTS



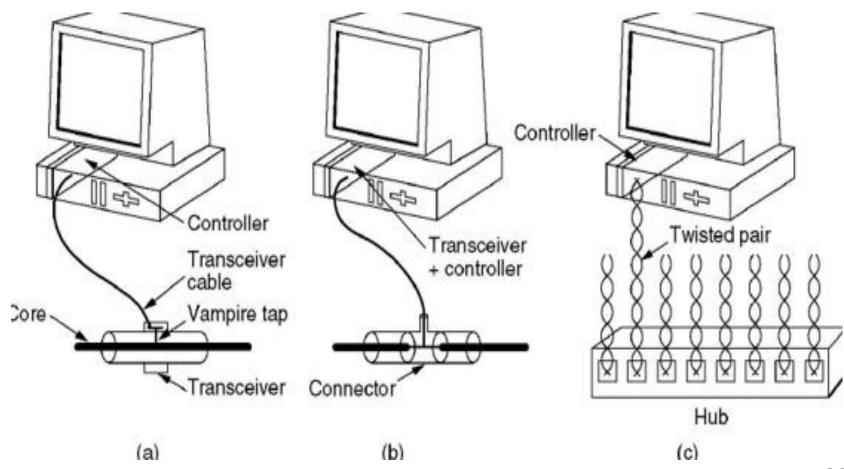
# IEEE 802.3 (Ethernet)

- Classic Ethernet Physical Layer
- Classic Ethernet MAC Sublayer Protocol
- **■** Ethernet Performance

- Switched Ethernet
- Fast Ethernet
- Gigabit Ethernet
- 10-Gigabit Ethernet
- Retrospective on Ethernet

- 197x: the real beginning was the ALOHA system constructed to allow radio communication between machines scattered over the Hawaiian Islands.
- Bob Metcalf is interested in Norman Abramson's work → after PhD graduation, Bob spend the summer in Hawaii working with Abramson (before work at Xerox PARC) → first local area network (Ethernet)
- The Ethernet was so successful. **Xerox**, **DEC**, and **Intel** drew up a standard for 10-Mbps Ethernet. (DIX standard)
- 802.3 standard describes a whole family of 1-persistent CSMA/CD system, running at speeds from 1 to 10-Mbps over various media. (802.3 standard)

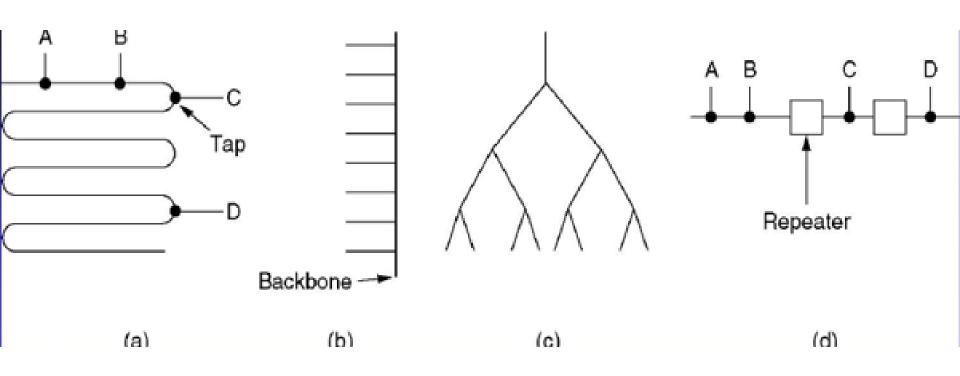
Three kinds of Ethernet cabling. (a)10Base5 (thick Ethernet), (b) 10Base2 (thin Ethernet), (c) 10Base-T.



# The most common kinds of Classic Ethernet cabling.

Name	Cable	Max. seg.	Nodes/seg.	Advantages	
10Base5	Thick coax	500 m	100	Original cable; now obsolete	
10Base2	Thin coax	185 m	30	No hub needed	
10Base-T	Twisted pair	100 m	1024	Cheapest system	
10Base-F	Fiber optics	2000 m	1024	Best between buildings	

Cable topologies.
(a) Linear, (b) Spine, (c) Tree, (d) Segmented.



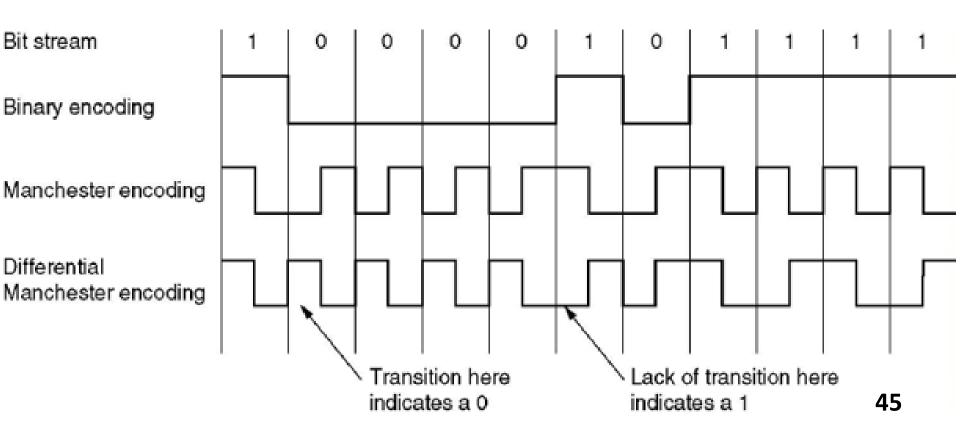
- With 0 volts for a 0 bit, with 5 volts for a 1 bit.
  - ◆ Difficult to tell the difference between an idle sender (0 volts) and a 0 bit (0 volts).
  - → If one station sends the bit string 0001000, others might falsely interpret it as 1000000 or 01000000.
- With -1 volts for a 0 bit, with 1 volts for a 1 bit
  - ◆ A receiver may sample the signal at a slightly different frequency than the sender used to generate it
  - → can be out of synchronization.
- To unambiguously determine the start, end, or middle of each bit without reference to an external clock.
  - **◆ Manchester** encoding
  - Differential Manchester encoding

Manchester encoding (used by Ethernet):

0: low-high; 1: high-low;

Differential Manchester encoding (used by Token Ring):

0: presence of transition; 1: absence of transition



Frame formats.

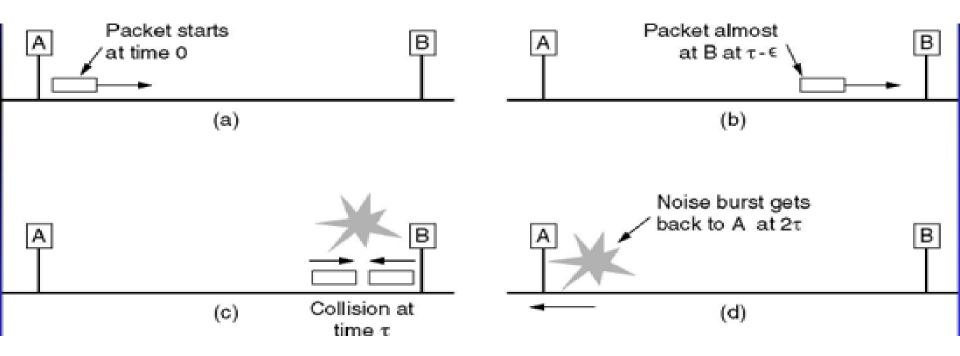
- a) DIX Ethernet,
- b) IEEE 802.3.

 $T/L \le 0x600$  (1536): length; otherwise, type

Bytes	8	6	6	2	0-1500	0-46	4
(a)	Preamble	Destination address	Source address	Туре	Data	Pad	Check- sum
					······································		
(b)	Preamble S F	Destination address	Source address	Length	Data ((	Pad	Check- sum

- Preamble: 8 bytes, containing the bit pattern 10101010, used for synchronization
- Destination address and source address: 6 bytes each
  - Unicast address
  - Broadcast address
  - Multicast address
- Type field or length field
- Data: 1500 bytes (maximum), 46 bytes (minimum)
- Checksum: 32 bits, CRC

How long does it take to find out whether there is a collision or not?



Collision detection can take as long as 2\tau.

- $\blacksquare$  All frames must take more than  $2\tau$  to send.
  - Too quick (to miss the collision)
  - Longer than  $2\tau$  to be sure of success.
- For a 10-Mbps LAN with a maximum length of 2500 meters and four repeaters, the maximum RTT is about 50us.

```
Min frame length = 50us * 10 Mbps
=50*10^{-6} s * 10*10^{6} bits/s = 500 bits ≈ 64 B
```

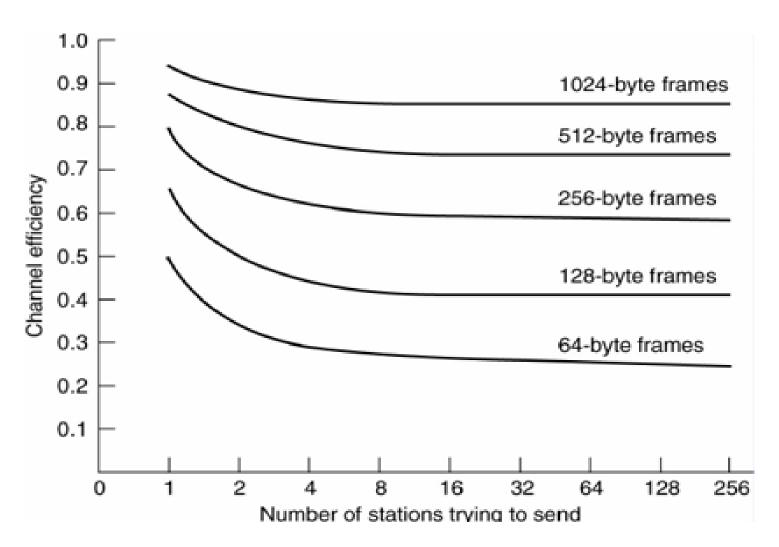
Min payload length = 64-18 (src:6,dest:6,type:2,crc:4) =  $46 \text{ B} (\rightarrow)$  Why min payload = 46 D

#### The Binary Exponential Backoff Algorithm

- Time is divided into discrete slots (51.2us).
- After the *1st* collision, each station waits either 0 or 1  $(k \text{ in } 0 \sim 2^1 1)$  slot times before trying again.
- After the 2nd collision, each station picks either 0,1,2,3  $(k \text{ in } 0\sim2^2\text{-}1)$  at random and waits that number of slot times.
- After *i*-th collisions, each station picks either 0,1,2,...,  $2^{i}-1$  at random and waits that number of slot times.
- After 10th collisions, the randomization interval is frozen at a maximum of 1023 slots.
- After 16 consecutive collisions, the controller reports failure back to the computer.
  - → limited contention.

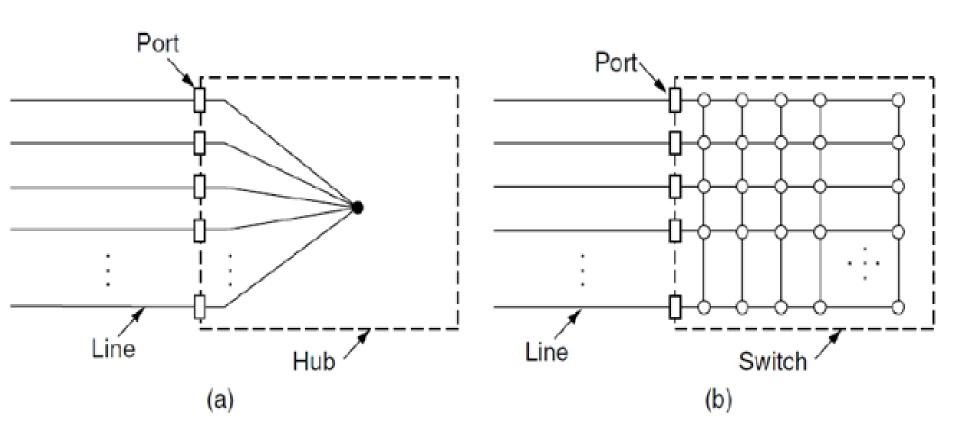
#### 802.3: Performance

Efficiency of Ethernet at 10 Mbps with 512-bit slot times.



## 802.3: Switched Ethernet

#### Hub → Switch



#### 802.3: Switched Ethernet

- Switch: The heart of this system is a switch containing a high-speed backplane that connects all of the ports
- Switch outputs frames to the ports for which those frames are destined. None of the other ports even knows the frame exists.
- What happens if more than one of the ports wants to send a frame at the same time?
  - Can send a frame on the cable at the same time
  - Why? Each port → one collision domain, whereas all stations attached to a hub → one collision domain

# 802.3: Fast Ethernet (100-Mbps)

- FDDI and Fiber Channel
  - ◆ Haven't done KISS (Keep It Simple, Stupid)
- IEEE 802
  - $\rightarrow$  IEEE 802.3u or Fast Ethernet (1992~1995)
  - ◆ → IEEE 802.3z or gigabit Ethernet (1995~1998)

#### The original fast Ethernet cabling.

Name	Cable	Max. segment	Advantages
100Base-T4	Twisted pair	100 m	Uses category 3 UTP
100Base-TX	Twisted pair	100 m	Full duplex at 100 Mbps
100Base-FX	Fiber optics	2000 m	Full duplex at 100 Mbps; long runs

# 802.3: Gigabit Ethernet (1-Gbps)

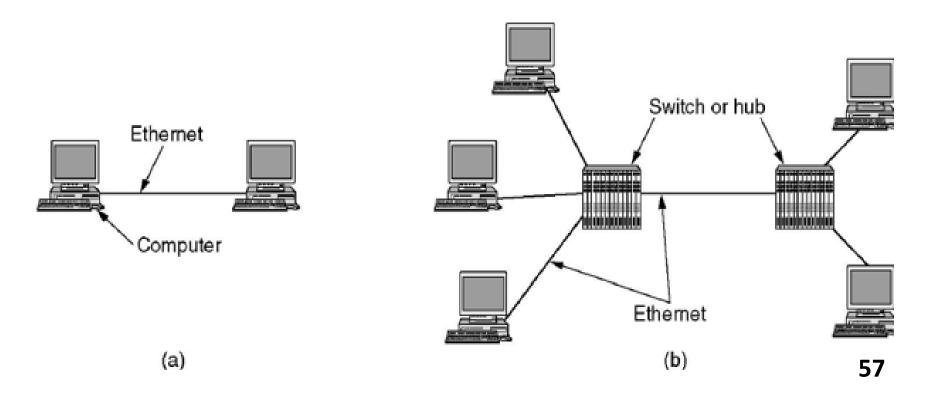
#### Gigabit Ethernet cabling.

Name	Cable	Max. segment	Advantages
1000Base-SX	Fiber optics	550 m	Multimode fiber (50, 62.5 microns)
1000Base-LX	Fiber optics	5000 m	Single (10 μ) or multimode (50, 62.5 μ)
1000Base-CX	2 Pairs of STP	25 m	Shielded twisted pair
1000Base-T	4 Pairs of UTP	100 m	Standard category 5 UTP

# 802.3: Gigabit Ethernet (1-Gbps)

#### Possible connections:

- a. A two-station Ethernet.
- b. A multistation Ethernet.



# 802.3: 10-Gigabit Ethernet

#### 10-Gigabit Ethernet cabling.

Name	Cable	Max. segment	Advantages
10GBase-SR	Fiber optics	Up to 300 m	Multimode fiber (0.85µ)
10GBase-LR	Fiber optics	10 km	Single-mode fiber (1.3 $\mu$ )
10GBase-ER	Fiber optics	40 km	Single-mode fiber (1.5 $\mu$ )
10GBase-CX4	4 Pairs of twinax	15 m	Twinaxial copper
10GBase-T	4 Pairs of UTP	100 m	Category 6a UTP

#### 802.3: Comments

- Ethernet has been around for over 20 years
- Simple and flexible
  - ◆ Cheap
  - ♦ Easy to maintain
  - ◆ Ethernet works easily with TCP/IP
- There are 3 LAN standards:
  - ◆ 802.3 (Ethernet),
  - ◆ 802.4 (Token bus),
  - ◆ 802.5 (Token ring).
- They use roughly similar technology and get roughly similar performance.
  59

#### 802.3: Comments

#### **802.3** (Ethernet):

- most widely used, simple, easy installation, low delay at low load.
- nondeterministic, no priorities, 64 byte minimum frame, collision problem

#### 802.4 (Token bus(令牌总线))

- more deterministic, short minimum frames, priorities, real-time, multiple channels.
- a lot of analog engineering and including modems and wideband amplifiers, extremely complex protocol, substantial delay at low load, poorly suited for fiber optic implementations and a small installed base of users.

#### 802.5 (Token Ring(令牌环))

- Easy engineering, fully digital, priorities, excellent throughput and efficiency at high load.
- centralized monitor, delay at low load.
- $\rightarrow$  the winner is 802.3.