

2.152 Project: Adaptive Control of 2-Link Robotic Arm

May 14th, 2018

- 1 Setup Luke Roberto
- 2 Adaptive Control of Double Integrator

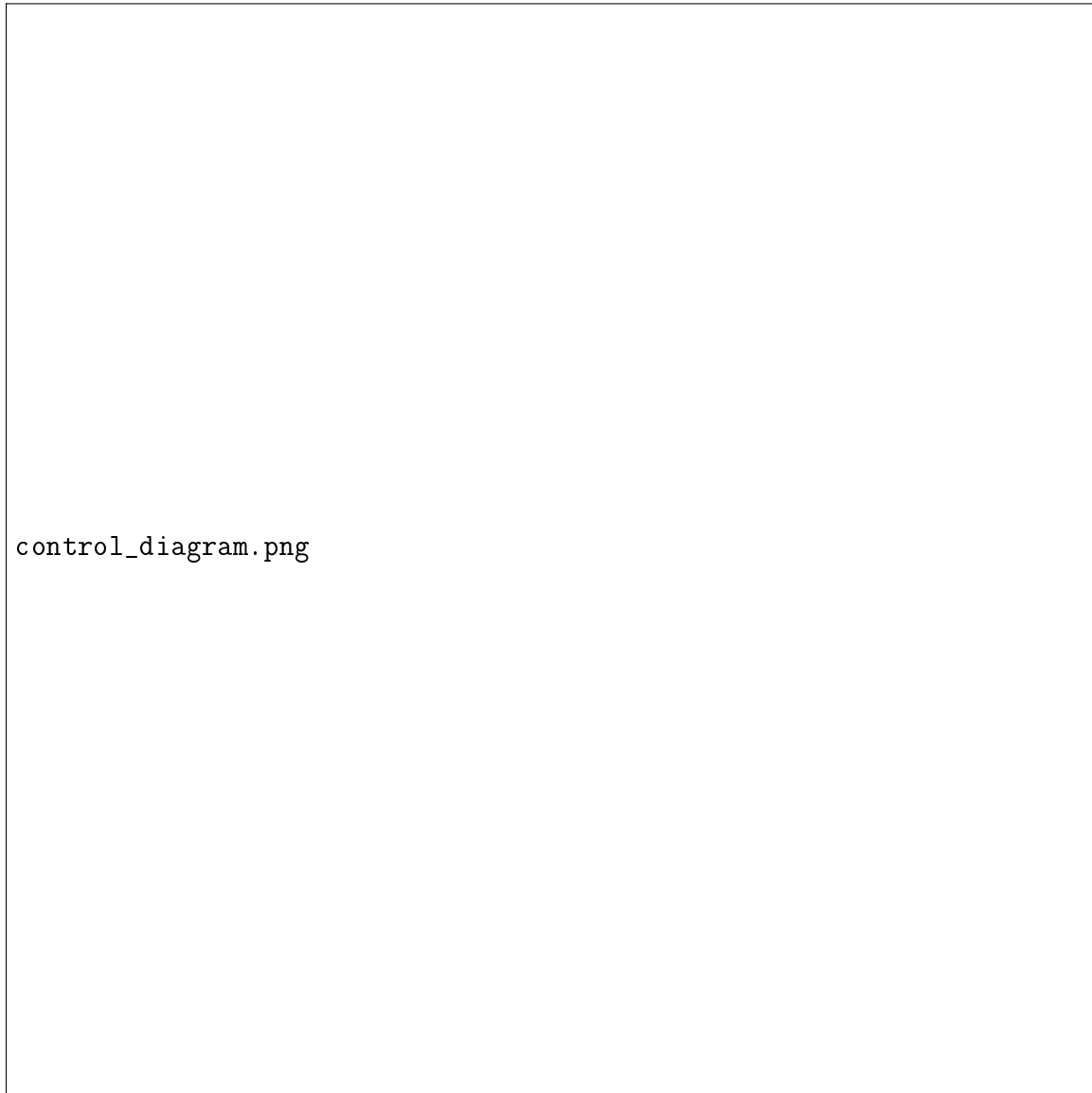


Figure 1: Sensor and Control Diagram

Fig. 1

- 3 Adaptive Control of 2-Link Arm
- 4 Risk Assessment