

libK8061

1.1

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# Chapter 1

## Main Page

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This page describes some general information on the libK8061 library, for a detailed description of all the routines, please see the **k8061.h** (p. 9) header file in the file list.

If you have problems with this library or comments, please drop me a line on the above email address.

### 1.1 Introduction to libK8061

libK8061 is basically a linux - port of the DLL that is provided with the Velleman k8061 USB interface card.

<http://www.velleman.be/ot/en/product/view/?id=364910><http://www.velleman.be/downloads/0/infosheetuk.pdf>

The library maintains an array of 8 usb filehandles which corresponds to the 8 possible addresses for the k8061 device on the USB bus. It then provides a set of routines which simply read analog/digital input values or set analog/digital output or the PWM value. It also contains an array with the jumper settings for the analog in/outputs so the user can set or read proper voltage levels instead of ADC/DAC values.

The library is distributed with a little command line interface to the card which enables the user to run some test commands to see whether his/her board works properly. This little ui tool is described in **The cmd8061 shell** (p. 3).

### 1.2 Compilation & installation

The library is based upon the default GNU autotools, so you should not have much difficulty in getting it to compile. Just issue the standard

```
bash$ tar -xvzf k8061-1.0.tar.gz
bash$ cd k8061-1.0
bash$ ./configure --prefix=/where/ever/you/want
bash$ make
bash$ make install
```

The library itself depends on the presence of libusb on your system along with it's development package libusb-devel. This package is included on most sytems and on fedora I've installed it using

```
bash# yum install libusb libusb-devel
```

So check you're own system's package management system (dpkg for Debian and Ubuntu, and I have no idea what SuSE uses nowadays...) Note that the compilation of the cmd8061 tool requires the presence of the GNU readline and history library ! See **cmd8061 compilation** (p. 4).

If you can't find it, feel free to compile libusb from source, you can find it at :

<http://libusb.sourceforge.net/>

## 1.3 Setting user permissions with udev

Using the USB interface via libusb is normally only possible as root. So one has to set some permissions right to be able to use USB devices as user. There are different ways to do that, but the cleanest is via the system's hotplug sytem. On fedora ( my system ) this is done via udev.

See <http://www.kernel.org/pub/linux/utils/kernel/hotplug/udev.html>

I will describe what worked for me on a fedora 8 machine. One simply needs to create a new set of udev rules. On my system I have created a new group of users called **daqusers** to group all the ones with permission to write to any USB DAQ device on my system and added myself to that list. On most systems there are loads of graphical tools to do that, but here are the simple commands :

```
bash# groupadd daqusers
bash# usermod -a -G daqusers <username>
```

Next, you should create a udev rules file in

```
bash# vi /etc/udev/rules.d/60-usbdaq.rules
```

with the following contents

```
# Sets up udev rules for USB DAQ devices
SUBSYSTEM!="usb", ACTION!="add", GOTO="usbdaq_end"
# The Velleman k8061 USB board
SYSFS{idVendor}=="10cf", SYSFS{idProduct}=="8061", GROUP="daqusers", MODE="0660"
LABEL="usbdaq_end"
```

I had to log in & out for the system to pick up my new user affiliation, but after that it worked just fine and I could communicate to the Velleman k8061 device as myself.



## Chapter 2

### The cmd8061 shell

In order to play around a bit with the USB board and easily run some tests to see whether my soldering was done okay, I have created a user interface which enables you to easily send some commands down to the card or read some ADC or DIN values back.

This little tool is distributed along with the library and is called **cmd8061**.

## 2.1 cmd8061 compilation

**cmd8061** Depends on libK8061 and is compiled along with it when the user issues a make in the top level source directory. Next to the libusb dependance, the configure script also checks the presence of the GNU readline and history libraries which are needed for the command line interface. On fedora you can install these with

```
bash# yum install readline readline-devel
```

The homepage for readline is found here :

<http://tiswww.case.edu/php/chet/readline/rltop.html>

## 2.2 cmd8061 usage

The **cmd8061** tool is fairly straightforward to use. It defined a small number of commands which issue library calls that interface with the k8061 USB board. When you startup the program you get a prompt. The prompt is done with libreadline and libhistory so therefore it has tab-completion as well as a command history the standard GNU-way.

```
[niblap] ~ $ cmd8061
cmd8061 Copyright (C) 2008 Bino Maiheu
A linux based command-line interface for the
Velleman K8061 Extended USB Interface

This program comes with ABSOLUTELY NO WARRANTY;
This is free software, and you are welcome to redistribute it
under conditions set out in the GNU General Public Licence version 2
See: http://www.gnu.org/licenses

Initializing interface...
Initializing k8061 USB devices...
Succesfully found K8061 card nr 0
cmd8061::0>
```

Then you can issue various command to .e.g. read the analog inputs or set the PWM value. when you issue the **help** command you'll see a list of possible commands. Always one card is selected and you can change to a different active USB card with the following command

```
cmd8061::1> card 0
Selected card 0
[Card 0 Status]
connected, power on, version : IC3: VK8061USB Rev: V1.3, IC6: VK8061CPU Rev: V1.5
[Card 0 Jumper Settings]
AIN Jumper Config 1->8: 0 0 0 0 0 0 0 0
AOUT Jumper Config 1->8: 0 0 0 0 0 0 0 0
cmd8061::0>
```

The program will output some status information of the selected card and update the number after the "cmd8061::" prompt, indicating the active card number. All commands that are issued, are done for the active card. Except of course the once that act upon the entire usb bus, like **scan** or **list**. The brief explanation should be enough for most commands in the help function, we will discuss some important commands below. To quit the program, the command is simply **quit**.

This is an overview of all the commands :

scan		Scan usb bus and update k8061 array..
list		List of known k8061 devices on USB bus.
stat		Show status of the active k8061 card..
card	<icard>	Select an active k8061 card on USB bus [0-7]..
get	<grp> [ch]	Get value of channel of group.
set	<grp> <ch> <v> [V]	Set value of channel of group to v, [AOUT in Volt].
reset		Resets the board, output values to 0.
clr		Clear read errors.
err		Show read errors.
jmps	<grp> <hex>	Set jumper values for analog in/out groups.
wait	<secs>	Wait for a number of seconds..
exec	<fname>	Execute the file with commands.
quit		Quit this program..
help		Display help text on the commands.
info		Display some usefull info about the program.

### 2.2.1 The get and set commands.

The get and set commands are used to control the different interface groups. See them with info :

```
cmd8061::0> info
Groups on the board are :
- dout ..... : digital outputs
- aout ..... : analog outputs
- din ..... : digital inputs
- ain ..... : analog inputs
- pwm ..... : pulser
```

In order e.g. to get the value of analog input 3 on the active card, simply issue

```
cmd8061::0> get ain 3
```

and the program will display the ADC value as an integer (and for the analog in/outputs) as a voltage value as well.

To display all the analog inputs, use

```
cmd8061::0> get ain
```

Identical behaviour exists for the digital inputs.

In order to set digital or analog outputs, use

```
cmd8061::0> set dout 2 0
cmd8061::0> set dout 3 1
```

This sets the digital output on channel 2 to low on the active card and the digital output on channel 3 to high.

If you want to set all the digital outputs to 1 of the active card use

```
cmd8061::0> set dout all 1
```

similarly you can set all the analog outputs to a value or individual analog outputs.

```
cmd8061::0> set aout 3 123
cmd8061::0> set aout all 234
```

### Attention:

When setting an analog output, you have the option of providing a voltage value instead of an integer DAC value. You can do this by adding a "V" to the command, like this :

```
cmd8061::0> set aout 3 0.87 V
cmd8061::0> set aout all 3.50 V
```

By issuing a get command on the dout, aout or pwm, the set values are read back and displayed.

## 2.2.2 The jmps command.

The jmps command sets the analog input/output jumpers, simply provide the group name (**ain** or **aout**) followed by a bitpattern which corresponds to the jumper settings, so AIN1 is bit 0, AIN8 bit 7, 1 means the jumper is there, 0 means it is not. An example is given here

```
cmd8061::0> jmps ain 0x0f
```

This tells the program and the library that the first 4 jumpers on the analog ADC inputs are there (AIN1->4), and on the 4 other ones (AIN5->8) not.

## 2.2.3 Running a macro

The command **exec** enables the user to run a file that has a set of commands. One useful command with this is the **wait** command that pauses for the number of seconds given. In the distribution tarballs test/ directory there is a file called *dout-runoff.k8061* which contains such a macro to try.

# Chapter 3

## File Index

### 3.1 File List

Here is a list of all files with brief descriptions:

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# Chapter 4

## File Documentation

### 4.1 libK8061/k8061.h File Reference

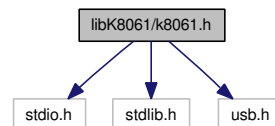
#### 4.1.1 Detailed Description

```
#include <stdio.h>
```

```
#include <stdlib.h>
```

```
#include <usb.h>
```

Include dependency graph for k8061.h:



#### Defines

- `#define k8061__idVendor 0x10cf`  
*k8061 Vendor ID*
- `#define k8061__idProduct 0x8061`  
*k8061 Product ID*
- `#define k8061__epRead 0x81`  
*Value of k8061 read end-point.*
- `#define k8061__epWrite 0x01`  
*Value of k8061 write end-point.*
- `#define k8061__ioTimeout 50`  
*timeout for usb\_bulk\_read/write calls*
- `#define k8061__ioWait 800`

*wait after usb\_bulk\_read/write calls*

- **#define k8061\_iConfig 1**  
*usb config to use on card*
- **#define k8061\_iClaim 0**  
*interface to claim*
- **#define k8061\_cmdReadAnalogChannel 0x00**  
*k8061 Command: Read analog channel*
- **#define k8061\_cmdReadAllAnalog 0x01**  
*k8061 Command: Read all analog channels*
- **#define k8061\_cmdSetAnalogChannel 0x02**  
*k8061 Command: Set analog channel*
- **#define k8061\_cmdSetAllAnalog 0x03**  
*k8061 Command: Set all analog channels*
- **#define k8061\_cmdOutputPWM 0x04**  
*k8061 Command: Output PWM level*
- **#define k8061\_cmdReadDigitalByte 0x05**  
*k8061 Command: Read the digital byte*
- **#define k8061\_cmdDigitalOut 0x06**  
*k8061 Command: Set Digital output*
- **#define k8061\_cmdClearDigitalChannel 0x07**  
*k8061 Command: Set a signal digital channel*
- **#define k8061\_cmdSetDigitalChannel 0x08**  
*k8061 Command: Set a signal digital channel*
- **#define k8061\_cmdReadCounters 0x09**  
*k8061 Command: Read the number of errors*
- **#define k8061\_cmdResetCounters 0x0a**  
*k8061 Command: Reset the number of errors*
- **#define k8061\_cmdReadVersion 0x0b**  
*k8061 Command: Read version*
- **#define k8061\_cmdJumpers 0x0c**  
*k8061 Command: Get Jumper status*
- **#define k8061\_cmdPowerStatus 0x0d**  
*k8061 Command: Power status*



- **#define k8061\_\_cmdReadDigitalOut 0x0e**  
*k8061 Command: Read back digital out*
- **#define k8061\_\_cmdReadAnalogOut 0x0f**  
*k8061 Command: Read back analog out*
- **#define k8061\_\_cmdReadPWMOut 0x10**  
*k8061 Command: Read back PWM out*

## Functions

- **void k8061\_\_Init (void)**  
*Initialises the library by initialising the readline interface and the usb library.*
- **int k8061\_\_GetDeviceCount (void)**  
*Scans for and returns the number of Velleman K8061 devices on the USB bus.*
- **int k8061\_\_OpenDevices (void)**  
*See k8061\_\_ScanBus.*
- **int k8061\_\_ScanBus (int verb)**  
*Scans the complete usb bus hierarchy and looks for k8061 devices.*
- **void k8061\_\_CloseDevices (void)**  
*Closes all k8061 devices that are currently open in the file handle list.*
- **int k8061\_\_ExecIO (int iCard, int nSend, int nReceive)**  
*Performs a basic input / output operation to the k8061 device, this consists of sending a command defined by the `_k8061_WriteBuffer` of `nSend` bytes and reading back the result of the command in the `_k8061_ReadBuffer` of `nReceive` bytes.*
- **void k8061\_\_CheckOpen (int iCard)**  
*Checks whether the card number really is open by performing a simple read & write to the device.*
- **void k8061\_\_ListDevices (FILE \*fp)**  
*Writes the status of all the devices that are currently open in the filehandle array.*
- **int k8061\_\_OutputAnalogChannel (int iCard, int iChan, int value)**  
*Sets the analog output on channel `iChan` of card `iCard`.*
- **int k8061\_\_OutputAnalogChannelVolt (int iCard, int iChan, double volt)**  
*Sets the analog output on channel `iChan` of card `iCard` to the voltage value.*
- **int k8061\_\_OutputAllAnalog (int iCard, int value\_arr[])**  
*Sets all analog output channels on card `iCard` to the values given by the array of DAC values.*
- **int k8061\_\_OutputAllAnalogVolt (int iCard, double volt\_arr[])**  
*Sets all analog output on channel on card `iCard` to the voltage values given by the array.*

- **int k8061 \_\_ClearAnalogChannel** (int iCard, int iChan)  
*Sets the analog output on channel iChan of card iCard to 0.*
- **int k8061 \_\_ClearAllAnalog** (int iCard)  
*Sets all the analog output on channels of card iCard to 0.*
- **int k8061 \_\_SetAnalogChannel** (int iCard, int iChan)  
*Sets the analog output on channel iChan of card iCard to its maximum (255).*
- **int k8061 \_\_SetAllAnalog** (int iCard)  
*Sets all the analog output on channels on card iCard to their maximum (255).*
- **int k8061 \_\_ReadAnalogChannel** (int iCard, int iChan)  
*Reads the value of the analog input channel.*
- **int k8061 \_\_ReadAllAnalog** (int iCard, int value\_arr[])  
*Reads the value of all analog input channels on the card and returns them in the array.*
- **double k8061 \_\_GetDACVolt** (int iCard, int chan, int val)  
*Converts the DAC value (Analog Output) into volts using the stored DAC jumper configuration.*
- **double k8061 \_\_GetADCVolt** (int iCard, int chan, int val)  
*Converts the ADC value (Analog Input) into volts using the stored DAC jumper configuration.*
- **int k8061 \_\_SetDACJumpers** (int iCard, unsigned char b)  
*Sets the Analog Output jumper configuration on the card to the given pattern b encoded as a single byte.*
- **int k8061 \_\_SetADCJumpers** (int iCard, unsigned char b)  
*Sets the Analog Input jumper configuration on the card to the given pattern b encoded as a single byte.*
- **int k8061 \_\_WriteJumpers** (int iCard, FILE \*fp)  
*Write the status of the ADC/DAC jumpers to the filepointer.*
- **int k8061 \_\_SetAllDigital** (int iCard)  
*Sets all digital outputs on the card to 1.*
- **int k8061 \_\_ClearAllDigital** (int iCard)  
*Sets all digital outputs on the card to 0.*
- **int k8061 \_\_SetDigitalChannel** (int iCard, int iChan)  
*Sets the digital output channel to 1.*
- **int k8061 \_\_ClearDigitalChannel** (int iCard, int iChan)  
*Sets the digital output channel to 0.*
- **int k8061 \_\_OutputAllDigital** (int iCard, unsigned char bPattern)  
*Set all digital output channels on the card according to some binary pattern, encoded as a single byte.*

- **int k8061 \_\_ReadAllDigital** (int iCard, int din\_arr[])  
*Reads the all the digital inputs and stores them as 8 integer 0/1 values in the array.*
- **int k8061 \_\_ReadAllDigitalByte** (int iCard, unsigned char \*din\_byte)  
*Reads the all the digital inputs and returns them as a single byte ( unsigned char ).*
- **int k8061 \_\_ReadDigitalChannel** (int iCard, int iChan)  
*Reads a single digital channel and returns it's state as 0 or 1 unsigned char ).*
- **int k8061 \_\_OutputPWM** (int iCard, int value)  
*Sets the PWM value, between 0 and 1024.*
- **int k8061 \_\_WriteStatus** (int iCard, FILE \*fp)  
*Writes some status report of the card to the filepointer, this shows whether the card is connected, whether the 12 VDC power cord is connected and what the version of the IC firmware is.*
- **int k8061 \_\_ReadVersion** (int iCard, char version\_str[])  
*Reads back the version of the IC firmware.*
- **int k8061 \_\_IsConnected** (int iCard)  
*Returns the \_k8061\_IsOpen value for the corresponding card.*
- **int k8061 \_\_HasPower** (int iCard)  
*Checks whether the card's 12 VDC power supply is ok.*
- **int k8061 \_\_ReadBackDigitalOut** (int iCard, int dout\_arr[])  
*Reads back the digital outputs and stores them ad 8 integer ones or zeros in the dout array.*
- **int k8061 \_\_ReadBackAnalogOut** (int iCard, int aout\_arr[])  
*Reads back the analog outputs and stores them ad 8 integer valuess in the aout array.*
- **int k8061 \_\_ReadBackPWMOut** (int iCard)  
*Reads back the set PWM value and returs it.*
- **int k8061 \_\_ResetCounters** (int iCard)  
*Resets the error counters.*
- **int k8061 \_\_ReadCounters** (int iCard, int cntr\_arr[])  
*Reads the error counters.*

## Variables

- **int \_\_k8061 \_\_IsOpen** [8]  
*Array with flags for the open k8061 devices.*
- **usb\_dev\_handle \* \_\_k8061 \_\_Handle** [8]  
*Array with filehandles for the k8061 devices.*

- char `__k8061_ReadBuffer` [50]  
*The read buffer.*
- char `__k8061_WriteBuffer` [50]  
*The receive buffer.*
- unsigned char `__k8061_jump_adc` [8]  
*Jumper settings for the AINs for each card.*
- unsigned char `__k8061_jump_dac` [8]  
*Jumper settings for the AOUTs for each card.*

### 4.1.2 Define Documentation

#### 4.1.2.1 `#define k8061__cmdClearDigitalChannel 0x07`

k8061 Command: Set a signal digital channel

#### 4.1.2.2 `#define k8061__cmdDigitalOut 0x06`

k8061 Command: Set Digital output

#### 4.1.2.3 `#define k8061__cmdJumpers 0x0c`

k8061 Command: Get Jumper status

#### 4.1.2.4 `#define k8061__cmdOutputPWM 0x04`

k8061 Command: Output PWM level

#### 4.1.2.5 `#define k8061__cmdPowerStatus 0x0d`

k8061 Command: Power status

#### 4.1.2.6 `#define k8061__cmdReadAllAnalog 0x01`

k8061 Command: Read all analog channels

#### 4.1.2.7 `#define k8061__cmdReadAnalogChannel 0x00`

k8061 Command: Read analog channel

#### 4.1.2.8 `#define k8061__cmdReadAnalogOut 0x0f`

k8061 Command: Read back analog out

**4.1.2.9    #define k8061 \_\_cmdReadCounters 0x09**

k8061 Command: Read the number of errors

**4.1.2.10   #define k8061 \_\_cmdReadDigitalByte 0x05**

k8061 Command: Read the digital byte

**4.1.2.11   #define k8061 \_\_cmdReadDigitalOut 0x0e**

k8061 Command: Read back digital out

**4.1.2.12   #define k8061 \_\_cmdReadPWMOut 0x10**

k8061 Command: Read back PWM out

**4.1.2.13   #define k8061 \_\_cmdReadVersion 0x0b**

k8061 Command: Read version

**4.1.2.14   #define k8061 \_\_cmdResetCounters 0x0a**

k8061 Command: Reset the number of errors

**4.1.2.15   #define k8061 \_\_cmdSetAllAnalog 0x03**

k8061 Command: Set all analog channels

**4.1.2.16   #define k8061 \_\_cmdSetAnalogChannel 0x02**

k8061 Command: Set analog channel

**4.1.2.17   #define k8061 \_\_cmdSetDigitalChannel 0x08**

k8061 Command: Set a signal digital channel

**4.1.2.18   #define k8061 \_\_epRead 0x81**

Value of k8061 read end-point.

**4.1.2.19   #define k8061 \_\_epWrite 0x01**

Value of k8061 write end-point.

**4.1.2.20   #define k8061 \_\_iClaim 0**

interface to claim

**4.1.2.21** `#define k8061 __iConfig 1`

usb config to use on card

**4.1.2.22** `#define k8061 __idProduct 0x8061`

k8061 Product ID

**4.1.2.23** `#define k8061 __idVendor 0x10cf`

k8061 Vendor ID

**4.1.2.24** `#define k8061 __ioTimeout 50`

timeout for usb\_bulk\_read/write calls

**4.1.2.25** `#define k8061 __ioWait 800`

wait after usb\_bulk\_read/write calls

**4.1.3 Function Documentation****4.1.3.1** `void k8061 __CheckOpen (int iCard)`

Checks whether the card number really is open by performing a simple read & write to the device. If it failes, the filehandle array is updated.

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus

**4.1.3.2** `int k8061 __ClearAllAnalog (int iCard)`

Sets all the analog output on channels of card iCard to 0.

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus [0-7]

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.3** `int k8061 __ClearAllDigital (int iCard)`

Sets all digital outputs on the card to 0.

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus [0-7]

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.4 int k8061\_ClearAnalogChannel (int *iCard*, int *iChan*)**

Sets the analog output on channel *iChan* of card *iCard* to 0.

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus [0-7]

*iChan* The channel number on the card [1-8]

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.5 int k8061\_ClearDigitalChannel (int *iCard*, int *iChan*)**

Sets the digital output channel to 0.

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus [0-7]

*iChan* The channel number on the card [1-8]

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.6 void k8061\_CloseDevices (void)**

Closes all k8061 devices that are currently open in the file handle list.

**4.1.3.7 int k8061\_ExecIO (int *iCard*, int *nSend*, int *nReceive*)**

Performs a basic input / output operation to the k8061 device, this consists of sending a command defined by the `_k8061_WriteBuffer` of *nSend* bytes and reading back the result of the command in the `_k8061_ReadBuffer` of *nReceive* bytes.

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus

*nSend* Number of bytes to send to the k8061 device

*nReceive* Number of bytes to read back from the k8061 device

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.8 double k8061 \_\_GetADCVolt (int *iCard*, int *chan*, int *val*)**

Converts the ADC value (Analog Input) into volts using the stored DAC jumper configuration.

**Parameters:**

- iCard*** The number (address) of the k8061 card on the bus [0-7]
- chan*** The channel number on the card [1-8]
- val*** The integer ADC value

**Returns:**

The ADC value in volts

**4.1.3.9 double k8061 \_\_GetDACVolt (int *iCard*, int *chan*, int *val*)**

Converts the DAC value (Analog Output) into volts using the stored DAC jumper configuration.

**Parameters:**

- iCard*** The number (address) of the k8061 card on the bus [0-7]
- chan*** The channel number on the card [1-8]
- val*** The integer DAC value

**Returns:**

The DAC value in volts

**4.1.3.10 int k8061 \_\_GetDeviceCount (void)**

Scans for and returns the number of Velleman K8061 devices on the USB bus.

**Returns:**

The number of K8061 devices found on the USB bus

**4.1.3.11 int k8061 \_\_HasPower (int *iCard*)**

Checks whether the card's 12 VDC power supply is ok.

**Parameters:**

- iCard*** The number (address) of the k8061 card on the bus [0-7]

**Returns:**

1 if it is, 0 if not

**4.1.3.12 void k8061 \_\_Init (void)**

Initialises the library by intialising the readline interface and the usb library.



#### 4.1.3.13 int k8061\_IsConnected (int *iCard*)

Returns the `_k8061_IsOpen` value for the corresponding card.

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus [0-7]

**Returns:**

Whether the card is connected in the filehandle array or not

#### 4.1.3.14 void k8061\_ListDevices (FILE \* *fp*)

Writes the status of all the devices that are currently open in the filehandle array.

**Parameters:**

*fp* Output filepointer, use stdout for terminal

#### 4.1.3.15 int k8061\_OpenDevices (void)

See `k8061_ScanBus`.

#### 4.1.3.16 int k8061\_OutputAllAnalog (int *iCard*, int *value\_arr*[])

Sets all analog output channels on card *iCard* to the values given by the array of DAC values.

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus [0-7]

*value\_arr* An array of 8 the integer DAC values

**Returns:**

0 upon success, < 0 upon failure

#### 4.1.3.17 int k8061\_OutputAllAnalogVolt (int *iCard*, double *volt\_arr*[])

Sets all analog output on channel on card *iCard* to the voltage values given by the array.

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus [0-7]

*volt\_arr* An array of 8 voltage values ( < 5 V or < 10 V, depending on the jumper )

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.18 int k8061\_OutputAllDigital (int *iCard*, unsigned char *bPattern*)**

Set all digital output channels on the card according to some binary pattern, encoded as a single byte.

**Parameters:**

- iCard* The number (address) of the k8061 card on the bus [0-7]
- bPattern* The 8-bit pattern for the digital outputs

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.19 int k8061\_OutputAnalogChannel (int *iCard*, int *iChan*, int *value*)**

Sets the analog output on channel *iChan* of card *iCard*.

**Parameters:**

- iCard* The number (address) of the k8061 card on the bus [0-7]
- iChan* The channel number on the card [1-8]
- value* The integer DAC value

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.20 int k8061\_OutputAnalogChannelVolt (int *iCard*, int *iChan*, double *volt*)**

Sets the analog output on channel *iChan* of card *iCard* to the voltage value.

**Parameters:**

- iCard* The number (address) of the k8061 card on the bus [0-7]
- iChan* The channel number on the card [1-8]
- volt* A voltage value ( < 5 V or < 10 V, depending on the jumper )

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.21 int k8061\_OutputPWM (int *iCard*, int *value*)**

Sets the PWM value, between 0 and 1024.

**Parameters:**

- iCard* The number (address) of the k8061 card on the bus [0-7]
- value* The PWM value

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.22 int k8061\_ReadAllAnalog (int *iCard*, int *value\_arr*[])**

Reads the value of all analog input channels on the card and returns them in the array.

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus [0-7]

*value\_arr* The array with the ADC values

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.23 int k8061\_ReadAllDigital (int *iCard*, int *din\_arr*[])**

Reads the all the digital inputs and stores them as 8 integer 0/1 values in the array.

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus [0-7]

*din\_arr* Array with 0 or 1 corresponding to the digital inputs

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.24 int k8061\_ReadAllDigitalByte (int *iCard*, unsigned char \* *din\_byte*)**

Reads the all the digital inputs and returns them as a single byte ( unsigned char ).

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus [0-7]

*din\_byte* Byte formed out of the 8 digital inputs

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.25 int k8061\_ReadAnalogChannel (int *iCard*, int *iChan*)**

Reads the value of the analog input channel.

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus [0-7]

*iChan* The channel number on the card [1-8]

**Returns:**

The ADC value

**4.1.3.26 int k8061\_ReadBackAnalogOut (int *iCard*, int *aout\_arr*[])**

Reads back the analog outputs and stores them as 8 integer values in the aout array.

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus [0-7]  
*aout\_arr* Array to store the analog outputs

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.27 int k8061\_ReadBackDigitalOut (int *iCard*, int *dout\_arr*[])**

Reads back the digital outputs and stores them as 8 integer ones or zeros in the dout array.

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus [0-7]  
*dout\_arr* Array to store the digital outputs

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.28 int k8061\_ReadBackPWMOut (int *iCard*)**

Reads back the set PWM value and returns it.

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus [0-7]

**Returns:**

the PWM value

**4.1.3.29 int k8061\_ReadCounters (int *iCard*, int *cntr\_arr*[])**

Reads the error counters.

.. don't really know what these do

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus [0-7]  
*cntr\_arr* Array of 2 integers

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.30 int k8061\_ReadDigitalChannel (int *iCard*, int *iChan*)**

Reads a single digital channel and returns it's state as 0 or 1 unsigned char ).

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus [0-7]

*iChan* The channel number on the card [1-8]

**Returns:**

1 when on, 0 when off

**4.1.3.31 int k8061\_ReadVersion (int *iCard*, char *version\_str*[])**

Reads back the version of the IC firmware.

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus [0-7]

*version\_str* The string to hold the IC firmware

**4.1.3.32 int k8061\_ResetCounters (int *iCard*)**

Resets the error counters.

.. don't really know what these do

**Parameters:**

*iCard* The number (address) of the k8061 card on the bus [0-7]

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.33 int k8061\_ScanBus (int *verb*)**

Scans the complete usb bus hierarchy and looks for k8061 devices.

If it finds a matching device, it tries to set the usb configuration and claim the interface. When that has succeeded, it reads the address of the k8061 device and opens the filehandle of the corresponding \_k8061\_Handle entry.

**Parameters:**

*verb* Some verbosity parameter

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.34 int k8061\_SetADCJumpers (int *iCard*, unsigned char *b*)**

Sets the Analog Input jumper configuration on the card to the given pattern *b* encoded as a single byte.

**Parameters:**

- iCard* The number (address) of the k8061 card on the bus [0-7]
- b* The bit pattern

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.35 int k8061\_SetAllAnalog (int *iCard*)**

Sets all the analog output on channels on card *iCard* to their maximum (255).

**Parameters:**

- iCard* The number (address) of the k8061 card on the bus [0-7]

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.36 int k8061\_SetAllDigital (int *iCard*)**

Sets all digital outputs on the card to 1.

**Parameters:**

- iCard* The number (address) of the k8061 card on the bus [0-7]

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.37 int k8061\_SetAnalogChannel (int *iCard*, int *iChan*)**

Sets the analog output on channel *iChan* of card *iCard* to its maximum (255).

**Parameters:**

- iCard* The number (address) of the k8061 card on the bus [0-7]
- iChan* The channel number on the card [1-8]

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.38 int k8061\_SetDACJumpers (int *iCard*, unsigned char *b*)**

Sets the Analog Output jumper configuration on the card to the given pattern *b* encoded as a single byte.

**Parameters:**

- iCard* The number (address) of the k8061 card on the bus [0-7]  
*b* The bit pattern

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.39 int k8061\_SetDigitalChannel (int *iCard*, int *iChan*)**

Sets the digital output channel to 1.

**Parameters:**

- iCard* The number (address) of the k8061 card on the bus [0-7]  
*iChan* The channel number on the card [1-8]

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.40 int k8061\_WriteJumpers (int *iCard*, FILE \* *fp*)**

Write the status of the ADC/DAC jumpers to the filepointer.

**Parameters:**

- iCard* The number (address) of the k8061 card on the bus [0-7]  
*fp* The filepointer, use stdout to write to terminal

**Returns:**

0 upon success, < 0 upon failure

**4.1.3.41 int k8061\_WriteStatus (int *iCard*, FILE \* *fp*)**

Writes some status report of the card to the filepointer, this shows whether the card is connected, whether the 12 VDC power cord is connected and what the version of the IC firmware is.

**Parameters:**

- iCard* The number (address) of the k8061 card on the bus [0-7]  
*fp* The filepointer, use stdout to write to terminal

## 4.1.4 Variable Documentation

### 4.1.4.1 `usb_dev_handle* __k8061_Handle[8]`

Array with filehandles for the k8061 devices.

### 4.1.4.2 `int __k8061_IsOpen[8]`

Array with flags for the open k8061 devices.

### 4.1.4.3 `unsigned char __k8061_jump_adc[8]`

Jumper settings for the AINs for each card.

### 4.1.4.4 `unsigned char __k8061_jump_dac[8]`

Jumper settings for the AOUTs for each card.

### 4.1.4.5 `char __k8061_ReadBuffer[50]`

The read buffer.

### 4.1.4.6 `char __k8061_WriteBuffer[50]`

The receive buffer.



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