

"Space Data Processing: Making Sense of Experimental Data"

# Continuation of topic 2 "Quasi-optimal approximation under uncertainty"

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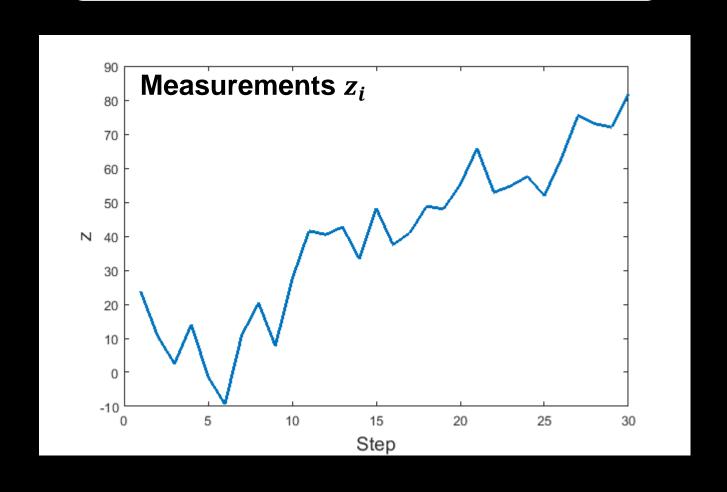
#### **Exponential smoothing**

$$\widehat{X}_i = \widehat{X}_{i-1} + \alpha(z_i - \widehat{X}_{i-1})$$

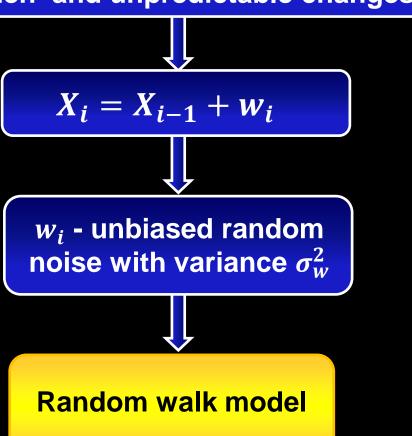
# Errors of exponential smoothing due to measurement errors

$$\sigma_{\widehat{X}}^2 = \sigma_{\eta}^2 \frac{\alpha}{2 - \alpha}$$

Process *X* is characterized by sudden and unpredictable changes





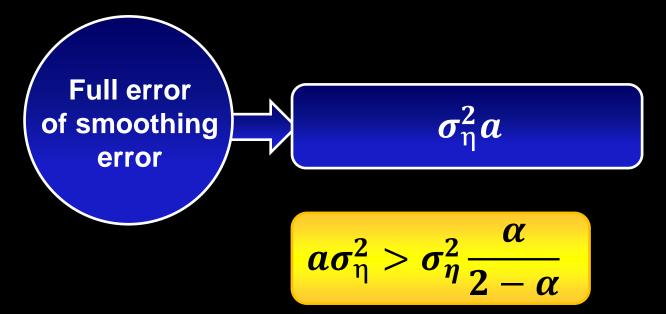


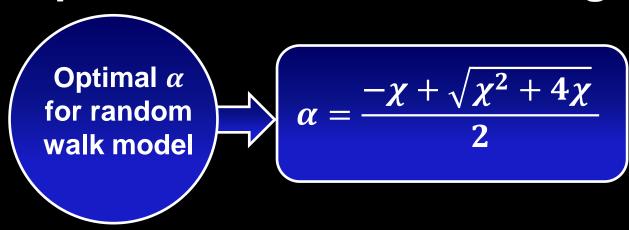
Optimal 
$$\alpha$$
 for random walk model 
$$\alpha = \frac{-\chi + \sqrt{\chi^2 + 4\chi}}{2}$$

Muth J.F. (1960), Optimal properties of exponentially weighted forecasts of time series with permanent and transitory components, J.Amer. Statist. Ass.01960.-Vol.55.-p.299.

$$\chi = rac{\sigma_w^2}{\sigma_\eta^2}$$

 $\sigma_{\eta}^2$  - variance of measurement noise

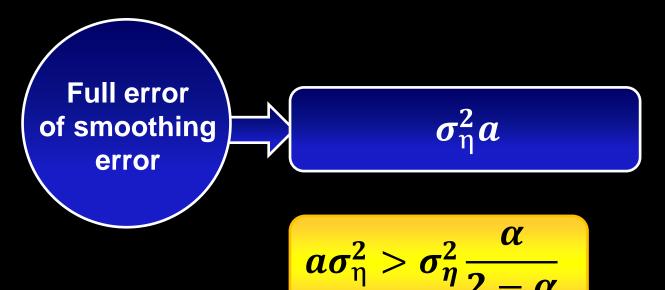




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$$\chi = \frac{\sigma_w^2}{\sigma_\eta^2}$$

 $\sigma_{\eta}^2$  - variance of measurement noise



Variances  $\sigma_w^2 \ \sigma_\eta^2$  should be identified

## Identification of noise statistics $\sigma_w^2$ and $\sigma_\eta^2$

Process 
$$X_i$$
  $\Rightarrow$   $X_i = X_{i-1} + w_i$  1

Measurements  $\Rightarrow$   $z_i = X_i + \eta_i$  2

Residual  $v_i$   $\Rightarrow$   $v_i = z_i - z_{i-1}$  3

Residual  $\rho_i$   $\Rightarrow$   $\rho_i = z_i - z_{i-2}$  4

Residual  $v_i$   $\Rightarrow$   $v_i = w_i + \eta_i - \eta_{i-1}$  5

Residual  $\rho_i$   $\Rightarrow$   $\rho_i = w_i + w_{i-1} + \eta_i - \eta_{i-2}$  6

Math. expectation  $\Rightarrow$   $E[v_i^2] = \sigma_w^2 + 2\sigma_\eta^2$  7

Math. expectation  $\Rightarrow$   $E[\rho_i^2] = 2\sigma_w^2 + 2\sigma_\eta^2$  8

Anderson, W. N., G. B. Kleindorfer, P. R. Kleindorfer, and M. B. Woodroofe (1969), Consistent estimates of the parameters of a linear system, Ann. Math. Stat., 40(3), 2064–2075.

## Identification of noise statistics $\sigma_w^2$ and $\sigma_\eta^2$

Process 
$$X_i$$
  $X_i = X_{i-1} + w_i$  1

Measurements  $Z_i = X_i + \eta_i$  2

Residual  $v_i$   $v_i = z_i - z_{i-1}$  3

Residual  $\rho_i$   $\rho_i = z_i - z_{i-2}$  4

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$$\left[E[
u_i^2]pprox rac{1}{N-2} \sum_{k=2}^N 
u_k^2
ight] \left[E[
ho_i^2]pprox rac{1}{N-3} \sum_{k=3}^N 
ho_k^2
ight]$$

Consistent estimates  $\sigma_w^2$  and  $\sigma_\eta^2$  are obtained by solving system of equations (7,8)