# OS Review 3

Chapter 10 - 13

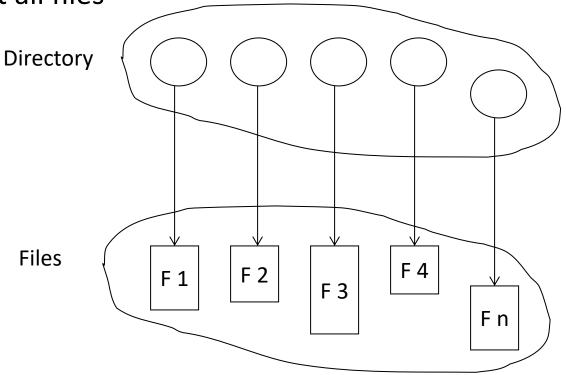
# Chapter 10: basic of file

- What is a file?
  - Contiguous logical address space
  - A sequence of bits, bytes, lines, or records. The meaning is defined by the creator and user.

sequential access	implementation for direct access		
reset	cp = 0;		
read next	read cp; $cp = cp + 1$ ;		
write next	write $cp$ ; $cp = cp + 1$ ;		

### Directory Structure

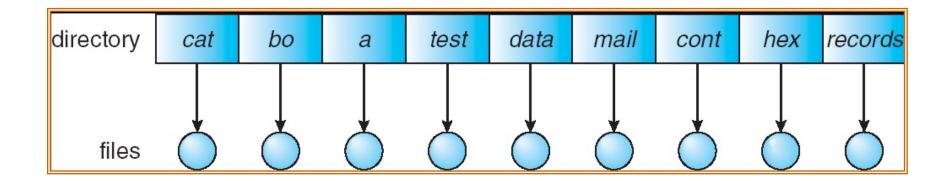
 A collection of nodes containing (management) information about all files



Both the directory structure and the files reside on disk Backups of these two structures are kept on tapes

# Single-Level Directory

A single directory for all users

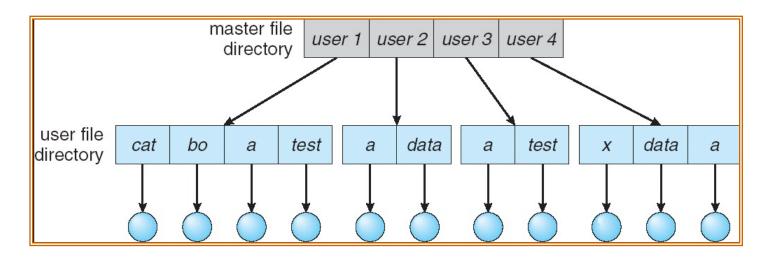


Naming problem

Grouping problem

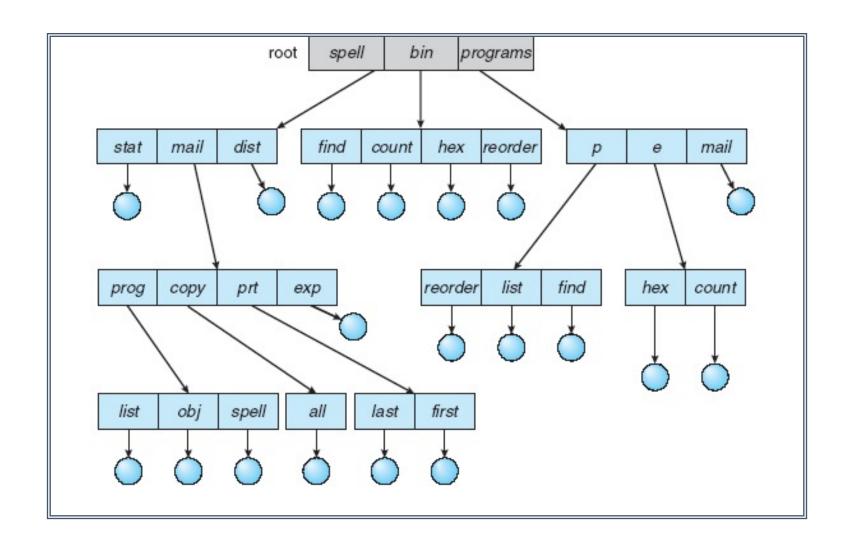
# Two-Level Directory

Separate directory for each user



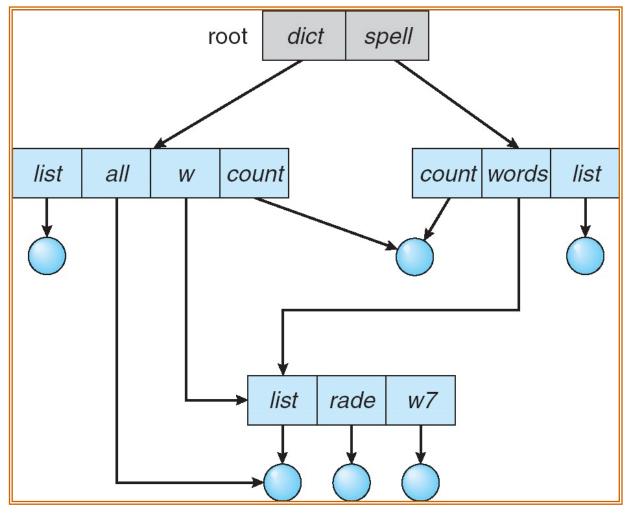
- Path name
- Can have the same file name for different user
- Efficient searching
- No grouping capability

#### Tree-Structured Directories

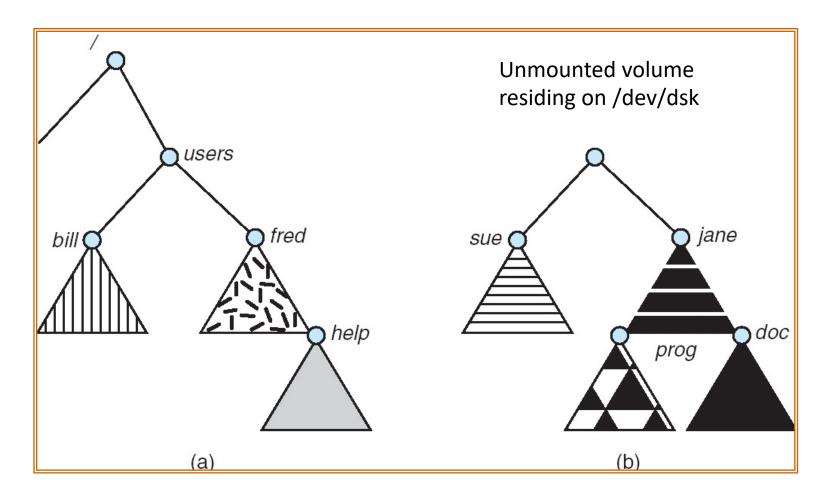


# Acyclic-Graph Directories

- Requirement for file sharing
- Have shared subdirectories and files

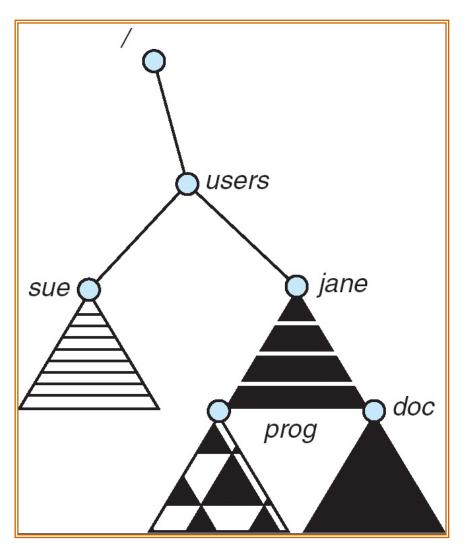


### Mount



#### Mount Point

\$ mount /dev/dsk /users

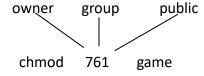


### Access Lists and Groups

- Mode of access: read, write, execute
- Three classes of users

			RWX
a) <b>owner access</b>	7	$\Rightarrow$	111
			RWX
b) group access	6	$\Rightarrow$	110
			RWX
c) public access	1	$\Rightarrow$	001

- Ask manager to create a group (unique name), say G, and add some users to the group.
- For a particular file (say *game*) or subdirectory, define an appropriate access.



Attach a group to a file

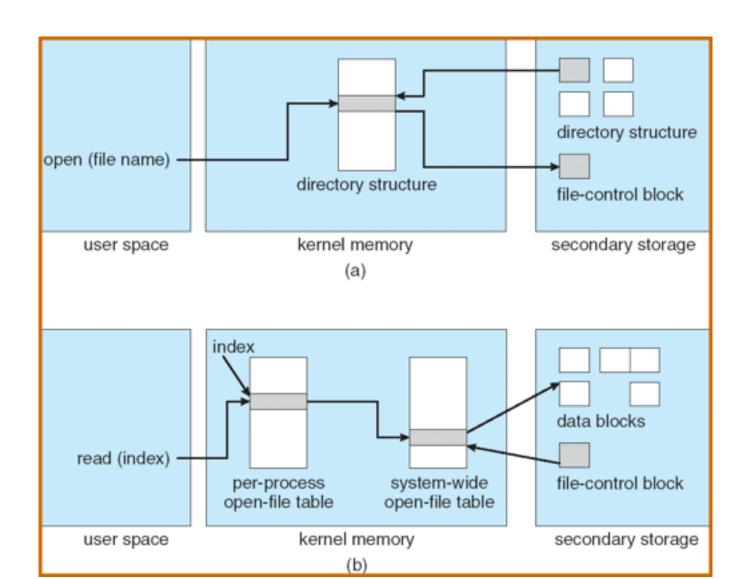
chgrp G game

### Chapter 11: File System Implementation

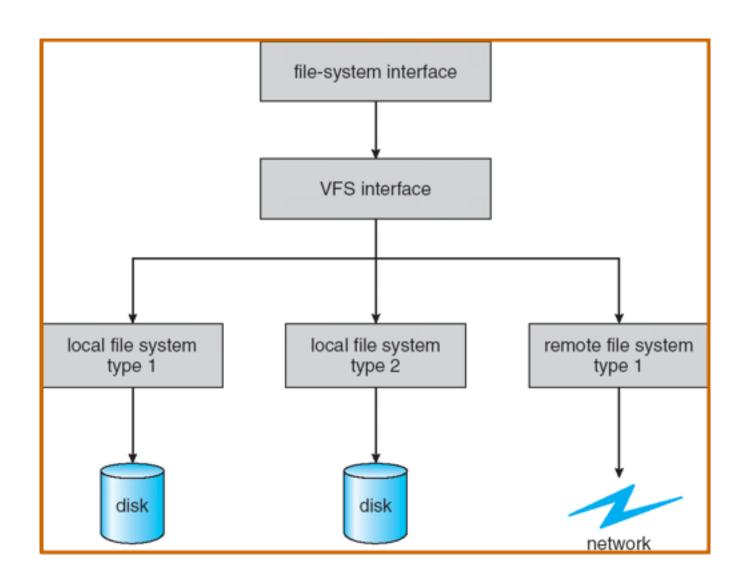
#### Data structures

- Disk structures
  - Boot control block
  - Volume control block
  - Directory structure per file system
  - Per-file FCB (inode in UFS, master file table entry in NTFS)
- In-memory structures
  - In-memory mount table about each mounted volume
  - Directory cache
  - System-wide open-file table
  - Per-process open-file table

### In-Memory File System Structures



# Semantic of Virtual File System



#### **Allocation Methods**

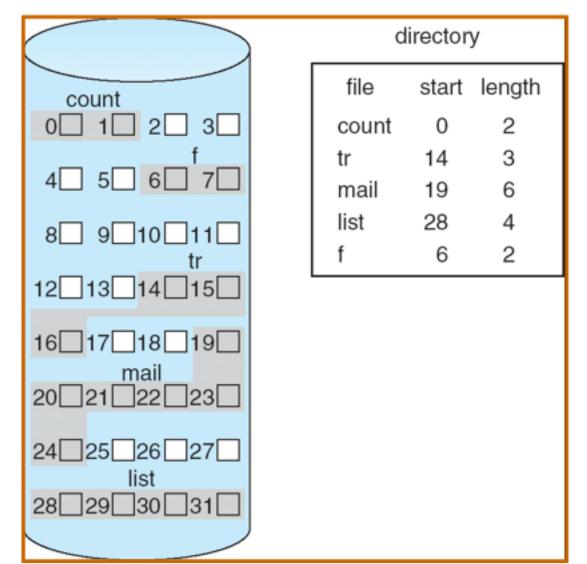
 An allocation method refers to how disk blocks are allocated for files:

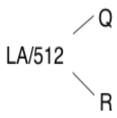
Contiguous allocation

Linked allocation

Indexed allocation

## Contiguous Allocation

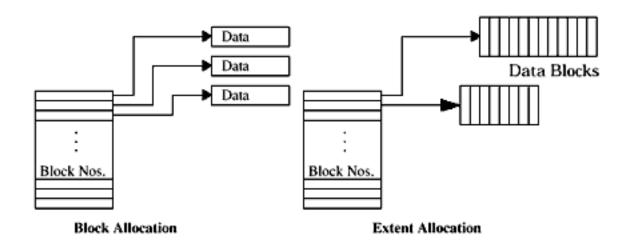




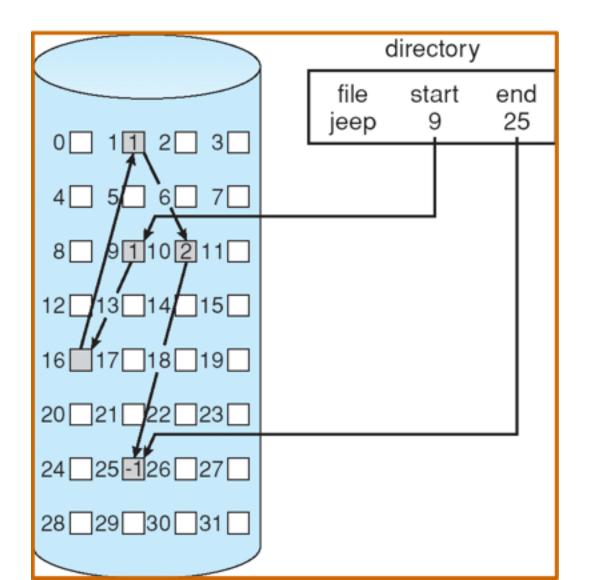
Block to be accessed = Q + start\_address Displacement into block = R

#### Extent-based Allocation

- Extent-based file systems allocate disk blocks in extents
- An extent is a contiguous block of disks
  - Extents are allocated for file allocation
  - A file consists of one or more extents.



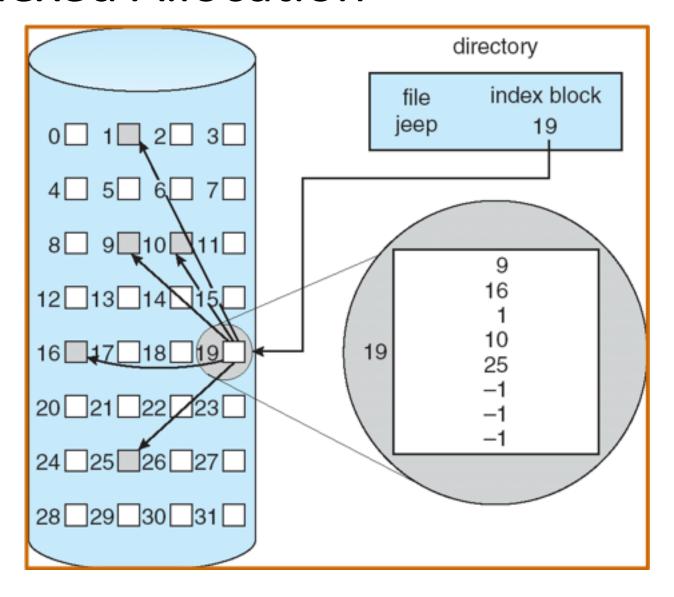
### Linked Allocation



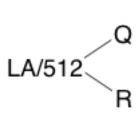
#### Linked Allocation

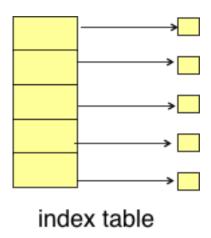
- Simple need only starting address
- Free-space management system no waste of space
- No random access, poor reliability
- Mapping

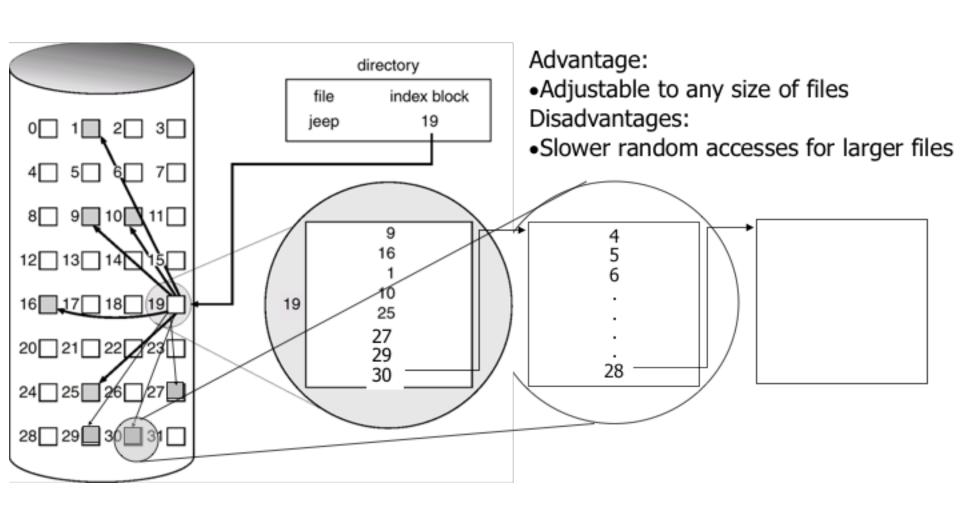




- Need index table (analogous to page table)
- Random access
- Dynamic access without external fragmentation, but have overhead of index block.
- When mapping from logical to physical in a file of maximum size of 256K words and block size of 512 words (512=2^9, 2^9 \* 2^9 = 2^18, 2^18 / 1024 = 256). We need only 1 block for index table.





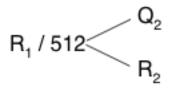


- When mapping from logical to physical in a file of unbounded length (block size of 512 words). – more pointers are needed
- Linked scheme Link blocks of index table (no limit on size).

LA / (512 x 511) 
$$< \frac{Q_1}{R_1}$$

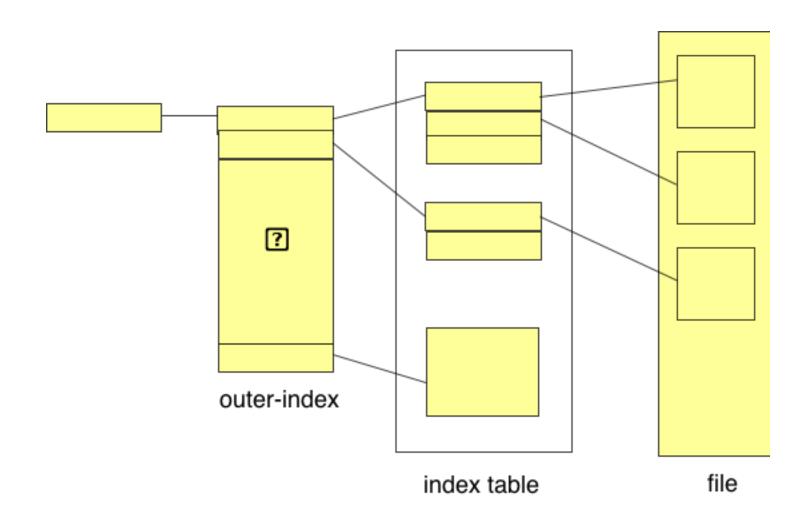
 $Q_1$  = block of index table

 $R_1$  is used as follows:



 $Q_2$  = displacement into block of index table  $R_2$  displacement into block of file:

### Two-level Indexed Allocation



#### Two-level Indexed Allocation

• Two-level index (maximum file size is 512<sup>3</sup>)

LA / (512 x 512) 
$$< \frac{Q_1}{R_1}$$

 $Q_1$  = displacement into outer-index

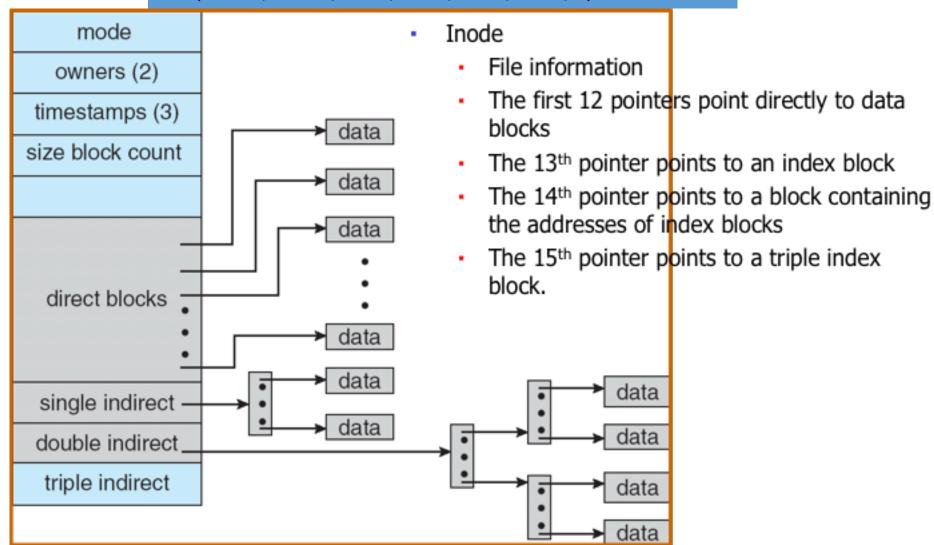
 $R_1$  is used as follows:

$$R_1 / 512 < Q_2 R_2$$

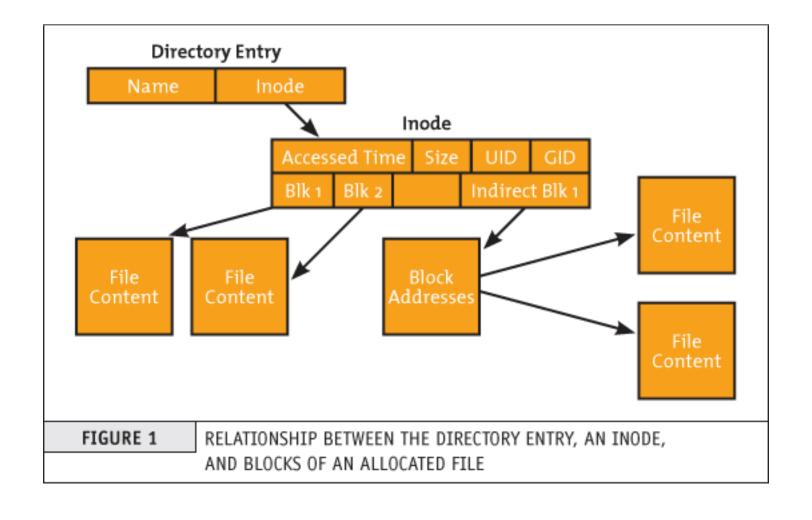
 $Q_2$  = displacement into block of index table  $R_2$  displacement into block of file:

#### Unix Disk Allocation

4K\*(12+4K/4 + 4K/4\*4K/4+4K/4\*4K/4\*4K/4)>4T

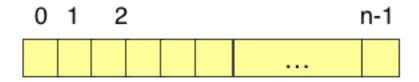


# Dentry and Inode



### Free-Space Management

• Bit vector (*n* blocks)



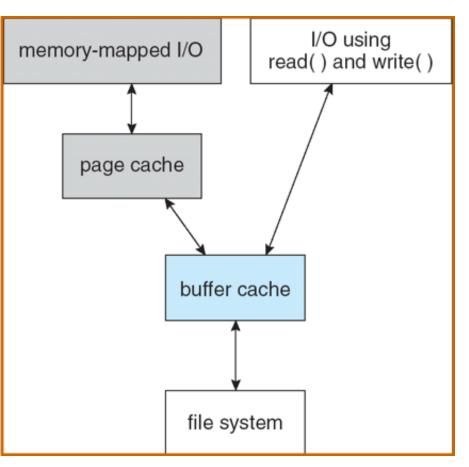
$$bit[i] = 0 \Rightarrow block[i] \text{ free}$$

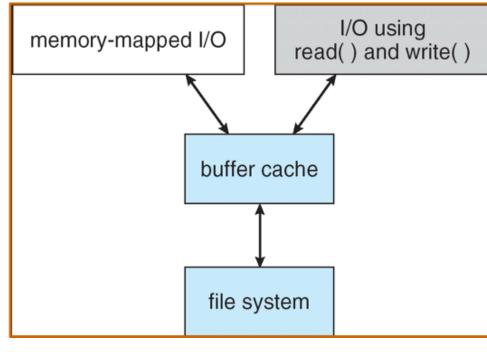
$$0 \Rightarrow block[i] \text{ occupied}$$

Block number calculation (finding the first free block)

(number of bits per word) \* (number of 0-value words) + offset of first 1 bit Bit map requires extra space block size =  $2^{12}$  bytes disk size =  $2^{30}$  bytes (1 gigabyte)  $n = 2^{30}/2^{12} = 2^{18}$  bits (or 32K bytes)

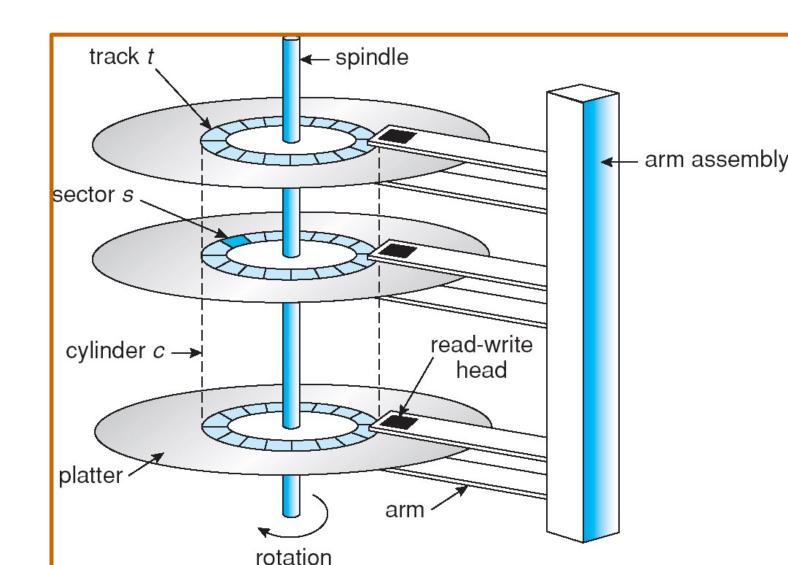
# Block/Page Buffer



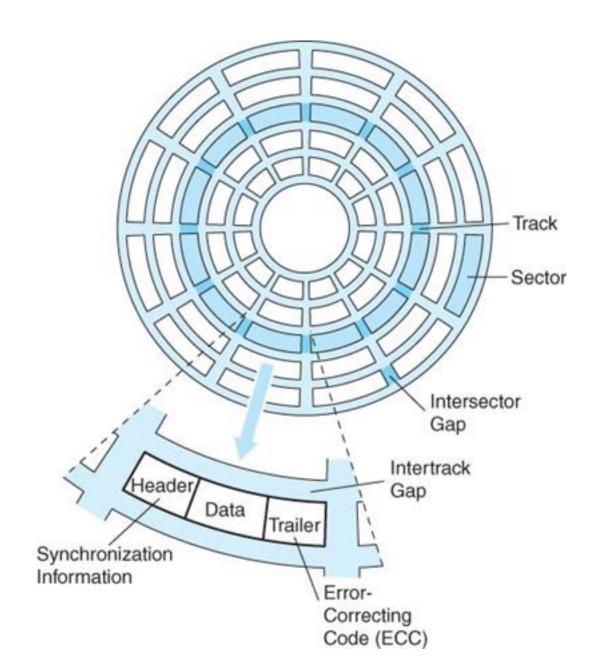


# Chapter 12: Mass Storage System

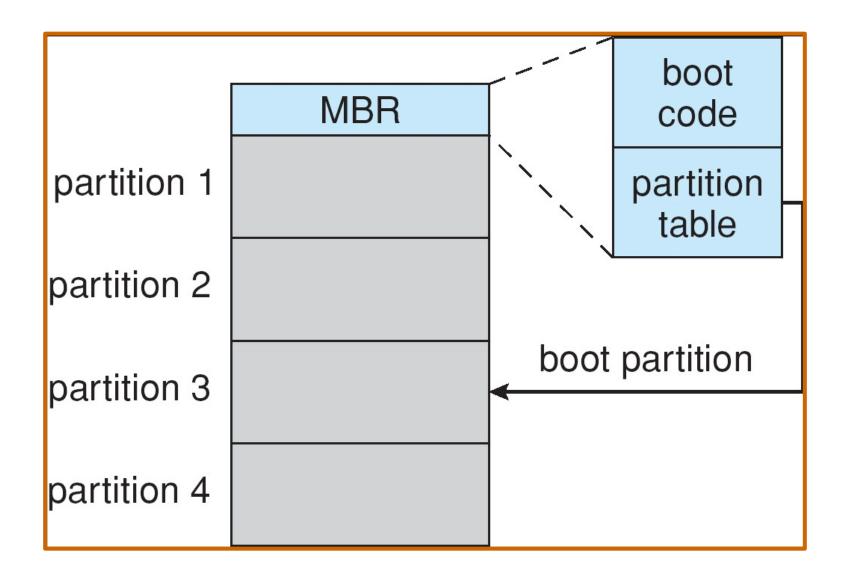
Disk



### Disk Sector



#### **MBR**



#### **Access Cost**

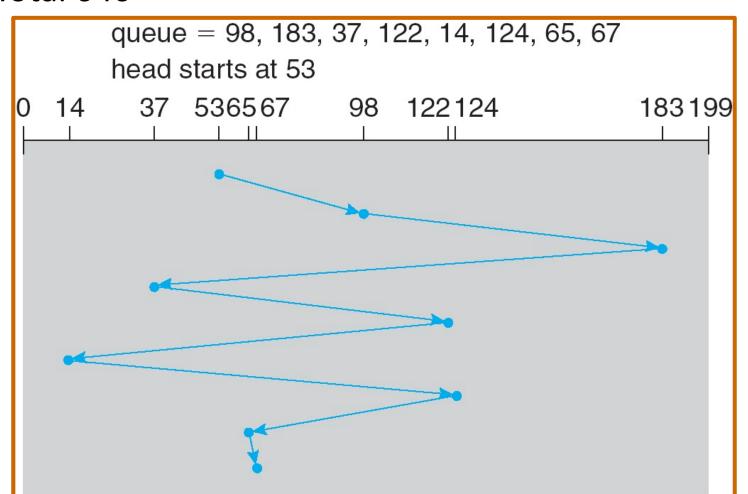
- Time to access (read/write) a disk block:
  - seek time (moving arms to position disk head on track)
  - rotational delay (waiting for block to rotate under head)
  - transfer time (actually moving data to/from disk surface)
- Seek time and rotational delay dominate.
  - Seek time varies from about 1 to 20msec
  - Rotational delay varies from 0 to 10msec
  - As of 2010, a typical 7200 RPM desktop HDD has a "diskto-buffer" data transfer rate up to 1030 Mbit/s
  - Key to lower I/O cost: reduce seek/rotation delays!
     Hardware vs. software solutions?

### Disk Scheduling

- The operating system is responsible for using hardware efficiently — for the disk drives, this means having a fast access time and disk bandwidth.
- Access time has two major components
  - Seek time is the time for the disk are to move the heads to the cylinder containing the desired sector.
  - Rotational latency is the additional time waiting for the disk to rotate the desired sector to the disk head.
- Minimize seek time
- Metric: Seek time ≈ seek distance
- Disk bandwidth is the total number of bytes transferred, divided by the total time between the first request for service and the completion of the last transfer.

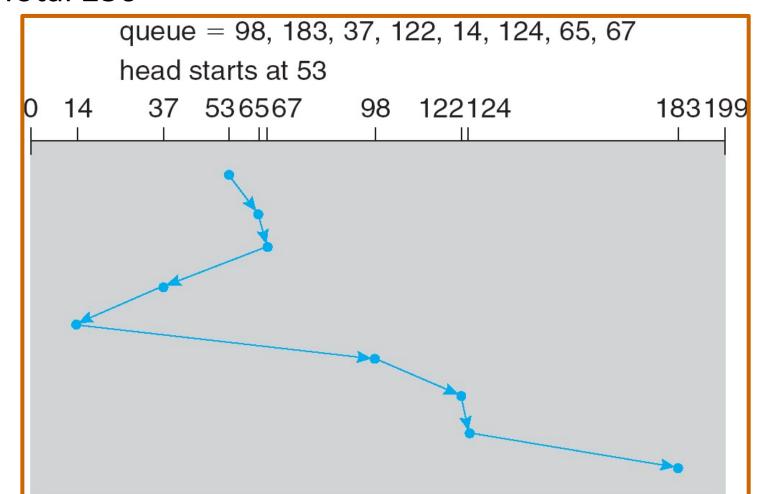
#### **FCFS**

#### • Total 640



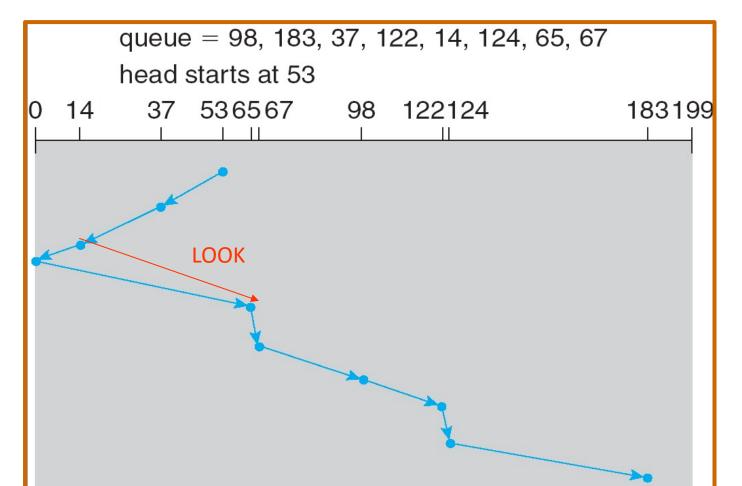
# Shortest-seek-time-first (SSTF)

#### • Total 236

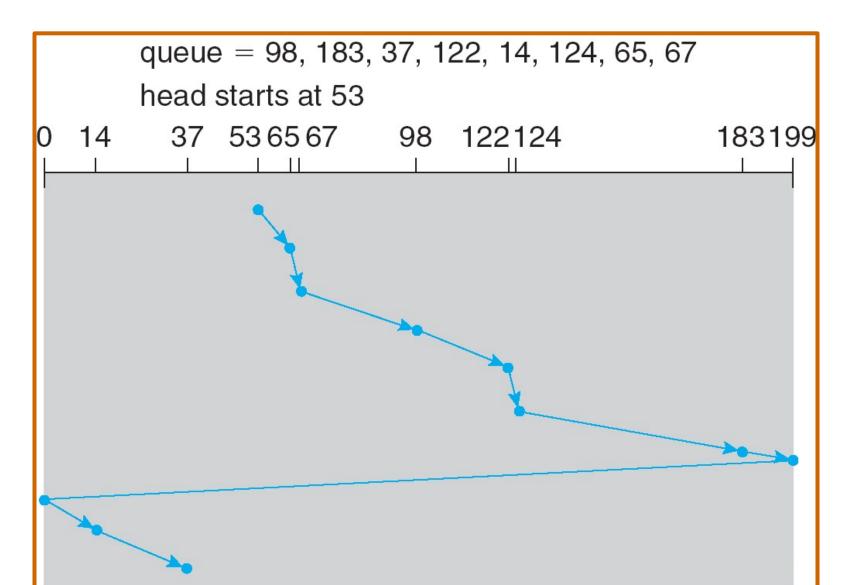


# SCAN (elevator) Algorithm

Total 208 (with look)



## C-SCAN (with look)



#### Raid (redundant arrays of inexpensive disks)

- Disk striping uses a group of disks as one storage unit.
  - Bit-level Striping
  - Block-level Striping different blocks of a file are striped

Disk 1	Disk 2	Disk 3	Disk 4
File 1, byte 1	File 1, byte 2	File 1, byte 3	File 1, byte 4
File 1, byte 5	File 1, byte 6	File 1, byte 7	File 2, byte 1
File 2, byte 2	File 3, byte 1	File 3, byte 2	File 4 byte 1
File 4, byte 2	File 4, byte 3	And so on	

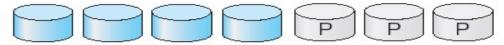
### Raid 0-6



(a) RAID 0: non-redundant striping.



(b) RAID 1: mirrored disks.



(c) RAID 2: memory-style error-correcting codes.



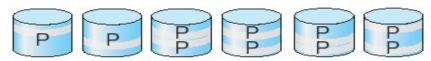
(d) RAID 3: bit-interleaved parity.



(e) RAID 4: block-interleaved parity.

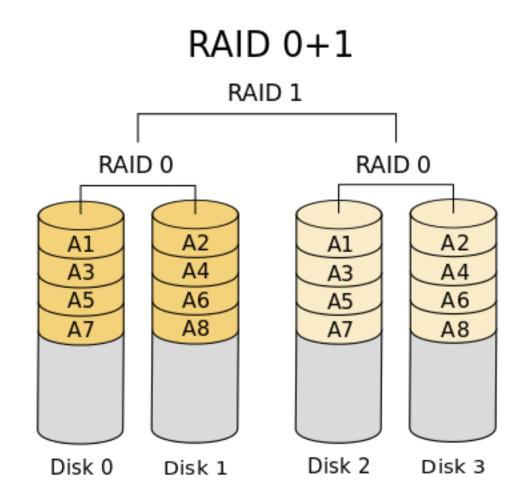


(f) RAID 5: block-interleaved distributed parity.



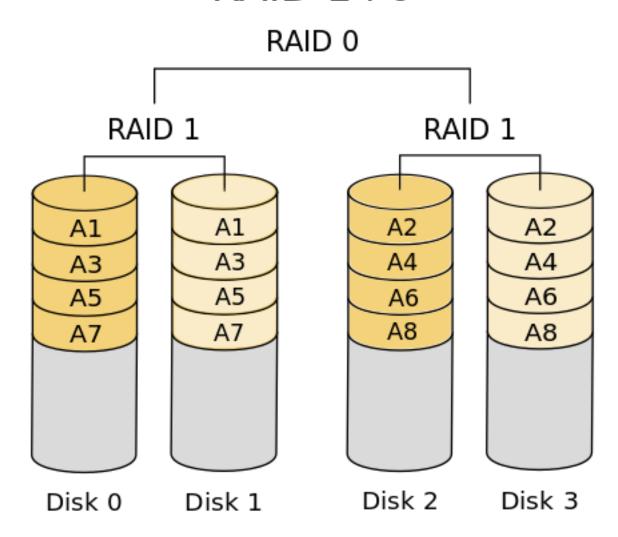
(g) RAID 6: P + Q redundancy.

### Raid 0+1

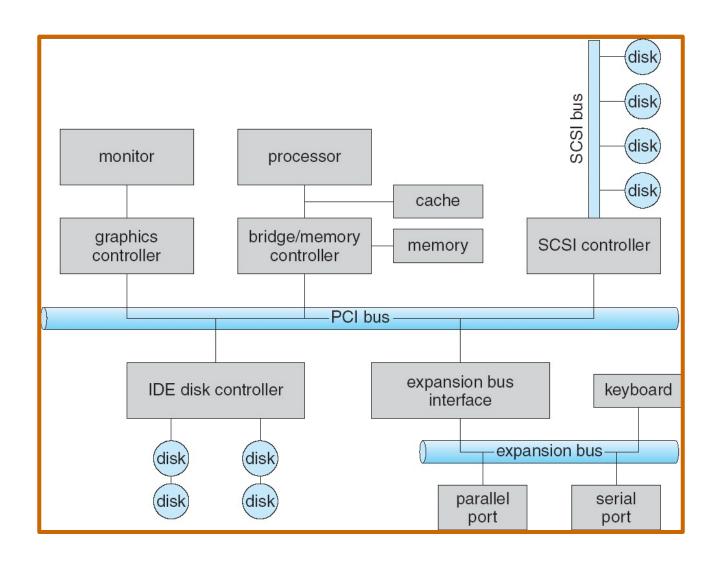


### Raid 1+0

#### **RAID 1+0**



## Chapter 13: I/O Systems



### **Device Ports**

I/O address range (hexadecimal)	device
000-00F	DMA controller
020–021	interrupt controller
040–043	timer
200–20F	game controller
2F8–2FF	serial port (secondary)
320–32F	hard-disk controller
378–37F	parallel port
3D0-3DF	graphics controller
3F0-3F7	diskette-drive controller
3F8-3FF	serial port (primary)

## I/O Port Register

- Data-in: read by the host to get input
- Data-out: written by the host to send output
- Status: device status read by the host
- Control: written by the host to start a command or change the mode of a device

## Old Style : Polling

- (Refer to textbook p.499 )Determines state of device
  - command-ready
  - busy
  - Error
- Busy-wait cycle to wait for I/O from device

Repeatedly reading the **status** register until the busy bit becomes clear.

Inefficient!!

### New Style: Interruption

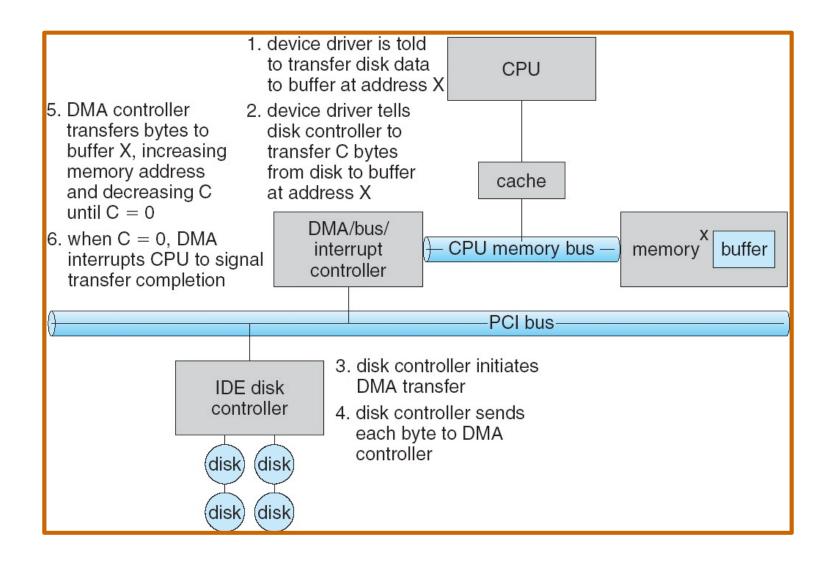
- CPU Interrupt-request line triggered by I/O device
- Interrupt handler receives interrupts
- Maskable to ignore or delay some interrupts
- Interrupt vector to dispatch interrupt to correct handler
  - Based on priority
  - Some nonmaskable
- Interrupt mechanism also used for exceptions

## Signal and Interrupt

 Signals are standardized messages sent to a running <u>program</u> to trigger specific behavior, such as quitting or error handling. They are a limited form of <u>inter-process communication</u> (IPC)

SIGINT	2	Interrupt a process (used by Ctrl-C)	
SIGHUP	1	Hang up or shut down and restart process	
SIGKILL	9	Kill the process (cannot be ignored or caught elsewhere)	
SIGTERM	15	Terminate signal, (can be ignored or caught)	
SIGTSTP	20	Stop the terminal (used by Ctrl-z)	
SIGSTOP	19	Stop execution (cannot be caught or ignored)	

## Direct Memory Access



#### DMA Cache Problem

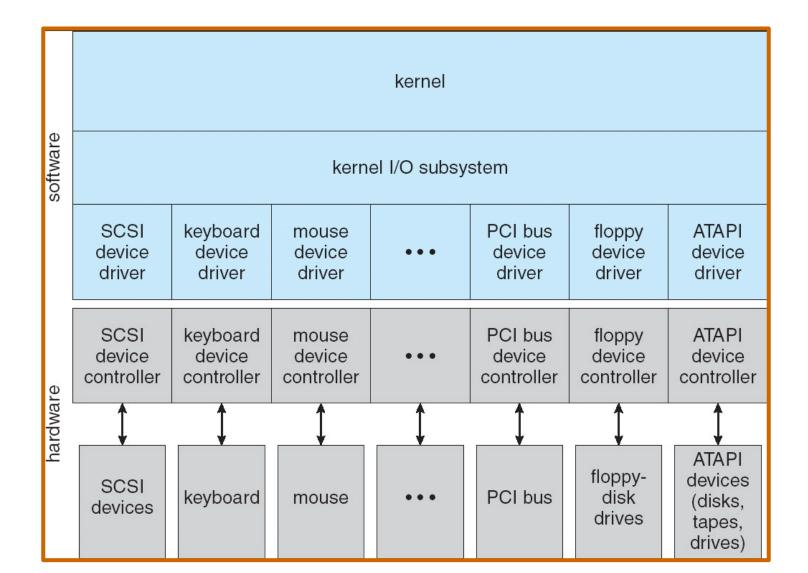
 DMA updates a value in memory which has been modified by CPU in cache



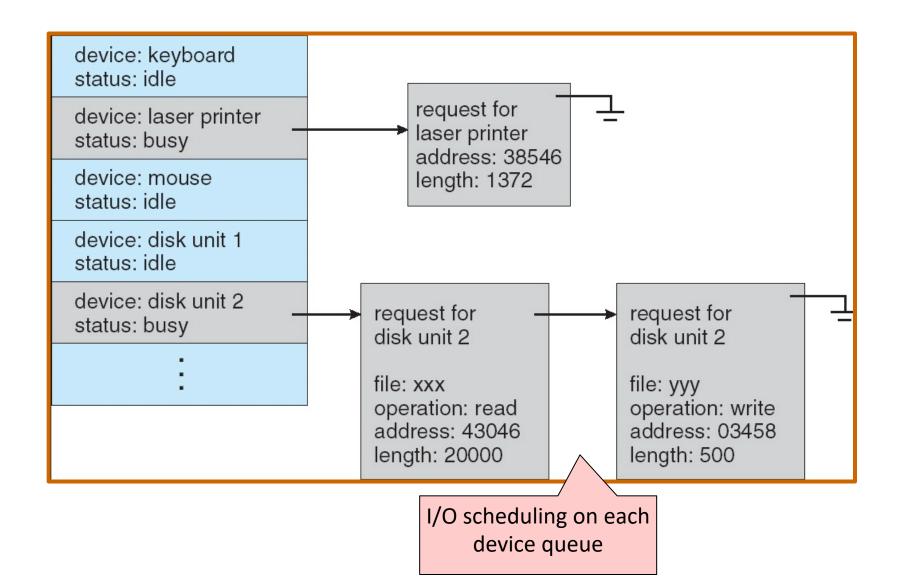
## Types of I/O Devices

aspect	variation	example
data-transfer mode	character block	terminal disk
access method	sequential random	modem CD-ROM
transfer schedule	synchronous asynchronous	tape keyboard
sharing	dedicated sharable	tape keyboard
device speed	latency seek time transfer rate delay between operations	
I/O direction	read only write only read–write	CD-ROM graphics controller disk

#### **Device Drivers**



### Device Status Table



# I/O Mode

	Blocking	Non-blocking
Synchronous	Read/write	Read/wirte (O_NONBLOCK)
Asynchronous	i/O multiplexing (select/poll)	AIO

### Examination Info

- 40 Selections
- 5 fill-in
- 1 mem + 1 scheduling + 1 synchronization