

Installation Guide



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Documentation http://embedXcode.weebly.com/

GitHub repository http://github.com/rei-vilo/embedXcode

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How to Help



Contribute to the project on GitHub.



Help me buy books on Xcode through my Amazon Wish List.

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1. Install the Template

Before installing the template, here are the pre-requisites:



For all boards:

- Install Arduino 0023 or Arduino 1.0.
- Launch it.
- Define the path of the sketchbook in the menu Arduino > Preferences > Sketchbook location.

Arduino provides the reference for code-sense.

As a matter of fact, Wiring is considered as the reference.

Arduino 0023 should be preferred over Arduino 1.0 because Arduino 0023 is Wiring compliant. So is chipKIT MPIDE 0023.

Arduino 1.0 has introduced many small changes in the syntax which are not compatible with previous release. Energia 1.0 is derived from Arduino 1.0.

So I strongly recommend to pick the release which is compatible with your platforms, either Arduino 0023 or Arduino 1.0.







As an option:

- If chipKIT boards are to be used, install Mpide 0023.
- · Launch it.
- Define the path of the sketchbook in the menu Mpide > Preferences > Sketchbook location.



- If Wiring boards are to be used, install Wiring 1.0.
- · Launch it.
- Define the path of the sketchbook in the menu Wiring > Preferences > Sketchbook location.

The two following files require to be deleted.



Multiplatform Arduino compatible IDE Arduino 0023 Compatiblity

Modified version of the Arduino IDE created by Rick Anderson and Mark Sproul of Fair Use Building and Research on May 21, 2011. This software is not supported by the Arduino LLC



/Applications/Wiring.app/Contents/Resources/ Java/cores/AVR8Bit/program.cpp

/Applications/Wiring.app/Contents/Resources/ Java/cores/AVR8Bit/makefile



As an option:

- If LauchPad board is to be used, install Energia 1.0.
- · Launch it.
- Define the path of the sketchbook in the menu Energia > Preferences > Sketchbook location.



Energia 1.0

Modified version of the Arduino IDE for the Texas Instrument LaunchPad MSP430 created by Robert Wessels on January 2012.

This software is not supported by the Arduino LLC.

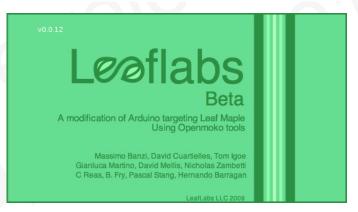


As an option:

- If Maple board is to be used, install MapleIDE.
- · Launch it.
- Define the path of the sketchbook in the menu MapleIDE > Preferences > Sketchbook location.

The Maple reset script —which sends control signals over the USB-serial connection to restart and enter the bootloader— is written in Python and requires the PySerial library:

- Read the instructions at http://leaflabs.com/docs/unix-toolchain.html#os-x and
- Download PySerial library from http://pypi.python.org/pypi/pyserial.



For other boards with a Processing-based IDE, same procedure:

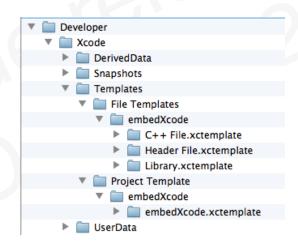
- Install the corresponding Processing-based IDE.
- · Launch it.
- Define the path of the sketchbook.
- Additionally, develop a specific makefile and adapt the Step1 makefile.



Check and create ~/Library/Developer/Xcode

Copy the folder Templates into ~/Library/Developer/Xcode

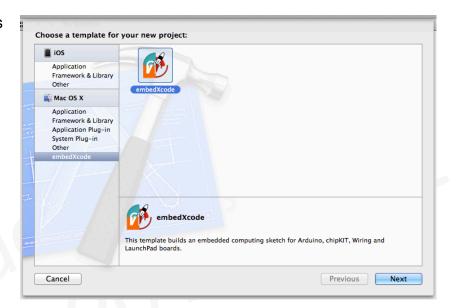




2. Create a New Project

Call the menu File > New > New Project... or press $\bigcirc \Re N$.

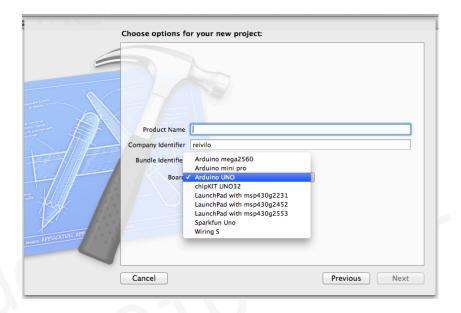
Select embedXcode > embedXcode.



Type in the name of the project.

Select the board on the drop-down list.

Click on Next to save.



3. Configure the Project

The template doesn't define all the parameters, so some of them need to be set manually.

The goal is to have the following work done by the template, provided the right keywords are known.

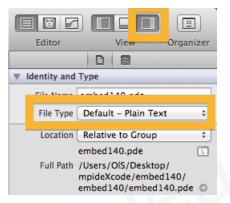
3.1. Declare Sketch .pde File as C++ File

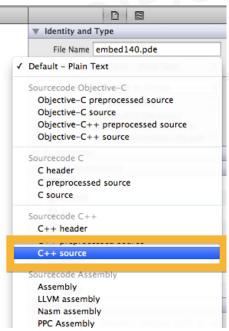
The sketch . pde file is considered as plan text. For code-sense, it should be declared as C++ file.

Select the sketch . pde file.

In the right-most column,

Click on the drop-down list of File Type. Select C++ source.





Now, the sketch is considered as C++ code for code-sense.

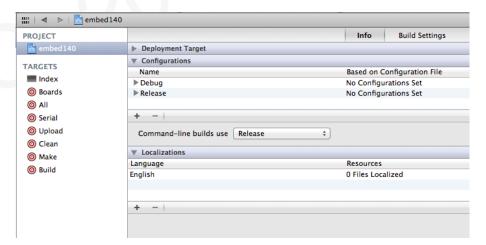


This manual procedure is considered as an issue and reported under #3 Declare PDE File as C++ Source.

3.2. Declare User's Sketchbook

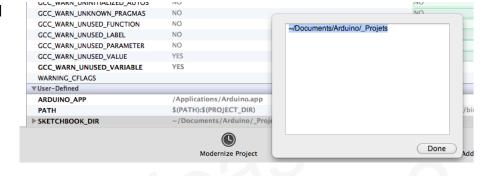
The user's sketchbook is a folder where the user's sketches are saved, among them the libraries in a dedicated sub-folder Libraries.

Select the project and the Build Settings pane.



At the very bottom, double-click on SKETCHB00K_DIR and either type in the name of the folder or drag-and-drop it from a Finder window.

The ~ character is accepted.

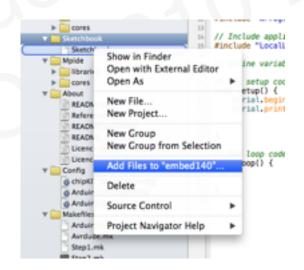


If no sketchbook is defined, SKETCHB00K_DIR takes the value defined for Arduino or chipKIT during the installation process.

3.3. Add User's Libraries

Open the Sketchbook group on the project hierarchy. Right-click to obtain the contextual menu.

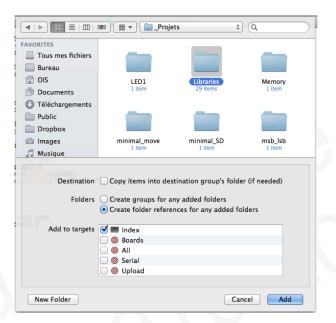
Choose Add file to...



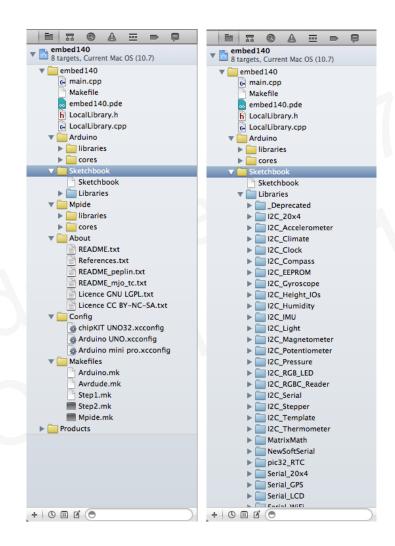
Select the Library sub-folder on the sketchbook folder, tick Add to target > Index and validate with Add.

Both Create group for any added folders and Create folder references for any added folders are relevant.

Don't tick Copy items into destination group's folder (in needed) to avoid duplicating files.



The project hierarchy shows all your libraries.



3.4. Declare Sources for Code-Sense

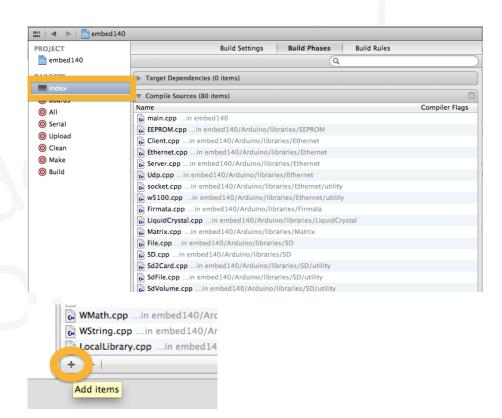
Standard C++ keywords are already known, but not some Arduino and user's library keywords.

The selection of a board defines the headers for code-sense.

So Xcode needs to be taught where to find them.

Select the target Index and the Build Phases pane.

Go a the bottom of the list and click on the + button.



A list shows up.



Select all the . h and . cpp files and click on Add.



This manual procedure is considered as an issue and reported under #2 Populated Sources List for Code-Sense.

3.5. Define the Directories for the Target

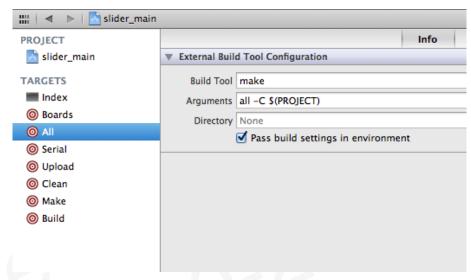
The template doesn't allow to specify the exact directory for the target. In case of an building error, the click-to-error feature may not work properly for the main sketch and the local libraries.

So Xcode needs to be taught where to find them.

This is an optional procedure.

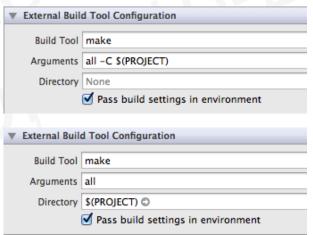
Select the target All.

Feel free to update other targets you use often, as Build and Make.



By default, the template mentions all -C (PROJECT) as arguments.

Remove –C \$(PR0JECT) from the arguments and add \$ (PR0JECT) into directory.



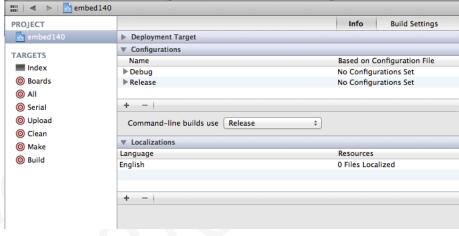
This manual procedure is considered as an issue and reported under #12 Define Directory for a Target.

You're ready now!

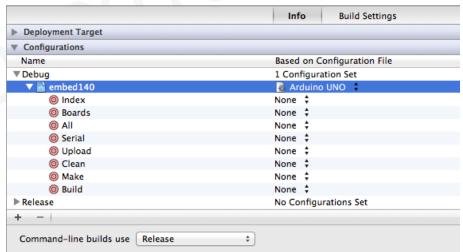
4. Use the Project

4.1. Change the Board

To change the board, select the project and the Info pane.



A drop-down list shows the boards available.



Just select one.

If your board isn't listed, you can create a configuration file. Please refer to §6 Add a file.

The sketch contains conditional #include for the supported IDEs.

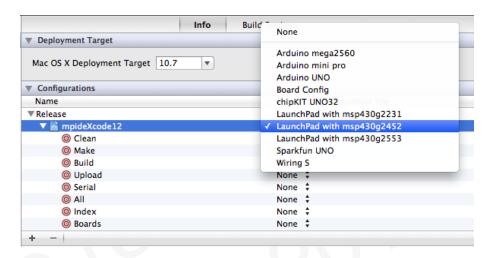
They are now based on the micro-controller reference.

In case Arduino version 0023 is used, replace Arduino.h by WProgram.h.

Those #include statements are included on a code snippet for easy use.

Please refer to <u>Insert Code Snippet with #include</u> Statements.

When a board is selected, the configuration file defines parameters for code-sense.



```
// Core library
#if defined (__AVR_ATmega328P__) || defined
( AVR ATmega2560 ) // Arduino specific
#include "WProgram.h" // - for Arduino 0023
// #include "Arduino.h" // - for Arduino 1.0
#elif defined( 32MX320F128H ) ||
defined( 32MX795F512L ) // chipKIT specific
#include "WProgram.h"
#elif defined( AVR ATmega644P ) // Wiring specific
#include "Wiring.h"
#elif defined( MSP430G2452 ) |
defined(__MSP430G2553__) || defined(__MSP430G2231__) //
LaunchPad specific
#include "Energia.h"
#elif defined(MCU STM32F103RB) ||
defined(MCU STM32F103ZE) || defined(MCU STM32F103CB) ||
defined(MCU_STM32F103RE) // Maple specific
#include "WProgram.h"
#endif
```

4.2. Add a File

Call the menu File > New > New File... or press $\Re N$

Select embedXcode and then Header File, C++ file, Library or Board Configuration Settings File.



Library creates a header file and a C++ code file with the #include statement ready!

#include "LocalLibrary.h"

Board Configuration Settings File allows to define the settings for a new board.

Specify:

- BOARD_TAG is the unique identifier of the board, found in the Boards.txt file.
- BOARD_PORT defines the USB port to be used. This parameter is optional.
- GCC_PREPROCESSOR_DEFINITIONS is the name of the micro-controller of the board, found in the Boards.txt file.
- HEADER_SEARCH_PATHS needs to be updated with the reference of the IDE, ARDUINO_APP for Arduino, MPIDE_APP for Mpide, WIRING_APP for Wiring, or ENERGIA_APP for Energia.

The last two parameters improves the selection of the headers for code-sense.

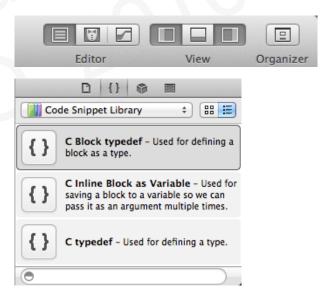
4.3. Insert #include Statements From Code Snippet

A code snippet includes all the #include statements for selecting the core libraries.

To display the code snippets, click on the right button of the View selector.

The library of code snippets is at the bottom of the rightmost pane.

```
// Core library
#if defined (__AVR_ATmega328P__) || defined
( AVR ATmega2560__) // Arduino specific
#include "WProgram.h" // - for Arduino 0023
// #include "Arduino.h" // - for Arduino 1.0
#elif defined(__32MX320F128H__) ||
defined( 32MX795F512L ) // chipKIT specific
#include "WProgram.h"
#elif defined( AVR ATmega644P ) // Wiring specific
#include "Wiring.h"
#elif defined(__MSP430G2452__) || defined(__MSP430G2553__)
|| defined( MSP430G2231 ) // LaunchPad specific
#include "Energia.h"
#elif defined(MCU STM32F103RB) || defined(MCU STM32F103ZE)
|| defined(MCU STM32F103CB) || defined(MCU STM32F103RE) //
Maple specific
#include "WProgram.h"
#endif
```



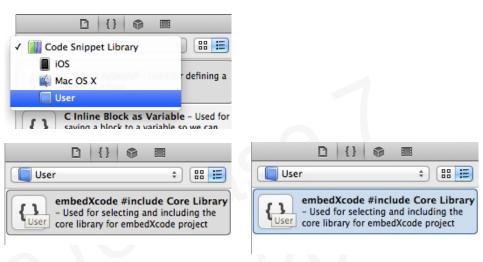
Select User on the drop-down list.

Select the embedXcode #include Core Library snippet.

Click and drop to the destination.

The pointer changes for

The cursor appears on the code.





The code is inserted.

```
2 //
        LocalLibrary.h
        Library header
        Developed with embedXcode
        Project mpideXcode12
        Created by Rei VILO on 27/03/12
        Copyright (c) 2012 http://sites.google.com/site/vilorei
 12 // Core library
 #if defined (_AVR_ATmega328P__) || defined (_AVR_ATmega2560__) // Arduino specific
 #include "WProgram.h" // - for Arduino 0023
// #include "Arduino.h" // - for Arduino 1.0
 #elif defined(__32MX320F128H__) || defined(__32MX795F512L__) // chipKIT specific
 17 #include "WProgram.h"
 #elif defined(_AVR_ATmega644P__) // Wiring specific
 19 #include "Wiring.h"
    #elif defined(_MSP430G2452_) || defined(_MSP430G253__) || defined(_MSP430G2231__) // LaunchPad
    #include "Energia.h"
    #endif
    #ifndef embed1_LocalLibrary_h
    #define embed1_LocalLibrary_h
     #endif
```

4.4. Re-Index the Keywords for Code-Sense

Code-sense is a major feature of Xcode.

Apart from pretty colours on the code and enhanced visibility, code-sense brings:

- · auto-completion,
- · code-snippets and check-as-you-type code monitoring,

click-to-definition

```
// Define variables and constants
12C_Serial mySerial;

// Add setup code
void setup() {
Serial.begin(19200);
Serial.print("\n\n\n***\n");
mySerial.print("\n\n\n\***\n");
mySerial.print(mySerial.whoAmI());

WhoAmi

Wame: WhoAmi

Void
Name: WhoAmi
Declared In: 12C_Serial.h

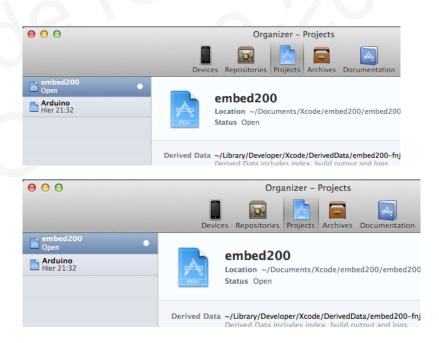
37
```

If code-sense doesn't work, we need to force a re-indexing of the key words.

To do so, first close the project.

Call the menu Window > Organiser and select the Projects pane.

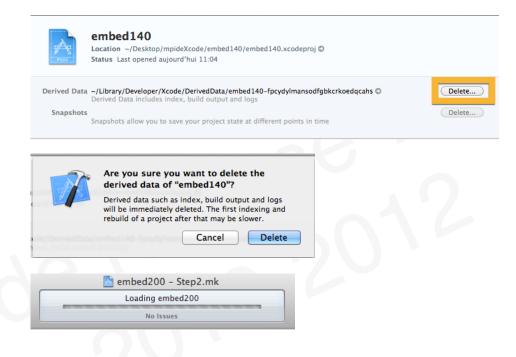
Select then the project.



The index is saved within the Derived Data folder. Click on the Delete button to delete them.

Confirm the deletion.

Load the project.



There's no code-sense yet: everything is in black-and-white, except standard C++ keywords.

The index is being built.



When the index is built, code-sense shows pretty colours.

```
mbed200 - embed200.pde
                                         Build Serial: Succeeded | Yesterday at 21:59
                        No Issues
                     Breakpoints
IIII │ ◀   ▶ │ 🚵 embed200 〉 🦲 embed200 〉 🔜 embed200.pde 〉 No Selection
          embedXcode
 // Core library
#include "WProgram.h"
    // Include application, user and local libraries
#include "LocalLibrary.h"
     // Define variables and constants
     // Add setup code
     void setup() {
          Serial.begin(19200);
Serial.print("\n\n\n***\n");
     // Add loop code
void loop() {
     Serial.print(".");
    delay(100);
```

5. Appendixes

5.1. What Has Been Tested

| Platform | What Has Been Tested | What Has Not Been Tested | Reference Boards |
|-----------|-------------------------------|--------------------------|--|
| Arduino | Sketch compilation and upload | | Arduino Uno, Arduino mega2560 and Arduino mini pro |
| chipKIT | Sketch compilation and upload | | chipKIT UNO32 |
| Wiring | Sketch compilation and upload | | Wiring S |
| LaunchPad | Sketch compilation and upload | | LaunchPad with MSP430G2542, MSP430G2331 and MSP430G2553 |
| Maple | Sketch compilation and upload | | Maple revision 5 |

5.2. Known Issues

Most of the issues are related to unknown keywords for the Xcode 4.3 template.

Most critical issues are:

#2 Populated Sources List for Code-Sense

#3 Declare PDE File as C++ Source

#12 Define Directory for a Target

5.3. Contributions and References

See documents on the About folder for additional contributions and detailed references.

5.4. Version History

| Date | mpideXcode | embedXcode | Installation Guide | Comment |
|--------------|------------|------------|-----------------------|---|
| Jan 22, 2012 | а | | | Initial release |
| Feb 02, 2012 | b | | | chipKIT operational |
| Feb 04, 2012 | С | | | Code-sense operational |
| Feb 06, 2012 | d | | | User libraries |
| Feb 06, 2012 | е | | | Code checking while typing with Index as target |
| Feb 08, 2012 | f | | | Code-sense, click-to-error with standard targets |
| Feb 14, 2012 | g | 1 | 1 | Multi-application, check-as-you-type, template |
| Feb 18, 2012 | 6 | 2 | 2 | Improvements |
| Feb 26, 2012 | | 3 | | Modular makefiles |
| Mar 06, 2012 | 7 | 4 | 3 | Arduino 1.0 implementation |
| Mar 12, 2012 | 8 | 5 | | Bugs fixed |
| Mar 15, 2012 | 9 | 6 | 4 | All Arduino/chipKIT/Wiring/Energia and user libraries included by default |
| Apr 05, 2012 | 10 | 7 | 5 | Wiring 1.0 and Energia 1.0 implementations |
| Apr 08, 2012 | 11 | 8 | 5 | Bugs fixed |
| Apr 16, 2012 | 12 | 9 | 6 | Code-sense reference defined by selected board |
| May 23, 2012 | 13 | 10 | 7 | LeafLabs Maple implementation |

5.5. Referenced Boards

Not all boards have been tested. Please refer to What Has Been Tested for more details.

According to the Boards.txt files:

| Arduino | chipKIT | Wiring | LaunchPad | Maple |
|--|---|--|----------------------------|---------------------------------------|
| Arduino Uno | chipKIT UNO32 | Wiring S @ 16 MHz | LaunchPad with mps430g2452 | LeafLabs Maple Rev 3+ to Flash |
| Arduino Duemilanove or Nano w/ ATmega328 | chipKIT MAX32 | Wiring S with Play Shield @ 16 MHz | LaunchPad with mps430g2231 | LeafLabs Maple Rev 3+ to RAM |
| Arduino Diecimila, Duemilanove, or Nano w/ ATmega168 | chipKIT MAX32-USB for Serial | Wiring V1.0/Wiring Mini V1.0 @ 16 MHz | LaunchPad with mps430g2553 | LeafLabs Maple Mini Rev 2 to Flash |
| Arduino Mega 2560 | Cerebot MX3cK | Wiring V1.1 ATmega1281 @ 16 MHz | | LeafLabs Maple Mini Rev 2 to RAM |
| Arduino Mega (ATmega1280) | Cerebot MX4cK | Wiring V1.1 ATmega2561 @ 16 MHz | | LeafLabs Maple RET6 Edition to Flash |
| Arduino Mini | Cerebot MX7cK | | | LeafLabs Maple RET6 Edition to RAM |
| Arduino Fio | Cerebot 32MX4 | | | LeafLabs Maple Native (Beta) to Flash |
| Arduino BT w/ ATmega328 | Cerebot 32MX7 | | | LeafLabs Maple Native (Beta) to RAM |
| Arduino BT w/ ATmega168 | Microchip PIC32 Starter kit | | | |
| LilyPad Arduino w/ ATmega328 | Microchip PIC32 Ethernet Starter kit | | | |
| LilyPad Arduino w/ ATmega168 | Microchip PIC32 USB Starter kit II | | | |

| Arduino | chipKIT | Wiring | LaunchPad | Maple |
|--|--|--------|-----------|-------|
| Arduino Pro or Pro Mini (5V, 16 MHz) w/ ATmega328 | Microchip PIC32 Explorer 16 | | | |
| Arduino Pro or Pro Mini (5V, 16 MHz) w/ ATmega168 | MirkoElektronika PIC32 Multimedia Board | | | |
| Arduino Pro or Pro Mini (3.3V, 8 MHz) w/ ATmega328 | MirkoElektronika PIC32 mikroMedia Board | | | |
| Arduino Pro or Pro Mini (3.3V, 8 MHz) w/ ATmega168 | Pic32 UBW32-MX460 | | | |
| Arduino NG or older w/ ATmega168 | Pic32 UBW32-MX795 | | | |
| Arduino NG or older w/ ATmega8 | Pic32 CUI32-Development Stick | | | |

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