

Q4

6.1.1)

$$T_1 \left( \begin{bmatrix} x \\ y \end{bmatrix} \right) = \begin{bmatrix} 2x+y \\ x-2y \\ -x-y \end{bmatrix} = x \begin{bmatrix} 2 \\ 1 \\ -1 \end{bmatrix} + y \begin{bmatrix} 1 \\ -2 \\ -1 \end{bmatrix} \quad A = \begin{bmatrix} 2 & 1 \\ 1 & -2 \\ -1 & -1 \end{bmatrix} \text{ linear } \checkmark$$

$$T_2 \left( \begin{bmatrix} x \\ y \\ z \end{bmatrix} \right) = \begin{bmatrix} x+y^2 \\ (x+y)z \\ 0 \end{bmatrix} \quad u+v = (0, 20), T_2(u+v) = (0+4, 0+2 \cdot 0, 0) = (4, 0, 0) \\ T_2(u) = (1, 0, 0), T_2(v) = (1, 0, 0) \quad T_2(u) + T_2(v) = (2, 0, 0) \\ \underline{\text{Not Linear}}$$

$$T_3 \left( \begin{bmatrix} x \\ y \\ z \end{bmatrix} \right) = \begin{bmatrix} 0 \\ 0 \\ 0 \end{bmatrix} \quad T_3(u+v) = 0+0+0 = T_3(u) + T_3(v) \quad \underline{\text{Linear}}$$

$T_1$  = linear  $T_3$  = linear  $T_2$  = not linear

6.2.1) a)

$$(T(v))_{ik} = \begin{cases} v_{ik} & \text{if } k \neq j \\ bv_i & \text{if } k=j \end{cases}$$

$$\text{For } k \neq j, (T(u+v))_{ik} = u_{ik} + v_{ik} = (T(u))_{ik} + (T(v))_{ik}$$

$$\text{For } k=j, (T(u+v))_{ij} = b(u_j + v_j) = bu_j + bv_j = (T(u))_{ij} + (T(v))_{ij}$$

$T$  is linear

$$A = I + (b-1)e_j e_j^\top \quad A = \begin{bmatrix} 1 & 0 & 0 \\ 0 & b & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

b)

$$\text{For } k \neq i, T(u+v)_k = u_{ik} + v_{ik} = T(u)_k + T(v)_k$$

$$\text{For } k=i, T(u+v)_i = (u_i + v_i) + b(u_j + v_j) = (u_i + bu_j) + (v_i + bv_j) = T(u)_i + T(v)_i$$

$T$  is linear

$$A = I + be_i e_i^\top$$

$$A = \begin{bmatrix} 1 & 0 & 0 \\ b & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

c)  $T(v)_k = v_k$  if  $k \neq i, j$ ,  $T(v)_i = v_j$ ,  $T(v)_j = v_i$

$$A_{kl} = \begin{cases} d_{kl} & \text{if } l \neq i, j \\ 1 & \text{if } (k,l) = (i,j) \text{ or } (k,l) = (j,i) \\ 0 & \text{if } (k,l) = (i,i) \text{ or } (j,j) \text{ when swapped} \end{cases}$$

$$A = \begin{bmatrix} 0 & 0 & 1 \\ 0 & 1 & 0 \\ 1 & 0 & 0 \end{bmatrix} \quad Ae_i = e_j, Ae_j = e_i, Ae_k = e_k$$

6.2.3)

$$u_1 = \begin{pmatrix} 1 \\ 2 \\ -6 \end{pmatrix}, u_2 = \begin{pmatrix} -1 \\ 5 \\ 3 \end{pmatrix}, u_3 = \begin{pmatrix} 0 \\ -1 \\ 2 \end{pmatrix}$$

$$v_1 = \begin{pmatrix} 5 \\ 1 \\ 3 \end{pmatrix}, v_2 = \begin{pmatrix} 1 \\ 1 \\ 5 \end{pmatrix}, v_3 = \begin{pmatrix} 5 \\ 3 \\ 2 \end{pmatrix}$$

$$A = \begin{pmatrix} 1 & -1 & 0 \\ 2 & -1 & -1 \\ -6 & 5 & 2 \end{pmatrix}, B = \begin{pmatrix} 5 & 1 & 5 \\ 1 & 1 & 3 \\ 3 & 5 & -2 \end{pmatrix}$$

$$\det(A) = \det \begin{pmatrix} 1 & -1 \\ 5 & 2 \end{pmatrix} - (-1) \det \begin{pmatrix} 2 & -1 \\ -6 & 2 \end{pmatrix}$$

$$1 \cdot (-1(2) - (-1)(5)) + 1((2)(2) - (-1)(6)) \\ 3 - 2 = 1$$

$$\left[ \begin{array}{ccc|ccc} 1 & -1 & 0 & 1 & 0 & 0 \\ 2 & -1 & -1 & 0 & 1 & 0 \\ -6 & 5 & 2 & 0 & 0 & 1 \end{array} \right] \xrightarrow{R_2 - 2R_1} \left[ \begin{array}{ccc|ccc} 1 & -1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & -2 & 0 & 0 \\ -6 & 5 & 2 & 0 & 0 & 1 \end{array} \right] \xrightarrow{R_3 - 6R_1} \left[ \begin{array}{ccc|ccc} 1 & -1 & 0 & 1 & 0 & 0 \\ 0 & 1 & 1 & -2 & 0 & 0 \\ 0 & 1 & 2 & 6 & 0 & 1 \end{array} \right]$$

$$\xrightarrow{R_3 + R_2} \left[ \begin{array}{ccc|ccc} 1 & -1 & 0 & 1 & 0 & 0 \\ 0 & 1 & -1 & -2 & 1 & 0 \\ 0 & 0 & 1 & 4 & 1 & 1 \end{array} \right] \xrightarrow{R_2 + R_3} \left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & 1 & 2 & 1 \\ 0 & 1 & 0 & 0 & 2 & 1 \\ 0 & 0 & 1 & 4 & 1 & 1 \end{array} \right] A^{-1} = \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & 1 \\ 0 & 1 & 1 \end{bmatrix}$$

$$BA^{-1} = \begin{bmatrix} 5 & 1 & 5 \\ 1 & 1 & 3 \\ 3 & 5 & -2 \end{bmatrix} \begin{bmatrix} 1 & 2 & 1 \\ 0 & 2 & 1 \\ 0 & 1 & 1 \end{bmatrix} = \boxed{\begin{bmatrix} 37 & 17 & 11 \\ 17 & 7 & 5 \\ 11 & 14 & 6 \end{bmatrix}}$$

$$6.3.1) R(\theta) = \begin{bmatrix} \cos \theta & -\sin \theta \\ \sin \theta & \cos \theta \end{bmatrix} \quad \theta = \pi/3$$

$$R\left(\frac{\pi}{3}\right) = \begin{bmatrix} \frac{1}{2} & -\frac{\sqrt{3}}{2} \\ \frac{\sqrt{3}}{2} & \frac{1}{2} \end{bmatrix}$$

$$6.4.1) R_x = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \quad R_y = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix}$$

$$R_y R_x = \begin{bmatrix} -1 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} = \boxed{\begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix}}$$

$$6.4.3) R_{\pi/6} = \begin{bmatrix} \cos \frac{\pi}{6} & -\sin \frac{\pi}{6} \\ \sin \frac{\pi}{6} & \cos \frac{\pi}{6} \end{bmatrix} = \begin{bmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix}$$

$$F_y F_x = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \quad M = (F_y F_x) R_{\pi/6} = \begin{bmatrix} -1 & 0 \\ 0 & -1 \end{bmatrix} \begin{bmatrix} \frac{\sqrt{3}}{2} & -\frac{1}{2} \\ \frac{1}{2} & \frac{\sqrt{3}}{2} \end{bmatrix} = \boxed{\begin{bmatrix} -\frac{\sqrt{3}}{2} & \frac{1}{2} \\ -\frac{1}{2} & -\frac{\sqrt{3}}{2} \end{bmatrix}}$$

6.4.7)

$$A_v = \begin{bmatrix} 3 & 1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 2 \\ -1 \end{bmatrix} = \begin{bmatrix} 3 \cdot 2 + 1 \cdot (-1) \\ -1 \cdot 2 + 2 \cdot (-1) \end{bmatrix} = \boxed{\begin{bmatrix} 5 \\ -4 \end{bmatrix}}$$

$$B \cdot A_v = \begin{bmatrix} 0 & -2 \\ 4 & 2 \end{bmatrix} \begin{bmatrix} 5 \\ -4 \end{bmatrix} = \begin{bmatrix} 0 \cdot 5 + (-2)(-4) \\ 4 \cdot 5 + 2(-4) \end{bmatrix} = \boxed{\begin{bmatrix} 8 \\ 12 \end{bmatrix}}$$

$$(S \circ T)(v) = \boxed{\begin{bmatrix} 8 \\ 12 \end{bmatrix}}$$

6.4.10)

$$\det(A) = (2)(2) - (1)(5) = -1$$

$$A^{-1} = \frac{1}{\det(A)} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix} = \frac{1}{-1} \begin{bmatrix} 2 & -1 \\ -5 & 2 \end{bmatrix}$$

$$T^{-1} = \boxed{\begin{bmatrix} -2 & 1 \\ 5 & -2 \end{bmatrix}}$$