Luke Schmitt

Luke@LukeSchmitt.me • LukeSchmitt.me

EDUCATION

Carnegie Mellon University   **Pittsburgh, PA**
Master of Science in Mechanical Engineering   May 2021
QPA: 3.83/4.00

The University of Akron   **Akron, OH**
Bachelor of Science in Mechanical Engineering, Minor in Applied Mathematics   May 2019
GPA: 3.78/4.00

WORK EXPERIENCE

Westinghouse Electric Company   **Madison, PA**
Robotics Engineer   Summer 2020
- Implemented and tested safe velocity filters in ROS to improve mobile robot autonomous navigation stack
- Performed conceptual design for a novel multi-robot inspection system
- Communicated with suppliers and potential vendors for product selection and market research

Moen   **North Olmsted, OH**
Engineering Co-op   Spring 2017, Fall 2017, Summer 2018
- Developed, prototyped, and evaluated new product concepts
- Designed critical components for a high-volume product based on analytical and marketing feedback
- Used CFD tools and math models to maximize product attributes such as flow rate and pressure
- Performed finite element analysis to efficiently design critical components against pressure and consumer use

S&C Electric   **Chicago, IL**
Electroplating Intern   Summer 2016
- Wrote standard work orders, formed relationships with suppliers, advanced operator aptitude certification system

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ACADEMIC & RESEARCH PROJECTS

Carnegie Mellon University   **Pittsburgh, PA**

Computational Engineering and Robotics Lab • *Control Project Group*   Spring 2020 - Present
- Research tethered drone controller design, simulation, and application
- Develop an adaptive controller for UAVs operated under windy conditions
- Design a drone controller development platform

24-787 Advanced Control Systems Integration • *Model Predictive Control Hardware Integration*   Fall 2020
- Wrote an MPC C++ application that achieved position and balance control of a two-wheeled robot

24-787 Machine Learning & Artificial Intelligence • *Tethered Quadcopter Reinforcement Learning*   Fall 2020
- Learned a stabilizing controller for a tethered drone using reinforcement learning methods

16-899 Adaptive Control & Reinforcement Learning • *Improving State Estimation Through Filter Learning*   Spring 2020
- Improved state estimation of a simulated quadcopter using machine learning techniques

16-868 Biomechanics & Motor Control • *Modeling Bipedal Balance Strategies*   Fall 2019
- Modeled a robust 2D bipedal controller using Simulink that recovers standing balance under disturbances

The University of Akron   **Akron, OH**

Senior Design Project • *Autonomous Combat Robot*   Spring 2018 - Spring 2019
- Designed, built, and analyzed a platform for the development of an autonomous combat robot
- Won first place at senior design showcase for Health, Robotic, and Manufacturing System Design

Undergraduate Research • *Bone Biomechanics and Mechanobiology Lab*   Fall 2016 - Fall 2018
- Worked with a small team to design and test a unit to evaluate the mechanics of bones of variable size
- Won second place for undergraduate biomedical engineering in university-wide poster showcase

NASA Robotic Mining Competition Team • *ME/EE Divisions & Treasurer*   Fall 2015 - Spring 2019
- Lead the design and fabrication of the robot's locomotion and excavation systems and LED driver PCB

Biomedical Engineering Design Team • *President & Various Projects*   Fall 2015 - Spring 2019
- Created tools and toys for children in the local community with disabilities

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SKILLS

Programming: Advanced - MATLAB, Simulink | Intermediate - C++, ROS, Python, Git | Basic – JavaScript, Web Dev

CAD & CAE: Advanced - SolidWorks, Creo Pro/E | Intermediate - ANSYS FEA | Basic - Eagle CAD