

Empirical Processes: Theory and Application

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Outline

- 1 Introduction
- 2 Glivenko-Cantelli Theorem
- 3 Donsker's Theorem

Overview

- Empirical processes arise naturally in the study of statistics as a way to understand the behavior of sample data relative to the underlying population distribution.
- They are essential in fields that require robust, non-parametric methods where traditional parametric assumptions cannot be satisfactorily met.
- This presentation explores the theoretical foundations of empirical processes, their practical applications, and how they inform modern statistical practice.
- Understanding these concepts is crucial for professionals in data-intensive fields such as data science, biostatistics, and financial analytics.

Basic Concepts - Empirical Distribution Function

- Empirical Distribution Function (EDF): For a sample X_1, X_2, \dots, X_n from a distribution F , the EDF is defined as follows:

$$\hat{F}_n(t) = \frac{1}{n} \sum_{i=1}^n I(X_i \leq t),$$

where I is the indicator function, which equals 1 if the condition inside the parentheses is true, and 0 otherwise.

- EDF is a step function that jumps $1/n$ at each sample point.
- Properties:
 - Right-continuous
 - Converges pointwise to the CDF as $n \rightarrow \infty$

Basic Concepts - Glivenko-Cantelli Theorem

- The Glivenko-Cantelli Theorem, a fundamental result in the theory of empirical processes, states that the EDF converges uniformly to the true distribution function as the sample size increases:

$$\sup_{t \in \mathbb{R}} |\hat{F}_n(t) - F(t)| \rightarrow 0 \text{ almost surely as } n \rightarrow \infty.$$

- This theorem assures us that the empirical distribution function is a good estimator of the true distribution function in a very strong sense.
- The Glivenko–Cantelli classes arise in Vapnik–Chervonenkis theory, with applications to machine learning.

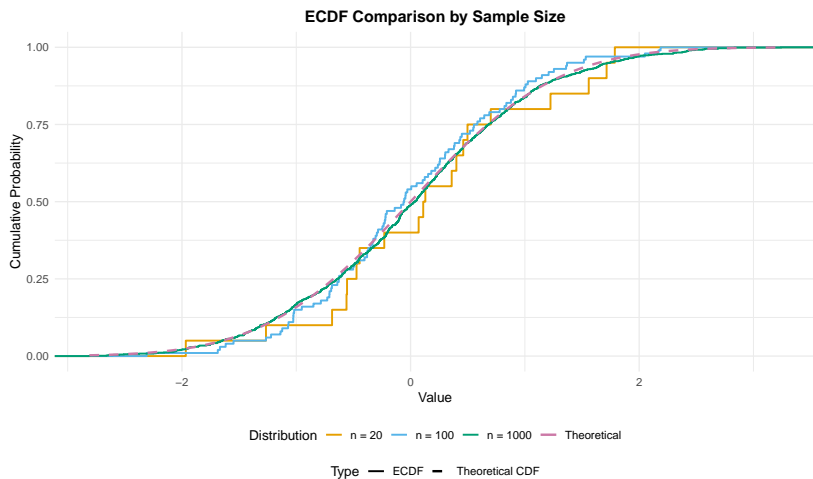
Cumulative Distribution Function

- The CDF F of a random variable X is defined as:

$$F(t) = P(X \leq t),$$

- F is right-continuous with left limits and increases monotonically.
- Properties:
 - Bounded: $0 \leq F(t) \leq 1$
 - Non-decreasing: If $a \leq b$, then $F(a) \leq F(b)$

Toy Example



Empirical process

- The empirical process $\alpha_n(t)$ associated with \hat{F}_n is then given by:

$$\alpha_n(t) = \sqrt{n}(\hat{F}_n(t) - F(t))$$

- This process measures the fluctuation of the EDF around the true distribution F .
- The empirical process provides a mathematical framework for understanding and quantifying how sample data approximates its true distribution. It reveals large sample properties, especially in the context of nonparametric statistics.

Outline

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- 2 Glivenko-Cantelli Theorem**
- 3 Donsker's Theorem

Introduction

- The Glivenko-Cantelli Theorem, also known as the "Fundamental Theorem of Statistics," is crucial for validating the empirical distribution function (EDF) as a consistent estimator of the cumulative distribution function (CDF).
- It guarantees that the EDF converges uniformly to the CDF across all points as the sample size increases indefinitely.

Glivenko-Cantelli Theorem

Theorem 2.1

For i.i.d. real-valued random variables X_1, X_2, \dots, X_n with distribution function F , we have almost sure convergence:

$$\|F_n - F\|_\infty = \sup_{x \in \mathbb{R}} |F_n(x) - F(x)| \xrightarrow{a.s.} 0 \quad \text{as } n \rightarrow \infty$$

This implies uniform convergence of the EDF to the CDF over the entire real line.

Glivenko–Cantelli class

Definition 2.2

A class \mathcal{F} is called a Glivenko–Cantelli class with respect to a probability measure P if

$$\|P_n - P\|_{\mathcal{F}} = \sup_{f \in \mathcal{F}} |P_n f - P f| \rightarrow 0,$$

where $Pf = \int_S f d\mathbb{P}$.

If convergence is:

- Almost surely: Strong GC class;
- In probability: weak GC class.

The GC Theorem is a special case, with $\mathcal{F} = \{I(x \leq t) : t \in \mathbb{R}\}$.

Proof Outline

- Concentration: with probability at least $1 - \exp(-2\epsilon^2 n)$,

$$\|P - P_n\|_G \leq \mathbf{E} \|P - P_n\|_G + \epsilon.$$

- Symmetrization: $\mathbf{E} \|P - P_n\|_G \leq 2\mathbf{E} \|R_n\|_G$, where we've defined the Rademacher process $R_n(g) = (1/n) \sum_{i=1}^n \epsilon_i g(X_i)$.
- Restrictions.

Proof - Concentration

- Fix $-\infty = x_0 < x_1 < \dots < x_{n-1} < x_n = \infty$ such that $F(x_j) - F(x_{j-1}) = \frac{1}{n}$ for $j = 1, \dots, n$. Now for all $x \in \mathbb{R}$ there exists $j \in \{1, \dots, m\}$ such that $x \in [x_{j-1}, x_j]$.

$$F_n(x) - F(x) \leq F_n(x_j) - F(x_{j-1}) = F_n(x_j) - F(x_j) + \frac{1}{n}$$

$$F_n(x) - F(x) \geq F_n(x_{j-1}) - F(x_j) = F_n(x_{j-1}) - F(x_{j-1}) - \frac{1}{n}$$

Therefore,

$$\|F_n - F\|_\infty = \sup_{x \in \mathbb{R}} |F_n(x) - F(x)| \leq \max_{j \in \{1, \dots, n\}} |F_n(x_j) - F(x_j)| + \frac{1}{n}$$

Proof - Concentration

- Let $G = \{I[x \leq t] : t \in \mathbf{R}\}$, then

$$\|F_n - F\|_\infty = \|P - P_n\|_G = \sup_{g \in G} \|Pg - P_ng\|.$$

- The concentration inequality implies that,

$$P(\|F_n - F\|_\infty \leq \mathbf{E}[\|F_n - F\|_\infty] + \epsilon) \leq 1 - \exp(-2\epsilon^2 n).$$

Proof - Symmetrization

We symmetrize by replacing Pg by $P'_n g = \frac{1}{n} \sum_{i=1}^n g(X'_i)$,

$$\begin{aligned}
 \mathbf{E}[\|P - P_n\|_G] &= \mathbf{E} \left[\sup_{g \in G} \left| \mathbf{E} \left[\frac{1}{n} \sum_{i=1}^n (g(X'_i) - g(X_i)) \right] \right| \right] \\
 &\leq \mathbf{E} \left[\mathbf{E} \left[\sup_{g \in G} \left| \frac{1}{n} \sum_{i=1}^n (g(X'_i) - g(X_i)) \right| \right] \right] \\
 &= \mathbf{E} \left[\sup_{g \in G} \left| \frac{1}{n} \sum_{i=1}^n (g(X'_i) - g(X_i)) \right| \right] \\
 &= \mathbf{E} \|P'_n - P_n\|_G.
 \end{aligned}$$

Proof - Symmetrization

We symmetrize again: for any $\epsilon_i \in \{+1, -1\}$,

$$\mathbf{E} \left[\sup_{g \in G} \left| \frac{1}{n} \sum_{i=1}^n (g(X'_i) - g(X_i)) \right| \right] = \mathbf{E} \left[\sup_{g \in G} \left| \frac{1}{n} \sum_{i=1}^n \epsilon_i (g(X'_i) - g(X_i)) \right| \right]$$

Then we have

$$\begin{aligned} & \mathbf{E} \left[\sup_{g \in G} \left| \frac{1}{n} \sum_{i=1}^n \epsilon_i (g(X'_i) - g(X_i)) \right| \right] \\ & \leq \mathbf{E} \left[\sup_{g \in G} \left| \frac{1}{n} \sum_{i=1}^n \epsilon_i g(X'_i) \right| \right] + \mathbf{E} \left[\sup_{g \in G} \left| \frac{1}{n} \sum_{i=1}^n \epsilon_i g(X_i) \right| \right] \\ & \leq 2\mathbf{E} \|R_n\|_G, \end{aligned}$$

where $R_n(g) = (1/n) \sum_{i=1}^n \epsilon_i g(X_i)$ is the Rademacher process .

Proof - Restrictions

Lemma 2.3

For $A \subseteq \mathbb{R}^n$ with $R = \max_{a \in A} \|a\|_2$,

$$\mathbf{E} \sup_{a \in A} \langle \epsilon, a \rangle \leq \sqrt{2R^2 \log |A|}.$$

Hence

$$\mathbf{E} \sup_{a \in A} |\langle \epsilon, a \rangle| = \mathbf{E} \sup_{a \in A \cup -A} \langle \epsilon, a \rangle \leq \sqrt{2R^2 \log(2|A|)}.$$

Proof - Restrictions

For the class G of step functions, $R \leq 1/\sqrt{n}$ and $|A| \leq n+1$. Thus, with probability at least $1 - \exp(-2\epsilon^2 n)$,

$$\|P - P_n\|_G \leq \sqrt{\frac{8 \log(2(n+1))}{n}} + \epsilon$$

By Borel-Cantelli, $\|P - P_n\|_G \xrightarrow{as} 0$.

Empirical Risk Minimization

We define a loss function $l(\theta, z)$ which measures how bad it is to choose θ when the outcome is z . For $Z \sim P$, the risk is $L(\theta) = Pl(\theta, z)$.

- Pattern classification: $\theta : \mathcal{X} \rightarrow \{0, 1\}, z = (x, y) \in \mathcal{X} \times \{0, 1\}$, $\ell(\theta, (x, y)) = 1[\theta(x) \neq y]$. Then we aim to choose $\theta \in \Theta$ to minimize the probability of misclassification.
- Density estimation: p_θ is a density, $X \sim P, p_{\theta^*}, \ell(\theta, z) = -\log p_\theta(z)$. Then we aim to choose θ to minimize

$$\mathbf{E} \log \frac{p_{\theta^*}(X)}{p_\theta(X)} = D_{KL}(p_{\theta^*} \| p_\theta)$$

- Regression: $\theta \in \mathbb{R}^p, z = (x, y), \ell(\theta, (x, y)) = |\theta'x - y|$. Then we aim to choose θ to minimize expected absolute error.

Empirical Risk Minimization

Suppose Z_1, \dots, Z_n are i.i.d. according to P . Define the empirical risk as

$$L_n(\theta) = P_n \ell(\theta, Z) = \frac{1}{n} \sum_{i=1}^n \ell(\theta, Z_i)$$

Empirical risk minimization chooses θ to minimize $L_n(\theta)$.

We are interested in controlling the excess risk,

$$L(\hat{\theta}) - \inf_{\theta \in \Theta} L(\theta) = L(\hat{\theta}) - L(\theta^*)$$

where θ^* minimizes L on Θ . We can decompose it as

$$L(\hat{\theta}) - L(\theta^*) = [L(\hat{\theta}) - L_n(\hat{\theta})] + [L_n(\hat{\theta}) - L_n(\theta^*)] + [L_n(\theta^*) - L(\theta^*)],$$

with approximation error and statistical error.

Empirical Risk Minimization

For statistical error, we have

$$L_n(\theta^*) - L(\theta^*) = \frac{1}{n} \sum_{i=1}^n \ell(\theta^*, Z_i) - P\ell(\theta^*, Z).$$

The law of large numbers shows that this term converges to zero. But more generally, we need to study the uniform laws of large numbers

$$L(\hat{\theta}) - L_n(\hat{\theta}) \leq \sup_{\theta \in \Theta} |L(\theta) - L_n(\theta)| = \sup_{\theta \in \Theta} |P\ell_\theta - P_n\ell_\theta|.$$

We need to show ℓ_θ is a GC class (or prove a general form of GC Theorem).

Empirical Risk Minimization

Recall that

Definition 2.4

The Rademacher complexity of F is $\mathbf{E} \|R_n\|_F$, where the empirical process R_n is defined as

$$R_n(f) = \left| \frac{1}{n} \sum_{i=1}^n \epsilon_i f(X_i) \right|$$

where the $\epsilon_1, \dots, \epsilon_n$ are Rademacher random variables: i.i.d. uniform on $\{\pm 1\}$.

Note that this is the expected supremum of the alignment between the random $\{\pm 1\}$ -vector ϵ and $F(X_1^n)$, the set of n -vectors obtained by restricting F to the sample X_1, \dots, X_n .

Uniform laws and Rademacher complexity

Theorem 2.5

For any F , $\mathbf{E} \|P - P_n\|_F \leq 2\mathbf{E} \|R_n\|_F$. If $F \subset [0, 1]^X$,

$$\frac{1}{2}\mathbf{E} \|R_n\|_F - \sqrt{\frac{\log 2}{2n}} \leq \mathbf{E} \|P - P_n\|_F \leq 2\mathbf{E} \|R_n\|_F$$

and, with probability at least $1 - 2\exp(-2\epsilon^2 n)$,

$$\mathbf{E} \|P - P_n\|_F - \epsilon \leq \|P - P_n\|_F \leq \mathbf{E} \|P - P_n\|_F + \epsilon$$

Thus, $\mathbf{E} \|R_n\|_F \rightarrow 0$ iff $\|P - P_n\|_F \xrightarrow{as} 0$.

The sup of the empirical process $P - P_n$ is concentrated about its expectation, and its expectation is about the same as the expected sup of the Rademacher process R_n .

Controlling Rademacher complexity

Control $\mathbf{E} \|R_n\|_F$:

- $|F(X_1^n)|$ small.
- For binary-valued functions: Vapnik-Chervonenkis dimension. Bounds rate of growth function. Can be bounded for parameterized families.
- Structural results on Rademacher complexity: Obtaining bounds for function classes constructed from other function classes.
- Covering numbers: Dudley entropy integral, Sudakov lower bound.
- For real-valued functions: scale-sensitive dimensions.

Extension: Glivenko-Cantelli Theorem of MDF

For $\forall \mathbf{u}, \mathbf{v} \in \mathcal{M}$, let

$$\delta(\mathbf{u}, \mathbf{v}, \mathbf{x}) = \prod_{k=1}^K I\{x_k \in \bar{B}(u_k, r_k)\} = \prod_{k=1}^K I\{x_k \in \bar{B}(u_k, d_k(u_k, v_k))\}.$$

Definition 2.6 (Metric distribution function)

Given a probability measure μ , we define the metric distribution function $F_{\mu}^M(u, v)$ of μ on $\mathcal{M} : \forall \mathbf{u}, \mathbf{v} \in \mathcal{M}$,

$$F_{\mu}^M(\mathbf{u}, \mathbf{v}) = \mu \left[\prod_{k=1}^K \bar{B}(u_k, r_k) \right] = E[\delta(\mathbf{u}, \mathbf{v}, \mathbf{X})]$$

Extension: Glivenko-Cantelli Theorem of MDF

Suppose that $\{\mathbf{X}_1, \dots, \mathbf{X}_n\}$ are iid samples generated from a probability measure μ on a product metric space $\mathcal{M} = \prod_{k=1}^K \mathcal{M}_k$. We define the empirical metric distribution function (EMDF) associated with μ by the following formula naturally:

$$F_{\mu,n}^M(\mathbf{u}, \mathbf{v}) = \frac{1}{n} \sum_{l=1}^n \delta(\mathbf{u}, \mathbf{v}, \mathbf{X}_l)$$

Extension: Glivenko-Cantelli Theorem of MDF

we define the collection of the indicator functions of closed balls on \mathcal{M} :
 $\mathcal{F} = \{\delta(\mathbf{u}, \mathbf{v}, \cdot) : \mathbf{u} \in \mathcal{M}, \mathbf{v}\}.$

Theorem 2.7

Let $\mathcal{M} = \prod_{k=1}^K \mathcal{M}_k$ be a product space and μ be a probability measure on it. Suppose that $\{\mathbf{X}_1, \dots, \mathbf{X}_n\}$ is a sample of iid observations from μ . Define $\mathcal{F}(\mathbf{X}_1^n) := \{(f(\mathbf{X}_1), \dots, f(\mathbf{X}_n)) \mid f \in \mathcal{F}\}$. If μ satisfies that

$$\frac{1}{n} E_{\mathbf{X}} [\log (\text{card} (\mathcal{F} (\mathbf{X}_1^n)))] \rightarrow 0$$

where $\text{card}(\cdot)$ is the cardinality of a set, we have the Glivenko-Cantelli property of our empirical metric distribution function:

$$\lim_{n \rightarrow \infty} \sup_{\mathbf{u} \in \mathcal{M}, \mathbf{v} \in \mathcal{M}} |F_{\mu, n}^M(\mathbf{u}, \mathbf{v}) - F_{\mu}^M(\mathbf{u}, \mathbf{v})| = 0, \text{ a.s.}$$

Remark

The conditions of Theorem are often satisfied in practice.

- The first example is $\mathcal{M} = \mathbb{R}^q$ with the ℓ_p -norm (where p is a positive integer or ∞), and μ is an arbitrary probability measure because the set of ℓ_p ball has a finite VC-dimension. Since the VC-dimension of closed balls in Euclidean space \mathbb{R}^q is $q + 2$, if $q = o\left(\frac{n}{\log n}\right)$ the Glivenko-Cantelli property still holds.
- The second example is that \mathcal{M} is a smooth regular curve in Euclidean space or a sphere in \mathbb{R}^q with the geodesic distance, and μ is an arbitrary probability measure.
- The third example is that \mathcal{M} is a set of polygonal curves in \mathbb{R}^d with the Hausdorff distance for the Fréchet distance and μ is an arbitrary probability measure.
- Another example is that \mathcal{M} is a separable Hilbert space with a probability measure μ with support on a finite-dimensional subspace because the set of balls on the support of μ has a finite VC-dimension.

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- 1 Introduction
- 2 Glivenko-Cantelli Theorem
- 3 Donsker's Theorem**

Introduction

- Donsker's Theorem is a fundamental result in the field of probability theory and statistical inference.
- It generalizes the central limit theorem (CLT) to the setting of stochastic processes.
- Often referred to as the "Invariance Principle" or "functional central limit theorem".

Donsker's Theorem

Theorem 3.1 (Donsker's Invariance Principle)

Let X_1, X_2, \dots be i.i.d. random variables with $\mathbb{E}[X_i] = 0$ and $\text{Var}(X_i) = 1$. Define the empirical process

$$S_n(t) = \frac{1}{\sqrt{n}} \sum_{i=1}^{\lfloor nt \rfloor} X_i,$$

for $t \in [0, 1]$. Then as $n \rightarrow \infty$, the process $S_n(t)$ converges in distribution in $D[0, 1]$ to a standard Brownian motion $W(t)$.

The central limit theorem asserts that $S_n(1)$ converges in distribution to a standard Gaussian random variable $W(1)$ as $n \rightarrow \infty$. Donsker's invariance principle extends this convergence to the whole function $S_n(t)$.

Tightness

Here we define a concept of tightness for collections of measures and random variables. Intuitively this ensures that a collection of measures does not have mass that escapes to infinity. Tightness is often used to prove weak convergence.

Definition 3.2

Let (S, \mathcal{S}) be a measurable space. A collection of measures $\{\mu_i\}$ is tight if for all $\epsilon > 0$ there exists a compact set $K \in S$ such that $\sup_i \mu_i(K^c) < \epsilon$ for all i .

We say a random variable X is tight if for all $\epsilon > 0$ there is an M_ϵ such that

$$\mathbb{P}(\|X\| > M_\epsilon) < \epsilon$$

Tightness

Definition 3.3

A set is relatively compact if its closure is compact.

Let Π be a family of probability measures on (S, \mathcal{S}) . We call Π relatively compact if every sequence of elements of Π contains a weakly convergent subsequence. Explicitly this means that if Π is relatively compact, then there exists a subsequence $(\mathbb{P}_{n_i}) \in \Pi$ and a probability measure Q , which need not be contained in (S, \mathcal{S}) , such that $\mathbb{P}_{n_i} \Rightarrow_i Q$.

Theorem 3.4

If Π is tight, then it is relatively compact.

Corollary 3.5

If (\mathbb{P}_n) is tight and each weakly convergent subsequence converges to \mathbb{P} , then the entire sequence converges weakly to \mathbb{P} .

Tightness

Definition 3.6

A modulus of continuity of an arbitrary function x is defined by

$$w(x, \delta) := \sup_{|s-t| \leq \delta} |x(s) - x(t)|$$

where $\delta \geq 0$.

Lemma 3.7

If

$$\left(X_{t_1}^n, \dots, X_{t_k}^n \right) \Rightarrow_n \left(X_{t_1}, \dots, X_{t_k} \right)$$

holds for all t_1, \dots, t_k , and if

$$\lim_{\delta \rightarrow 0} \limsup_{n \rightarrow \infty} \mathbf{P} [w(X^n, \delta) \geq \epsilon] = 0$$

for each positive ϵ , then $X^n \Rightarrow_n X$.

Tightness

Lemma 3.8

Suppose $0 = t_0 < t_1 < \dots < t_k = 1$ and

$$\min_{1 \leq i \leq k} (t_i - t_{i-1}) \geq \delta$$

If we define $I_i := [t_{i-1}, t_i]$, then for arbitrary x ,

$$w(x, \delta) \leq 3 \max_{1 \leq i \leq k} \sup_{s \in I_i} |x(s) - x(t_{i-1})|$$

and, for arbitrary \mathbb{P} ,

$$\mathbb{P}[x : w(x, \delta) \geq 3\epsilon] \leq \sum_{i=1}^k \mathbb{P}\left[x : \sup_{s \in I_i} |x(s) - x(t_{i-1})| \geq \epsilon\right]$$

Proof Outline

- Show tightness of the sequence of processes.
- Demonstrate finite-dimensional convergence to those of the Brownian motion.
- Apply Prokhorov's theorem to conclude the weak convergence to Brownian motion.

Proof

Theorem 3.9

There exists on (C, C) a probability measure, \mathbb{W} , with the finite dimensional distribution specified by Wiener measure.

Proof

Define

$$S_n(t) := \frac{1}{\sqrt{n}} S_{\lfloor nt \rfloor} + (nt - \lfloor nt \rfloor) \frac{1}{\sqrt{n}} X_{\lfloor nt \rfloor + 1}$$

at t . The function $X^n(w)$ is a linear interpolation (a linear mapping between points) between values at $S_i(t)/\sqrt{ns}$ at points i/n .

- The existence of the Wiener measure \mathbb{W} is proven.
- Then

$$(S_n(s), S_n(t) - S_n(s)) \xRightarrow[n]{} (W_s, W_t - W_s)$$

which implies

$$(S_n(s), S_n(t)) \xRightarrow[n]{} (W_s, W_t)$$

Proof

- Show the tightness

$$\lim_{\delta \rightarrow 0} \limsup_{n \rightarrow \infty} \mathbb{P} [w(S_n, \delta) \geq \epsilon] = 0$$

to obtain

$$(S_n(t_1), \dots, S_n(t_k)) \xRightarrow[n]{} (W_{t_1}, \dots, W_{t_k})$$

- For lemma

$$\begin{aligned} \mathbb{P} [w(S_n, \delta) \geq 3\epsilon] &\leq \sum_{i=1}^k \mathbb{P} \left(\sup_{t_{i-1} \leq s \leq t_i} |S_n(s) - S_n(t_{i-1})| \geq \epsilon \right) \\ &\leq \sum_{i=1}^k \mathbb{P} \left(\sup_{s < t_i - t_{i-1}} |S_s| \geq \epsilon \sqrt{n} \right) \\ &\leq k \mathbb{P} \left(\max_{s \leq m} |S_s| \geq \epsilon \sqrt{n} \right). \end{aligned}$$

Proof

- By Etemadi's inequality, we then see that

$$\mathbb{P} [w(S_n, \delta) \geq 3\epsilon] \leq 3k \max_{s \leq m} \mathbb{P} \left[|S_s| \geq \frac{\epsilon \sqrt{n}}{3} \right]$$

- We can reformulate with Etemadi's inequality to be

$$\lim_{\lambda \rightarrow \infty} \limsup_{n \rightarrow \infty} \lambda^2 \max_{s \leq n} \mathbb{P} [|S_s| \geq \lambda \sqrt{n}] = 0.$$

Proof

- First, for large s , we use the central limit theorem to show that the partial sum converges to the standard normal distribution. So, by the central limit theorem, if s_λ in the maximum is large enough and $s_\lambda \leq s \leq n$, then

$$\mathbb{P} [|S_s| \geq \lambda \sqrt{n}] < \frac{3}{\lambda^4}$$

- In the second case, for small $s \leq s_\lambda$, we use Chebyshev's inequality to show that

$$\mathbb{P} [|S_s| \geq \lambda \sqrt{n}] < \frac{s_\lambda}{\lambda^2 n}.$$

Donsker Theorem

Theorem 3.10 (Donsker (1952))

Let F be continuous distribution function. Define the empirical process:

$$\mathbb{G}_n(t) = \sqrt{n}(F_n(t) - F(t))$$

Then \mathbb{G}_n converges weakly to a Brownian bridge G in the space $\mathcal{D}[0, 1]$:

$$\mathbb{G}_n \rightsquigarrow G$$

where G is a Gaussian process with covariance function:

$$\mathbb{E}[G(s)G(t)] = F(s \wedge t) - F(s)F(t)$$

Definition and Properties

Definition

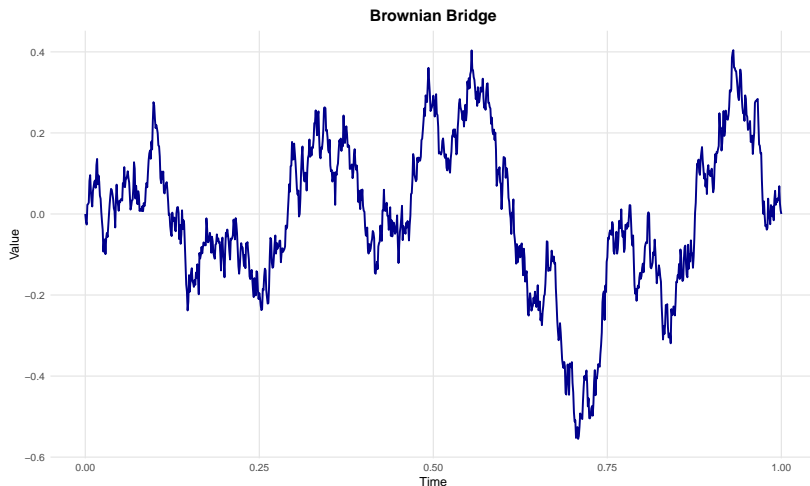
A **Brownian Bridge** is a stochastic process $B(t)$, for $t \in [0, 1]$, defined by the conditional property that $B(0) = B(1) = 0$ given a standard Brownian motion $W(t)$. It can be expressed as:

$$B(t) = W(t) - tW(1)$$

Key Properties

- **Gaussian Process:** $B(t)$ has Gaussian increments with mean zero and covariance function given by $\min(s, t) - st$.
- **Continuity:** $B(t)$ enjoys the continuity properties of Brownian motion, but it is "pinned" at the endpoints 0 and 1 to be zero.

Brownian Bridge



Application: Extreme Process

Theorem 3.11 (Mapping Theorem)

If h is continuous on C , then $X^n \Rightarrow W$ implies $h(X^n) \Rightarrow h(W)$.

We can find the limiting distribution of $h(X^n)$ if we can find the distribution of $h(W)$, and we can in many cases find the distribution of $h(W)$ by finding the limiting distribution of $h(X^n)$ in some simple special case and then using $h(X^n) \Rightarrow h(W)$ in the other direction.

Application: Extreme Process

- Our goal is to derive the limiting distribution of

$$M_n = \max_{0 \leq i \leq n} S_i$$

- Since $h(x) = \sup_t x(t)$ is a continuous function on C , it follows from $X^n \Rightarrow W$ and the mapping theorem that $\sup_t X_t^n \Rightarrow \sup_t W_t$. Obviously, $\sup_t X_t^n = M_n / \sigma \sqrt{n}$, and so

$$\frac{M_n}{\sigma \sqrt{n}} \Rightarrow \sup_t W_t$$

Application: Extreme Process

- For the easy special case, assume that the independent ξ_i take the values ± 1 with probability $\frac{1}{2}$ each, so that S_0, S_1, \dots are the successive positions in a symmetric random walk starting from the origin.
- For each nonnegative integer a ,

$$P[M_n \geq a] = 2P[S_n > a] + P[S_n = a].$$

- Since

$$P[M_n \geq a] - P[S_n = a] = P[M_n \geq a, S_n < a] + P[M_n \geq a, S_n > a]$$

The second term on the right is just $P[S_n > a]$

- For reflection principle, we have

$$P[M_n \geq a, S_n < a] = P[M_n \geq a, S_n > a]$$

Application: Extreme Process

- Let $a_n = \lceil an^{1/2} \rceil$, then

$$\mathbb{P} \left[M_n / \sqrt{n} \geq a \right] = 2\mathbb{P} [S_n > a_n] + \mathbb{P} [S_n = a_n] .$$

- The second term here goes to 0.
- $\mathbb{P} [S_n > a_n] \rightarrow \mathbb{P} [N > a]$ by the central limit theorem, and so $\mathbb{P} [M_n / \sqrt{n}] \rightarrow 2\mathbb{P} [N > a]$ for $a \geq 0$.
- The limit distribution become

$$\mathbb{P} \left[\sup_t W_t \leq a \right] = \frac{2}{\sqrt{2\pi}} \int_0^a e^{u^2/2} du, \quad a \geq 0$$

Application: Kolmogorov-Smirnov test

- The Kolmogorov-Smirnov (K-S) test is a nonparametric test used to determine whether two samples come from the same distribution.
- It compares the empirical distribution functions of two samples, or one sample with a theoretical distribution.
- It is particularly useful because it makes no assumption about the distribution of data.

The K-S Test Statistic

Definition

Given an empirical distribution function $F_n(x)$ for a sample and a theoretical distribution $F(x)$, the K-S test statistic is defined as:

$$D_n = \sup_x |F_n(x) - F(x)|$$

where \sup denotes the supremum of the set of absolute differences.

Interpretation

D_n measures the maximum distance between the empirical distribution function of the sample and the theoretical distribution function.

Kolmogorov distribution

The Kolmogorov distribution is the distribution of the random variable

$$K = \sup_{t \in [0,1]} |B(t)|$$

where $B(t)$ is the Brownian bridge. The cumulative distribution function of K is given by

$$\Pr(K \leq x) = 1 - 2 \sum_{k=1}^{\infty} (-1)^{k-1} e^{-2k^2 x^2} = \frac{\sqrt{2\pi}}{x} \sum_{k=1}^{\infty} e^{-(2k-1)^2 \pi^2 / (8x^2)}.$$

Thank You