

Installation Guide



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Documentation http://embedXcode.weebly.com/

GitHub repository http://github.com/rei-vilo/embedXcode

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How to Help



Contribute to the project on GitHub.



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Summary

1.	Install	nstall the Template3				
2.	Create	Create a New Project7				
3.	Config	gure the Project	8			
	3.1.	Declare Sketch .pde File as C++ File	8			
	3.2.	Declare User's Sketchbook	10			
	3.3.	Add User's Libraries	11			
	3.4.	Declare Sources for Code-Sense	14			
	3.5.	Define the Directories for the Target	16			
4.	Use th	ne Project	18			
	4.1.	Change the Board	18			
	4.2.	Add a File	20			
	4.3.	Insert #include Statements From Code Snippet	22			
	4.4.	Manage Code for Multiple Platforms	25			
	4.5.	Re-Index the Keywords for Code-Sense	27			
5.	Apper	ndixes	32			
	5.1.	What Has Been Tested	32			
	5.2.	Known Issues	32			
	5.3.	Contributions and References				
	5.4.	Version History				
	5.5.	Referenced Boards				
6.	Copyright and Licence					
	6.1.	Summary	36			
	6.2.	Legal Code	37			

1. Install the Template

Before installing the template, you need to install at least one IDE.



If you plan to use Arduino boards:

- Download and install Arduino 0023 or Arduino 1.0.
- Launch it.
- Define the path of the sketchbook in the menu Aduino >
 Preferences > Sketchbook location.

embedXcode identifies the version of Arduino automatically.

As a matter of fact, Wiring is considered as the framework of reference for embedded computing.

Arduino 0023 should be preferred over Arduino 1.0 because Arduino 0023 is Wiring compliant. So is chipKIT MPIDE 0023.

Arduino 1.0 has introduced many small changes in the syntax which are not compatible with previous release. Energia 1.0 is derived from Arduino 1.0.

So I strongly recommend to pick the release of Arduino which is compatible with the other platforms you plan to use:

- either Arduino 0023 with chipKIT MPIDE, Wiring and Maple IDES,
- or Arduino 1.0 with LaunchPad Energia IDE.





MDP

If you plan to use chipKIT boards:

- · Download and install Mpide 0023.
- · Launch it.
- Define the path of the sketchbook in the menu Mpide > Preferences > Sketchbook location.

If you plan to use Wiring boards:

- Download and install Wiring 1.0.
- · Launch it.
- Define the path of the sketchbook in the menu Wiring > Preferences > Sketchbook location.

The two following files require to be deleted.



Multiplatform Arduino compatible IDE Arduino 0023 Compatiblity

Modified version of the Arduino IDE created by Rick Anderson and Mark Sproul of Fair Use Building and Research on May 21, 2011.

This software is not supported by the Arduino LLC



/Applications/Wiring.app/Contents/Resources/ Java/cores/AVR8Bit/program.cpp

/Applications/Wiring.app/Contents/Resources/ Java/cores/AVR8Bit/makefile



If you plan to use LaunchPad boards:

- · Download and install Energia 1.0.
- · Launch it.
- Define the path of the sketchbook in the menu Energia > Preferences > Sketchbook location.



Energia 1.0

Modified version of the Arduino IDE for the Texas Instrument LaunchPad MSP430 created by Robert Wessels on January 2012.

This software is not supported by the Arduino LLC.

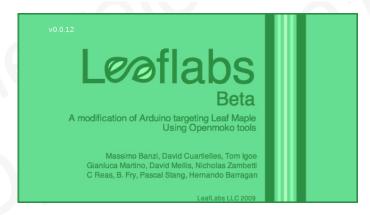


If you plan to use Maple boards:

- Download and install MapleIDE.
- · Launch it.
- Define the path of the sketchbook in the menu MapleIDE
 - > Preferences > Sketchbook location.

The Maple reset script —which sends control signals over the USB-serial connection to restart and enter the bootloader— is written in Python and requires the PySerial library:

- Read the instructions at http://leaflabs.com/docs/unix-toolchain.html#os-x and
- Download PySerial library from http://pypi.python.org/pypi/pyserial.



For other boards with a Processing-based IDE, same procedure:

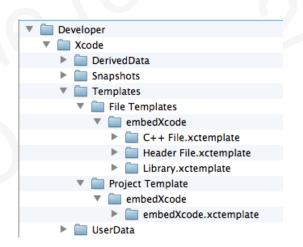
- Download and install the corresponding Processing-based IDE.
- · Launch it.
- Define the path of the sketchbook.
- Additionally, develop a specific makefile and adapt the Step1 makefile.

Now, the template can be installed:

Check and create ~ /Library/Developer/Xcode.

Copy the folder Templates into ~/Library/Developer/Xcode



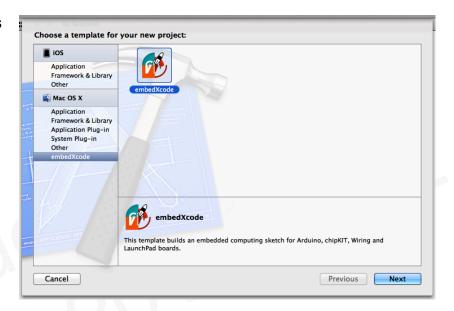


2. Create a New Project

Call the menu File > New > New Project... or press $\bigcirc \Re N$.

Select embedXcode > embedXcode.

Click on Next to proceed to the next step.



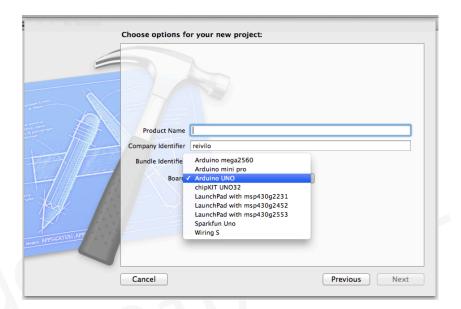
Type in the name of the project.

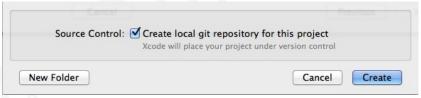
Select the board on the drop-down list.

Click on Next to proceed to the last step.

Select the folder where the project is going to be saved and check Create local git repository for this project if you want so.

Then click Create to confirm and create the project.





3. Configure the Project

The template doesn't define all the parameters, so some of them need to be set manually.

The goal is to have the following work done by the template, provided the right keywords are known.

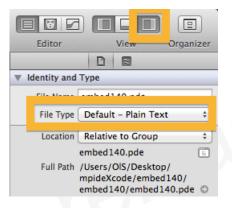
3.1. Declare Sketch .pde File as C++ File

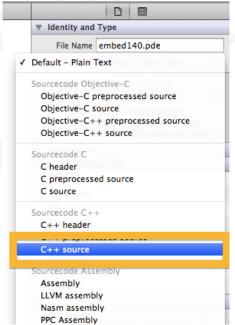
The sketch . pde file is considered as plan text. For code-sense, it should be declared as C++ file.

Select the sketch . pde file.

In the right-most column,

Click on the drop-down list of File Type. Select C++ source.





Now, the sketch is considered as C++ code for code-sense.

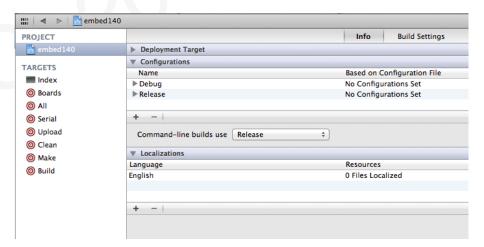


This manual procedure is considered as an issue and reported under #3 Declare PDE File as C++ Source.

3.2. Declare User's Sketchbook

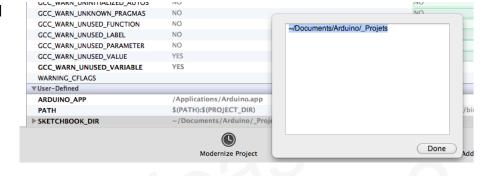
The user's sketchbook is a folder where the user's sketches are saved, among them the libraries in a dedicated sub-folder Libraries.

Select the project and the Build Settings pane.



At the very bottom, double-click on SKETCHB00K_DIR and either type in the name of the folder or drag-and-drop it from a Finder window.

The ~ character is accepted.



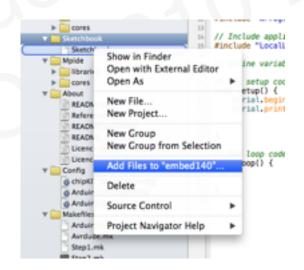
If no sketchbook is defined, SKETCHB00K_DIR takes the value defined for Arduino or chipKIT during the installation process.

3.3. Add User's Libraries

Open the Sketchbook group on the project hierarchy.

Right-click to obtain the contextual menu.

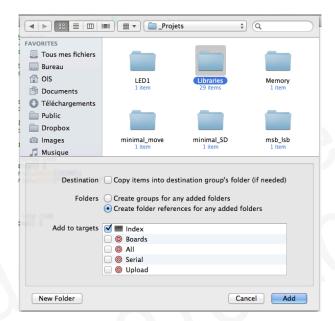
Choose Add file to...



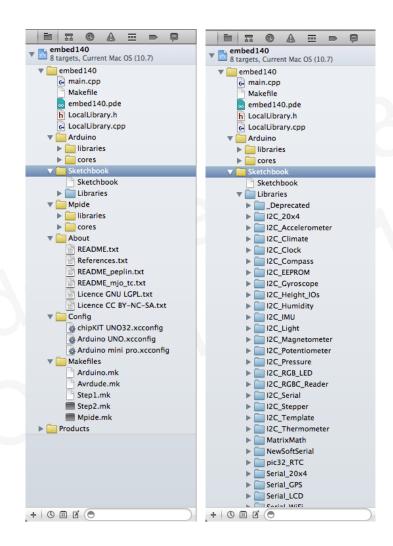
Select the Library sub-folder on the sketchbook folder, tick Add to target > Index and validate with Add.

Both Create group for any added folders and Create folder references for any added folders are relevant.

Don't tick Copy items into destination group's folder (in needed) to avoid duplicating files.



The project hierarchy shows all your libraries.



3.4. Declare Sources for Code-Sense

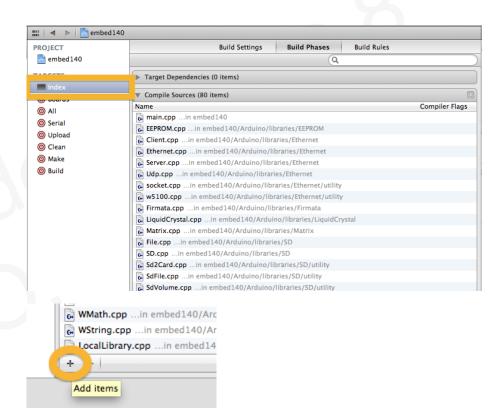
Standard C++ keywords are already known, but not some Arduino and user's library keywords.

The selection of a board defines the headers for code-sense.

So Xcode needs to be taught where to find them.

Select the target Index and the Build Phases pane.

Go a the bottom of the list and click on the + button.



A list shows up.



Select all the . h and . cpp files and click on Add.



This manual procedure is considered as an issue and reported under #2 Populated Sources List for Code-Sense.

3.5. Define the Directories for the Target

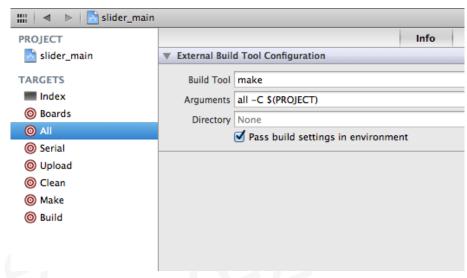
The template doesn't allow to specify the exact directory for the target. In case of an building error, the click-to-error feature may not work properly for the main sketch and the local libraries.

So Xcode needs to be taught where to find them.

This is an optional procedure.

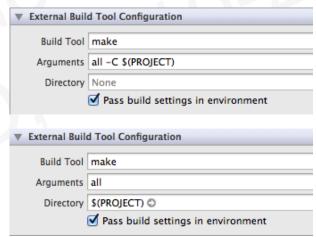
Select the target All.

Feel free to update other targets you use often, as Build and Make.



By default, the template mentions all -C (PROJECT) as arguments.

Remove –C \$(PR0JECT) from the arguments and add \$ (PR0JECT) into directory.



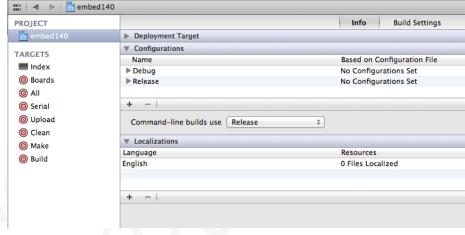
This manual procedure is considered as an issue and reported under #12 Define Directory for a Target.

You're ready now!

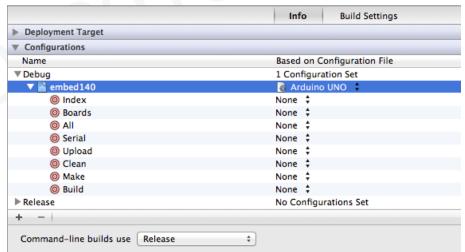
4. Use the Project

4.1. Change the Board

To change the board, select the project and the Info pane.



A drop-down list shows the boards available.



Just select one.

If your board isn't listed, you can create a configuration file. Please refer to §6 Add a file.

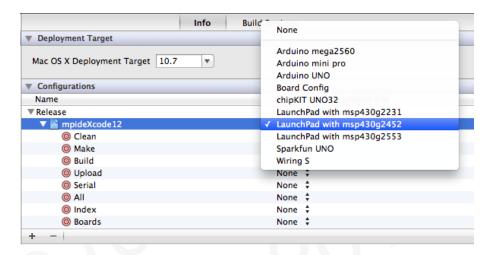
The sketch contains conditional #include for the supported IDEs.

They are based on the micro-controller reference or on the IDE version. For more information, please refer to <u>Manage Code for Multiple Platforms</u>.

The version of Arduino, either 0023 or 1.0, is detected automatically and the corresponding library Arduino.h or WProgram.h. selected accordingly.

Those #include statements are included on a code snippet for easy use.

Please refer to <u>Insert Code Snippet with #include</u> Statements.



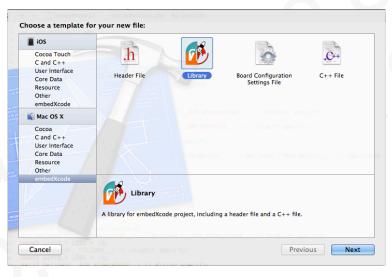
```
// Core library - MCU-based
#if defined (__AVR_ATmega328P__) || defined
  AVR ATmega2560 ) // Arduino specific
  #if defined(ARDUINO) && (ARDUINO >= 100)
  #include "arduino.h" // - for Arduino 1.0
  #else
  #include "WProgram.h" // - for Arduino 23
#elif defined( 32MX320F128H ) ||
defined( 32MX795F512L ) // chipKIT specific
#include "WProgram.h"
#elif defined( AVR ATmega644P ) // Wiring specific
#include "Wiring.h"
#elif defined( MSP430G2452 )
defined(__MSP430G2553__) || defined(__MSP430G2231__) //
LaunchPad specific
#include "Energia.h"
#elif defined(MCU_STM32F103RB) ||
defined(MCU STM32F103ZE) || defined(MCU STM32F103CB) ||
defined(MCU STM32F103RE) // Maple specific
#include "WProgram.h"
#endif
```

When a board is selected, the configuration file defines parameters for code-sense.

4.2. Add a File

Call the menu File > New > New File... or press ₩N

Select embedXcode and then Header File, C++ file, Library or Board Configuration Settings File.



Library creates a header file and a C++ code file with the #include "LocalLibrary.h" #include statement ready!

Board Configuration Settings File allows to define the settings for a new board.

Specify:

- BOARD_TAG is the unique identifier of the board, found in the Boards.txt file.
- BOARD_PORT defines the USB port to be used. This parameter is optional.
- GCC_PREPROCESSOR_DEFINITIONS is the name of the micro-controller of the board, found in the Boards.txt file.
- HEADER_SEARCH_PATHS needs to be updated with the reference of the IDE, ARDUINO_APP for Arduino, MPIDE_APP for Mpide, WIRING_APP for Wiring, or ENERGIA_APP for Energia.

The last two parameters improves the selection of the headers for code-sense.

4.3. Insert #include Statements From Code Snippet

A code snippet includes all the #include statements for selecting the core libraries.

There are two versions: one MCU-based and another IDE-based.

For more information, please refer to <u>Manage Code for Multiple Platforms</u>.

To display the code snippets, click on the right button of the View selector.

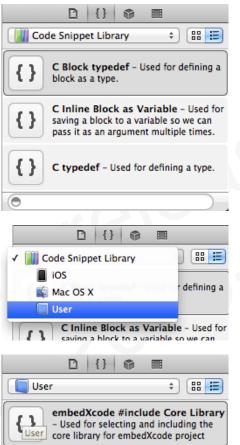
```
// Core library - MCU-based
#if defined (__AVR_ATmega328P__) || defined
  AVR ATmega2560 ) // Arduino specific
 #if defined(ARDUINO) && (ARDUINO >= 100)
 #include "arduino.h" // - for Arduino 1.0
  #else
 #include "WProgram.h" // - for Arduino 23
  #endif
#elif defined( 32MX320F128H ) | |
defined( 32MX795F512L ) // chipKIT specific
#include "WProgram.h"
#elif defined(__AVR_ATmega644P__) // Wiring specific
#include "Wiring.h"
#elif defined( MSP430G2452 ) || defined( MSP430G2553 )
|| defined(__MSP430G2231__) // LaunchPad specific
#include "Energia.h"
#elif defined(MCU_STM32F103RB) || defined(MCU_STM32F103ZE)
|| defined(MCU STM32F103CB) || defined(MCU STM32F103RE) //
Maple specific
#include "WProgram.h"
#endif
```

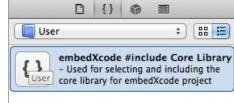


The library of code snippets is at the bottom of the rightmost pane.

Select User on the drop-down list.

Select the embedXcode #include Core Library snippet.





Click and drop to the destination.



The pointer changes for

The cursor appears on the code.

```
mpideXcode12 ) h LocalLibrary.h ) No Selection
     // LocalLibrary.h
          Library header
          Developed with embedXcode
          Project mpideXcode12
Created by Rei VILO on 27/03/12
Copyright (c) 2012 http://sites.google.com/site/vilorei
11
12
13
     #ifndef embed1_LocalLibrary_h
#define embed1_LocalLibrary_h
15
16
17
18
19
     #endif
20
```

The code is inserted.

```
IIII | ◀ ▶ | Maride Minimum Maride Minimum Maride 
                               LocalLibrary.h
                                Library header
                                Developed with embedXcode
                                Project mpideXcode12
                                Created by Rei VILO on 27/03/12
                                 Copyright (c) 2012 http://sites.google.com/site/vilorei
     12 // Core library
     #if defined (_AVR_ATmega328P__) || defined (_AVR_ATmega2560__) // Arduino specific
     #include "WProgram.h" // - for Arduino 0023
// #include "Arduino.h" // - for Arduino 1.0
     #elif defined(__32MX320F128H__) || defined(__32MX795F512L__) // chipKIT specific
     17 #include "WProgram.h"
                 #elif defined(__AVR_ATmega644P__) // Wiring specific
     #include "Wiring.h" #elif defined(_MSP430G2452_) || defined(_MSP430G2553_) || defined(_MSP430G2231_) // LaunchPad
                  #include "Energia.h"
                  #endif
     #ifndef embed1_LocalLibrary_h
                 #define embed1_LocalLibrary_h
                    #endif
```

4.4. Manage Code for Multiple Platforms

Managing code for multiples platforms is a real issue, and needs to take into account two dimensions:

- the boards, as Arduino Uno or Wiring S,
- and the frameworks, some of them with incompatible releases, as Arduino 0023, Arduino 1.0 or Wiring.

This can be done in two ways, MCU-based or IDE-based. Both are valid from an embedXcode point of view.

The first approach is **MCU-based** and relies on the micro-controller type.

This approach is compatible with the respective IDEs, as no new environment variable is created or required.

In the Arduino case, two frameworks exist so the IDE variable is required for disambiguation.

The second approach is **IDE-based**. Most of the IDEs defines a specific environment variable combine boards type and framework version.

For example, the Arduino IDE defines ARDUIN0=101 and passes it on to the tool-chain with -D, as -DARDUIN0=101.

As at today, this approach is compatible with Arduino, Wiring and Maple IDEs, which have the environment variables already defined: ARDUIN0=23, ARDUIN0=101, WIRING=100 and MAPLE_IDE.

The remaining two IDEs, MPIDE and Energia doesn't know the environment variables used by embedXcode: MPIDE=23 and ENERGIA=6. embedXcode creates them.

```
// Core library — MCU-based
#if defined (__AVR_ATmega328P__) || defined
  AVR ATmega2560 ) // Arduino specific
  #if defined(ARDUINO) && (ARDUINO >= 100)
  #include "arduino.h" // - for Arduino 1.0
  #else
  #include "WProgram.h" // - for Arduino 23
#endif
#elif defined( 32MX320F128H ) ||
defined(__32MX795F512L__) // chipKIT specific
#include "WProgram.h"
#elif defined( AVR ATmega644P ) // Wiring specific
#include "Wiring.h"
#elif defined(_MSP430G2452__) || defined(_MSP430G2553__)
|| defined( MSP430G2231 ) // LaunchPad specific
#include "Energia.h"
#else // error
#error Platform not defined
#endif
// Core library - IDE-based
#if defined(WIRING) // Wiring specific - official
#include "Wiring.h"
#elif defined(MAPLE IDE) // Maple specific - official
#include "WProgram.h"
#elif defined(MPIDE) // chipKIT specific - embedXcode only
#include "WProgram.h"
#elif defined(ENERGIA) // LaunchPad specific - embedXcode
onlv
#include "Energia.h"
#elif defined(ARDUINO) && (ARDUINO >= 100) // Arduino 1.0
specific - official
#include "Arduino.h"
#elif defined(ARDUINO) && (ARDUINO < 100) // Arduino 23
specific - official
#include "WProgram.h"
#else // error
#error Platform not defined
#endif
```

The second approach allows more compact and easier to read code, and doesn't require maintenance at code level when a new MCU appears.

Both approaches are valid from an embedXcode point of view.

The first is not compatible with chipKIT MPIDE and Energia for LaunchPad IDEs.

4.5. Re-Index the Keywords for Code-Sense

Code-sense is a major feature of Xcode.

Apart from pretty colours on the code and enhanced visibility, code-sense brings:

· auto-completion,

· code-snippets and check-as-you-type code monitoring,

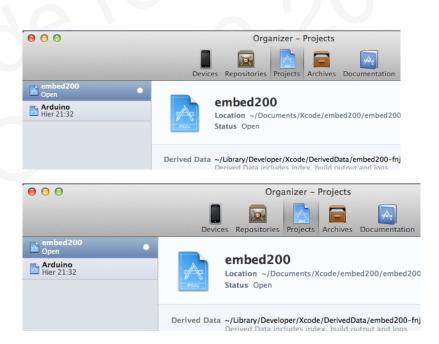
click-to-definition

If code-sense doesn't work, we need to force a re-indexing of the key words.

To do so, first close the project.

Call the menu Window > Organiser and select the Projects pane.

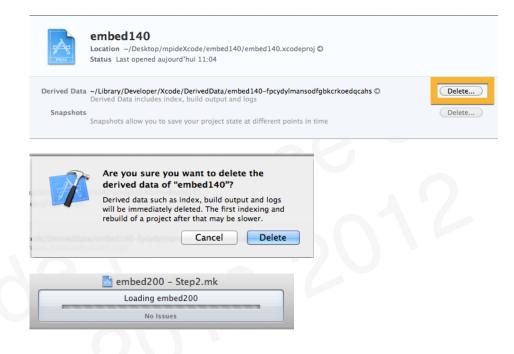
Select then the project.



The index is saved within the Derived Data folder. Click on the Delete button to delete them.

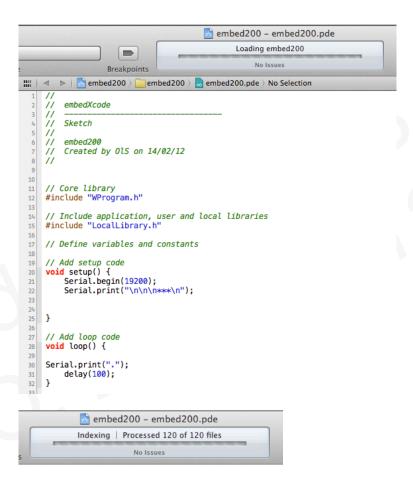
Confirm the deletion.

Load the project.



There's no code-sense yet: everything is in black-and-white, except standard C++ keywords.

The index is being built.



When the index is built, code-sense shows pretty colours.

```
Breakpoints

Break
```

5. Appendixes

5.1. What Has Been Tested

Platform	What Has Been Tested	What Has Not Been Tested	Reference Boards
Arduino	Sketch compilation and upload		Arduino Uno, Arduino mega2560 and Arduino mini pro
chipKIT	Sketch compilation and upload		chipKIT UNO32
Wiring	Sketch compilation and upload		Wiring S
LaunchPad	Sketch compilation and upload		LaunchPad with MSP430G2542, MSP430G2331 and MSP430G2553
Maple	Sketch compilation and upload		Maple revision 5

5.2. Known Issues

Most of the issues are related to unknown keywords for the Xcode 4.3 template.

Most critical issues are:

#2 Populated Sources List for Code-Sense

#3 Declare PDE File as C++ Source

#12 Define Directory for a Target

5.3. Contributions and References

See documents on the About folder for additional contributions and detailed references.

5.4. Version History

Date	mpideXcode	embedXcode	Installation Guide	Comment
Jan 22, 2012	a			Initial release
Feb 02, 2012	b			chipKIT operational
Feb 04, 2012	С			Code-sense operational
Feb 06, 2012	d			User libraries
Feb 06, 2012	е			Code checking while typing with Index as target
Feb 08, 2012	f			Code-sense, click-to-error with standard targets
Feb 14, 2012	g	1	1	Multi-application, check-as-you-type, template
Feb 18, 2012	6	2	2	Improvements
Feb 26, 2012		3		Modular makefiles
Mar 06, 2012	7	4	3	Arduino 1.0 implementation
Mar 12, 2012	8	5		Bugs fixed
Mar 15, 2012	9	6	4	All Arduino/chipKIT/Wiring/Energia and user libraries included by default
Apr 05, 2012	10	7	5	Wiring 1.0 and Energia 1.0 implementations
Apr 08, 2012	11	8	5	Bugs fixed
Apr 16, 2012	12	9	6	Code-sense reference defined by selected board
May 23, 2012	13	10	7	LeafLabs Maple implementation
Jun 03, 2012	14	11	8	MCU- or IDE-based platform identification for #include library

5.5. Referenced Boards

Not all boards have been tested. Please refer to What Has Been Tested for more details.

According to the Boards.txt files:

Arduino	chipKIT	Wiring	LaunchPad	Maple
Arduino Uno	chipKIT UNO32	Wiring S @ 16 MHz	LaunchPad with mps430g2452	LeafLabs Maple Rev 3+ to Flash
Arduino Duemilanove or Nano w/ ATmega328	chipKIT MAX32	Wiring S with Play Shield @ 16 MHz	LaunchPad with mps430g2231	LeafLabs Maple Rev 3+ to RAM
Arduino Diecimila, Duemilanove, or Nano w/ ATmega168	chipKIT MAX32-USB for Serial	Wiring V1.0/Wiring Mini V1.0 @ 16 MHz	LaunchPad with mps430g2553	LeafLabs Maple Mini Rev 2 to Flash
Arduino Mega 2560	Cerebot MX3cK	Wiring V1.1 ATmega1281 @ 16 MHz		LeafLabs Maple Mini Rev 2 to RAM
Arduino Mega (ATmega1280)	Cerebot MX4cK	Wiring V1.1 ATmega2561 @ 16 MHz		LeafLabs Maple RET6 Edition to Flash
Arduino Mini	Cerebot MX7cK			LeafLabs Maple RET6 Edition to RAM
Arduino Fio	Cerebot 32MX4			LeafLabs Maple Native (Beta) to Flash
Arduino BT w/ ATmega328	Cerebot 32MX7			LeafLabs Maple Native (Beta) to RAM
Arduino BT w/ ATmega168	Microchip PIC32 Starter kit			
LilyPad Arduino w/ ATmega328	Microchip PIC32 Ethernet Starter kit			
LilyPad Arduino w/ ATmega168	Microchip PIC32 USB Starter kit II			

Arduino	chipKIT	Wiring	LaunchPad	Maple
Arduino Pro or Pro Mini (5V, 16 MHz) w/ ATmega328	Microchip PIC32 Explorer 16			
Arduino Pro or Pro Mini (5V, 16 MHz) w/ ATmega168	MirkoElektronika PIC32 Multimedia Board			
Arduino Pro or Pro Mini (3.3V, 8 MHz) w/ ATmega328	MirkoElektronika PIC32 mikroMedia Board			
Arduino Pro or Pro Mini (3.3V, 8 MHz) w/ ATmega168	Pic32 UBW32-MX460			
Arduino NG or older w/ ATmega168	Pic32 UBW32-MX795			
Arduino NG or older w/ ATmega8	Pic32 CUI32-Development Stick			

6. Copyright and Licence

Attribution-NonCommercial-ShareAlike 3.0 Unported (CC BY-NC-SA 3.0)

This is a <u>human-readable summary</u> of the <u>Legal Code</u>.

6.1. Summary

You are free:

- to Share to copy, distribute and transmit the work
- to Remix to adapt the work

Under the following conditions:

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- Noncommercial You may not use this work for commercial purposes.
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