

DQN

April 25, 2022

1 Deep Q Learning

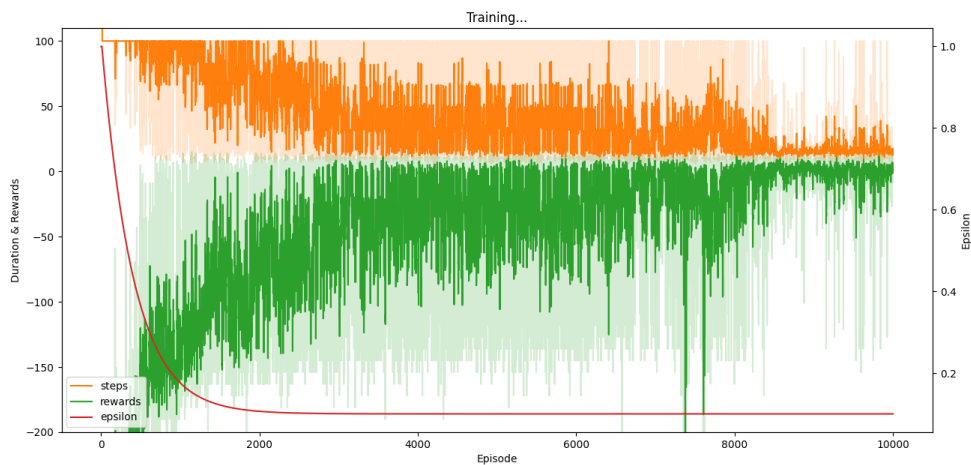
```
[ ]: from DQN_Train import TrainingAgent
import gym
```

1.1 Reference Architecture 1

This model was trained to use as a reference to compare future model trained with different parameters

```
[ ]: env = gym.make("Taxi-v3").env
env.seed(42)
agent = TrainingAgent(env=env,
                      name="notebook_reference",
                      save=False,
                      architecture=1)

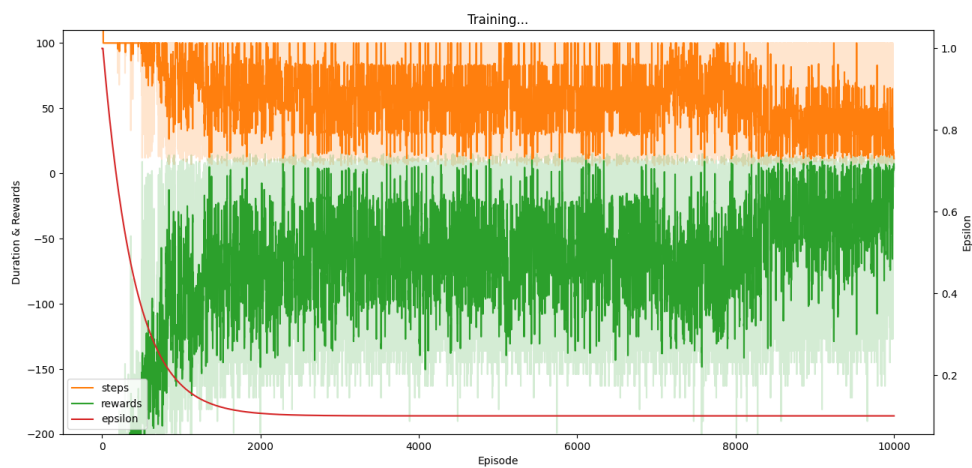
agent.compile()
agent.fit()
```



1.2 Constant Learning Rate

```
[ ]: env = gym.make("Taxi-v3").env
env.seed(42)
agent = TrainingAgent(env=env,
                      lr_min=0.001,
                      name="notebook_lr_const",
                      save=False,
                      architecture=1)

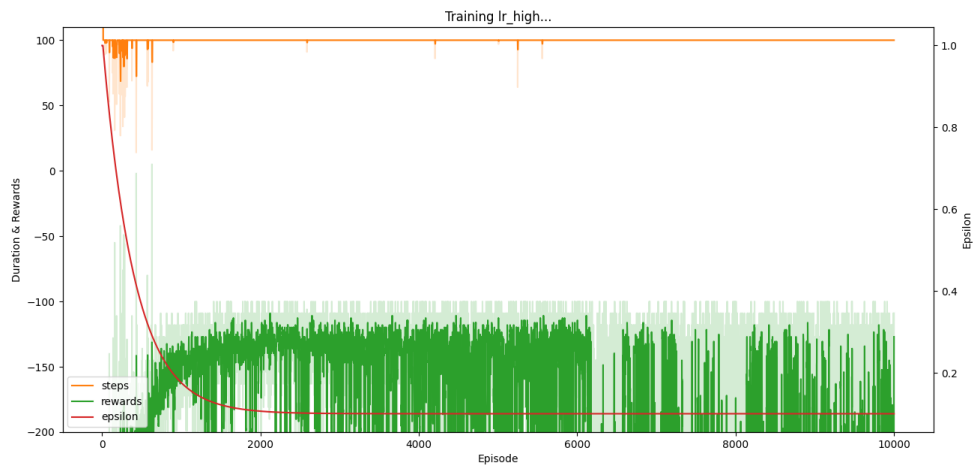
agent.compile()
agent.fit()
```



1.3 High Learning Rate

```
[ ]: env = gym.make("Taxi-v3").env
env.seed(42)
agent = TrainingAgent(env=env,
                      lr=0.01,
                      lr_min=0.01,
                      name="notebook_lr_high",
                      save=False,
                      architecture=1)

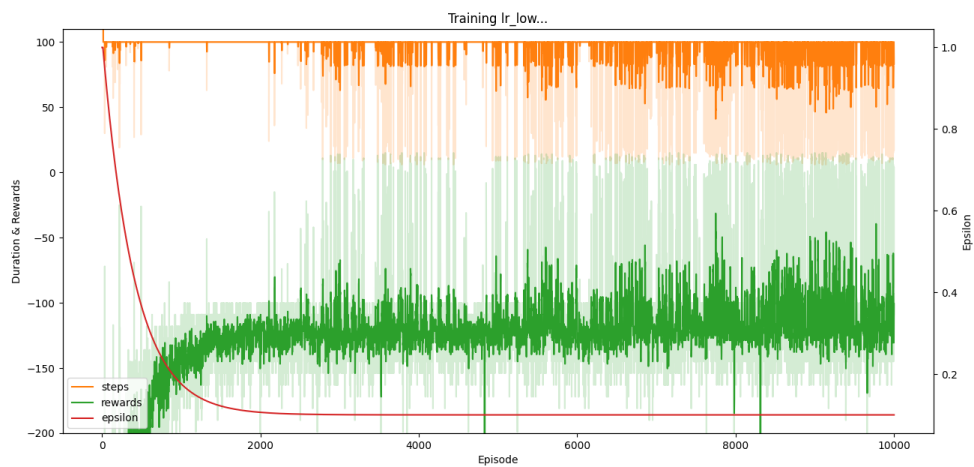
agent.compile()
agent.fit()
```



1.4 Low Learning Rate

```
[ ]: env = gym.make("Taxi-v3").env
env.seed(42)
agent = TrainingAgent(env=env,
                      lr=0.0001,
                      lr_min=0.0001,
                      name="notebook_lr_low",
                      save=False,
                      architecture=1)

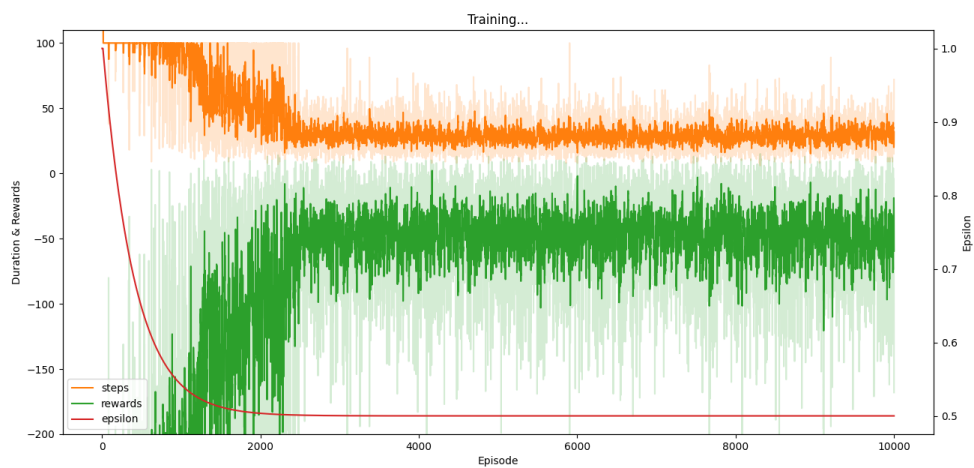
agent.compile()
agent.fit()
```



1.5 High Epsilon

```
[ ]: env = gym.make("Taxi-v3").env
env.seed(42)
agent = TrainingAgent(env=env,
                      eps_end=0.5,
                      name="notebook_eps_high",
                      save=False,
                      architecture=1)

agent.compile()
agent.fit()
```



1.6 Low Epsilon

```
[ ]: env = gym.make("Taxi-v3").env
env.seed(42)
agent = TrainingAgent(env=env,
                      eps_end=0.01,
                      name="notebook_eps_low",
                      save=False,
                      architecture=1)

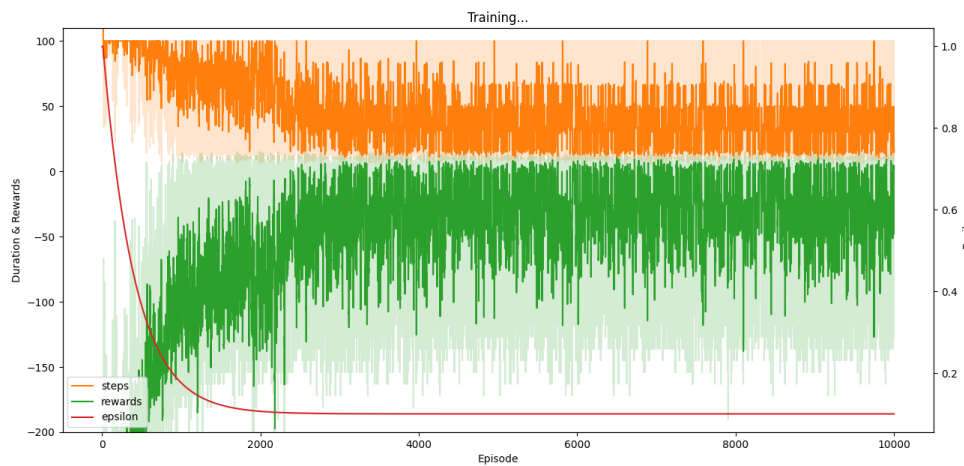
agent.compile()
agent.fit()
```



1.7 Update Rate High

```
[ ]: env = gym.make("Taxi-v3").env
env.seed(42)
agent = TrainingAgent(env=env,
                      target_update=2,
                      name="notebook_update_high",
                      save=False,
                      architecture=1)

agent.compile()
agent.fit()
```



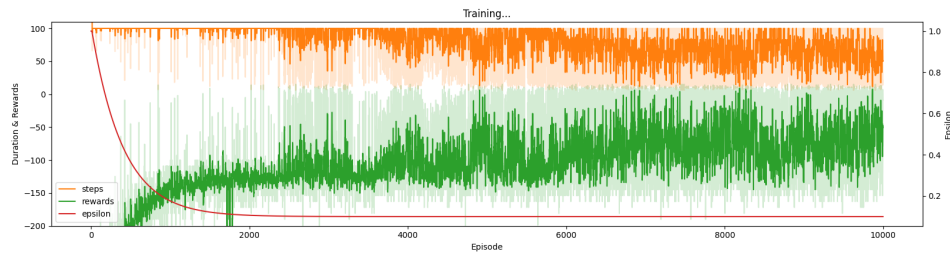
1.8 Update Rate Low

```
[ ]: env = gym.make("Taxi-v3").env
env.seed(42)
agent = TrainingAgent(env=env,
                      target_update=200,
                      name="notebook_update_low",
```

```

        save=False,
        architecture=1)
agent.compile()
agent.fit()

```



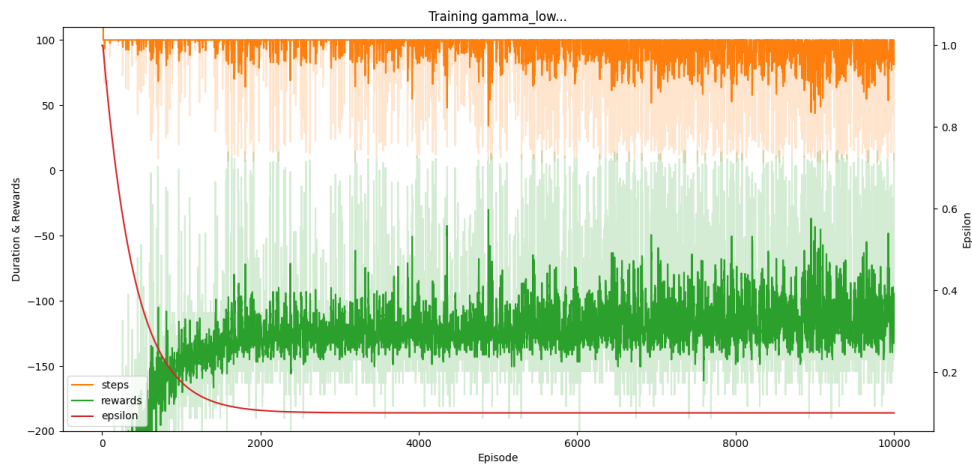
1.9 Gamma Low

```

[ ]: env = gym.make("Taxi-v3").env
env.seed(42)
agent = TrainingAgent(env=env,
                      gamma=0.2,
                      name="notebook_gamma_low",
                      save=False,
                      architecture=1)

agent.compile()
agent.fit()

```



1.10 Batch Size High

```

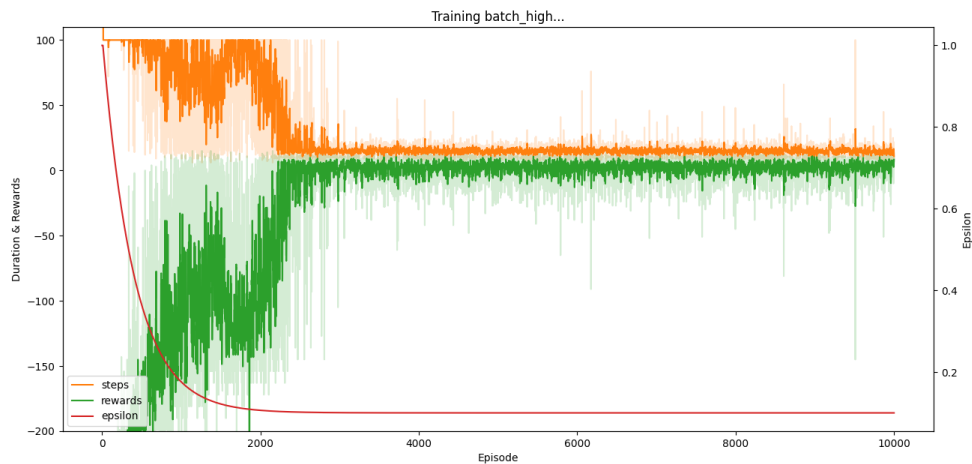
[ ]: env = gym.make("Taxi-v3").env
env.seed(42)
agent = TrainingAgent(env=env,
                      batch_size=512,

```

```

        name="notebook_batch_high",
        save=False,
        architecture=1)
agent.compile()
agent.fit()

```



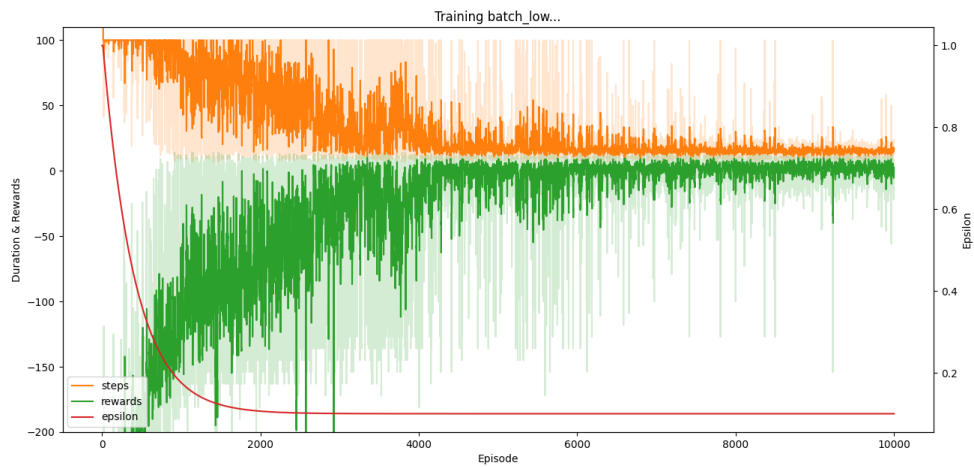
1.11 Batch Size Low

```

[ ]: env = gym.make("Taxi-v3").env
env.seed(42)
agent = TrainingAgent(env=env,
                      batch_size=32,
                      name="notebook_batch_low",
                      save=False,
                      architecture=1)

agent.compile()
agent.fit()

```



1.12 Reference Architecture 2

```
[ ]: env = gym.make("Taxi-v3").env
env.seed(42)
agent = TrainingAgent(env=env,
                      name="notebook_reference_2",
                      save=False,
                      architecture=2)

agent.compile()
agent.fit()
```

